

SHEET 10
LTPP TRAFFIC DATA
TRAFFIC VOLUME AND LOAD
ESTIMATE UPDATE - NO SITE COUNT

*STATE ASSIGNED ID [_ _ _ _]

*STATE CODE [06]

*SHRP SECTION ID [3017]

1. ANNUAL TRAFFIC ESTIMATES

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S/YR GPS LANE (1000's)
<u>1994</u>	<u>88000</u>	<u>2200</u>	<u>6000</u>	<u>850</u>	<u>192</u>

**2. METHOD FOR ESTIMATING TOTAL VEHICLE
AADT (TWO-WAY)**

- ☒ Growth factored last year's estimate.
☐ Estimated based on volume counts at nearby locations.
☐ Used computerized network analysis.
☐ Other _____

**5. METHOD FOR ESTIMATING TOTAL
TRUCKS, GPS LANE, AADT**

- ☒ System distribution factors.
☐ Other _____

**3. METHOD FOR ESTIMATING TOTAL TRUCK
AADT (TWO-WAY)**

- ☐ Used system average from counts taken this year.
☒ Used count data from nearby sites.
☐ Used count data from previous years at GPS site.
☐ Used system averages from previous year counts.
☐ Used computerized network analysis.
☐ Other _____

**6. METHOD FOR ESTIMATING ESAL/YEAR
IN GPS LANE**

- ☒ ESAL/Truck factor.
☐ ESAL/vehicle class factors -
 Number of classes _____
☐ Other _____

**4. METHOD FOR ESTIMATING TOTAL VEHICLES
GPS LANE AADT**

- ☒ System distribution factors.
☐ Other _____

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
☒ Current year system average.
☐ Prior year system average.
☐ Historical W-4 tables.
☐ Other _____

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
☐ Static scale used for enforcement.
☐ Static scale not used for enforcement.
☐ Other _____

ENTERED
OCT 09 1995
 By (19)

NAME OF PREPARER _____	PHONE # _____
DATE PREPARED _____	

SHEET 14
LTPP TRAFFIC DATA

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [3252]

STATE CODE [06]

SHRP SECTION ID [3017]

LOCATION Los Angeles County, RTE 2, PM 21.7 DATE OF INSTALLATION 9-94

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	WEIGH-IN-MOTION	IRD	
Interface			
Modem		FAST TALK UDS	
Loop Amplifiers		IRD	
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	PIEZO, WEIGHING	PHILLIPS	
Sensor Next Adjacent Lane (1)	" "	"	
Sensor Next Adjacent Lane (2)	" "	"	
Sensor Next Adjacent Lane (3)	" "	"	
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package		IRD OFFICE/ SITE	
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			