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|---|---|
| SH-10 LTPP TRAFFIC DATA TRAFFIC VOLUME AND LOAD ESTIMATE UPDATE - NO SITE COUNT | *STATE ASSIGNED ID [_ _ _ _] *STATE CODE [04] *SHRP SECTION ID [1025] |
|---|---|

1. ANNUAL TRAFFIC ESTIMATES

| YEAR | ESTIMATED TOTAL VEHICLES AADT (TWO-WAY) | ESTIMATED TOTAL TRUCK AADT (TWO-WAY) | ESTIMATED TOTAL VEHICLES AADT GPS LANE | ESTIMATED TOTAL TRUCKS AADT GPS LANE | ESTIMATED ESAL'S/YR GPS LANE (1000's) |
|-------------|--|---|---|---|--|
| <u>1992</u> | <u>9,500</u> | <u>3,600</u> | <u>3,800</u> | <u>1,450</u> | <u>950</u> |

2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)

- ☐ Growth factored last year's estimate.
☐ Estimated based on volume counts at nearby locations.
☐ Used computerized network analysis.
☐ Other _____

5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT

- ☐ System distribution factors.
☐ Other _____

3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
☐ Used count data from nearby sites.
☐ Used count data from previous years at GPS site.
☐ Used system averages from previous year counts.
☐ Used computerized network analysis.
☐ Other _____

6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE

- ☐ ESAL/Truck factor.
☐ ESAL/vehicle class factors -
 Number of classes _____
☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT

- ☐ System distribution factors.
☐ Other _____

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
☐ Current year system average.
☐ Prior year system average.
☐ Historical W-4 tables.
☐ Other _____

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
☐ Static scale used for enforcement.
☐ Static scale not used for enforcement.
☐ Other _____

ENTERED
 MAR - 1 1994
 By _____

| | |
|------------------------|---------------|
| NAME OF PREPARER _____ | PHONE # _____ |
| DATE PREPARED _____ | |

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [019]

STATE CODE [04]

SHRP SECTION ID [1025]

LOCATION MP 113.2 WB, I-40

DATE OF INSTALLATION 11/92

| | TYPE | BRAND NAME | SERIAL NUMBER |
|--|---------|------------|---------------|
| Control Unit(s) and peripheral equipment | | | |
| Control Unit | AVC 100 | PAT | |
| Interface | | | |
| Modem | | | |
| Loop Amplifiers | | | |
| Other _____ | | | |
| Sensor(s) / Platform(s) | | | |
| GPS Lane Sensor | Piezo | PAT | |
| Sensor Next Adjacent Lane (1) | | | |
| Sensor Next Adjacent Lane (2) | | | |
| Sensor Next Adjacent Lane (3) | | | |
| Diagonal Sensor | | | |
| Offscale Sensor | | | |
| Right Platform | | | |
| Left Platform | | | |
| Other _____ | | | |
| Software | | | |
| Complete Package | | | |
| Axle Spacing Algorithm Only | | | |
| Other _____ | | | |
| Loops | | | |
| Upstream - Lane 1 | | | |
| Downstream - Lane 1 | | | |
| Upstream - Other Lanes | | | |
| Downstream - Other Lanes | | | |