

SHEET 10 <b>LTPP TRAFFIC DATA</b>  <b>TRAFFIC VOLUME AND LOAD</b> <b>ESTIMATE UPDATE - NO SITE COUNT</b>	*STATE SIGN ID [ _ _ _ _ ]  *STATE CODE [ 04 ]  *SHRP SECTION ID [ 1024 ]
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1. ANNUAL TRAFFIC ESTIMATES

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S / YR GPS LANE (1000's)
1992	9,900	3,750	3,950	1500	970

2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)

- ☐ Growth factored last year's estimate.  
☐ Estimated based on volume counts at nearby locations.  
☐ Used computerized network analysis.  
☐ Other \_\_\_\_\_

5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT

- ☐ System distribution factors.  
☐ Other \_\_\_\_\_

3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.  
☐ Used count data from nearby sites.  
☐ Used count data from previous years at GPS site.  
☐ Used system averages from previous year counts.  
☐ Used computerized network analysis.  
☐ Other \_\_\_\_\_

6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE

- ☐ ESAL/Truck factor.  
☐ ESAL/vehicle class factors -  
                                     Number of classes  
☐ Other \_\_\_\_\_

4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT

- ☐ System distribution factors.  
☐ Other \_\_\_\_\_

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.  
☐ Current year system average.  
☐ Prior year system average.  
☐ Historical W-4 tables.  
☐ Other \_\_\_\_\_

ENTERED

MAR - 1 1994

By \_\_\_\_\_

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.  
☐ Static scale used for enforcement.  
☐ Static scale not used for enforcement.  
☐ Other \_\_\_\_\_

NAME OF PREPARER _____	PHONE # _____
DATE PREPARED _____	

**SHEET 14  
LTPP TRAFFIC DATA**

**EQUIPMENT INSTALLATION LOG**

STATE ASSIGNED ID [ 018 ]

STATE CODE [ 04 ]

SHRP SECTION ID [ 1024 ]

LOCATION MP 106.8 EB, I-40 DATE OF INSTALLATION 11/92

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	<u>AVC 100</u>	<u>PAT</u>	
Interface			
Modem			
Loop Amplifiers			
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	<u>Piezo</u>	<u>PAT</u>	
Sensor Next Adjacent Lane (1)			
Sensor Next Adjacent Lane (2)			
Sensor Next Adjacent Lane (3)			
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package			
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			