

<p>SHEET 10</p> <p>LTPP TRAFFIC DATA</p> <p>TRAFFIC VOLUME AND LOAD</p> <p>ESTIMATE UPDATE - NO SITE COUNT</p>	<p>STATE ASSIGNED ID [_ _ _ _]</p> <p>STATE CODE [87]</p> <p>SHRP SECTION ID [3001]</p>
---	---

1. ANNUAL TRAFFIC ESTIMATES

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S / YR GPS LANE (1000's)
1991	<u>9300</u> 8061	<u>1030</u> 915	<u>4343</u> 3627	<u>500</u> 412	<u>238</u> 195

TRF-108

2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)

- ☒ Growth factored last year's estimate.
- ☐ Estimated based on volume counts at nearby locations.
- ☐ Used computerized network analysis.
- ☐ Other _____

5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT

- ☒ System distribution factors.
- ☐ Other _____

3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
- ☐ Used count data from nearby sites.
- ☐ Used count data from previous years at GPS site.
- ☒ Used system averages from previous year counts.
- ☐ Used computerized network analysis.
- ☐ Other _____

6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE

- ☒ ESAL/Truck factor.
- ☐ ESAL/vehicle class factors -
Number of classes _____
- ☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT

- ☒ System distribution factors.
- ☐ Other _____

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
- ☐ Current year system average.
- ☒ Prior year system average.
- ☐ Historical W-4 tables.
- ☐ Other _____

8. WEIGHT SCALE TYPE

- ☒ WIM Scale.
- ☐ Static scale used for enforcement.
- ☐ Static scale not used for enforcement.
- ☐ Other _____

SCANNED

8-31-2009

NAME OF PREPARER _____	PHONE # _____
DATE PREPARED _____	

SHEET 14
LTPP TRAFFIC DATA

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID []

STATE CODE [89]

SHRP SECTION ID [3001]

LOCATION CONTRECOEUR

DATE OF INSTALLATION 1991

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	1060 P	IRD	9103-
Interface			
Modem	14 400	GVQ	
Loop Amplifiers			
Other			
Sensor(s) / Platform(s)			
GPS Lane Sensor			
Sensor Next Adjacent Lane (1)	2 PIEZOS		
Sensor Next Adjacent Lane (2)			
Sensor Next Adjacent Lane (3)			
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other			
Software			
Complete Package	IRD Ver 7.32		
Axle Spacing Algorithm Only			
Other			
Loops			
Upstream - Lane 1	1 LOOP 6x6		
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			