

SHEET 1

LTPP TRAFFIC DATA

TRAFFIC VOLUME AND LOAD
ESTIMATE UPDATE - NO SITE COUNT

STATE ASSIGNED ID [1012]

STATE CODE [53]

SHRP SECTION ID [1002]

1. ANNUAL TRAFFIC ESTIMATES

YEAR	① ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	② ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	③ ESTIMATED TOTAL VEHICLES AADT GPS LANE	④ ESTIMATED TOTAL TRUCKS AADT GPS LANE	⑤ ESTIMATED ESAL'S / YR GPS LANE (1000's)
1991	1966	389 ① X .198	983 ① X .50	190 ③ X .193	82.62 ④ X .4355

2. METHOD FOR ESTIMATING TOTAL VEHICLE
AADT (TWO-WAY)

- ☒ Growth factored last year's estimate.
☐ Estimated based on volume counts at nearby locations.
☐ Used computerized network analysis.
☐ Other _____

5. METHOD FOR ESTIMATING TOTAL
TRUCKS, GPS LANE, AADT

- ☐ System distribution factors.
☒ Other Count 7-26-90

3. METHOD FOR ESTIMATING TOTAL TRUCK
AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
☒ Used count data from nearby sites.
☒ Used count data from previous years at GPS site.
☐ Used system averages from previous year counts.
☐ Used computerized network analysis.
☒ Other Ratio from
Count 7-26-90

6. METHOD FOR ESTIMATING ESAL/YEAR
IN GPS LANE

- ☒ ESAL/Truck factor.
☐ ESAL/vehicle class factors -
 Number of classes _____
☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES
GPS LANE AADT

- ☐ System distribution factors.
☒ Other Ratio from 7-26-90

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
☐ Current year system average.
☒ Prior year system average.
☐ Historical W-4 tables.
☐ Other _____

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
☒ Static scale used for enforcement.
☐ Static scale not used for enforcement.
☐ Other _____

ENTERED

OCT 10 1995

By

NAME OF PREPARER

Barbara Hertzog

PHONE #

(360) 753-1422

DATE PREPARED

9-22-95

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [PO5]

STATE CODE [53]

SHRP SECTION ID [1002]

LOCATION SR 12 MP 376.98
4.32 Mi. N. of Jct. SR 126

DATE OF INSTALLATION Dec. 11, 1991

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	IRD Model 1060	IRD WIM	9104-1036
Interface	(included in control unit)		
Modem	2400 Baud	Multi-Tech Systems	1499396
Loop Amplifiers	(included in control unit)		
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	2 each - Piezo Class 1		
Sensor Next Adjacent Lane (1)	" " " "		
Sensor Next Adjacent Lane (2)	" " " "		
Sensor Next Adjacent Lane (3)	" " " "		
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package	Version # 7.2.2	IRD	
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1	Yes		
Downstream - Lane 1	Yes		
Upstream - Other Lanes	Yes		
Downstream - Other Lanes	Yes		

<p align="center">SHEET 15</p> <p align="center">LTPP TRAFFIC DATA</p> <p align="center">LOG OF CHANGES AT GPS TEST LOCATIONS WITH PERM. AVC OR WIM</p>	<p>*STATE ASSIGNED ID [<u> P05 </u>]</p> <p>*STATE CODE [<u> 53 </u>]</p> <p>*SHRP SECTION ID [<u> J002 </u>]</p>
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*SHRP SECTION ID [1002]

MP # 376.98 MODEL # IRD 1060

[illegible]