

<p>SHEET 10</p> <p>LTPP TRAFFIC DATA</p> <p>TRAFFIC VOLUME AND LOAD</p> <p>ESTIMATE UPDATE - NO SITE COUNT</p>	<p>*STATE ASSIGNED ID [_ _ _ _]</p> <p>*STATE CODE [<u>06</u>]</p> <p>*SHRP SECTION ID [<u>3017</u>]</p>
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1. ANNUAL TRAFFIC ESTIMATES

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S/YR GPS LANE (1000's)
<u>1994</u>	<u>88000</u>	<u>2200</u>	<u>6000</u>	<u>850</u>	<u>192</u>

2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)

- ☒ Growth factored last year's estimate.
- ☐ Estimated based on volume counts at nearby locations.
- ☐ Used computerized network analysis.
- ☐ Other _____

5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT

- ☒ System distribution factors.
- ☐ Other _____

3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
- ☒ Used count data from nearby sites.
- ☐ Used count data from previous years at GPS site.
- ☐ Used system averages from previous year counts.
- ☐ Used computerized network analysis.
- ☐ Other _____

6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE

- ☒ ESAL/Truck factor.
- ☐ ESAL/vehicle class factors -
Number of classes _____
- ☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT

- ☒ System distribution factors.
- ☐ Other _____

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
- ☒ Current year system average.
- ☐ Prior year system average.
- ☐ Historical W-4 tables.
- ☐ Other _____

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
- ☐ Static scale used for enforcement.
- ☐ Static scale not used for enforcement.
- ☐ Other _____

ENTERED

OCT 09 1995

By (Signature)

NAME OF PREPARER _____	PHONE # _____
DATE PREPARED _____	

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [3252]

STATE CODE [06]

SHRP SECTION ID [3017]

LOCATION Los Angeles County, RTE 2, PM 21.7 DATE OF INSTALLATION 9-94

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	WEIGH-IN-MOTION	IRD	
Interface			
Modem		FAST TALK UDS	
Loop Amplifiers		IRD	
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	PIEZO, WEIGHING	PHILLIPS	
Sensor Next Adjacent Lane (1)	" "	"	
Sensor Next Adjacent Lane (2)	" "	"	
Sensor Next Adjacent Lane (3)	" "	"	
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package		IRD OFFICE/ SITE	
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			