

LTPP TRAFFIC DATA

TRAFFIC VOLUME AND LOAD
ESTIMATE UPDATE - NO SITE COUNT

STATE ASSIGNED ID [_ _ _ _]

STATE CODE [04]

SHRP SECTION ID [0100]

1. ANNUAL TRAFFIC ESTIMATES

YEAR	ESTIMATED TOTAL VEHICLES AADT (TWO-WAY)	ESTIMATED TOTAL TRUCK AADT (TWO-WAY)	ESTIMATED TOTAL VEHICLES AADT GPS LANE	ESTIMATED TOTAL TRUCKS AADT GPS LANE	ESTIMATED ESAL'S / YR GPS LANE (1000's)
1993	6000	1000	2600	400	230

2. METHOD FOR ESTIMATING TOTAL VEHICLE
AADT (TWO-WAY)

- ☐ Growth factored last year's estimate.
☒ Estimated based on volume counts at nearby locations.
☐ Used computerized network analysis.
☐ Other _____

5. METHOD FOR ESTIMATING TOTAL
TRUCKS, GPS LANE, AADT

- ☐ System distribution factors.
☒ Other Counts from nearby site.

3. METHOD FOR ESTIMATING TOTAL TRUCK
AADT (TWO-WAY)

- ☐ Used system average from counts taken this year.
☒ Used count data from nearby sites.
☐ Used count data from previous years at GPS site.
☐ Used system averages from previous year counts.
☐ Used computerized network analysis.
☐ Other _____

6. METHOD FOR ESTIMATING ESAL/YEAR
IN GPS LANE

- ☐ ESAL/Truck factor.
☐ ESAL/vehicle class factors -
 Number of classes _____
☒ Other Counts from nearby site with observed ESALS in following year.

4. METHOD FOR ESTIMATING TOTAL VEHICLES
GPS LANE AADT

- ☐ System distribution factors.
☒ Other Counts from nearby sites

7. ESAL ESTIMATES - SOURCE OF DATA

- ☐ Prior years data collected at GPS site.
☐ Current year system average.
☐ Prior year system average.
☐ Historical W-4 tables.
☒ Other Prior year nearby site vs. data at site for 1994

8. WEIGHT SCALE TYPE

- ☐ WIM Scale.
☐ Static scale used for enforcement.
☐ Static scale not used for enforcement.
☒ Other _____

ENTERED

OCT 30 1995

By (78)NAME OF PREPARER ESTOMIAT KOMBE PHONE # 602.407-3135DATE PREPARED 10-16-95.

**SHEET 14
LTPP TRAFFIC DATA**

EQUIPMENT INSTALLATION LOG

STATE ASSIGNED ID [025]

STATE CODE [04]

SHRP SECTION ID [0100]

LOCATION US 93 - MP 52.7 NB

DATE OF INSTALLATION Nov/Dec 1993

	TYPE	BRAND NAME	SERIAL NUMBER
Control Unit(s) and peripheral equipment			
Control Unit	Bending Plate	PAT DAW 100	
Interface			
Modem	Cellular	Telebit Qblazer	
Loop Amplifiers			
Other _____			
Sensor(s) / Platform(s)			
GPS Lane Sensor	Bending Plate	PAT	
Sensor Next Adjacent Lane (1)	"	"	
Sensor Next Adjacent Lane (2)	_____		
Sensor Next Adjacent Lane (3)	_____		
Diagonal Sensor	_____		
Offscale Sensor	_____		
Right Platform	_____		
Left Platform	_____		
Other _____	_____		
Software			
Complete Package		PAT	
Axle Spacing Algorithm Only	_____		
Other _____	_____		
Loops			
Upstream - Lane 1			
Downstream - Lane 1			
Upstream - Other Lanes			
Downstream - Other Lanes			