

SHEET 10

LTPP TRAFFIC DATA

TRAFFIC VOLUME AND LOAD
ESTIMATE UPDATE - NO SITE COUNT

*STATE ASSIGNED ID [_ _ _ _]

*STATE CODE [_ _]

*SHRP SECTION ID [_ _ _ _]

1. ANNUAL TRAFFIC ESTIMATES

245807 I-195 EB W of B/W 04.

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S/YR GPS LANE (1000's)
1991	21000	1260	5670	328	186.15 196

2. METHOD FOR ESTIMATING TOTAL VEHICLE
AADT (TWO-WAY)

- ☐ Growth factored last year's estimate.
☐ Estimated based on volume counts at nearby locations.
☐ Used computerized network analysis.
☒ Other Estimate of Reverse
Growth Rate 125% (1991)

3. METHOD FOR ESTIMATING TOTAL
TRUCKS/GPS LANE, AADT

- ☐ System distribution factors.
☐ Other _____

3. METHOD FOR ESTIMATING TOTAL TRUCK
AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
☐ Used count data from nearby sites.
☐ Used count data from previous years at GPS site.
☐ Used system averages from previous year counts.
☐ Used computerized network analysis.
☐ Other _____

4. METHOD FOR ESTIMATING ESAL/YEAR
IN GPS LANE

- ☐ ESAL/Truck factor.
☐ ESAL/vehicle class factors -
 Number of classes
☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES
GPS LANE AADT

- ☐ System distribution factors.
☐ Other _____

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
☐ Current year system average.
☐ Prior year system average.
☐ Historical W-4 tables.
☐ Other _____

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
☐ Static scale used for enforcement.
☐ Static scale not used for enforcement.
☐ Other _____

NAME OF PREPARER _____

PHONE # _____

DATE PREPARED _____

ENTERED NOV 26 1998

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [0066]

STATE CODE [24]

SHRP SECTION ID [5807]

LOCATION I-195 west of B/w Parkway

DATE OF INSTALLATION 3-91

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	241	PENIC	
Interface			
Modem	U.S. Robotics		
Loop Amplifiers	PENK		
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	CLASS II PIEZO		
Sensor Next Adjacent Lane (1)			
Sensor Next Adjacent Lane (2)			
Sensor Next Adjacent Lane (3)			
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package	261	PENK	
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1	6x6		
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			