

Rome

SHEET 10 LTPP TRAFFIC DATA TRAFFIC VOLUME AND LOAD ESTIMATE UPDATE - NO SITE COUNT	*STATE ASSIGNED ID [6107] *STATE CODE [36] *SHRP SECTION ID [1008]
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Installed, 1991.

1. ANNUAL TRAFFIC ESTIMATES

ENTERED JUL 11 2000

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S / YR GPS LANE (1000's)
1991	12,800	896	5632	394	194

2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)

- ☐ Growth factored last year's estimate.
☒ Estimated based on volume counts at nearby locations.
☐ Used computerized network analysis.
☐ Other _____

5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT

- ☐ System distribution factors.
☒ Other EXISTING CLASS DATA

3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
☒ Used count data from nearby sites.
☐ Used count data from previous years at GPS site.
☐ Used system averages from previous year counts.
☐ Used computerized network analysis.
☒ Other with subefficiency 70 of truck at 7%

6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE

- ☒ ESAL/Truck factor.
☐ ESAL/vehicle class factors -
 Number of classes _____
☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT

- ☐ System distribution factors.
☒ Other HISTORICAL FACTORS

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
☐ Current year system average.
☐ Prior year system average.
☐ Historical W-4 tables.
☒ Other HISTORICAL FACTORS

8. WEIGHT SCALE TYPE

- ☒ WIM Scale.
☐ Static scale used for enforcement.
☐ Static scale not used for enforcement.
☐ Other _____

NAME OF PREPARER LIM CERQUA PHONE # 518-457-7203
 DATE PREPARED JUNE 6, 2000

SHEET 12 LTPP TRAFFIC DATA CLASSIFICATION DATA TRANSMITTAL FORM	*STATE ASSIGNED ID [<u>260</u>]
	*STATE CODE [<u>36</u>]
	*SHRP SECTION ID [<u>1008</u>]

HIGHWAY RT. NO. (THIS SESSION) 49 MILEPOST NO. (THIS SESSION) 49-2602-6007

LOCATION (THIS COUNT) IN ROME

FILENAME C361008.EPI

DISK/TAPE ID 1

BEGINNING DATE 3/26/91

BEGINNING TIME 10

ENDING DATE 3/31/91

ENDING TIME 23

COUNT DURATION 134 ☒ HOURS [] DAYS [] MONTHS

VEHICLE CLASSIFICATION METHOD: FHWA ☒ OTHER* ☐ #BINS ☐

NOTE: IF NOT PREVIOUSLY PROVIDED TO SHRP, PLEASE ATTACH SHEET 6 DESCRIBING THE VEHICLE CLASSIFICATION CATEGORIES AND ALSO ATTACH SHEET 7 DESCRIBING HOW THE SHA WOULD CONVERT ITS CLASSIFICATION SCHEME TO THE FHWA 13 CLASS SYSTEM.

TYPE OF AVC EQUIPMENT: PORTABLE ☒

PERMANENT ☐

EQUIPMENT MAKE/MODEL # GK 6000

SENSOR TYPE ☐

ADJUSTMENT FACTORS FOR ESTIMATING AVERAGE ANNUAL VOLUMES BY CLASSIFICATION.

GENERAL FACTORS ☐

CLASS SPECIFIC FACTORS (PROVIDE BY CLASS OR CLASS GROUPS) ☐

COMMENTS TO TEXT ☐

FILL OUT ONE TRANSMITTAL SHEET FOR EACH DATA FILE SUBMITTED.

NAME OF PREPARER PAUL POLANSKY

PHONE # 518-4578512

DATE PREPARED 4/5/91

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [260]

STATE CODE [36]

SHRP SECTION ID [1008]

LOCATION RT. 49, IN BOME

DATE OF INSTALLATION 6/91

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	80386SX MICROPROCESSOR	IRD	NOT PERMANENTLY ASSIGNED
Interface	CUSTOM	IRD	
Modem	9600 BAUD V.32/42 B/S	IRD	
Loop Amplifiers	INDUCTIVE LOOP DETECTOR	IRD	
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	BENDING PLATE	IRD	
Sensor Next Adjacent Lane (1)	BENDING PLATE	IRD	
Sensor Next Adjacent Lane (2)	BENDING PLATE	IRD	
Sensor Next Adjacent Lane (3)	BENDING PLATE	IRD	
Diagonal Sensor			
Offscale Sensor	DYNAX (RESISTIVE)	IRD	
Right Platform			
Left Platform			
Other <u>AXLE</u>	DYNAX (RESISTIVE)	IRD	
Software			
Complete Package	CUSTOM VERSION 7.3.0	IRD	
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1	PERMANENT INDUCTIVE	IRD	
Downstream - Lane 1	PERMANENT INDUCTIVE	IRD	
Upstream - Other Lanes	PERMANENT INDUCTIVE	IRD	
Downstream - Other Lanes	PERMANENT INDUCTIVE	IRD	