

<p>SHEET 10</p> <p>LTPP TRAFFIC DATA</p> <p>TRAFFIC VOLUME AND LOAD</p> <p>ESTIMATE UPDATE - NO SITE COUNT</p>	<p>*STATE ASSIGNMENT ID [_ _ _ _]</p> <p>*STATE CODE [04]</p> <p>*SHRP SECTION ID [1002]</p>
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1. ANNUAL TRAFFIC ESTIMATES

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S / YR GPS LANE (1000's)
<u>1992</u>	<u>10,000</u>	<u>3,000</u>	<u>4,000</u>	<u>1,200</u>	<u>750</u>

2. METHOD FOR ESTIMATING TOTAL VEHICLE AADT (TWO-WAY)

- ☐ Growth factored last year's estimate.
- ☐ Estimated based on volume counts at nearby locations.
- ☐ Used computerized network analysis.
- ☐ Other _____

5. METHOD FOR ESTIMATING TOTAL TRUCKS, GPS LANE, AADT

- ☐ System distribution factors.
- ☐ Other _____

3. METHOD FOR ESTIMATING TOTAL TRUCK AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
- ☐ Used count data from nearby sites.
- ☐ Used count data from previous years at GPS site.
- ☐ Used system averages from previous year counts.
- ☐ Used computerized network analysis.
- ☐ Other _____

6. METHOD FOR ESTIMATING ESAL/YEAR IN GPS LANE

- ☐ ESAL/Truck factor.
- ☐ ESAL/vehicle class factors -
Number of classes _____
- ☐ Other _____

4. METHOD FOR ESTIMATING TOTAL VEHICLES GPS LANE AADT

- ☐ System distribution factors.
- ☐ Other _____

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
- ☐ Current year system average.
- ☐ Prior year system average.
- ☐ Historical W-4 tables.
- ☐ Other _____

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
- ☐ Static scale used for enforcement.
- ☐ Static scale not used for enforcement.
- ☐ Other _____

ENTERED

MAR - 1 1994

By _____

NAME OF PREPARER _____	PHONE # _____
DATE PREPARED _____	

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [020]

STATE CODE [04]

SHRP SECTION ID [1002]

LOCATION MP 145.5 WB, I-40

DATE OF INSTALLATION 11/92

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	AVC 100	PAT	
Interface			
Modem			
Loop Amplifiers			
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	Piezo	PAT	
Sensor Next Adjacent Lane (1)			
Sensor Next Adjacent Lane (2)			
Sensor Next Adjacent Lane (3)			
Diagonal Sensor			
Offscale Sensor			
Right Platform			
Left Platform			
Other _____			
Software			
Complete Package			
Axle Spacing Algorithm Only			
Other _____			
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			