

<p>SHE 10</p> <p><b>LTPP TRAFFIC DATA</b></p> <p><b>TRAFFIC VOLUME AND LOAD</b></p> <p><b>ESTIMATE UPDATE - NO SITE COUNT</b></p>	<p>*STATE ASSIGNED ID [ _ _ _ _ ]</p> <p>*STATE CODE [ 04 ]</p> <p>*SHRP SECTION ID [ 7414 ]</p>
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**1. ANNUAL TRAFFIC ESTIMATES**

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S/YR GPS LANE (1000's)
1992	19,000	3,000	7,600	1,325	925

**2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)**

- ☐ Growth factored last year's estimate.
- ☐ Estimated based on volume counts at nearby locations.
- ☐ Used computerized network analysis.
- ☐ Other \_\_\_\_\_

**5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT**

- ☐ System distribution factors.
- ☐ Other \_\_\_\_\_

**3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)**

- ☐ Used system average from counts taken this year.
- ☐ Used count data from nearby sites.
- ☐ Used count data from previous years at GPS site.
- ☐ Used system averages from previous year counts.
- ☐ Used computerized network analysis.
- ☐ Other \_\_\_\_\_

**6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE**

- ☐ ESAL/Truck factor.
- ☐ ESAL/vehicle class factors -  
Number of classes \_\_\_\_\_
- ☐ Other \_\_\_\_\_

**4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT**

- ☐ System distribution factors.
- ☐ Other \_\_\_\_\_

**7. ESAL ESTIMATES - SOURCE OF DATA**

- ☐ Prior years data collected at GPS site.
- ☐ Current year system average.
- ☐ Prior year system average.
- ☐ Historical W-4 tables.
- ☐ Other \_\_\_\_\_

**8. WEIGHT SCALE TYPE**

- ☐ WIM Scale.
- ☐ Static scale used for enforcement.
- ☐ Static scale not used for enforcement.
- ☐ Other \_\_\_\_\_

ENTERED

MAR - 1 1994

By \_\_\_\_\_

NAME OF PREPARER _____	PHONE # _____
DATE PREPARED _____	

**SHEET 14  
LTPP TRAFFIC DATA**

**EQUIPMENT INSTALLATION LOG**

STATE ASSIGNED ID [ 022 ]

STATE CODE [ 04 ]

SHRP SECTION ID [ 7614 ]

LOCATION MP 130.4 WB, I-10

DATE OF INSTALLATION 11/92

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	<u>AVC 100</u>	<u>PAT</u>	
Interface			
Modem			
Loop Amplifiers			
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	<u>Piezo</u>	<u>PAT</u>	
Sensor Next Adjacent Lane (1)			
Sensor Next Adjacent Lane (2)			
Sensor Next Adjacent Lane (3)			
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package			
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			