

**SHEET 0**  
**LTPP TRAFFIC DATA**  
**TRAFFIC VOLUME AND LOAD**  
**ESTIMATE UPDATE - NO SITE COUNT**

\*STATE ASSESSMENT ID [ ]  
 \*STATE CODE 106  
 \*SHRP SECTION ID 8150

**1. ANNUAL TRAFFIC ESTIMATES**

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S/YR GPS LANE (1000's)
<u>1992</u>	<u>10,000</u>	<u>500</u>	<u>3976</u>	<u>196</u>	<u>171</u>

**2. METHOD FOR ESTIMATING TOTAL VEHICLE  
AADT (TWO-WAY)**

- ☒ Growth factored last year's estimate.  
☐ Estimated based on volume counts at nearby locations.  
☐ Used computerized network analysis.  
☐ Other \_\_\_\_\_

**5. METHOD FOR ESTIMATING TOTAL  
TRUCKS, GPS LANE, AADT**

- ☒ System distribution factors.  
☐ Other \_\_\_\_\_

**3. METHOD FOR ESTIMATING TOTAL TRUCK  
AADT (TWO-WAY)**

- ☐ Used system average from counts taken this year.  
☒ Used count data from nearby sites.  
☐ Used count data from previous years at GPS site.  
☐ Used system averages from previous year counts.  
☐ Used computerized network analysis.  
☐ Other \_\_\_\_\_

**6. METHOD FOR ESTIMATING ESAL/YEAR  
IN GPS LANE**

- ☒ ESAL/Truck factor.  
☐ ESAL/vehicle class factors -  
 Number of classes \_\_\_\_\_  
☐ Other \_\_\_\_\_

**4. METHOD FOR ESTIMATING TOTAL VEHICLES  
GPS LANE AADT**

- ☒ System distribution factors.  
☐ Other \_\_\_\_\_

**7. ESAL ESTIMATES - SOURCE OF DATA**

- ☒ Prior years data collected at GPS site.  
☐ Current year system average.  
☐ Prior year system average.  
☐ Historical W-4 tables.  
☐ Other \_\_\_\_\_

**8. WEIGHT SCALE TYPE**

- ☐ WIM Scale.  
☐ Static scale used for enforcement.  
☐ Static scale not used for enforcement.  
☐ Other \_\_\_\_\_

NAME OF PREPARER \_\_\_\_\_

PHONE # \_\_\_\_\_

DATE PREPARED \_\_\_\_\_

**SHEET 14  
LTPP TRAFFIC DATA**

**EQUIPMENT INSTALLATION LOG**

STATE ASSIGNED ID [2721]

STATE CODE [06]

SHRP SECTION ID [8] 509

LOCATION SAN BERNARDINO County, Rte 301M 31.7 DATE OF INSTALLATION 8 92

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	WEIGH-IN-MOTION	PAT DAW200	
Interface			
Modem		MOTOROLA UOS	
Loop Amplifiers		PAT	
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	BENDING PLATE	PAT	
Sensor Next Adjacent Lane (1)	" "	"	
Sensor Next Adjacent Lane (2)	" "	"	
Sensor Next Adjacent Lane (3)	" "	"	
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package		CC200/REPORTER	
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			