

US  
05|2016

**GERWAH®**

## Metal Bellows & Servo-Insert Couplings, Line Shafts



Partner for Performance  
[www.ringfeder.com](http://www.ringfeder.com)

 **RINGFEDER**  
POWER TRANSMISSION



# Welcome to your system supplier for every aspect of power transmission



## RINGFEDER POWER TRANSMISSION

- We say what we mean and mean what we say.
- We see things from our customers' perspective.
- We are considerate of our employees and their families as well as our environment and the society.

RINGFEDER POWER TRANSMISSION is the global market leader in the niche markets of drive technology and is well regarded for its customer-specific, application-oriented solutions that ensure excellent and failure-free operation for its clients.







**Mars Rover:**  
Courtesy NASA/  
JPL-Caltech



We offer locking devices, couplings, bearing housings and damping technology for OEMs but also for the final customer under our strong brand names RINGFEDER, TSCHAN, HENFEL and GERWAH. Our brand ECOLOC supplies reliable products off the shelf.

We not only provide competent advice to our customers on the basis of our 90 years of experience but also develop innovative ideas in cooperation with them. This is part of our aspiration to be a **Partner for Performance**.

#### **Around the power transmission we promise**

- Excellent know-how for our challenging customers
- Best cost-benefit ratio
- Short reaction times and a high product availability

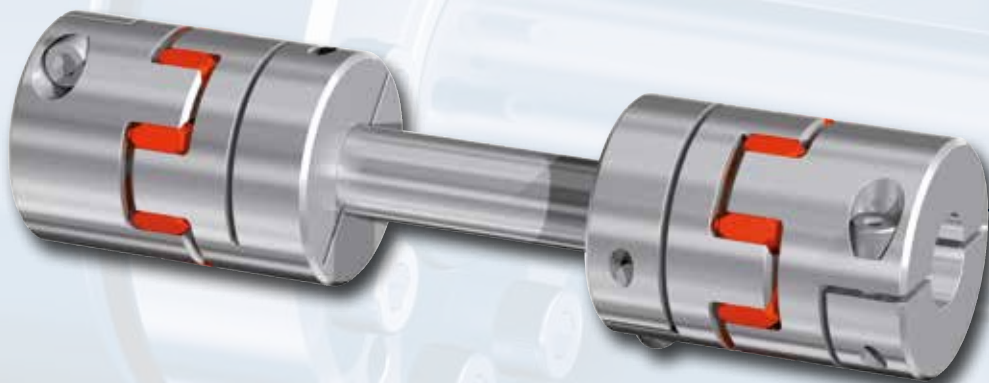






**Metal Bellows Couplings**

**Servo-Insert Couplings**



**Line Shafts**

# Content

## 02 Pages Corporate Image

---

## 04 Overview

---

## 05 Content

---

### Metal Bellows Couplings

---

- 06 Basics
- 08 Product Overview
- 10 GERWAH® EKN
- 12 GERWAH® DKN
- 14 GERWAH® DKN/S
- 16 GERWAH® PKA
- 18 GERWAH® PKB
- 20 GERWAH® PKN
- 22 GERWAH® AKN
- 24 GERWAH® AKN-H
- 26 GERWAH® AKD
- 28 GERWAH® AKD-H
- 30 GERWAH® AK
- 32 GERWAH® CKN
- 34 Technical Information

### Servo-Insert Couplings

---

- 36 Basics
- 39 Product Overview
- 40 GERWAH® GWE 5102
- 42 GERWAH® GWE 5103
- 44 GERWAH® GWE 5103.1
- 46 GERWAH® GWE 5107
- 48 GERWAH® GWE 5104
- 50 GERWAH® GWE 5106
- 52 GERWAH® GWE 5112

## 54 Technical Information

## 56 ISO Tolerances

### Line Shafts

---

- 57 Basics
- 59 Product Overview
- 60 GERWAH® GWZ 5104.1
- 62 GERWAH® GWZ 5106.1
- 64 GERWAH® GWZ 5116
- 66 GERWAH® GWZ 5106

### Mounting Instructions

---

- 68 Metal Bellows Couplings
- 70 Servo-Insert Couplings
- 71 Line Shafts
- 72 Critical bending speed

### Fax Inquiry

---

- 74 Fax Inquiry Couplings
- 75 Fax Inquiry Line Shafts

## 76 Online Service

---

## 78 Product Range RINGFEDER POWER TRANSMISSION

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CAD data available:  
[www.ringfeder.com](http://www.ringfeder.com)

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# Metal Bellows Couplings Basics

## Backlash-free Metal Bellows Couplings

### Characteristics of Metal Bellows Couplings:

- Backlash-free transmission of torque
- High torsional stiffness, precise transmission of rotational angle
- Different torsional stiffness
- Compact design, low moment of inertia
- Metal bellows made of stainless steel
- Simple and safe assembly
- Compensation of radial, axial and angular misalignment
- Free of wear, maintenance-free, no downtimes
- Not sensitive to temperatures between -22 °F and +212 °F
- Nominal torques between 0.4 ft-lbs – 3688 ft-lbs



**GERWAH®**

**Premium  
Metal Bellows Couplings  
with 20% higher torques!**

### Advantages

- 100% inspection and traceability through individual marking
- Higher torques at same dimensions
- Compact design
- Extended bore ranges
- Customer-specific solutions
- Higher safety in application, e.g. no wrong screw tightening torques



# Metal Bellows Couplings Basics

Backlash-free Metal Bellows Couplings are used in the sector of mechanical engineering, where torque or rotary motion has to be transmitted from shaft to shaft with the highest accuracy of angle.

- Pumps with axial and vertical drives
- High dynamic portal drives
- Spindle lifting units
- Linear units
- Packaging machines
- Machine tools
- Special machines



# Overview Metal Bellows Couplings



GERWAH®  
**EKN**

Miniature metal bellows coupling with  
radial set screws

Page 10



GERWAH®  
**DKN**

Miniature metal bellows coupling with  
clamping hubs

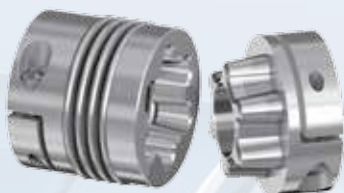
Page 12



GERWAH®  
**DKN/S**

Miniature metal bellows coupling with  
clamping hubs and expanding clamps

Page 14



GERWAH®  
**PKA**

Metal bellows coupling with  
axial pluggable clamping hub

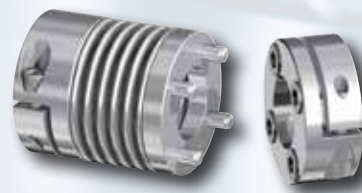
Page 16



GERWAH®  
**PKB**

Metal bellows coupling with  
axial pluggable locking ring

Page 18



GERWAH®  
**PKN**

Metal bellows coupling with  
pluggable clamping hub

Page 20



# Overview Metal Bellows Couplings



**GERWAH®  
AKN**

Metal bellows coupling with clamping hubs, short length and higher torsional stiffness

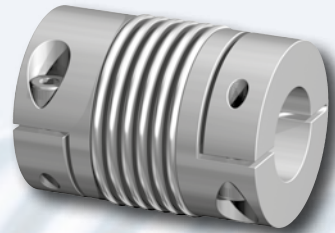
Page 22



**GERWAH®  
AKN-H**

Metal bellows coupling with clamping hubs, short length and higher torsional stiffness in split hub design

Page 24



**GERWAH®  
AKD**

Metal bellows coupling with clamping hubs

Page 26



**GERWAH®  
AKD-H**

Metal bellows coupling with clamping hubs in split hub design

Page 28



**GERWAH®  
AK**

Metal bellows coupling with inner conical hub

Page 30



**GERWAH®  
CKN**

Metal bellows coupling with flange

Page 32

CAD data available:  
[www.ringfeder.com](http://www.ringfeder.com)

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $l$  = Distance between center screw hole and hub end  
 $L$  = Total length



## Dimensions

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway					
			$C_1$	$D_1$	$l$	$L$	
	inch		inch	inch	inch	inch	
4	0.118 - 0.354	0.236 - 0.315	0.236	0.630	0.079	0.787/0.906/1.024	
9	0.118 - 0.354	0.236 - 0.315	0.236	0.630	0.079	0.827/0.984/1.102	
15	0.118 - 0.472	0.236 - 0.394	0.394	0.787	0.118	0.984/1.181	
20	0.118 - 0.630	0.236 - 0.551	0.433	0.984	0.079	1.024/1.260/1.417	
45	0.236 - 0.866	0.236 - 0.630	0.630	1.299	0.157	1.535/1.890	
100	0.236 - 1.102	0.236 - 0.984	0.787	1.575	0.157	1.732/2.126	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

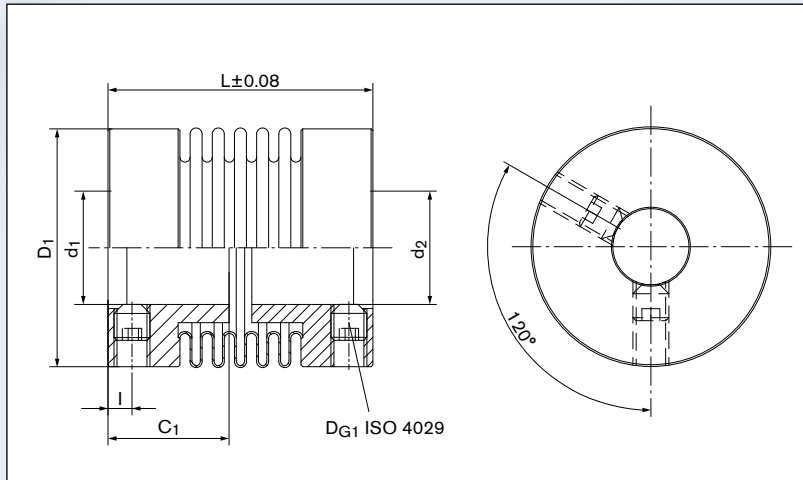
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: EKN

Series Size	Length $L$	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
EKN 20	1.024	0.236	0.393	*

\* Keyway





Sectional view EKN

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- G<sub>w</sub>** = Weight
- D<sub>G1</sub>** = Thread
- T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	G <sub>w</sub>	D <sub>G1</sub>	T <sub>A1</sub>
		ft-lbs	rpm	10 <sup>3</sup> ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	4	0.4	15000	0.18/0.14/0.11	731/308/148	103/74/63	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0007	0.01/0.01/0.02	1 x M3	0.37
	9	0.8	15000	0.37/0.28/0.22	1068/468/240	206/154/126	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0007/0.0008/0.0009	0.01/0.02/0.02	1 x M3	0.37
	15	1.3	15000	0.55/0.52	794/463	69/131	0.010/0.016	1.2/2.0	0.004/0.006	0.0026/0.0027	0.03	2 x M4	1.11
	20	1.8	15000	1.11/0.96/0.74	839/548/263	103/80/51	0.012/0.016/0.020	1.2/2.0/2.0	0.004/0.008/0.010	0.0048/0.0055/0.0058	0.04	2 x M3	1.11
	45	4.1	15000	4.79/2.95	2535/617	268/166	0.012/0.020	1.2/2.0	0.004/0.008	0.0232/0.0249	0.11	2 x M6	2.21
	100	8.9	15000	5.97/4.94	2061/1102	263/194	0.016/0.020	1.2/2.0	0.006/0.010	0.0683/0.0752	0.11/0.13	2 x M6	2.21

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																				
	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	20	22	24	26	28
	0.118	0.157	0.197	0.236	0.276	0.315	0.354	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.670	0.707	0.787	0.866	0.945	1.023	1.102
4	0.4	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---
9	0.7	0.5	0.8	0.8	0.8	0.8	0.8	---	---	---	---	---	---	---	---	---	---	---	---	---	---
15	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3	---	---	---	---	---	---	---	---	---	---	---
20	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	---	---	---	---	---	---	---
45	---	---	---	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	---	---	---
100	---	---	---	5.4	6.3	7.2	8.1	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9

## Dimensions

- d<sub>1</sub>; d<sub>2min</sub>** = Min. bore diameter  
**d<sub>1</sub>; d<sub>2max</sub>** = Min. bore diameter  
**d<sub>1k</sub>; d<sub>2kmin</sub>** = Min. bore diameter with keyway acc. to DIN 6885-1  
**d<sub>1k</sub>; d<sub>2kmax</sub>** = Max. bore diameter with keyway acc. to DIN 6885-1  
**C<sub>1</sub>** = Guided length in hub boring  
**D<sub>1</sub>** = Outer diameter hub  
**H** = Clearance diameter  
**I** = Distance between center screw hole and hub end  
**K** = Distance shaft axis - clamping screw axis  
**L** = Total length



## Dimensions

Size	d <sub>1</sub> ; d <sub>2</sub> min-max	d <sub>1k</sub> ; d <sub>2k</sub> min-max							
	Without keyway	With keyway	C <sub>1</sub>	D <sub>1</sub>	H	I	K	L	
	inch	inch	inch	inch	inch	inch		inch	
4	0.118 - 0.315	0.236 - 0.315	0.276	0.630	0.709	0.094	0.197	0.827/0.945/1.102	
9	0.118 - 0.315	0.236 - 0.315	0.276	0.630	0.709	0.094	0.197	0.906/1.024/1.181	
15	0.118 - 0.394	0.236 - 0.394	0.354	0.787	0.827	0.118	0.276	1.024/1.181	
20	0.118 - 0.551	0.236 - 0.551	0.433	0.984	1.063	0.138	0.354	1.260/1.496/1.654	
45	0.197 - 0.669	0.236 - 0.669	0.512	1.299	1.339	0.177	0.472	1.614/1.969	
100	0.197 - 0.945	0.236 - 0.945	0.551	1.575	1.654	0.189	0.630	1.850/2.244	

Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings < d<sub>min</sub>. Types with borings < d<sub>min</sub>, however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel

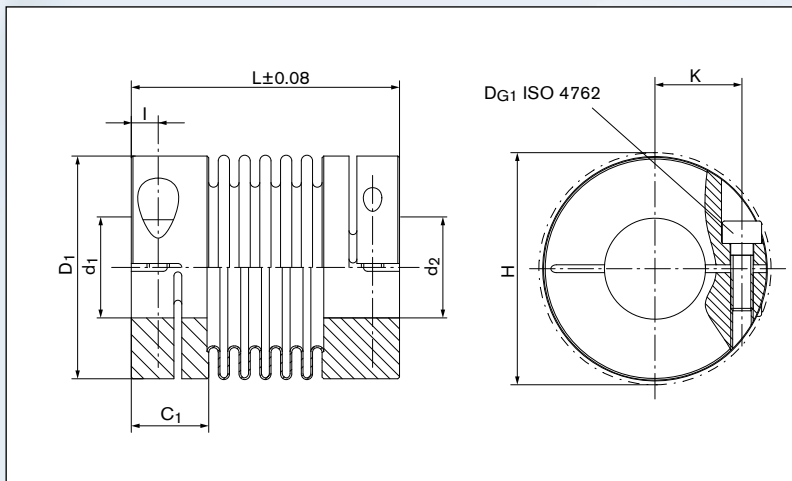
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: DKN

Series Size	Length L	Bore diameter d <sub>1</sub>	Bore diameter d <sub>2</sub>	Further details*
DKN 20	1.654	0.236	0.394	*

\* Keyway or stainless steel





Sectional view DKN

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- $D_{G1}$**  = Thread
- $T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Technical Data

Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
	ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
4	0.4	15000	0.18/0.14/0.11	731/308/148	103/74/63	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0009	0.01/0.01/0.02	1 x M2	0.2
9	0.8	15000	0.37/0.28/0.22	1068/468/240	206/154/126	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0009/0.0010/0.0011	0.01/0.02/0.02	1 x M2	0.2
15	1.3	15000	0.55/0.52	794/463	131/69	0.010/0.016	1.2/2.0	0.004/0.006	0.0038/0.0041	0.03	1 x M2.5	0.6
20	1.8	15000	1.11/0.96/0.74	839/548/263	103/80/51	0.012/0.016/0.020	1.2/2.0/2.0	0.004/0.008/0.010	0.0085/0.0092/0.0096	0.04/0.05/0.05	1 x M3	1.1
45	4.1	15000	4.79/2.95	2535/617	268/166	0.012/0.020	1.2/2.0	0.004/0.008	0.0335/0.0352	0.13/0.14	1 x M4	2.2
100	8.9	15000	5.97/4.94	2061/1102	263/194	0.016/0.020	1.2/2.0	0.006/0.010	0.0789/0.0854	0.13/0.15	1 x M4	2.2

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																					
	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	24	
	0.118	0.157	0.197	0.236	0.276	0.315	0.354	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.670	0.707	0.748	0.787	0.827	0.866	0.945	
4	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
9	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
15	1.1	1.3	1.3	1.3	1.3	1.3	1.3	1.3	---	---	---	---	---	---	---	---	---	---	---	---	---	
20	1.3	1.7	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	---	---	---	---	---	---	---	---	---	
45	---	---	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	---	---	---	---	---	---	
100	---	---	5.2	5.9	6.6	7.7	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	

## Dimensions

- $d_{1min}$  = Min. bore diameter  
 $d_{1max}$  = Max. bore diameter  
 $d_{1kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  
 $D_1$  = Outer diameter hub  
 $D_4$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length  
 $L_5$  = Expanding mandrel length



## Dimensions

Size	$d_1$ min-max Without keyway	$d_{1k}$ min-max With keyway	$C_1$	$D_1$	$D_4$	$H$	$I$	$K$	$L$	$L_5$
	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch
4	0.118 - 0.315	0.236 - 0.315	0.276	0.630	0.315	0.709	0.094	0.197	1.142/1.220/1.378	0.315
9	0.118 - 0.315	0.236 - 0.315	0.276	0.630	0.315	0.709	0.094	0.197	1.181/1.299/1.457	0.315
15	0.118 - 0.394	0.236 - 0.394	0.354	0.787	0.394	0.827	0.118	0.276	1.457/1.614	0.472
20	0.118 - 0.551	0.236 - 0.551	0.433	0.984	0.394	1.063	0.138	0.354	1.614/1.850/2.008	0.472
45	0.197 - 0.669	0.236 - 0.669	0.512	1.299	0.551	1.339	0.177	0.472	2.047/2.402	0.63
100	0.197 - 0.945	0.236 - 0.945	0.551	1.575	0.630	1.654	0.189	0.630	2.402/2.795	0.787

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel
- For the bore tolerances we recommend fit tolerance H7

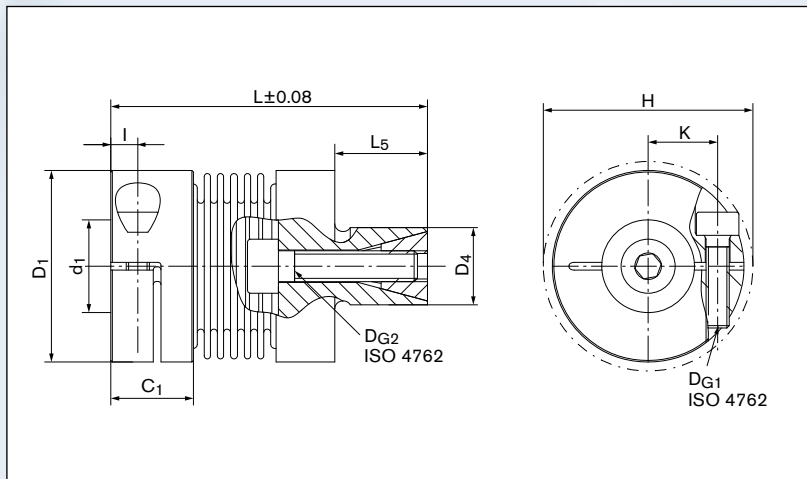
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: DKN/S

Series Size	Length $L$	Bore diameter $d_1$	Further details*
DKN/S 20	1.614	0.236	*

\* Keyway or stainless steel





Sectional view DKN/S

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- DG1** = Thread
- $T_{A1}$**  = Tightened torque of clamping screw DG1
- DG2** = Thread diameter
- $T_{A2}$**  = Tightened torque of clamping screw DG2

## Technical Data

Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	DG1	$T_{A1}$	DG2	$T_{A2}$
	ft-lbs	rpm	10 <sup>3</sup> ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs	mm	ft-lbs
4	0.4	15000	0.184/0.140/0.111	731/308/148	103/74/63	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0010	0.015/0.018/0.020	1 x M2	0.2	1 x M3	1.3
9	0.8	15000	0.369/0.280/0.221	1068/468/240	206/154/126	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0010	0.020/0.022/0.022	1 x M2	0.2	1 x M3	1.3
15	1.3	15000	0.553/0.516	794/463	131/69	0.010/0.016	1.2/2.0	0.004/0.006	0.0038/0.0041	0.035/0.037	1 x M2.5	0.6	1 x M4	2.2
20	1.8	15000	1.106/0.959/0.738	839/548/263	103/80/51	0.012/0.016/0.020	1.2/2.0/2.0	0.004/0.008/0.010	0.0072/0.0079/0.0085	0.053/0.060/0.062	1 x M3	1.1	1 x M4	2.2
45	4.1	15000	4.794/2.950	2535/617	268/166	0.012/0.020	1.2/2.0	0.004/0.008	0.0273/0.0294	0.141/0.154	1 x M4	2.2	1 x M5	3.0
100	9.0	15000	5.974/4.942	2061/1102	263/194	0.016/0.020	1.2/2.0	0.006/0.010	0.0782/0.0875	0.154/0.192	1 x M4	2.2	1 x M6	4.4

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																					
	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	24	
	0.118	0.157	0.197	0.236	0.276	0.315	0.354	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.670	0.707	0.748	0.787	0.827	0.866	0.945	
4	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
9	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
15	1.1	1.3	1.3	1.3	1.3	1.3	1.3	1.3	---	---	---	---	---	---	---	---	---	---	---	---	---	
20	1.3	1.7	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	---	---	---	---	---	---	---	---	---	
45	---	---	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	---	---	---	---	---	---	
100	---	---	5.2	5.9	6.6	7.7	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	

## Dimensions

$d_1; d_{2min}$	= Min. bore diameter
$d_1; d_{2max}$	= Max. bore diameter
$d_{1k}; d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}; d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
$C_1$	= Guided length in hub boring
$D_1$	= Outer diameter hub
$H$	= Clearance diameter
$I$	= Distance between center screw hole and hub end
$K$	= Distance shaft axis - clamping screw axis
$L$	= Total length
$L_6$	= Length of basic part
$L_7$	= Body length until bellow beginning or plug connection
$V$	= Preload distance



## Dimensions

Size	$d_1$ min-max Without keyway	$d_2$ min-max Without keyway	$d_{1k}$ min-max With keyway	$d_{2k}$ min-max With keyway	$C_1$	$D_1$	$H$	$I$	$K$	$L$	$L_6$	$L_7$	$V$
	inch				inch	inch	inch	inch		inch	inch	inch	inch
0.4	0.118 - 0.315	0.118 - 0.236	---	---	0.276	0.630	0.669	0.094	0.197	1.024/1.102/1.260	0.787/0.866/1.024	0.217	0.016
0.9	0.118 - 0.315	0.118 - 0.236	---	---	0.276	0.630	0.669	0.094	0.197	1.063/1.181/1.339	0.787/0.866/1.024	0.217	0.016
1.5	0.118 - 0.394	0.118 - 0.394	0.236 - 0.394	---	0.335	0.787	0.846	0.118	0.276	1.260/1.417	0.906/1.063	0.315	0.020
2	0.118 - 0.551	0.118 - 0.472	0.236 - 0.551	0.236 - 0.394	0.433	0.984	1.063	0.138	0.354	1.457/1.693/1.850	1.102/1.339/1.496	0.315	0.020
4.5	0.197 - 0.669	0.197 - 0.630	0.236 - 0.669	0.236 - 0.472	0.512	1.299	1.358	0.177	0.453	1.929/2.244	1.417/1.732	0.453	0.028
10	0.197 - 0.945	0.197 - 0.787	0.236 - 0.945	0.236 - 0.630	0.551	1.575	1.634	0.189	0.610	2.165/2.598	1.654/2.087	0.433	0.039
18	0.394 - 1.024	0.315 - 0.827	0.394 - 1.024	0.315 - 0.669	0.650	1.772	1.850	0.217	0.689	2.323/2.638	1.535/1.850	0.689	0.020
30	0.394 - 1.181	0.394 - 0.984	0.394 - 1.181	0.394 - 0.866	0.827	2.165	2.224	0.295	0.787	2.756/3.071	1.890/2.205	0.748	0.020
60	0.551 - 1.339	0.472 - 1.260	0.551 - 1.339	0.472 - 1.181	0.925	2.520	2.618	0.354	0.886	3.346/3.780	2.461/2.894	0.787	0.020
150	0.669 - 1.654	0.591 - 1.575	0.669 - 1.654	0.591 - 1.496	1.083	3.150	3.268	0.394	1.102	3.740/4.213	2.795/3.268	0.866	0.020
300	0.945 - 2.362	0.945 - 2.205	0.945 - 2.362	0.945 - 1.732	1.299	4.331	4.331	0.492	1.535	4.409/4.843	2.835/3.307	1.476	0.020
500	1.378 - 2.520	1.378 - 2.520	1.378 - 2.520	1.378 - 1.969	1.614	4.685	4.685	0.591	1.693	5.276/5.709	3.583/4.016	1.594	0.020

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.  
Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics / Series PKA with clamping hub

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- High power performance
- The contact surfaces have to be free from oil and grease
- Axial pluggable

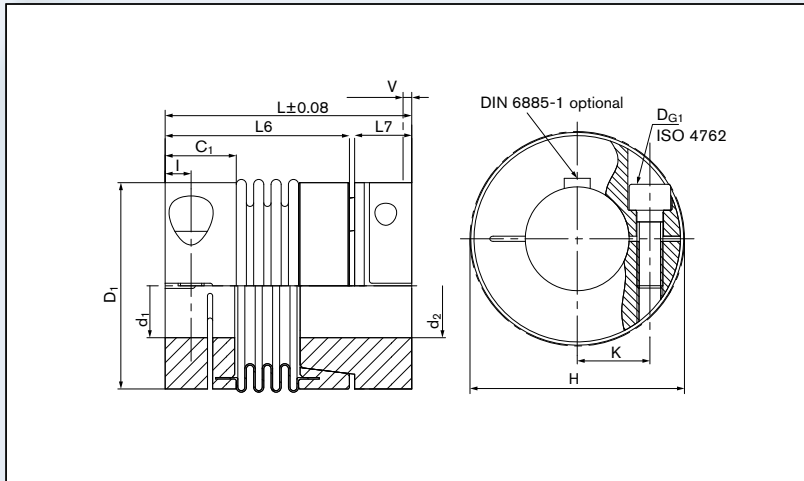
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: PKA

Series Size	Length L	Bore diameter $d_1$	Bore diameter $d_2$	Position	Further details*
PKA 150	3.740	1.181	1.377	D	*

C = Single position    D = Multi position    \* Keyway





## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- $D_{G1}$**  = Thread
- $T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Sectional view PKA

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
		ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	0.4	0.4	15000	0.18/0.14/0.11	731/308/148	103/74/63	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0010	0.02	1 x M2	0.22
	0.9	0.8	15000	0.37/0.28/0.22	1068/468/240	206/154/126	0.008/0.012/0.016	1.2/2.0/2.0	0.004/0.006/0.008	0.0014	0.02	1 x M2	0.44
	1.5	1.3	15000	0.55/0.52	794/463	131/69	0.010/0.016	1.2/2.0	0.004/0.006	0.0034/0.0038	0.03/0.04	1 x M2.5	0.59
	2	1.8	15000	1.11/0.96/0.74	839/548/263	103/80/51	0.012/0.016/0.020	1.2/2.0/2.0	0.004/0.008/0.010	0.0096/0.0103/0.0106	0.06/0.07/0.07	1 x M3	1.11
	4.5	4.1	15000	4.79/2.95	2535/617	268/166	0.012/0.020	1.2/2.0	0.004/0.008	0.0383/0.0400	0.15/0.16	1 x M4	2.21
	10	8.9	15000	5.97/4.94	2061/1102	263/194	0.016/0.020	1.2/2.0	0.006/0.010	0.0871/0.0936	0.21/0.24	1 x M4	2.21
	18	16.2	12700	5.90/4.43	1142/485	286/228	0.016/0.020	1.2/1.5	0.006/0.008	0.1647/0.1989	0.34/0.37	1 x M5	4.43
	30	26.6	10200	25.81/18.44	4111/1256	286/171	0.016/0.020	1.0/1.5	0.004/0.008	0.4558/0.4917	0.62/0.66	1 x M6	8.85
	60	55.3	8600	55.32/36.88	6281/1884	514/314	0.016/0.020	1.0/1.5	0.004/0.008	1.1030/1.1372	1.06/1.12	1 x M8	22.13
	150	132.8	6800	110.64/73.76	11420/3426	857/485	0.016/0.020	1.0/1.5	0.008	2.8324/2.9349	1.77/1.88	1 x M10	62.69
	300	265.5	5900	368.79/206.52	35973/8565	1599/857	0.016/0.020	1.0/1.5	0.008	11.2727/11.8023	3.77/3.90	1 x M12	88.51
	500	442.5	4900	501.55/228.65	50248/5710	571/485	0.020/0.039	1.0/1.5	0.008	19.0839/20.0065	5.27/5.49	1 x M14	140.14

## Transmissible torque T [Nm]

Size	Ø mm																															
	Ø inch																															
	3 0.118	4 0.157	5 0.197	6 0.236	7 0.276	8 0.315	9 0.354	10 0.394	11 0.433	12 0.472	13 0.512	14 0.551	15 0.591	16 0.630	17 0.670	18 0.707	19 0.748	20 0.787	21 0.827	22 0.866	24 0.945	25 0.984	28 1.102	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	64 2.520	
0.4	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
0.9	0.4	0.4	0.4	0.4	0.4	0.4	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
1.5	1.1	1.3	1.3	1.3	1.3	1.3	1.3	1.3	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
2	1.3	1.7	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	1.8	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
4.5	---	---	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
10	---	---	---	5.2	5.9	6.6	7.7	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	8.9	---	---	---	---	---	---	---	---	---	---	
18	---	---	---	---	---	13.3	14.8	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	16.2	---	---	---	---	---	---	---	---	---	
30	---	---	---	---	---	---	---	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	---	---	---	---	---	---	
60	---	---	---	---	---	---	---	---	---	---	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	---	---	---	---	---	
150	---	---	---	---	---	---	---	---	---	---	---	---	---	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	---	---	---	---	
300	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	265.5	265.5	265.5	265.5	265.5	265.5	265.5	265.5	---	---
500	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	442.5	442.5	442.5	442.5	442.5	442.5	442.5	442.5

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $C_1$  = Guided length in hub boring  $d_1$   
 $C_2$  = Guided length in hub boring  $d_2$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $L$  = Total length  
 $L_6$  = Length of basic part  
 $L_7$  = Body length until bellow beginning or plug connection  
 $V$  = Preload distance



## Dimensions

Size	$d_1; d_2$ min-max Without keyway	$C_1$	$C_2$	$D_1$	$H$	$L$	$L_6$	$L_7$	$V$	
	inch									inch
18	0.394 - 0.630	0.630	1.024	1.772	1.772	2.283/2.598	1.535/1.850	0.669	0.02 - 0.04	
30	0.472 - 0.945	0.787	1.260	2.165	2.205	2.677/2.992	1.850/2.165	0.748	0.02 - 0.04	
60	0.472 - 1.260	0.866	1.457	2.598	2.598	3.110/3.504	1.654/2.047	0.866	0.02 - 0.06	
150	0.591 - 1.575	1.102	1.772	3.150	3.228	3.819/4.291	2.047/2.520	1.102	0.02 - 0.06	
300	0.945 - 2.205	1.496	1.811	4.331	4.331	4.449/4.882	3.091/3.524	1.299	0.02 - 0.06	
500	1.181 - 2.362	1.654	2.441	4.685	4.803	5.197/5.709	3.583/4.094	1.496	0.02 - 0.08	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

### Characteristics / Series PKB with locking ring

- Axial mountable from in- and outside
- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- High power performance
- The contact surfaces have to be free from oil and grease
- Axial pluggable

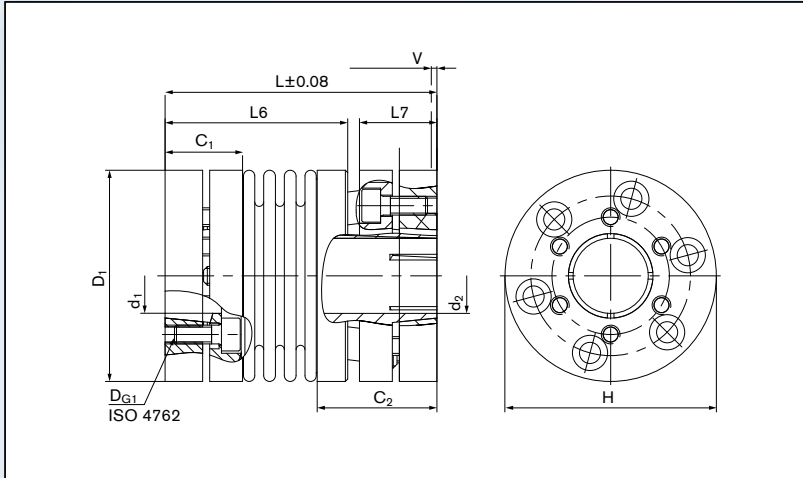
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

### Ordering example: PKB

Series Size	Length $L$	Bore diameter $d_1$	Bore diameter $d_2$	Position	Further details*
PKB 150	3.819	1.181	1.377	C	*

C = Single position    D = Multi position    \* Keyway





Sectional view PKB

## Technical Data

- T** = Transmissible torque at given  $T_A$   
 **$n_{max}$**  = Max. rotation speed  
 **$C_{Tdyn}$**  = Dynamic torsional stiffness  
 **$C_r$**  = Radial spring stiffness  
 **$C_a$**  = Axial spring stiffness  
 **$\Delta K_a$**  = Max. permissible axial misalignment  
 **$\Delta K_w$**  = Max. permissible angular misalignment  
 **$\Delta K_r$**  = Max. permissible radial misalignment  
**J** = Total moment of inertia  
**Gw** = Weight  
 **$D_{G1}$**  = Thread  
 **$T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
		ft-lbs	rpm	10 <sup>3</sup> ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	18	16.2	12700	6	1142	286	0.020	1.5	0.008	0.251/0.263	0.56/0.58	6 x M4	1.5
	30	26.6	10200	26/18	4111/1256	286/171	0.016/0.020	1.0/1.5	0.004/0.008	0.681/0.717	0.95/0.99	6 x M4	1.8
	60	55.3	8600	55/37	6281/1884	514/314	0.016/0.020	1.0/1.5	0.004/0.008	1.548/1.637	1.45/1.51	6 x M5	3.0
	150	132.8	6800	111/74	11420/3426	857/485	0.016/0.020	1.0/1.5	0.008	4.271/4.497	2.67/2.78	6 x M5	5.9
	300	265.5	5900	369/207	35973/8565	1599/857	0.016/0.020	1.0/1.5	0.008	18.141/18.676	6.71/6.84	6 x M8	11.8
	500	442.5	4900	502/229	50248/5710	571/485	0.020/0.039	1.0/1.5	0.008	26.533/27.455	7.76/7.96	6 x M8	14.8

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																			
	10 0.394	12 0.472	14 0.551	15 0.591	16 0.630	18 0.707	20 0.787	22 0.866	24 0.945	26 1.023	30 1.181	32 1.260	35 1.378	38 1.496	40 1.575	44 1.732	48 1.890	50 1.989	55 2.165	60 2.362
18	16.2	16.2	16.2	16.2	16.2	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---
30	---	26.6	26.6	26.6	26.6	26.6	26.6	26.6	26.6	---	---	---	---	---	---	---	---	---	---	---
60	---	24.3	49.4	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	---	---	---	---	---	---	---	---
150	---	---	---	70.8	90.7	115.1	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	132.8	---	---	---	---	---
300	---	---	---	---	---	---	---	---	168.9	199.1	265.5	265.5	265.5	265.5	265.5	265.5	265.5	265.5	265.5	---
500	---	---	---	---	---	---	---	---	---	---	310.5	355.5	428.5	442.5	442.5	442.5	442.5	442.5	442.5	442.5

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $C_2$  = Guided length in hub boring  $d_2$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length  
 $L_6$  = Length of basic part



## Dimensions

Size	$d_1$ min-max	$d_2$ min-max	$d_{1k}$ min-max	$d_{2k}$ min-max									
	Without keyway	With keyway	With keyway	Without keyway	$C_1$	$C_2$	$D_1$	$H$	$I$	$K$	$L$	$L_6$	
	inch	inch	inch		inch			inch	inch		inch	inch	
2	0.118 - 0.551	0.118 - 0.354	0.236 - 0.551	0.236 - 0.354	0.433	0.453	0.984	1.102	0.157	0.354	1.535	1.024	
4.5	0.236 - 0.669	0.236 - 0.630	0.236 - 0.669	0.236 - 0.630	0.512	0.512	1.299	1.378	0.197	0.472	1.870	1.299	
10	0.236 - 0.945	0.236 - 0.866	0.236 - 0.945	0.236 - 0.866	0.551	0.512	1.575	1.654	0.197	0.630	2.106	1.535	
18	0.315 - 1.024	0.315 - 0.866	0.315 - 1.024	0.315 - 0.866	0.787	0.728	1.772	1.890	0.236	0.709	2.776	1.969	
30	0.394 - 1.181	0.394 - 1.102	0.394 - 1.181	0.394 - 1.102	0.984	0.866	2.165	2.205	0.315	0.787	2.835	1.890	
60	0.394 - 1.378	0.394 - 1.181	0.394 - 1.378	0.394 - 1.181	1.142	1.142	2.598	2.638	0.394	0.945	3.484	2.244	
80	0.551 - 1.654	0.551 - 1.654	0.551 - 1.654	0.551 - 1.654	1.339	1.299	3.150	3.346	0.472	1.102	4.035	2.638	
150	0.551 - 1.654	0.551 - 1.654	0.551 - 1.654	0.551 - 1.654	1.339	1.299	3.150	3.346	0.472	1.102	4.035	2.638	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel

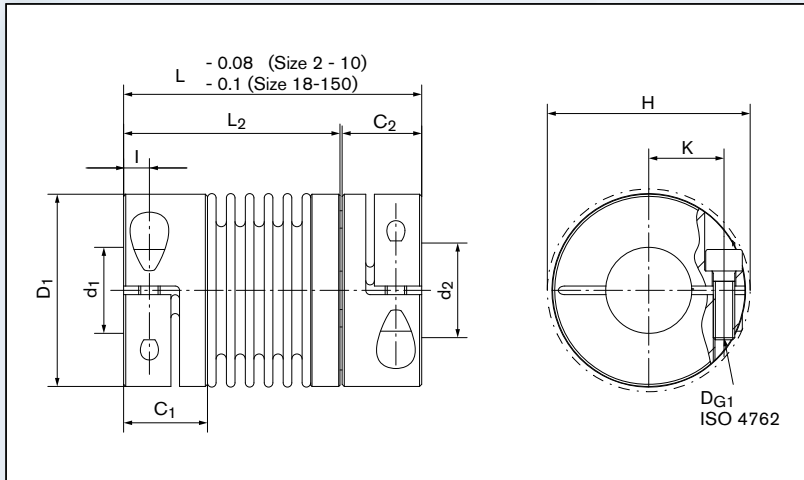
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: PKN

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
PKN 150	1.181	1.377	*

\* Keyway or stainless steel





Sectional view PKN

## Technical Data

- T** = Transmissible torque at given  $T_A$   
 **$n_{max}$**  = Max. rotation speed  
 **$C_{Tdyn}$**  = Dynamic torsional stiffness  
 **$C_r$**  = Radial spring stiffness  
 **$C_a$**  = Axial spring stiffness  
 **$\Delta K_a$**  = Max. permissible axial misalignment  
 **$\Delta K_w$**  = Max. permissible angular misalignment  
 **$\Delta K_r$**  = Max. permissible radial misalignment  
**J** = Total moment of inertia  
**Gw** = Weight  
 **$D_{G1}$**  = Thread  
 **$T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
		ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	2	1.8	22900	1.1	839	103	0.016	1.2	0.008	0.07	0.07	1 x M3	1.1
	4.5	4.1	17600	4.8	2535	268	0.012	1.2	0.004	0.10	0.15	1 x M4	2.2
	10	9	14100	5.9	2061	263	0.016	1.2	0.006	0.14	0.20	1 x M4	2.2
	18	16	12700	5.9	286	1142	0.020	1.5	0.008	0.18	0.36	1 x M5	4.4
	30	27	10200	26	286	4111	0.016	1.0	0.004	0.42	0.62	1 x M6	9
	60	55	8600	55	514	6281	0.016	1.0	0.004	1.11	1.10	1 x M8	22
	80	70	6800	96	457	6852	0.016	1.0	0.008	3.02	1.90	1 x M10	44
	150	133	6800	111	857	11420	0.016	1.0	0.008	3.02	1.90	1 x M10	63

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																				
	3	4	5	6	8	10	12	14	15	18	20	21	24	27	28	30	32	35	36	38	41
	0.118	0.157	0.197	0.236	0.315	0.394	0.472	0.551	0.591	0.707	0.787	0.827	0.945	1.063	1.102	1.181	1.260	1.378	1.417	1.496	1.614
2	1.3	1.7	1.8	1.8	1.8	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---
4.5	---	---	4.1	4.1	4.1	4.1	4.1	4.1	---	---	---	---	---	---	---	---	---	---	---	---	---
10	---	---	---	5.9	8	9	9	9	9	9	9	---	---	---	---	---	---	---	---	---	---
18	---	---	---	---	---	13	16	16	16	16	16	16	---	---	---	---	---	---	---	---	---
30	---	---	---	---	---	27	27	27	27	27	27	27	27	27	---	---	---	---	---	---	---
60	---	---	---	---	---	---	---	55	55	55	55	55	55	55	55	---	---	---	---	---	---
80	---	---	---	---	---	---	---	70	70	70	70	70	70	70	70	70	70	70	70	70	70
150	---	---	---	---	---	---	---	133	133	133	133	133	133	133	133	133	133	133	133	133	133

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length



## Dimensions

Size	$d_1; d_2$ min-max	$d_{1k}; d_{2k}$ min-max							
	Without keyway	With keyway	$C_1$	$D_1$	$H$	$I$	$K$	$L$	
	inch	inch	inch	inch	inch	inch		inch	
18	0.315 - 1.024	0.315 - 1.024	0.756	1.772	1.850	0.236	0.709	2.480	
30	0.394 - 1.181	0.394 - 1.181	0.949	2.165	2.205	0.315	0.787	2.559	
60	0.472 - 1.378	0.472 - 1.378	1.126	2.520	2.638	0.394	0.945	3.071	
80	0.551 - 1.654	0.551 - 1.654	1.276	3.150	3.307	0.472	1.102	3.543	
150	0.551 - 1.654	0.551 - 1.654	1.276	3.150	3.307	0.472	1.102	3.543	
200	0.866 - 1.811	0.866 - 1.811	1.453	3.543	3.661	0.512	1.220	3.898	
300	0.945 - 2.362	0.945 - 2.362	1.453	4.331	4.331	0.512	1.535	4.094	
500	1.378 - 2.520	1.378 - 2.520	1.591	4.685	4.803	0.591	1.693	4.370	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel

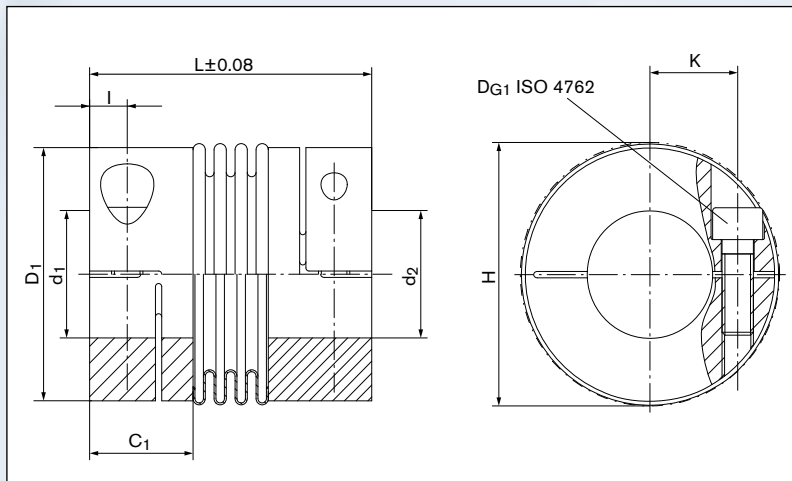
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: AKN

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
AKN 150	1.181	1.377	*

\* Keyway or stainless steel





Sectional view AKN

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- $D_{G1}$**  = Thread
- $T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
		ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	18	16	12700	6	1142	286	0.02	1.5	0.008	0.2	0.29	1 x M5	4.5
	30	27	10200	26	4111	286	0.016	1.0	0.004	0.4	0.54	1 x M6	9
	60	55	8600	55	6281	514	0.016	1.0	0.004	1.0	0.9	1 x M8	22
	80	70	6800	96	6852	457	0.016	1.0	0.008	3.0	1.6	1 x M10	45
	150	133	6800	111	11420	857	0.016	1.0	0.008	3.0	1.6	1 x M10	63
	200	177	6300	125	14276	857	0.016	1.0	0.008	4.9	2.3	1 x M12	74
	300	266	5900	369	35974	1599	0.016	1.0	0.008	10.3	3.2	1 x M12	86
	500	443	4900	502	50250	571	0.02	1.0	0.008	16.1	4.3	1 x M14	140

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																				
	8	9	10	11	12	13	15	16	18	20	22	25	28	30	35	40	45	50	55	60	64
	0.315	0.354	0.394	0.433	0.472	0.512	0.591	0.630	0.707	0.787	0.866	0.984	1.102	1.181	1.378	1.575	1.772	1.989	2.165	2.362	2.520
18	13	15	16	16	16	16	16	16	16	16	16	16	---	---	---	---	---	---	---	---	---
30	---	---	27	27	27	27	27	27	27	27	27	27	27	27	---	---	---	---	---	---	---
60	---	---	---	---	55	55	55	55	55	55	55	55	55	55	55	---	---	---	---	---	---
80	---	---	---	---	---	---	70	70	70	70	70	70	70	70	70	70	---	---	---	---	---
150	---	---	---	---	---	---	133	133	133	133	133	133	133	133	133	133	---	---	---	---	---
200	---	---	---	---	---	---	---	---	---	---	177	177	177	177	177	177	177	---	---	---	---
300	---	---	---	---	---	---	---	---	---	---	---	266	266	266	266	266	266	266	266	266	---
500	---	---	---	---	---	---	---	---	---	---	---	---	---	---	443	443	443	443	443	443	443

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $K_1$  = Clamping length  
 $L$  = Total length



## Dimensions

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway								
			$C_1$	$D_1$	$H$	$I$	$K$	$K_1$	$L$	
	inch		inch	inch	inch	inch			inch	
18	0.315 - 1.024	0.315 - 1.024	0.787	1.772	1.85	0.236	0.709	0.433	2.480	
30	0.394 - 1.181	0.394 - 1.181	0.984	2.165	2.205	0.315	0.787	0.591	2.559	
60	0.472 - 1.378	0.472 - 1.378	1.142	2.520	2.638	0.394	0.945	0.748	3.071	
80	0.551 - 1.654	0.551 - 1.654	1.339	3.150	3.307	0.472	1.102	0.827	3.543	
150	0.551 - 1.654	0.551 - 1.654	1.339	3.150	3.307	0.472	1.102	0.827	3.543	
200	0.866 - 1.811	0.866 - 1.811	1.496	3.543	3.661	0.512	1.220	0.945	3.898	
300	0.945 - 2.362	0.945 - 2.362	1.496	4.331	4.331	0.512	1.535	0.945	4.094	
500	1.378 - 2.52	1.378 - 2.520	1.614	4.685	4.803	0.591	1.693	1.083	4.370	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

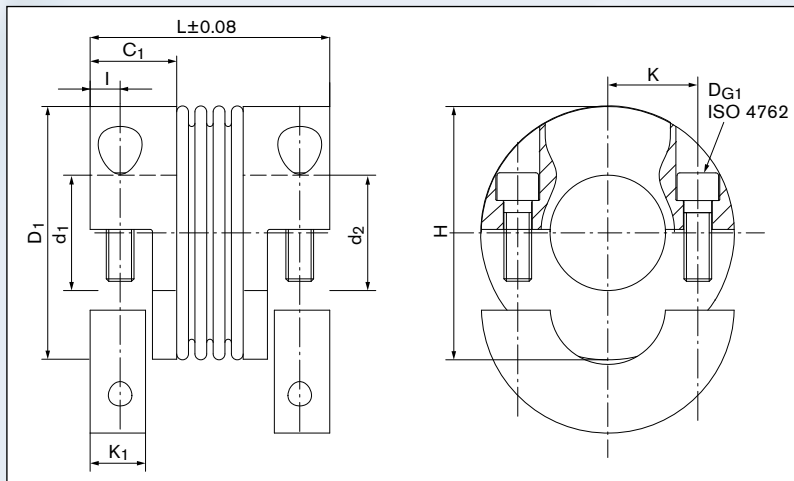
## Ordering example: AKN-H

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
AKN-H 150	1.377	1.654	*

\* Keyway or stainless steel



# GERWAH® AKN-H



Sectional view AKN-H

## Technical Data

- T** = Transmissible torque at given  $T_A$   
 **$n_{max}$**  = Max. rotation speed  
 **$C_{Tdyn}$**  = Dynamic torsional stiffness  
 **$C_r$**  = Radial spring stiffness  
 **$C_a$**  = Axial spring stiffness  
 **$\Delta K_a$**  = Max. permissible axial misalignment  
 **$\Delta K_w$**  = Max. permissible angular misalignment  
 **$\Delta K_r$**  = Max. permissible radial misalignment  
**J** = Total moment of inertia  
**Gw** = Weight  
**DG1** = Thread  
 **$T_{A1}$**  = Tightened torque of clamping screw DG1

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	DG1	$T_{A1}$
		ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	18	16	12700	6	1142	286	0.020	1.5	0.008	0.2	0.33	2 x M5	4.4
	30	27	10200	26	4111	286	0.016	1.0	0.004	0.4	0.55	2 x M6	9
	60	55	8600	55	6281	514	0.016	1.0	0.004	1.0	0.93	2 x M8	22
	80	70	6800	96	6852	457	0.016	1.0	0.008	3.0	1.7	2 x M10	44
	150	133	6800	111	11420	857	0.016	1.0	0.008	3.0	1.7	2 x M10	63
	200	177	6300	125	14276	857	0.016	1.0	0.008	4.9	2.4	2 x M12	74
	300	266	5900	369	35974	1599	0.016	1.0	0.008	10.3	3.3	2 x M12	89
	500	443	4900	502	50250	571	0.020	1.0	0.008	16.1	4.4	2 x M14	140

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																			
	8	9	10	11	12	14	15	18	20	22	24	25	28	30	35	40	45	50	55	60
	0.315	0.354	0.394	0.433	0.472	0.551	0.591	0.707	0.787	0.866	0.945	0.984	1.102	1.181	1.378	1.575	1.772	1.989	2.165	2.362
18	10	11	13	14	15	16	16	16	16	16	16	16	---	---	---	---	---	---	---	---
30	---	---	21	22	24	27	27	27	27	27	27	27	27	27	---	---	---	---	---	---
60	---	---	---	---	46	55	55	55	55	55	55	55	55	55	55	---	---	---	---	---
80	---	---	---	---	---	70	70	70	70	70	70	70	70	70	70	70	---	---	---	---
150	---	---	---	---	---	123	133	133	133	133	133	133	133	133	133	133	---	---	---	---
200	---	---	---	---	---	---	---	---	---	177	177	177	177	177	177	177	177	---	---	---
300	---	---	---	---	---	---	---	---	---	---	252	266	266	266	266	266	266	266	266	266
500	---	---	---	---	---	---	---	---	---	---	---	---	---	---	443	443	443	443	443	443

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length



## Dimensions

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway							
			$C_1$	$D_1$	$H$	$I$	$K$	$L$	
	inch		inch	inch	inch	inch		inch	
18	0.315 - 1.024	0.315 - 1.024	0.756	1.772	1.850	0.236	0.709	2.795	
30	0.394 - 1.181	0.394 - 1.181	0.949	2.165	2.205	0.315	0.787	2.874	
60	0.472 - 1.378	0.472 - 1.378	1.126	2.520	2.638	0.394	0.945	3.504	
80	0.551 - 1.654	0.551 - 1.654	1.276	3.150	3.307	0.472	1.102	4.055	
150	0.551 - 1.654	0.551 - 1.654	1.276	3.150	3.307	0.472	1.102	4.055	
200	0.866 - 1.811	0.866 - 1.811	1.453	3.543	3.661	0.512	1.220	4.449	
300	0.945 - 2.362	0.945 - 2.362	1.453	4.331	4.331	0.512	1.535	4.528	
500	1.378 - 2.520	1.378 - 2.520	1.591	4.685	4.803	0.591	1.693	4.803	
800	1.575 - 2.953	1.575 - 2.953	1.780	5.197	5.472	0.669	1.890	5.512	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum / hubs size 800 and larger made of steel
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel
- Other sizes available on request

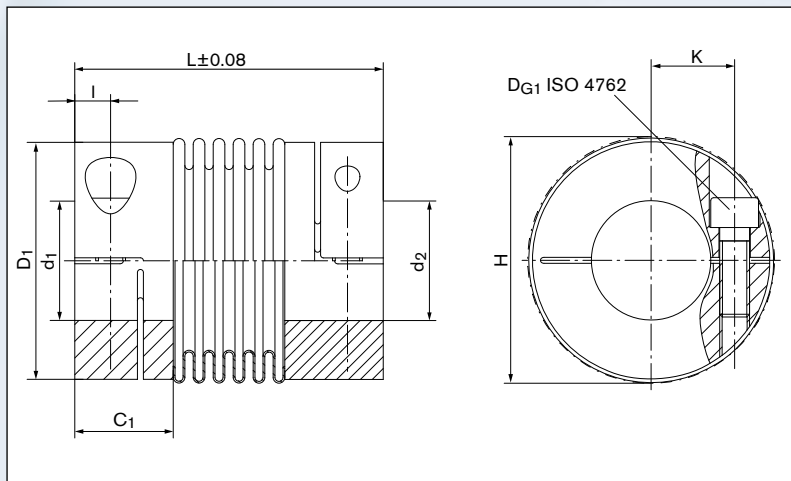
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: AKD

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
AKD 150	1.181	1.378	*

\* Keyway or stainless steel





Sectional view AKD

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- DG1** = Thread
- $T_{A1}$**  = Tightened torque of clamping screw DG1

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	DG1	$T_{A1}$
		ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	18	16	12700	4	485	228	0.020	1.5	0.008	0.2	0.4	2 x M5	4.4
	30	27	10200	18	1256	171	0.020	1.5	0.008	0.3	0.6	2 x M6	9
	60	55	8600	37	1884	314	0.020	1.5	0.008	1.0	1.0	2 x M8	22
	80	70	6800	55	2284	314	0.020	1.5	0.008	3.1	2.0	2 x M10	44
	150	133	6800	74	3426	485	0.020	1.5	0.008	3.1	2.0	2 x M10	63
	200	177	6300	89	2570	485	0.020	1.5	0.008	5.1	3.0	2 x M12	74
	300	266	5900	207	8565	857	0.020	1.5	0.008	10.9	3.0	2 x M12	89
	500	443	4900	229	5710	485	0.039	1.5	0.008	16.7	5.0	2 x M14	140
	800	590	5000	575	35403	571	0.138	1.5	0.014	59.8	13.0	2 x M16	184

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																				
	8 0.315	9 0.354	10 0.394	11 0.433	12 0.472	14 0.551	15 0.591	16 0.630	18 0.707	20 0.787	25 0.984	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	64 2.520	70 2.756	75 2.953
18	13	15	16	16	16	16	16	16	16	16	16	---	---	---	---	---	---	---	---	---	---
30	---	---	27	27	27	27	27	27	27	27	27	27	---	---	---	---	---	---	---	---	---
60	---	---	---	---	55	55	55	55	55	55	55	55	55	---	---	---	---	---	---	---	---
80	---	---	---	---	---	---	70	70	70	70	70	70	70	70	---	---	---	---	---	---	---
150	---	---	---	---	---	---	133	133	133	133	133	133	133	133	---	---	---	---	---	---	---
200	---	---	---	---	---	---	---	---	---	---	177	177	177	177	177	---	---	---	---	---	---
300	---	---	---	---	---	---	---	---	---	---	266	266	266	266	266	266	266	266	---	---	---
500	---	---	---	---	---	---	---	---	---	---	---	---	443	443	443	443	443	443	443	---	---
800	---	---	---	---	---	---	---	---	---	---	---	---	---	---	590	590	590	590	590	590	590

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $K_1$  = Clamping length  
 $L$  = Total length



## Dimensions

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway								
	inch	inch	$C_1$	$D_1$	$H$	$I$	$K$	$K_1$	$L$	
	inch	inch	inch	inch	inch	inch	inch	inch	inch	
18	0.315 - 1.024	0.315 - 1.024	0.756	1.772	1.850	0.236	0.709	0.433	2.795	
30	0.394 - 1.181	0.394 - 1.181	0.949	2.165	2.205	0.315	0.787	0.591	2.874	
60	0.472 - 1.378	0.472 - 1.378	1.126	2.520	2.638	0.394	0.945	0.748	3.504	
80	0.551 - 1.654	0.551 - 1.654	1.276	3.150	3.307	0.472	1.102	0.827	4.055	
150	0.551 - 1.654	0.551 - 1.654	1.276	3.150	3.307	0.472	1.102	0.827	4.055	
200	0.866 - 1.811	0.866 - 1.811	1.453	3.543	3.661	0.512	1.220	0.945	4.449	
300	0.945 - 2.362	0.945 - 2.362	1.453	4.331	4.331	0.512	1.535	0.945	4.528	
500	1.378 - 2.520	1.378 - 2.520	1.591	4.685	4.803	0.591	1.693	1.083	4.803	
800	1.575 - 2.953	1.575 - 2.953	1.780	5.197	5.472	0.669	1.890	1.339	5.512	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.  
 Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum / hubs size 800 and larger made of steel
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel
- Other sizes available on request

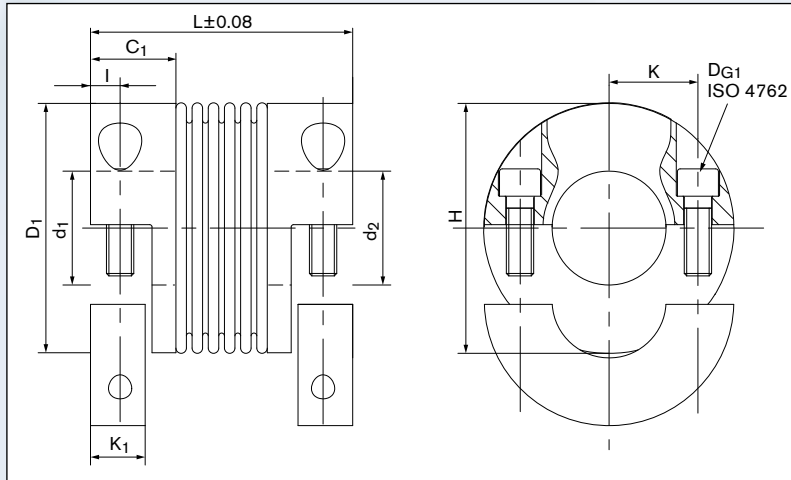
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: AKD-H

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
AKD-H 150	1.181	1.378	*

\* Keyway or stainless steel

# GERWAH® AKD-H



Sectional view AKD-H

## Technical Data

- T** = Transmissible torque at given  $T_A$   
 **$n_{max}$**  = Max. rotation speed  
 **$C_{Tdyn}$**  = Dynamic torsional stiffness  
 **$C_r$**  = Radial spring stiffness  
 **$C_a$**  = Axial spring stiffness  
 **$\Delta K_a$**  = Max. permissible axial misalignment  
 **$\Delta K_w$**  = Max. permissible angular misalignment  
 **$\Delta K_r$**  = Max. permissible radial misalignment  
**J** = Total moment of inertia  
**Gw** = Weight  
 **$D_{G1}$**  = Thread  
 **$T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
		ft-lbs	rpm	10 <sup>3</sup> ft-lbs/rad	lbs/inch		inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	18	16	12700	4	485	228	0.02	1.5	0.008	0.2	0.4	2 x M5	4
	30	27	10200	18	1256	171	0.02	1.5	0.008	0.3	0.6	2 x M6	9
	60	55	8600	37	1884	314	0.02	1.5	0.008	1.0	1	2 x M8	22
	80	70	6800	55	2284	314	0.02	1.5	0.008	3.1	2	2 x M10	44
	150	133	6800	74	3426	485	0.02	1.5	0.008	3.1	2	2 x M10	63
	200	177	6300	89	2570	485	0.02	1.5	0.008	5.1	3	2 x M12	74
	300	266	5900	207	8565	857	0.02	1.5	0.008	10.9	3	2 x M12	89
	500	443	4900	229	5710	485	0.039	1.5	0.008	16.7	5	2 x M14	140
	800	590	5000	575	35403	571	0.138	1.5	0.014	59.8	13	2 x M16	184

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																			
	8 0.315	9 0.354	10 0.394	11 0.433	12 0.472	14 0.551	15 0.591	18 0.707	20 0.787	24 0.945	25 0.984	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	64 2.520	70 2.756
18	10	11	13	14	15	16	16	16	16	16	16	---	---	---	---	---	---	---	---	---
30	---	---	21	22	24	27	27	27	27	27	27	27	---	---	---	---	---	---	---	---
60	---	---	---	---	46	55	55	55	55	55	55	55	55	---	---	---	---	---	---	---
80	---	---	---	---	---	70	70	70	70	70	70	70	70	70	---	---	---	---	---	---
150	---	---	---	---	---	123	133	133	133	133	133	133	133	133	---	---	---	---	---	---
200	---	---	---	---	---	---	---	---	---	177	177	177	177	177	177	---	---	---	---	---
300	---	---	---	---	---	---	---	---	---	252	266	266	266	266	266	266	266	266	---	---
500	---	---	---	---	---	---	---	---	---	---	---	---	443	443	443	443	443	443	443	---
800	---	---	---	---	---	---	---	---	---	---	---	---	---	590	590	590	590	590	590	590



## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $B$  = Bellow outer diameter  
 $C$  = Pitch circle diameter  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $L$  = Total length  
 $L_1$  = Length of coupling  
 $L_4$  = Length of coupling piece (without conical bushing)



## Dimensions

Size	$d_1; d_2$ min-max Without keyway								
		B	C	$C_1$	$D_1$	L	$L_1$	$L_4$	
	inch	inch			inch	inch		inch	
30	0.354 - 0.787	2.205	1.220	0.787	2.165	2.047/2.362	1.772/2.087	1.181/1.496	
60	0.472 - 0.984	2.598	1.457	0.984	2.520	2.480/2.874	2.165/2.559	1.378/1.811	
80	0.591 - 1.378	3.228	2.008	1.181	3.150	3.110/3.583	2.835/3.268	1.929/2.402	
150	0.591 - 1.378	3.228	2.008	1.181	3.150	3.110/3.583	2.835/3.307	1.929/2.402	
200	0.591/1.382/0.591/1.382 - 1.378/1.654/1.378/1.654	3.543	2.008/2.205/2.008/2.205	1.181	3.543	3.150/3.150/3.661/3.661	2.835/2.835/3.346/3.346	1.969/1.969/2.480/2.480	
300	0.591/1.181/0.591/1.181 - 1.654/1.969/1.654/1.969	4.331	2.441/2.953/2.441/2.953	1.299	4.331	3.661/3.661/4.094/4.094	3.150/3.150/3.661/3.661	2.205/2.205/2.638/2.638	
500	0.945/1.575/0.945/1.575 - 1.969/2.165/1.969/2.165	4.803	2.953/3.150/2.953/3.150	1.496	4.685	4.016/4.016/4.449/4.449	3.701/3.701/4.134/4.134	2.402/2.402/2.835/2.835	
800	1.181/2.366 - 2.362/2.756	6.181	3.622/3.937	2.362	5.512	6.693	5.906	4.331	
1400	1.378/2.362 - 2.362/2.756	6.181	3.622/3.937	2.362	5.512	6.693	5.906	4.331	
3000	1.969/2.760 - 2.756/3.150	7.835	3.937/4.921	2.362	7.087	7.520	6.732	5.157	
5000	2.362/2.760 - 2.756/3.543	9.843	3.937/4.921	2.559	9.055	7.835	7.047	5.472	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.  
 Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Characteristics

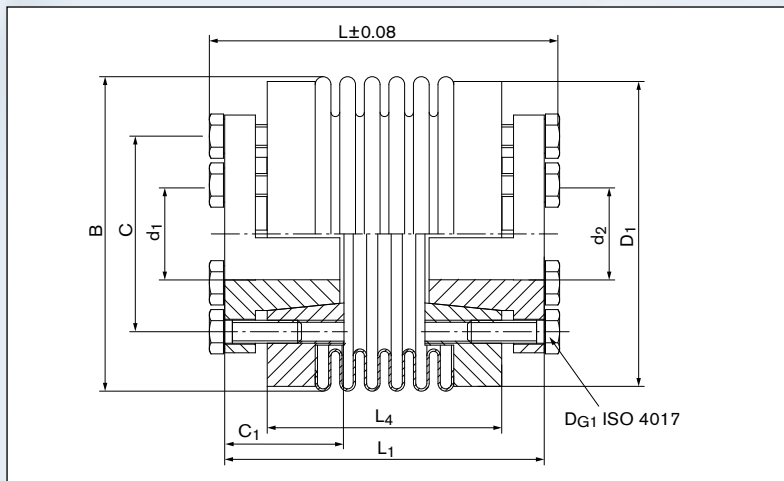
- Metal bellows made of stainless steel, conical bushings made of steel
- Hubs up to size 500 made of aluminum, sizes 800 – 5000 hubs made of steel
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: AK

Series Size	Length L	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
AK 150	3.110	1.181	1.378	*

\* Stainless steel



Sectional view AK

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- $D_{G1}$**  = Thread
- $T_{A1}$**  = Tightened torque of clamping screw  $D_{G1}$

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	$D_{G1}$	$T_{A1}$
		ft-lbs	rpm	10 <sup>3</sup> ft-lbs/rad	lbs/inch		±inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	30	27	11000	25.8/18.4	4111/1256	286/171	0.016/0.020	1.0/1.5	0.004/0.008	0.5	0.62	6 x M4	2.2
	60	53	9100	55.3/36.9	6281/1884	514/314	0.016/0.020	1.0/1.5	0.004/0.008	0.8	1.10	6 x M6	6.3
	80	71	7000	95.9/55.3	6852/2284	457/314	0.016/0.020	1.0/1.5	0.008	2.2	1.90	6 x M6	7.4
	150	133	7000	110.6/73.8	11420/3426	857/485	0.016/0.020	1.0/1.5	0.008	2.2	1.90	6 x M6	10.0
	200	177	6700	125.4/125.4/88.5/88.5	14275/14275/2570/2570	857/857/485/485	0.016/0.016/0.020/0.020	1.0/1.0/1.5/1.5	0.008	3.0	2.20/2.22/2.20/2.22	6 x M6	10.0/10.3/10.0/10.3
	300	266	5200	234.5/368.8/206.5/206.5	35973/35973/8565/8565	1342/1599/857/857	0.016/0.016/0.020/0.020	1.0/1.0/1.5/1.5	0.008	8.0	4.20/4.22/4.20/4.22	6 x M8	13.0/13.3/13.0/13.3
	500	443	4600	501.5/501.5/228.6/228.6	50248/50248/5710/5710	571/571/485/485	0.020/0.020/0.039/0.039	1.0/1.0/1.5/1.5	0.008	20.0/19.6/20.0/19.6	5.40	6 x M8	19.0/19.2/19.0/19.2
	800	590	3700	561.0/560.6	2912	1085	0.039	1.5	0.008	89.0/89.2	22.00	6 x M16	37.0/36.9
	1400	1033	3700	959.0/958.8	4054	1599	0.039	1.5	0.008	89.0/89.2	20.00/20.29	6 x M16	59.0
	3000	2213	2800	2065.0/2065.2	46023	5025	0.039	1.5	0.008	297.0/296.7	32.00/32.12	6 x M16	96.0/95.9
	5000	3688	2800	3540.0/3540.3	52475	4208	0.039	1.5	0.008	582.0/581.9	54.00/53.57	6 x M16	155.0/154.9

## Transmissible torque T [Nm]

Size	Ø mm Ø inch																			
	9 0.354	10 0.394	12 0.472	14 0.551	15 0.591	18 0.707	20 0.787	24 0.945	28 1.102	32 1.260	38 1.496	44 1.732	48 1.890	50 1.989	58 2.283	60 2.362	65 2.560	70 2.756	75 2.953	80 3.150
30	27	27	27	27	27	27	27	---	---	---	---	---	---	---	---	---	---	---	---	---
60	---	---	53	53	53	53	53	53	---	---	---	---	---	---	---	---	---	---	---	---
80	---	---	---	---	71	71	71	71	71	---	---	---	---	---	---	---	---	---	---	---
150	---	---	---	---	133	133	133	133	133	133	---	---	---	---	---	---	---	---	---	---
200	---	---	---	---	177	177	177	177	177	177	---	---	---	---	---	---	---	---	---	---
300	---	---	---	---	214	258	266	266	266	266	266	266	266	---	---	---	---	---	---	---
500	---	---	---	---	---	---	---	443	443	443	443	443	443	443	---	---	---	---	---	---
800	---	---	---	---	---	---	---	---	590	590	590	590	590	590	590	590	590	---	---	---
1400	---	---	---	---	---	---	---	---	1033	1033	1033	1033	1033	1033	1033	1033	1033	---	---	---
3000	---	---	---	---	---	---	---	---	---	---	---	---	2213	2213	2213	2213	2213	2213	2213	---
5000	---	---	---	---	---	---	---	---	---	---	---	---	---	3688/---	3688	3688	3688	3688	3688	3688

## Dimensions

**d<sub>1</sub>; d<sub>2</sub>** = Inner diameter  
**B** = Bellow outer diameter  
**C** = Pitch circle diameter  
**D<sub>1</sub>** = Outer diameter hub  
**L** = Total length  
**M** = Max. depth of thread



## Dimensions

Size	d <sub>1</sub> ; d <sub>2</sub>	B	C	D <sub>1</sub>	L	M	
		inch		inch	inch	mm	
18	0.866	1.811	1.220	1.811	1.417/1.732	6	
30	1.102	2.205	1.457	2.165	1.181/1.496	7	
60	1.496	2.598	1.811	2.520	1.614/2.008	10	
80	1.969	3.228	2.441	3.150	2.047/2.441	13	
150	1.969	3.228	2.441	3.150	2.047/2.441	13	
200	1.969	3.543	2.441	3.543	2.008/2.480	13	
300	1.969	4.331	3.150	4.291	2.165/2.598	13	
500	2.756	4.803	3.701	4.685	2.402/2.835	16	
800	3.346	6.181	4.331	5.984	5.118	18	
1400	3.346	6.181	4.331	5.984	5.118	18	
3000	3.937	7.835	5.512	7.087	5.118	25	
5000	5.709	9.843	7.480	9.055	5.630	25	

## Characteristics

- Metal bellows made of stainless steel
- Hubs up to size 500 made of aluminum, sizes 800 and larger hubs made of steel
- The contact surfaces have to be free from oil and grease
- Optional special design in stainless steel

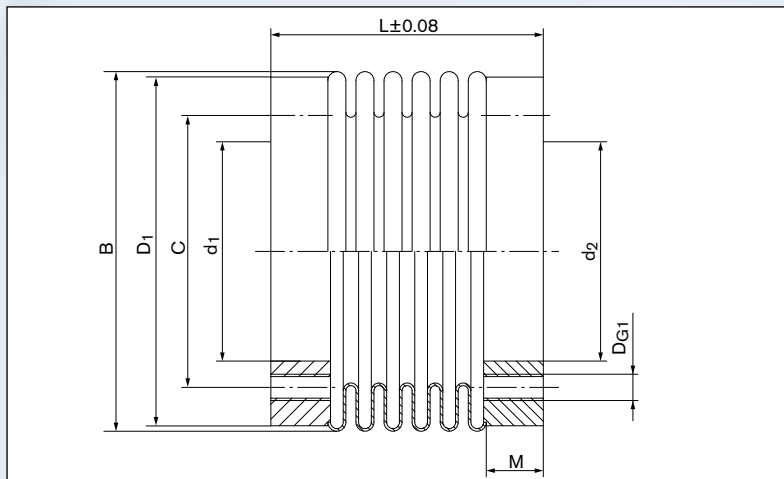
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: CKN

Series Size	Length L	Further details*
CKN 150	2.047	*

\* Stainless steel





Sectional view CKN

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $n_{max}$**  = Max. rotation speed
- $C_{Tdyn}$**  = Dynamic torsional stiffness
- $C_r$**  = Radial spring stiffness
- $C_a$**  = Axial spring stiffness
- $\Delta K_a$**  = Max. permissible axial misalignment
- $\Delta K_w$**  = Max. permissible angular misalignment
- $\Delta K_r$**  = Max. permissible radial misalignment
- J** = Total moment of inertia
- Gw** = Weight
- DG1** = Thread
- $T_{A1}$**  = Tightened torque of clamping screw DG1

## Technical Data

	Size	T	$n_{max}$	$C_{Tdyn}$	$C_r$	$C_a$	$\Delta K_a$	$\Delta K_w$	$\Delta K_r$	J	Gw	DG1	$T_{A1}$
		ft-lbs	rpm	$10^3$ ft-lbs/rad	lbs/inch		±inch	Degree	inch	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
	18	16	13900	5.9/4.4	1142.0/485.4	285.5/228.4	0.020	1.5	0.008	0.2	0.14	6 x M5	4.4
	30	27	11000	25.8/18.4	4111.2/1256.2	285.5/171.3	0.016/0.020	1.0/1.5	0.004/0.008	0.3	0.26	6 x M5	4.4
	60	55	9000	55.3/36.9	6281.0/1884.3	513.9/314.1	0.016/0.020	1.0/1.5	0.004/0.008	0.5	0.42	6 x M6	7.4
	80	71	7100	95.9/55.3	6852.0/2284.0	456.8/314.1	0.016/0.020	1.0/1.5	0.008	1.5	0.78	6 x M6	7.4
	150	133	7100	110.6/73.8	11420.0/3426.0	856.5/485.4	0.016/0.020	1.0/1.5	0.008	1.5	0.78	6 x M6	11.0
	200	177	6600	125.4/88.5	14275.0/2569.5	856.5/485.4	0.016/0.020	1.0/1.5	0.008	2.7	1.05	6 x M6	13.0
	300	266	5200	368.8/206.5	35973.0/8565.0	1598.8/856.5	0.016/0.020	1.0/1.5	0.008	5.8	1.30	6 x M8	18.0
	500	443	4600	501.5/228.6	50248.0/5710.0	571.0/485.4	0.020/0.039	1.0/1.5	0.008	7.9	1.93	6 x M8	27.0
	800	708	3700	560.6	2912.1	1084.9	0.039	1.5	0.008	37.6	8.20	6 x M16	155.0
	1400	1239	3700	958.8	4054.1	1598.8	0.039	1.5	0.008	37.6	8.20	6 x M16	155.0
	3000	2213	3700	2065.2	46022.6	5024.8	0.039	1.5	0.008	160.6	17.20	6 x M20	269.0
	5000	3688	3000	3540.3	52474.9	4208.3	0.039	1.5	0.008	406.6	26.00	8 x M20	269.0

Screw quality should be selected according to the tightening torque.  
The contact surfaces have to be dry and free from oil and grease.

# Technical Information · Metal Bellows Couplings

## Design/Sample calculation

### Design/Product information

Backlash-free, torsionally stiff metal bellows couplings are ready to install when delivered. The metal bellows are made of stainless steel, all other parts are made of aluminum or steel. The shaft tolerance should be within the fit tolerance "g6" or "h7". The power transmission between the coupling hub and the shaft is generated by compression and friction between the contact surfaces. Special attention must be paid to the tightening torque of the retaining screws as well as the perfect condition of the surfaces. The contact surfaces must be free of oil and grease and have a surface finish of  $R_{tmax}$  0.00063 in for the shaft. Versions with keyway are available. The torques indicated can be guaranteed if you follow all instructions.

### Dimensioning in accordance with the torque

Metal bellows couplings are generally mostly selected according to the transmissible torque. In all cases the torque of the selected coupling size must be higher than the regular transmitted torque. This generally applies to the use of servo motors, whose acceleration torque in both positive and negative directions exceeds the nominal torque. For the use of metal bellows couplings which are fitted in controlled, high dynamic drives, the following dimensioning values (K) have proven to be reliable in practice:

$K = 1.5$  for evenly shaped movements

$K = 2$  for unevenly shaped movements

$K = 2.5 - 4$  for jerky movements

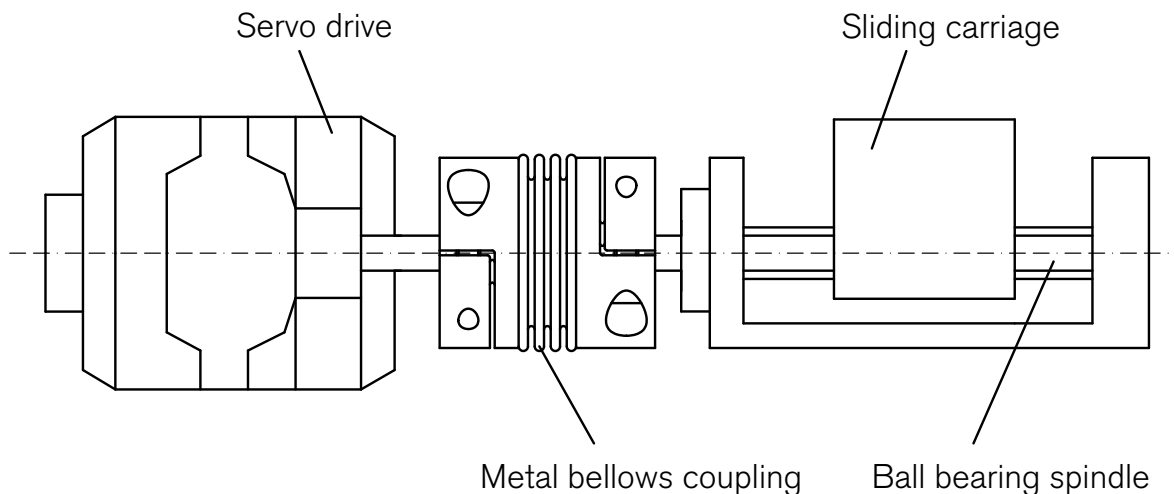
For servo drives within tool making machines, the values for

$K = 1.5 - 2$  should be used.

We would be pleased to design your metal bellows coupling for you. Feel free to use our experience and know-how for your success. Give us a call!

$$T \geq K \cdot T_{AS} \cdot \frac{J_{mach}}{J_{eng} + J_{mach}} [ft-lbs]$$

### Example



# Technical Information · Metal Bellows Couplings

## Design in consideration of dynamic torsional stiffness

Although metal bellows couplings are backlash-free and torsion-rigid, it should not be ignored that they link two rotating masses. In adverse cases the couplings can act like a torsion spring with high stiffness. The regulating oscillation of the drives and the harmonic oscillation in the armature current of the motor therefore must never be within the range of the mechanical resonance frequency. In practice the resonance frequency “ $f_{res}$ ” must be twice as high as the excitation frequency of the drive.

The dynamic torsional stiffness  $C_{Tdyn}$  was selected so that it would not be within the range of parasitic oscillation of most applications. Various levels of torsional stiffness are available as standard versions.

We would be pleased to design your metal bellows couplings for you. Feel free to use our experience and know-how for your success. Give us a call!

### Calculation for the application of a metal bellows coupling in a machine tool drive

**Drive related data for servo motor/FT 5104:** Peak torque  $T_{AS} = 118$  ft-lbs  
Moment of inertia  
 $J_{eng} = 62.543$  lbs-in<sup>2</sup>

The low moment of inertia for the metal bellows coupling is disregarded.  $K$  = Load factor, impulse factor selected for this drive  $K = 2$

**Output data for machine tool:** Moment of inertia of ball screw and slide:  $J_{mach} = 58.1$  lbs-in<sup>2</sup>

$$f_{res} = \frac{1}{2\pi} \sqrt{C_{Tdyn} \cdot \frac{J_{eng} + J_{mach}}{J_{eng} \cdot J_{mach}}} \text{ [Hz]}$$

### Design according to torque:

Coupling selection:  
AKD 200,  $T = 177$  ft-lbs,  $C_{Tdyn} = 89 \times 10^3$  ft-lbs/rad

The metal bellows coupling is dimensioned sufficient, since  $177$  ft-lbs  $> 113.6$  ft-lbs

$$T \geq K \cdot T_{AS} \cdot \frac{J_{mach}}{J_{eng} + J_{mach}} = 118 \text{ [ft-lbs]} \cdot \frac{58.1 \text{ [lbs-in}^2\text{]}}{62.543 + 58.1 \text{ [lbs-in}^2\text{]}} = 113.6 \text{ [ft-lbs]}$$

### Design according the resonance frequency:

The arithmetic calculation is clearly higher than the expected resonance frequency. Usually for the most established nc-machine tools this value is between 150 to 350 Hz.

$$f_{res} = \frac{1}{2\pi} \cdot \sqrt{C_{Tdyn} \cdot \frac{J_{eng} + J_{mach}}{J_{eng} \cdot J_{mach}}} = \frac{1}{2\pi} \cdot \sqrt{1062088.8 \frac{\text{[in-lbs]}}{\text{[rad]}} \cdot 386.2 \frac{\text{[in]}}{\text{[s}^2\text{]}} \cdot \frac{(62.543 + 58.1) \text{ [lbs-in}^2\text{]}}{62.543 \text{ [lbs-in}^2\text{]} \cdot 51.1 \text{ [lbs-in}^2\text{]}}} = 587 \text{ [Hz]}$$



# Servo-Insert Couplings Basics

## Backlash-free Servo-Insert Couplings

Backlash-free Servo-Insert Couplings are used in mechanical engineering, where shock absorption is requested and pluggable coupling solutions are applied.

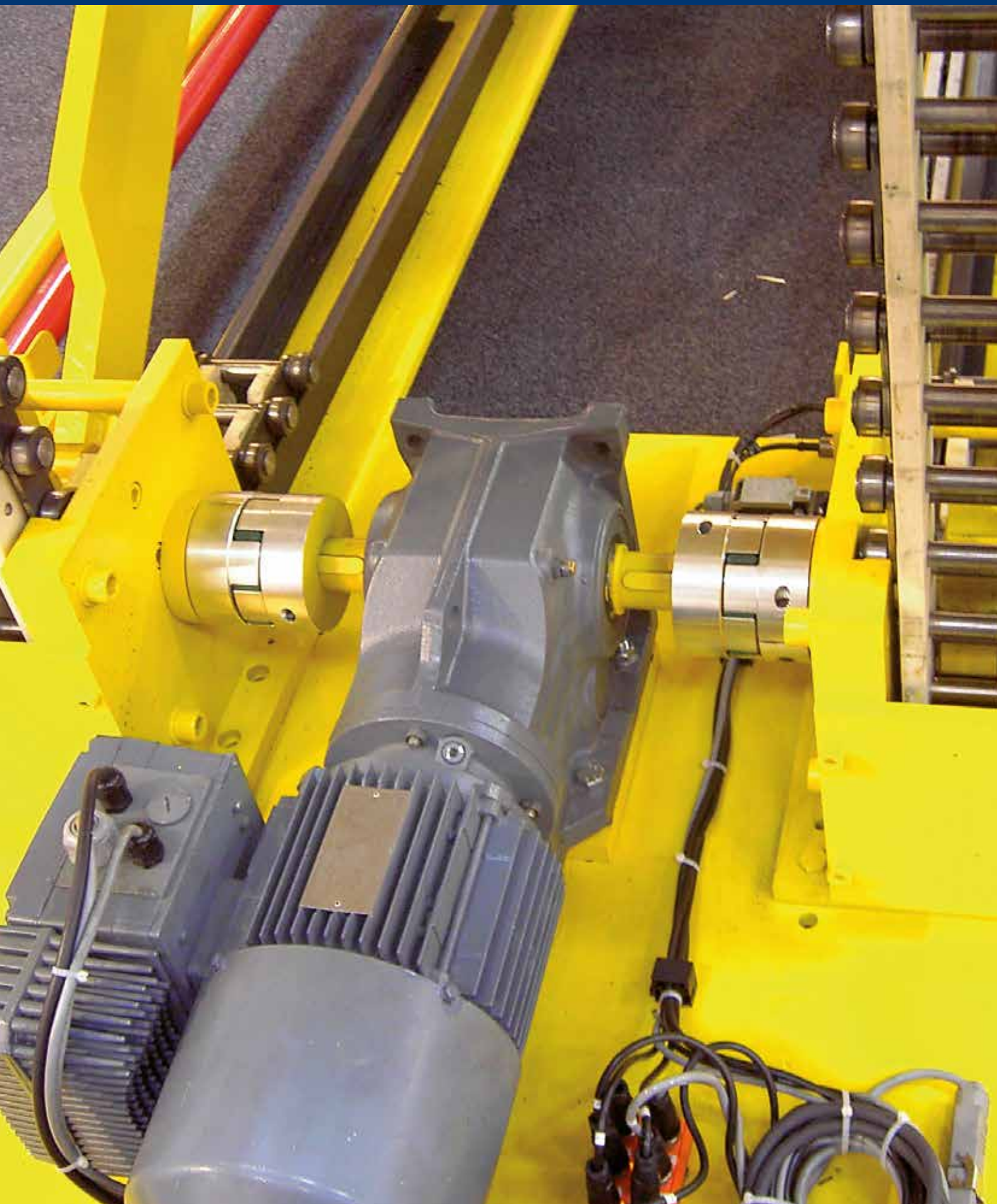
## Special Features

- Backlash-free
- Pluggable
- Vibration damping
- Torques from 0.22 - 1416 ft-lbs
- Compensation of radial, axial and angular misalignment
- Electrically isolating

## Common Applications

- Encoder
- Precision drives
- Feed drives
- Grinding and milling spindles
- Machine tools
- Packing machines
- Robotics
- Transfer lines
- Multi-spindle heads
- Wood processing equipment
- Textile machinery
- Conveying equipment
- Linear motion
- Measuring equipment and control technology
- Test rigs

Hoist





# Automation





# Overview Servo-Insert Couplings



**GERWAH®**  
**GWE 5102**

Miniature servo-insert coupling with set screw hubs

Page 40



**GERWAH®**  
**GWE 5103**

Miniature servo-insert coupling with clamping hubs, short length and single slit

Page 42



**GERWAH®**  
**GWE 5103.1**

Miniature servo-insert coupling with clamping hubs and single slit

Page 44



**GERWAH®**  
**GWE 5107**

Servo-insert coupling with clamping hubs and expanding clamps

Page 46



**GERWAH®**  
**GWE 5104**

Servo-insert coupling with clamping hubs and dual slits

Page 48



**GERWAH®**  
**GWE 5106**

Servo-insert coupling with clamping hubs in split hub design

Page 50



**GERWAH®**  
**GWE 5112**

Servo-insert coupling with outer cone

Page 52

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H_3$  = Length of damping part  
 $l$  = Distance between center screw hole and hub end  
 $L$  = Total length



## Dimensions

## Technical Data

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway												
	inch	inch	$C_1$	$D_1$	$H_3$	$l$	$L$	T	$H_{es}$	$n_{max}$	J	Gw	$D_{G1}$	$T_{A1}$
	inch	inch	inch	inch	inch	inch	inch	ft-lbs		rpm	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
5	0.079 - 0.197	--- - ---	0.197	0.394	0.197	0.098	0.591	0.37	92 SH A	47500	0.12	0.01	1 x M3	1
7	0.118 - 0.315	0.236 - 0.315	0.276	0.551	0.315	0.138	0.866	0.89	92 SH A	34000	0.67	0.02	1 x M3	1
9	0.118 - 0.472	0.236 - 0.394	0.394	0.787	0.394	0.197	1.181	2.2	92 SH A	24000	3.7	0.04	2 x M4	2.2
12	0.157 - 0.472	0.236 - 0.472	0.433	0.984	0.472	0.197	1.339	3.7	92 SH A	19000	9.7	0.07	2 x M4	3.7
14	0.157 - 0.63	0.236 - 0.63	0.433	1.181	0.512	0.197	1.378	6	92 SH A	16000	19	0.09	2 x M6	4.5
19	0.236 - 0.945	0.236 - 0.945	0.984	1.575	0.63	0.394	2.598	7	92 SH A	12000	123	0.3	2 x M6	4.5
24	0.315 - 1.378	0.315 - 1.378	1.181	2.165	0.709	0.394	3.071	26	92 SH A	8500	554	0.62	2 x M6	4.5
28	--- - ---	0.394 - 1.496	1.378	2.559	0.787	0.591	3.543	70	92 SH A	7300	1100	1	2 x M6	4.5
38	--- - ---	0.472 - 1.89	1.772	3.15	0.945	0.591	4.488	140	92 SH A	5900	3260	1.93	2 x M6	4.5

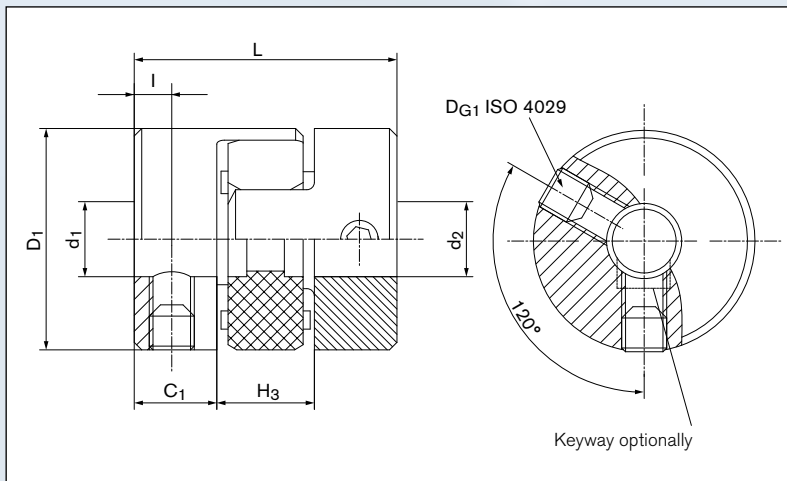
Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings <  $d_{min}$ . Types with borings <  $d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Ordering example: GWE 5102

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWE 5102-14	0.393	0.551	*

\* Keyway

# GERWAH® GWE 5102



Sectional view GWE 5102

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw  $D_{G1}$

## Transmissible torque T [Nm]

	Size	<div> <div>Ø mm</div> <div>Ø inch</div> </div>															
		3	4	5	6	7	8	9	10	12	14	16	18	20	22	24	28
	5	0,02	0,02	0,02	---	---	---	---	---	---	---	---	---	---	---	---	---
	7	0.89	0.89	0.89	0.89	0.89	0.89	---	---	---	---	---	---	---	---	---	---
	9	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	---	---	---	---	---	---	---
	12	---	3.7	3.7	3.7	3.7	3.7	3.7	3.7	3.7	---	---	---	---	---	---	---
	14	---	6	6	6	6	6	6	6	6	6	6	---	---	---	---	---
	19	---	---	---	7	7	7	7	7	7	7	7	7	7	7	7	---
	24	---	---	---	---	---	15	16	18	21	25	26	26	26	26	26	26
	28	---	---	---	---	---	---	---	70	70	70	70	70	70	70	70	70
	38	---	---	---	---	---	---	---	---	140	140	140	140	140	140	140	140

## Characteristics

- Hubs made of aluminum
- Standard elastomeric spider with 92 SH A (yellow spider), optional with through bore hole see page 54/55
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.



## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $H_3$  = Length of damping part  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length



## Dimensions

## Technical Data

	$d_1; d_2$ min-max	$d_{1k}; d_{2k}$ min-max															
Size	Without keyway	With keyway	$C_1$	$D_1$	H	$H_3$	I	K	L	T	$H_{es}$	$n_{max}$	J	Gw	$D_{G1}$	$T_{A1}$	
	inch	inch	inch	inch	inch	inch	inch	inch	inch	ft-lbs		rpm	lbs-in <sup>2</sup>	lbs	mm	ft-lbs	
7	0.118 - 0.276	0.236 - 0.276	0.236	0.551	0.65	0.315	0.118	0.197	0.787	0.89	92 SH A	27000	0.0003	0.01	1 x M2	0.26	
9	0.157 - 0.433	0.236 - 0.433	0.315	0.768	0.906	0.394	0.157	0.295	1.024	2.2	92 SH A	19000	0.0007	0.04	1 x M2.5	0.55	
12	0.157 - 0.472	0.236 - 0.472	0.276	0.984	1.024	0.472	0.138	0.335	1.024	3.7	92 SH A	15000	0.008	0.05	1 x M3	1.1	
14	0.197 - 0.591	0.236 - 0.591	0.374	1.161	1.299	0.512	0.197	0.413	1.26	9	98 SH A	13000	0.021	0.11	1 x M4	3.7	
19	0.315 - 0.866	0.315 - 0.866	0.669	1.555	1.693	0.63	0.236	0.591	1.969	13	98 SH A	10000	0.099	0.26	1 x M5	7.5	
24	0.394 - 1.22	0.394 - 1.22	0.787	2.146	2.205	0.709	0.394	0.787	2.283	44	98 SH A	7000	0.413	0.62	1 x M6	13	
28	0.551 - 1.378	0.551 - 1.378	0.846	2.539	2.638	0.748	0.433	0.925	2.441	118	98 SH A	6000	0.806	0.78	1 x M8	26	
38	0.591 - 1.811	0.591 - 1.811	1.22	3.13	3.465	0.906	0.512	1.181	3.346	240	98 SH A	5000	2.723	1.9	1 x M10	62	
42	0.787 - 2.205	0.787 - 2.205	1.496	3.72	3.74	1.024	0.551	1.378	4.016	332	98 SH A	4000	6.079	3.3	1 x M10	62	

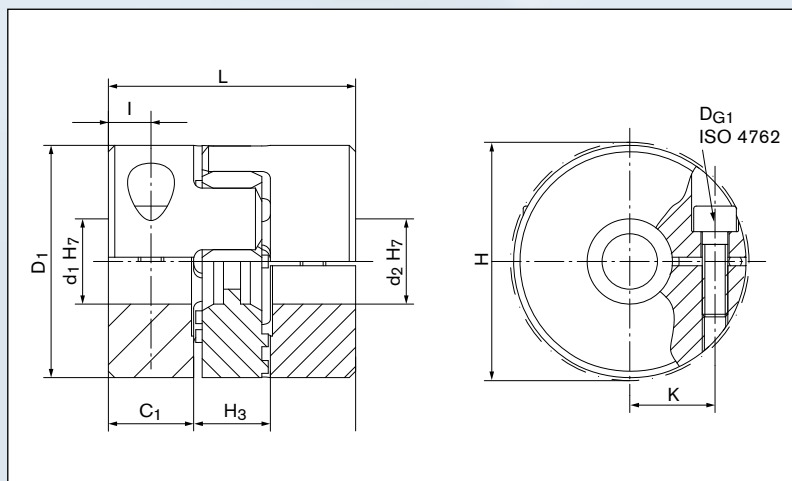
Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Ordering example: GWE 5103

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWE 5103-42	0.787	1.732	*

\* Keyway or stainless steel

# GERWAH® GWE 5103



Sectional view GWE 5103

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Transmissible torque T [Nm]

	Ø mm Ø inch																					
	Size	3	4	5	6	8	10	12	14	15	18	20	25	26	28	30	35	40	45	50	55	56
		0.118	0.157	0.197	0.236	0.315	0.394	0.472	0.551	0.591	0.707	0.787	0.984	1.023	1.102	1.181	1.378	1.575	1.772	1.989	2.165	2.205
	7	0.52	0.66	0.81	0.89	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---
	9	---	1.3	1.5	1.8	2.2	2.2	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---
	12	---	2.1	2.7	3.1	3.7	3.7	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---
	14	---	---	7	8	9	9	9	9	9	---	---	---	---	---	---	---	---	---	---	---	---
	19	---	---	---	---	13	13	13	13	13	13	---	---	---	---	---	---	---	---	---	---	---
	24	---	---	---	---	---	32	38	44	44	44	44	44	44	44	---	---	---	---	---	---	---
	28	---	---	---	---	---	---	---	68	72	85	93	113	117	118	118	118	---	---	---	---	---
	38	---	---	---	---	---	---	---	---	141	267	283	223	230	240	240	240	240	240	---	---	---
	42	---	---	---	---	---	---	---	---	---	---	184	225	233	249	264	302	332	332	332	332	332

## Characteristics

- Hubs made of aluminum
- Elastomeric spider sizes 7 and 9 with 92 SH A (yellow spider)
- Elastomeric spider sizes 14 and 42 with 98 SH A (red spider), optional with through bore hole see page 54/55
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Dimensions

- $d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $d_{1k}; d_{2kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1k}; d_{2kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H$  = Clearance diameter  
 $H_3$  = Length of damping part  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length



## Dimensions

## Technical Data

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway														
	inch	inch	$C_1$	$D_1$	$H$	$H_3$	$I$	$K$	$L$	T	$H_{es}$	$n_{max}$	J	Gw	$D_{G1}$	$T_{A1}$
	inch	inch	inch	inch	inch	inch	inch	inch	inch	ft-lbs		rpm	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
5	0.079 - 0.157	---	0.197	0.394	0.453	0.197	0.098	0.126	0.591	0.37	92 SH A	38000	0.12	0.01	1 x M1.6	0.19
7	0.118 - 0.276	0.236 - 0.276	0.276	0.551	0.65	0.315	0.138	0.197	0.866	0.89	92 SH A	27000	0.67	0.02	1 x M2	0.26
9	0.118 - 0.433	0.236 - 0.433	0.394	0.787	0.925	0.394	0.197	0.287	1.181	2.2	92 SH A	19000	3.7	0.03	1 x M2.5	0.55

Transmission of the couplings transmissible torque T can no longer be guaranteed for certain with borings <  $d_{min}$ . Types with borings <  $d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

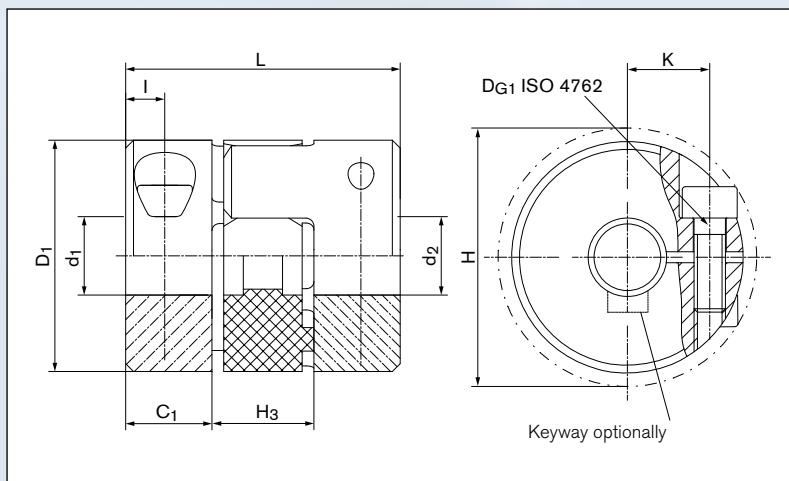
## Ordering example: GWE 5103.1

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWE 5103.1-9	0.157	0.394	*

\* Keyway



# GERWAH® GWE 5103.1



Sectional view GWE 5103.1

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Transmissible torque T [Nm]

	Size	Ø mm Ø inch									
		2 0.079	3 0.118	4 0.157	5 0.197	6 0.236	7 0.276	8 0.315	9 0.354	10 0.394	11 0.433
	5	0.37	0.37	0.37	---	---	---	---	---	---	---
	7	---	0.59	0.81	0.89	0.89	0.89	---	---	---	---
	9	---	1.1	1.5	1.8	2.1	2.2	2.2	2.2	2.2	2.2

## Characteristics

- Hubs made of aluminum
- Standard elastomeric spider with 92 SH A (yellow spider), optional with through bore hole see page 54/55
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Dimensions

- $d_{1min}$  = Min. bore diameter  
 $d_{1max}$  = Max. bore diameter  
 $d_{1kmin}$  = Min. bore diameter with keyway acc. to DIN 6885-1  
 $d_{1kmax}$  = Max. bore diameter with keyway acc. to DIN 6885-1  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $D_{4min}$  = Min. outer diameter of the cone hub  
 $D_{4max}$  = Max. outer diameter of the cone hub  
 $H$  = Clearance diameter  
 $H_3$  = Length of damping part  
 $I$  = Distance between center screw hole and hub end  
 $K$  = Distance shaft axis - clamping screw axis  
 $L$  = Total length  
 $L_5$  = Expanding mandrel length



## Dimensions

## Technical Data

Size	$d_1$ min-max	$d_{1k}$ min-max																			
	Without keyway	With keyway	$C_1$	$D_1$	$D_4$ min-max	$H$	$H_3$	$I$	$K$	$L$	$L_5$	$T$	$H_{es}$	$n_{max}$	$J$	$G_w$	$D_{G1}$	$T_{A1}$	$D_{G2}$	$T_{A2}$	
	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	ft-lbs		rpm	lbs-in <sup>2</sup>	lbs	mm	ft-lbs		ft-lbs	
9	0.157 - 0.433	0.236 - 0.433	0.315	0.768	0.394 - 0.591	0.886	0.394	0.157	0.287	1.339	0.472	2.21	92 SH A	19000	0.007	0.09	1 x M2.5	0.55	1 x M4	3	
12	0.157 - 0.472	0.236 - 0.472	0.276	0.984	0.394 - 0.591	1.024	0.472	0.138	0.335	1.496	0.472	3.69	92 SH A	15000	0.016	0.14	1 x M3	1.1	1 x M4	3	
14	0.197 - 0.591	0.236 - 0.591	0.374	1.161	0.512 - 0.984	1.299	0.512	0.197	0.413	1.89	0.787	9.22	98 SH A	13000	0.038	0.24	1 x M4	3.7	1 x M5	6.7	
19	0.315 - 0.866	0.315 - 0.866	0.669	1.555	0.551 - 1.181	1.693	0.630	0.236	0.591	2.559	0.984	12.54	98 SH A	10000	0.15	0.57	1 x M5	7.5	1 x M6	9	
24	0.394 - 1.220	0.394 - 1.220	0.787	2.146	0.906 - 1.417	2.205	0.709	0.394	0.787	2.874	1.063	44.25	98 SH A	7000	0.56	1.1	1 x M6	13	1 x M8	24	
28	0.551 - 1.378	0.551 - 1.378	0.846	2.539	1.024 - 1.654	2.638	0.748	0.433	0.925	3.268	1.26	118.01	98 SH A	6000	1.3	1.8	1 x M8	32	1 x M10	45	

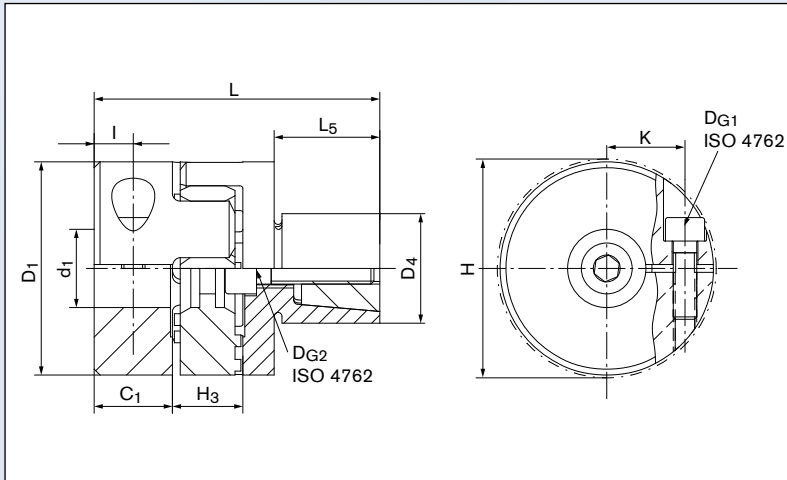
Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.  
 Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Ordering example: GWE 5107

Series Size	Bore diameter $d_1$	Outer diameter of the cone hub $D_4$	Further details*
GWE 5107-24	0.984	1.102	*

\* Keyway

# GERWAH® GWE 5107



Sectional view GWE 5107

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**D<sub>G2</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>  
**T<sub>A2</sub>** = Tightened torque of clamping screw D<sub>G2</sub>

## Transmissible torque T [Nm]

	Size	Ø mm Ø inch														
		4 0.157	5 0.197	6 0.236	8 0.315	10 0.394	12 0.472	14 0.551	15 0.591	18 0.707	20 0.787	25 0.984	26 1.023	28 1.102	30 1.181	35 1.378
	9	1.3	1.5	1.8	2.2	2.2	---	---	---	---	---	---	---	---	---	---
	12	2.1	2.7	3.3	4	4	4	---	---	---	---	---	---	---	---	---
	14	---	7	8	9	9	9	9	10	---	---	---	---	---	---	---
	19	---	---	---	13	13	13	13	13	13	13	---	---	---	---	---
	24	---	---	---	---	32	38	44	44	44	44	44	44	44	44	---
	28	---	---	---	---	---	---	83	89	104	114	118	118	118	118	118

## Characteristics

- Hubs made of aluminum
- Expanding mandrel and inner cone made of steel
- Elastomeric spider sizes 7 and 9 with 92 SH A (yellow spider), optional with through bore hole see page 54/55
- Elastomeric spider sizes 14 and 42 with 98 SH A (red spider), optional with through bore hole see page 54/55
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- For the bore tolerances we recommend fit tolerance H7
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.



## Dimensions

$d_1; d_{2min}$	= Min. bore diameter
$d_1; d_{2max}$	= Max. bore diameter
$d_{1k}; d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}; d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
$C_1$	= Guided length in hub boring $d_1$
$D_1$	= Outer diameter hub
$D_3$	= Outer diameter hub
$H$	= Clearance diameter
$H_3$	= Length of damping part
$I$	= Distance between center screw hole and hub end
$K$	= Distance shaft axis - clamping screw axis
$L$	= Total length
$L_3$	= Section length of hub



## Dimensions

## Technical Data

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway																	
	inch	inch	$C_1$	$D_1$	$D_3$	$H$	$H_3$	$I$	$K$	$L$	$L_3$	T	$H_{es}$	$n_{max}$	J	Gw	$D_{G1}$	$T_{A1}$	
14	0.197 - 0.63	0.197 - 0.63	0.433	1.181	---	1.268	0.512	0.197	0.433	1.378	---	9	98 SH A	13000	0.021	0.09	1 x M3	1.5	
19	0.236 - 0.787	0.236 - 0.787	0.984	1.575	---	1.811	0.63	0.472	0.571	2.598	---	13	98 SH A	10000	0.12	0.35	1 x M6	8	
24	0.394 - 1.26	0.394 - 1.26	1.181	2.165	---	2.244	0.709	0.413	0.787	3.071	---	44	98 SH A	7000	0.51	0.7	1 x M6	11	
28	0.394 - 1.496	0.394 - 1.496	1.378	2.559	---	2.795	0.787	0.453	0.965	3.543	---	118	98 SH A	6000	1.1	1.1	1 x M8	24	
38	0.472 - 1.89	0.472 - 1.89	1.772	3.15	---	3.268	0.945	0.61	1.181	4.488	---	240	98 SH A	5000	3.3	2.1	1 x M8	28	
42	0.551 - 2.126	0.551 - 2.126	1.969	3.74	3.346	3.74	1.024	0.709	1.28	4.961	1.102	332	98 SH A	4000	17	8.4	1 x M10	62	
48	0.591 - 2.362	0.591 - 2.362	2.205	4.134	3.74	4.173	1.102	0.827	1.457	5.512	1.26	387	98 SH A	3600	28	11	1 x M12	107	
55	1.378 - 2.913	1.378 - 2.913	2.559	4.724	---	4.724	1.181	1.024	1.772	6.299	---	505	98 SH A	3150	65	22	1 x M12	107	
65	1.378 - 3.15	1.378 - 3.15	2.953	5.315	---	5.315	1.378	1.102	1.969	7.283	---	693	95 SH A	2800	105	30	1 x M12	107	
75	1.181 - 3.74	1.181 - 3.74	3.346	6.299	---	6.299	1.575	1.417	2.362	8.268	---	1416	95 SH A	2350	228	47	1 x M16	218	

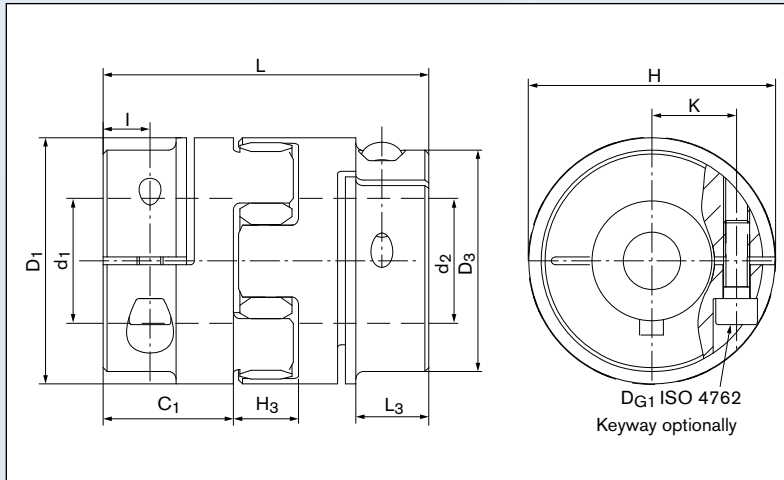
Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings <  $d_{min}$ . Types with borings <  $d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Ordering example: GWE 5104

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWE 5104-42	0.787	0.984	*

\* Keyway

# GERWAH® GWE 5104



Sectional view GWE 5104

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Transmissible torque T [Nm]

	Ø mm Ø inch																					
	Size	5 0.197	6 0.236	8 0.315	10 0.394	12 0.472	14 0.551	16 0.630	20 0.787	25 0.984	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	65 2.560	70 2.756	80 3.150	90 3.543	95 3.740
	14	4	4	6	7	8	9	9	---	---	---	---	---	---	---	---	---	---	---	---	---	---
	19	---	12	13	13	13	13	13	13	---	---	---	---	---	---	---	---	---	---	---	---	---
	24	---	---	---	27	32	37	41	44	44	44	---	---	---	---	---	---	---	---	---	---	---
	28	---	---	---	45	53	61	69	84	102	118	118	---	---	---	---	---	---	---	---	---	---
	38	---	---	---	---	64	74	83	102	124	145	166	185	204	---	---	---	---	---	---	---	---
	42	---	---	---	---	---	128	145	178	218	257	294	332	332	---	---	---	---	---	---	---	---
	48	---	---	---	---	---	---	204	253	313	370	387	387	387	387	387	---	---	---	---	---	---
	55	---	---	---	---	---	---	---	---	---	---	465	505	505	505	505	505	505	505	---	---	---
	65	---	---	---	---	---	---	---	---	---	---	468	527	583	639	693	693	693	693	693	---	---
	75	---	---	---	---	---	---	---	---	---	---	736	830	922	1010	1098	1183	1267	1350	1416	1416	1416

## Characteristics

- Hubs up to size 48 made of aluminum, from size 55 made of steel
- Hubs up to size 19 single slit, from size 24 double slit
- Standard elastomeric spider with 98 SH A (red spider), from size 65 with 95 SH A (yellow spider), optional with through bore hole see page 54/55
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Dimensions

$d_1; d_{2min}$	= Min. bore diameter
$d_1; d_{2max}$	= Max. bore diameter
$d_{1k}; d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}; d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
$C_1$	= Guided length in hub boring $d_1$
$D_1$	= Outer diameter hub
$D_3$	= Outer diameter hub
$H$	= Clearance diameter
$H_3$	= Length of damping part
$I$	= Distance between center screw hole and hub end
$K$	= Distance shaft axis - clamping screw axis
$K_1$	= Clamping length
$L$	= Total length
$L_3$	= Section length of hub



## Dimensions

## Technical Data

Size	$d_1; d_2$ min-max Without keyway	$d_{1k}; d_{2k}$ min-max With keyway																	
	inch	inch	$C_1$	$D_1$	$D_3$	$H$	$H_3$	$I$	$K$	$K_1$	$L$	$L_3$	T	$H_{es}$	$n_{max}$	J	Gw	$D_{G1}$	$T_{A1}$
14	0.197 - 0.63	0.197 - 0.63	0.433	1.181	---	1.28	0.512	0.197	0.433	0.315	1.378	---	9	98 SH A	13000	0.021	0.09	2 x M3	1.5
19	0.236 - 0.787	0.236 - 0.787	0.984	1.575	---	1.811	0.63	0.276	0.571	0.472	2.598	---	13	98 SH A	10000	0.12	0.35	2 x M6	8
24	0.394 - 1.26	0.394 - 1.26	1.181	2.165	---	2.244	0.709	0.413	0.787	0.748	3.071	---	44	98 SH A	7000	0.51	0.67	2 x M8	11
28	0.394 - 1.496	0.394 - 1.496	1.378	2.559	---	2.795	0.787	0.453	0.965	0.846	3.543	---	118	98 SH A	6000	1.1	1.1	2 x M8	24
38	0.472 - 1.89	0.472 - 1.89	1.772	3.15	---	3.268	0.945	0.61	1.181	1.22	4.488	---	240	98 SH A	5000	3.3	2.1	2 x M8	28
42	0.551 - 2.126	0.551 - 2.126	1.969	3.74	3.346	3.74	1.024	0.709	1.28	1.26	4.961	1.102	332	98 SH A	4000	17	8.4	2 x M10	62
48	0.591 - 2.362	0.591 - 2.362	2.205	4.134	3.74	4.173	1.102	0.827	1.417	1.496	5.512	1.26	387	98 SH A	3600	28	11	2 x M12	107
55	1.378 - 2.913	1.378 - 2.913	2.559	4.724	---	4.724	1.181	1.024	1.772	1.831	6.299	---	505	98 SH A	3150	65	22	2 x M12	107
65	1.378 - 3.15	1.378 - 3.15	2.953	5.315	---	5.315	1.378	1.102	1.969	2.047	7.283	---	693	95 SH A	2800	105	30	2 x M12	107
75	1.181 - 3.74	1.181 - 3.74	3.346	6.299	---	6.299	1.575	1.417	2.362	2.579	8.268	---	1416	95 SH A	2350	228	47	2 x M16	218

Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings <  $d_{min}$ . Types with borings <  $d_{min}$ , however, can be supplied.  
Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

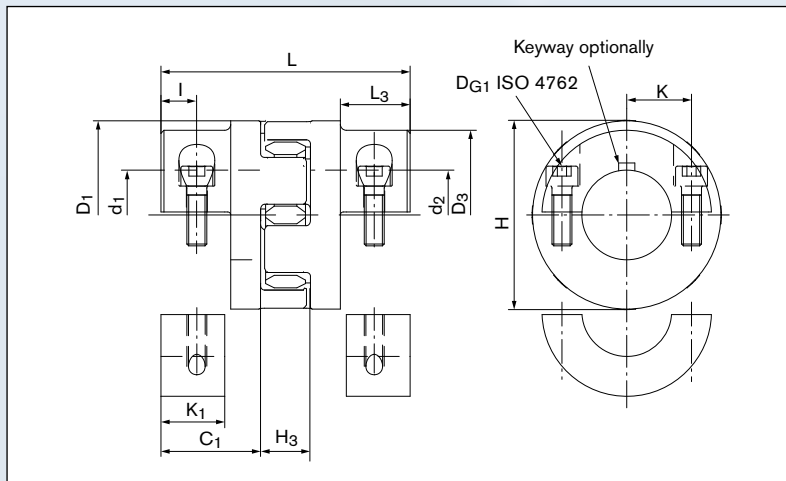
## Ordering example: GWE 5106

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWE 5106-42	1.574	1.732	*

\* Keyway



# GERWAH® GWE 5106



Sectional view GWE 5106

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Transmissible torque T [Nm]

	Ø mm Ø inch																					
	Size	5 0.197	6 0.236	8 0.315	10 0.394	12 0.472	14 0.551	16 0.630	20 0.787	25 0.984	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	65 2.560	70 2.756	80 3.150	90 3.543	95 3.740
	14	2.7	3.2	4	5	6	8	9	---	---	---	---	---	---	---	---	---	---	---	---	---	---
	19	---	9	13	13	13	13	13	13	---	---	---	---	---	---	---	---	---	---	---	---	---
	24	---	---	---	21	25	30	34	42	44	44	---	---	---	---	---	---	---	---	---	---	---
	28	---	---	---	34	41	48	55	68	86	103	119	---	---	---	---	---	---	---	---	---	---
	38	---	---	---	---	49	57	65	81	101	122	142	162	182	---	---	---	---	---	---	---	---
	42	---	---	---	---	---	103	117	146	183	220	256	293	329	---	---	---	---	---	---	---	---
	48	---	---	---	---	---	---	172	215	268	322	376	387	387	387	387	---	---	---	---	---	---
	55	---	---	---	---	---	---	---	---	---	---	376	430	484	505	505	505	505	505	---	---	---
	65	---	---	---	---	---	---	---	---	---	---	376	430	484	537	591	645	693	693	693	---	---
	75	---	---	---	---	---	---	---	---	---	---	578	660	743	825	908	991	1073	1156	1320	1416	1416

## Characteristics

- Hubs up to size 48 made of aluminum, from size 55 made of steel
- Standard elastomeric spider with 98 SH A (red spider), from size 65 with 95 SH A (yellow spider), optional with through bore hole see page 54/55
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Dimensions

$d_1; d_{2min}$  = Min. bore diameter  
 $d_1; d_{2max}$  = Max. bore diameter  
 $C_1$  = Guided length in hub boring  $d_1$   
 $D_1$  = Outer diameter hub  
 $H_3$  = Length of damping part  
 $K_5$  = Width of clamping ring  
 $L$  = Total length



## Dimensions

## Technical Data

Size	$d_1; d_2$ min-max Without keyway	$C_1$	$D_1$	$H_3$	$K_5$	$L$	$T$	$H_{es}$	$n_{max}$	$J$	$G_w$	$D_{G1}$	$T_{A1}$
	inch	inch	inch	inch	inch	inch	ft-lbs		rpm	lbs-in <sup>2</sup>	lbs	mm	ft-lbs
14	0.236 - 0.551	0.728	1.26	0.512	0.315	1.969	9	98 SH A	25400	0.05	0.09	M3	1.3
19	0.315 - 0.787	0.984	1.575	0.63	0.394	2.598	13	98 SH A	19000	0.22	0.35	M4	2.2
24	0.433 - 0.984	1.181	2.165	0.709	0.512	3.071	44	98 SH A	13800	0.9	0.67	M5	4.5
28	0.591 - 1.417	1.378	2.559	0.787	0.63	3.543	118	98 SH A	11700	2.2	1.1	M5	4.5
38	0.787 - 1.614	1.772	3.15	0.945	0.866	4.488	240	98 SH A	9550	6.7	2.1	M6	7.5
42	0.984 - 1.969	1.969	3.74	1.024	0.984	5.276	332	98 SH A	8050	22	8.4	M8	26
48	1.102 - 2.165	2.205	4.134	1.102	1.102	5.512	387	98 SH A	7200	36	11	M10	51

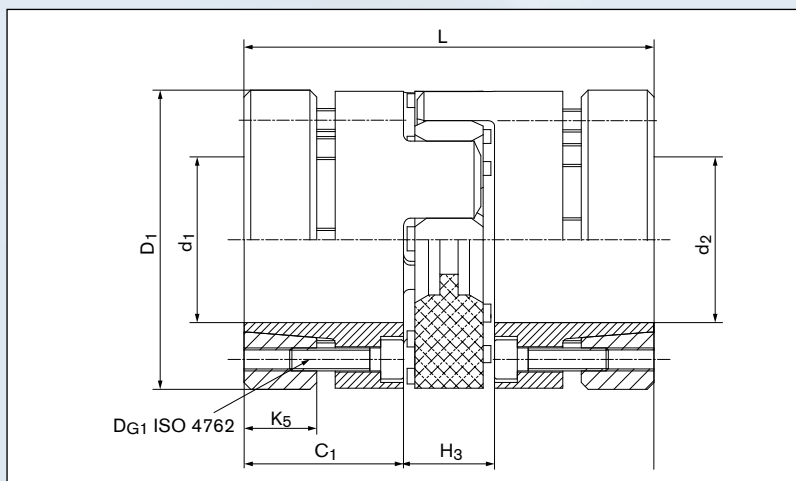
Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied. Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

## Ordering example: GWE 5112

Series Size	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWE 5112-42	1.26	1.614	*

\* Different spider shore hardness

# GERWAH® GWE 5112



Sectional view GWE 5112

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**H<sub>es</sub>** = Hardness of the elastomeric spider  
**n<sub>max</sub>** = Max. rotation speed  
**J** = Total moment of inertia  
**Gw** = Weight  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw  $D_{G1}$

## Transmissible torque T [Nm]

	<div>Ø mm</div> <div>Ø inch</div>																						
	Size	6 0.236	10 0.394	11 0.433	13 0.512	14 0.551	15 0.591	17 0.670	19 0.748	20 0.787	24 0.945	25 0.984	27 1.063	30 1.181	32 1.260	36 1.417	38 1.496	42 1.654	44 1.732	48 1.890	50 1.989	55 2.165	
	14	2.7	7	9	9	9	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	
	19	---	13	13	13	13	13	13	13	13	---	---	---	---	---	---	---	---	---	---	---	---	
	24	---	---	16	27	34	41	44	44	44	44	44	---	---	---	---	---	---	---	---	---	---	
	28	---	---	---	---	---	41	50	84	99	118	118	118	118	118	118	---	---	---	---	---	---	
	38	---	---	---	---	---	---	---	---	99	170	193	240	240	240	240	240	---	---	---	---	---	
	42	---	---	---	---	---	---	---	---	---	---	192	243	332	332	332	332	332	332	332	332	---	
	48	---	---	---	---	---	---	---	---	---	---	---	240	332	387	387	387	387	387	387	387	387	

## Characteristics

- Hubs up to size 38 made of aluminum, from size 42 made of steel
- Clamping bush made of steel
- Standard elastomeric spider with 98 SH A (red spider), optional with through bore hole see page 54/55
- Optimal concentricity
- Easy to install
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.



# Technical Information Servo-Insert Couplings

## Backlash-free Servo-Insert Couplings

### Technical description

The couplings can be fine tuned to the specific application requirements in terms of torsional stiffness and vibration behaviour by selecting from various colour coded elastomeric spiders having different grades of shore hardness.

### Technical terms for the coupling design

#### Pre-Compression:

The elastic pre-compression varies in dependence from the shore hardness of spiders, the size of the coupling and the machining tolerances. From this the axial insertion force results: From light (as a push fit with torsionally soft spider) to heavy (with high pre-compression with torsionally stiff spider).

#### $T_N$ – Nominal torque of coupling (Nm):

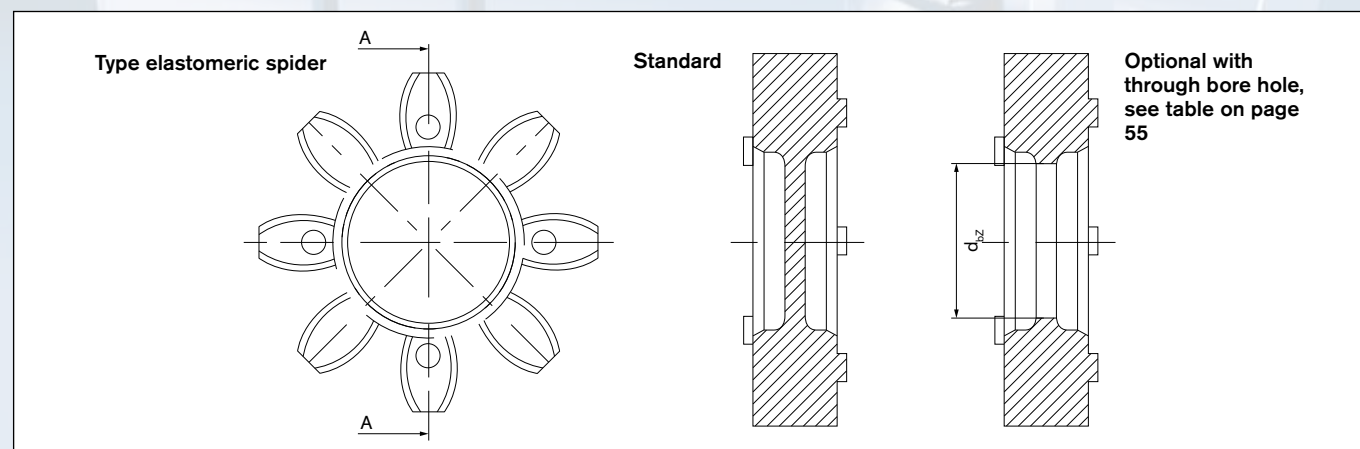
Continuous torque which can be transmitted throughout the entire speed range, taking into consideration operational factors such as ambient temperatures and torsional stiffness.

#### $T_{max}$ – Maximum torque of coupling (Nm):

Torque which can be transmitted  $>10^5$  time as a peak load or  $5 \cdot 10^4$  times as an alternating load during the entire life of the coupling taking into consideration factors such as temperatures, torsional stiffness and shock loading.

Spider Durometer (shore hardness)	Colour	Material	Allowable temperature °F		Available for size	Typical applications
			Continuous temperature	Max. temp. short term		
80 SH A	blue	Polyurethane	-58 to +176	-76 to +248	5-19	Drives in electronic measuring systems; backlash-free when pre-compressed
92 SH A	yellow	Polyurethane	-40 to +194	-58 to +248	5-55	Main spindle drives; backlash-free when pre-compressed
*95/98 SH A	red	Polyurethane	-22 to +194	-40 to +248	5-75	Positioning drives; backlash-free when pre-compressed
64 SH D-H	green	Hytrell	-58 to +248	-76 to +302	7-38	Machine tool spindles, control drives, lead units, planetary gearboxes; heavy loads, torsionally stiff, high ambient temperature, water proof
64 SH D	green	Polyurethane	-4 to +230	-22 to +248	42-75	

\* From size 65  $\pm$  95° A



# Technical Information Servo-Insert Couplings

## Technical Information Spiders

Size	Sh	n <sub>max</sub> (5102)	n <sub>max</sub> (5103)	n <sub>max</sub> (5103.1)	n <sub>max</sub> (5104)	n <sub>max</sub> (5112)	T <sub>N</sub>	T <sub>max</sub>	C <sub>Tstat</sub>	C <sub>Tdyn</sub>	C <sub>r</sub>	d <sub>bZ</sub>	ΔKa	ΔKr	ΔKw
5	80 Sh A	47500	---	38000	---	---	0.22	0.44	2.4	7.4	468	---	0.016/-0.008	0.005	1.1
5	92 Sh A	47500	---	3800	---	---	0.37	0.74	3.8	12	879	---	0.016/-0.008	0.002	1
5	98 Sh A	47500	---	38000	---	---	0.66	1.3	6.1	18	1690	---	0.016/-0.008	0.002	0.9
7	64 Sh D-H	34000	27000	27000	---	---	1.8	3.5	25	76	3597	---	0.024/-0.012	0.002	0.8
7	80 Sh A	34000	27000	27000	---	---	0.5	1.0	6.3	19	651	---	0.024/-0.012	0.006	1.1
7	92 Sh A	34000	27000	27000	---	---	0.9	1.8	11	32	1251	---	0.024/-0.012	0.004	1
7	98 Sh A	34000	27000	27000	---	---	1.5	3.0	17	51	2404	---	0.024/-0.012	0.002	0.9
9	64 Sh D-H	24000	19000	19000	---	---	4.4	8.9	55	165	4391	0.256	0.031/-0.016	0.002	0.8
9	80 Sh A	24000	19000	19000	---	---	1.3	2.7	13	38	714	0.256	0.031/-0.016	0.035	1.1
9	92 Sh A	24000	19000	19000	---	---	2.2	4.4	23	70	1496	0.256	0.031/-0.016	0.005	1
9	98 Sh A	24000	19000	19000	---	---	3.7	7.4	38	114	2958	0.256	0.031/-0.016	0.003	0.9
12	64 Sh D-H	19000	15000	---	---	---	8.9	17.7	242	724	6841	0.295	0.035/-0.016	0.002	0.8
12	80 Sh A/	19000	15000	---	---	---	2.2	4.4	62	186	1565	0.295	0.035/-0.016	0.008	1.1
12	92 Sh A	19000	15000	---	---	---	3.7	7.4	118	355	2684	0.295	0.035/-0.016	0.006	1
12	98 Sh A	19000	15000	---	---	---	6.6	13.3	178	530	4831	0.295	0.035/-0.016	0.003	0.9
14	64 Sh D-H	16000	13000	---	13000	25400	12	24	173	518	4888	0.335	0.039/-0.02	0.002	0.8
14	80 Sh A	16000	13000	---	13000	25400	3.0	5.9	44	133	874	0.335	0.039/-0.02	0.008	1.1
14	92 Sh A	16000	13000	---	13000	25400	5.5	11	85	254	1919	0.335	0.039/-0.02	0.006	1
14	98 Sh A	16000	13000	---	13000	25400	9.2	18	127	378	3734	0.335	0.039/-0.02	0.004	0.9
19	64 Sh D-H	12000	10000	---	10000	19000	15	31	915	2744	16731	0.630	0.047/-0.02	0.002	0.8
19	80 Sh A	12000	10000	---	10000	19000	3.7	7.4	251	760	3323	0.630	0.047/-0.02	0.006	1.1
19	92 Sh A	12000	10000	---	10000	19000	7.4	15	420	1269	6395	0.630	0.047/-0.02	0.004	1
19	98 Sh A	12000	10000	---	10000	19000	12.5	25	634	1903	11477	0.630	0.047/-0.02	0.002	0.9
24	64 Sh D-H	8500	7000	---	7000	13800	55	111	2198	6589	21105	0.945	0.055/-0.02	0.003	0.8
24	92 Sh A	8500	7000	---	7000	13800	26	52	1055	3169	8451	0.945	0.055/-0.02	0.006	1
24	98 Sh A	8500	7000	---	7000	13800	44	89	1519	4565	14618	0.945	0.055/-0.02	0.004	0.9
28	64 Sh D-H	7300	6000	---	6000	11700	148	295	3208	9625	24828	1.063	0.059/-0.028	0.003	0.8
28	92 Sh A	7300	6000	---	6000	11700	70	140	1689	5072	10164	1.063	0.059/-0.028	0.006	1
28	98 Sh A	7300	6000	---	6000	11700	118	236	2537	7607	18273	1.063	0.059/-0.028	0.004	0.9
38	64 Sh D-H	5900	5000	---	5000	9550	299	597	7774	23322	36968	1.378	0.071/-0.028	0.004	0.8
38	92 Sh A	5900	5000	---	5000	9550	140	280	3378	10143	13419	1.378	0.071/-0.028	0.007	1
38	98 Sh A	5900	5000	---	5000	9550	240	479	5281	15847	25125	1.378	0.071/-0.028	0.005	0.9
42	64 Sh D	---	4000	---	4000	8050	413	826	20342	52883	41513	1.654	0.079/-0.039	0.004	0.8
42	92 Sh A	---	4000	---	4000	8050	195	391	4647	17922	13876	1.654	0.079/-0.039	0.007	1
42	98 Sh A	---	4000	---	4000	8050	332	664	14161	35403	33861	1.654	0.079/-0.039	0.006	0.9
48	64 Sh D	---	3600	---	3600	7200	483	966	26700	66750	47246	1.811	0.083/-0.039	0.004	0.8
48	92 Sh A	---	3600	---	3600	7200	229	457	5790	13317	14732	1.811	0.083/-0.039	0.009	1
48	98 Sh A	---	3600	---	3600	7200	387	774	16499	41248	33861	1.811	0.083/-0.039	0.006	0.9
55	64Sh D	---	3150	---	3150	---	608	1217	77983	96032	52808	---	0.087/-0.039	0.005	0.8
55	92Sh A	---	3150	---	3150	---	302	605	11419	15766	17016	---	0.087/-0.039	0.009	1
55	98Sh A	---	3150	---	3150	---	505	1010	31064	45398	38178	---	0.087/-0.039	0.007	0.9
65	64Sh D	---	2800	---	2800	---	867	1217	87410	139540	50649	---	0.1/-0.039	0.005	0.8
65	95Sh A	---	2800	---	2800	---	693	1387	357870	52854	36648	---	0.1/-0.039	0.007	0.9
75	64Sh D	---	2350	---	2350	---	1770	3540	134474	233351	68082	---	0.118/-0.059	0.006	0.8
75	95Sh A	---	2350	---	2350	---	1416	2832	58379	110968	49393	---	0.118/-0.059	0.008	0.9

# ISO Tolerances

## Shafts

Nominal diameter of shaft		d11		e8		e7		f8		f7		g6		h11		h9		h8		h7	
mm		µm		µm		µm		µm		µm		µm		µm		µm		µm		µm	
above	to	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower
3	6	- 30	- 105	- 20	- 38	- 20	- 32	- 10	- 28	- 10	- 22	- 4	- 12	0	- 75	0	- 30	0	- 18	0	- 12
6	10	- 40	- 130	- 25	- 47	- 25	- 40	- 13	- 35	- 13	- 28	- 5	- 14	0	- 90	0	- 36	0	- 22	0	- 15
10	18	- 50	- 160	- 32	- 59	- 32	- 50	- 16	- 43	- 16	- 34	- 6	- 17	0	- 110	0	- 43	0	- 27	0	- 18
18	30	- 65	- 195	- 40	- 73	- 40	- 61	- 20	- 53	- 20	- 42	- 7	- 20	0	- 130	0	- 52	0	- 33	0	- 21
30	50	- 80	- 240	- 50	- 89	- 50	- 75	- 25	- 64	- 25	- 50	- 9	- 25	0	- 160	0	- 62	0	- 39	0	- 25
50	80	- 100	- 290	- 60	- 106	- 60	- 90	- 30	- 76	- 30	- 60	- 10	- 29	0	- 190	0	- 74	0	- 46	0	- 30
80	120	- 120	- 340	- 72	- 126	- 72	- 107	- 36	- 90	- 36	- 71	- 12	- 34	0	- 220	0	- 87	0	- 54	0	- 35
120	180	- 145	- 395	- 85	- 148	- 85	- 125	- 43	- 106	- 43	- 83	- 14	- 39	0	- 250	0	- 100	0	- 63	0	- 40
180	250	- 170	- 460	- 100	- 172	- 100	- 146	- 50	- 122	- 50	- 96	- 15	- 44	0	- 290	0	- 115	0	- 72	0	- 46
250	315	- 190	- 510	- 110	- 191	- 110	- 162	- 56	- 137	- 56	- 108	- 17	- 49	0	- 320	0	- 130	0	- 81	0	- 52
315	400	- 210	- 570	- 125	- 214	- 125	- 182	- 62	- 151	- 62	- 119	- 18	- 54	0	- 360	0	- 140	0	- 89	0	- 57
400	500	- 230	- 630	- 135	- 232	- 135	- 198	- 68	- 165	- 68	- 131	- 20	- 60	0	- 440	0	- 155	0	- 97	0	- 63
500	630	- 260	- 700	- 145	- 255	- 145	- 215	- 76	- 186	- 76	- 146	- 22	- 66	0	- 440	0	- 175	0	- 110	0	- 70
630	800	- 290	- 790	- 160	- 285	- 160	- 240	- 80	- 205	- 80	- 160	- 24	- 74	0	- 500	0	- 200	0	- 125	0	- 80

Nominal diameter of shaft		h6		h5		j6		k6		k5		m6		m5		n6		p6	
mm		µm		µm		µm		µm		µm		µm		µm		µm		µm	
above	to	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower	upper	lower
3	6	0	- 8	0	- 5	+ 7	- 1	-	-	-	-	+ 12	+ 4	+ 9	+ 4	+ 16	+ 8	+ 20	+ 12
6	10	0	- 9	0	- 6	+ 7	- 2	+ 10	+ 1	+ 7	+ 1	+ 15	+ 6	+ 12	+ 6	+ 19	+ 10	+ 24	+ 15
10	18	0	- 11	0	- 8	+ 8	- 3	+ 12	+ 1	+ 9	+ 1	+ 18	+ 7	+ 15	+ 7	+ 23	+ 12	+ 29	+ 18
18	30	0	- 13	0	- 9	+ 9	- 4	+ 15	+ 2	+ 11	+ 2	+ 21	+ 8	+ 17	+ 8	+ 28	+ 15	+ 35	+ 26
30	50	0	- 16	0	- 11	+ 11	- 5	- 18	+ 2	+ 13	+ 2	+ 25	+ 9	+ 20	+ 9	+ 33	+ 17	+ 42	+ 26
50	80	0	- 19	0	- 13	+ 12	- 7	+ 21	+ 2	+ 15	+ 2	+ 30	+ 11	+ 24	+ 11	+ 39	+ 20	+ 51	+ 32
80	120	0	- 22	0	- 15	+ 13	- 9	+ 25	+ 3	+ 18	+ 3	+ 35	+ 13	+ 28	+ 13	+ 45	+ 23	+ 59	+ 37
120	180	0	- 25	0	- 18	+ 14	- 11	+ 28	+ 3	+ 21	+ 3	+ 40	+ 15	+ 33	+ 15	+ 52	+ 27	+ 68	+ 43
180	250	0	- 29	0	- 20	+ 16	- 13	+ 33	+ 4	+ 24	+ 4	+ 46	+ 17	+ 37	+ 17	+ 60	+ 31	+ 79	+ 50
250	315	0	- 32	0	- 23	+ 16	- 16	+ 36	+ 4	+ 27	+ 4	+ 53	+ 20	+ 43	+ 20	+ 66	+ 34	+ 88	+ 56
315	400	0	- 36	0	- 25	+ 18	- 18	+ 40	+ 4	+ 29	+ 4	+ 57	+ 21	+ 46	+ 21	+ 73	+ 37	+ 98	+ 62
400	500	0	- 40	0	- 27	+ 20	- 20	+ 45	+ 5	+ 32	+ 5	+ 63	+ 23	+ 50	+ 23	+ 80	+ 40	+ 108	+ 68
500	630	0	- 44	0	- 28	-	-	+ 44	0	-	-	+ 70	+ 26	-	-	+ 88	+ 44	+ 122	+ 78
630	800	0	- 50	0	- 32	-	-	+ 50	0	-	-	+ 80	+ 30	-	-	+ 100	+ 50	+ 138	+ 88



# Line Shafts Basics

## Backlash-free Line Shafts Series

Torsionally stiff and flexible line shafts are used in applications, where torque and rotational motion combined with the highest possible angular precision should be transmitted or considerable distances between shafts need to be bridged. The application range of line shafts covers almost all technical areas, where mechanical power transmission and stiffness are important:

### Torsionally flexible line shafts with elastomeric spider

- Absolutely backlash-free
- Installation length up to 13.12 ft possible
- Compensation of axial, radial and angular misalignment
- Cost-effective, simple assembly
- Maintenance-free
- Variable length of the intermediate steel or aluminum tube
- Backlash-free elastomeric spider
- Excellent transmission of torque and compensation of misalignment
- High transmission accuracy
- Temperature range -22° F to +248° F

## Torsionally stiff line shafts with metal bellows

- Absolutely backlash-free
- Installation length up to 13.12 ft possible
- Compensation of axial, radial and angular misalignment
- Aluminum lightweight construction up to size 200
- Optional with CFK-tube
- Maintenance-free, no wear
- Cardanical structure
- Special stainless steel bellows
- Excellent power transmission
- High torsional stiffness and misalignment compensation
- Optimal moment of inertia
- Additional balancing holes for better concentricity
- Temperature range -22° F to +212° F
- High precision of rotation angle

## Packaging Machine





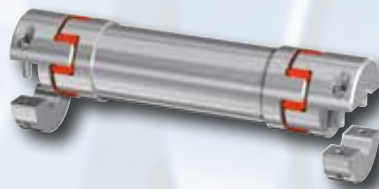
# Overview Line Shafts



GERWAH®  
**GWZ 5104.1**

Servo-insert coupling with clamping hubs

Page 60



GERWAH®  
**GWZ 5106.1**

Servo-insert coupling with clamping hubs in half shell construction

Page 62



GERWAH®  
**GWZ 5116**

Metal bellows coupling with clamping hubs in flange construction

Page 64



GERWAH®  
**GWZ 5106**

Metal bellows coupling with clamping in split hub design

Page 66



## Dimensions

$d_1; d_{2min}$	= Min. bore diameter
$d_1; d_{2max}$	= Max. bore diameter
$d_{1k}; d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}; d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
$C_1$	= Guided length in hub boring $d_1$
$D_1$	= Outer diameter hub
$D_5$	= Tube diameter
$H$	= Clearance diameter
$H_3$	= Length of damping part
$I$	= Distance between center screw hole and hub end
$K$	= Distance shaft axis - clamping screw axis
$K_1$	= Clamping length
$L_1$	= Length of coupling
$L_{3min}$	= Min. length of inside shaft
$L_{3max}$	= Max. length of inside shaft



## Dimensions

Size	$d_1; d_2$ min-max	$d_{1k}; d_{2k}$ min-max											$L_3$ min-max
	Without keyway	With keyway	$C_1$	$D_1$	$D_5$	$H$	$H_3$	$I$	$K$	$K_1$	$L_1$	$L_3$ min-max	
	inch	inch	inch	inch			inch				inch		
14	0.197 - 0.630	0.197 - 0.630	0.433	1.181	0.630	1.244	0.512	0.197	0.433	0.433	1.378	3.150 - 78.740	
19	0.236 - 0.787	0.236 - 0.787	0.984	1.575	0.787	1.811	0.630	0.472	0.571	0.984	2.598	5.315 - 78.740	
24	0.394 - 1.260	0.394 - 1.260	1.181	2.165	0.984	2.244	0.709	0.413	0.787	0.748	3.071	6.299 - 78.740	
28	0.394 - 1.496	0.394 - 1.496	1.378	2.559	1.181	2.795	0.787	0.453	0.965	0.846	3.543	7.283 - 78.740	
38	0.472 - 1.890	0.472 - 1.890	1.772	3.150	1.575	3.268	0.945	0.610	1.181	1.220	4.488	9.055 - 78.740	
42	0.551 - 2.126	0.551 - 2.126	1.969	3.740	1.575	3.740	1.024	0.709	1.280	1.260	4.961	10.039 - 78.740	
48	0.591 - 2.362	0.591 - 2.362	2.205	4.134	1.969	4.114	1.102	0.827	1.417	1.496	5.512	11.417 - 78.740	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.

## Characteristics

- Hubs made of aluminum
- Hubs up to size 19 simple slit, from size 24 double slit
- Precision hollow shaft made of steel
- Standard elastomeric spider with 98 SH A (red spider), optional with through bore hole see page 54/55
- Fail-safe design
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

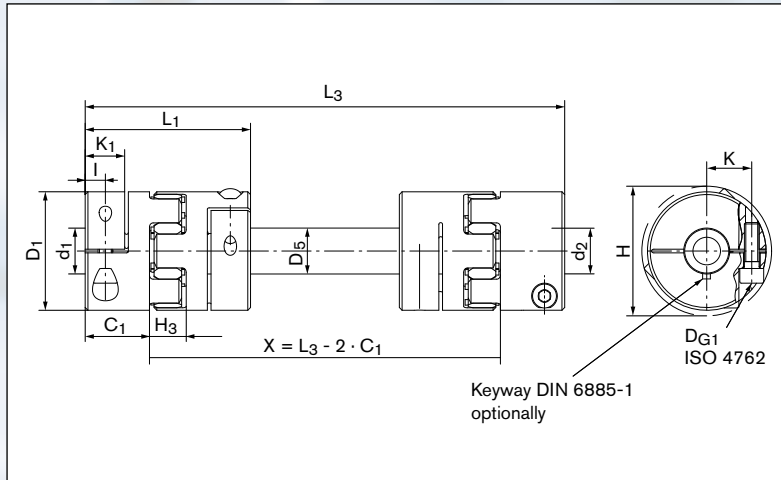
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: GWZ 5104.1

Series Size	Total length $L$	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWZ 5104.1-14	9.843	0.394	0.551	*

\* Keyway

# GERWAH® GWZ 5104.1



Sectional view GWZ 5104.1

## Technical Data

- T** = Transmissible torque at given  $T_A$
- H<sub>es</sub>** = Hardness of the elastomeric spider
- C<sub>m</sub>** = Torsional stiffness of extension tube per meter
- D<sub>G1</sub>** = Thread
- T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Technical Data

	Size	T	H <sub>es</sub>	C <sub>m</sub>	D <sub>G1</sub>	T <sub>A1</sub>
		ft-lbs		ft-lbs/rad	mm	ft-lbs
	14	9	98 SH A	376	1 x M3	1.5
	19	13	98 SH A	712	1 x M6	8
	24	44	98 SH A	1943	1 x M6	11
	28	118	98 SH A	4093	1 x M8	24
	38	240	98 SH A	11410	1 x M8	28
	42	332	98 SH A	11410	1 x M10	62
	48	387	98 SH A	32095	1 x M12	107

## Transmissible torque T [Nm]

Ø mm Ø inch																					
Size	5 0.197	6 0.236	8 0.315	9 0.354	10 0.394	12 0.472	14 0.551	15 0.591	16 0.630	18 0.707	20 0.787	22 0.866	24 0.945	25 0.984	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	58 2.283
14	4	4	6	6	7	8	8	8	8	---	---	---	---	---	---	---	---	---	---	---	---
19	---	12	13	13	13	13	13	13	13	13	13	---	---	---	---	---	---	---	---	---	---
24	---	---	---	---	27	32	37	39	41	44	44	44	44	44	44	---	---	---	---	---	---
28	---	---	---	---	45	53	61	65	69	77	84	91	99	102	118	118	---	---	---	---	---
38	---	---	---	---	---	64	74	79	83	93	102	111	120	124	145	166	185	204	---	---	---
42	---	---	---	---	---	---	128	137	145	162	178	195	210	218	257	294	332	332	---	---	---
48	---	---	---	---	---	---	---	---	204	228	253	277	301	313	370	387	387	387	387	387	387

### Dimensions

$d_1; d_{2min}$	= Min. bore diameter
$d_1; d_{2max}$	= Max. bore diameter
$d_{1k}; d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}; d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
$C_1$	= Guided length in hub boring $d_1$
$D_1$	= Outer diameter hub
$D_5$	= Tube diameter
$H$	= Clearance diameter
$H_3$	= Length of damping part
$I$	= Distance between center screw hole and hub end
$K$	= Distance shaft axis - clamping screw axis
$K_1$	= Clamping length
$L_{3min}$	= Min. length of inside shaft
$L_{3max}$	= Max. length of inside shaft



### Dimensions

Size	$d_1; d_2$ min-max	$d_{1k}; d_{2k}$ min-max										$L_3$ min-max
	Without keyway	With keyway	$C_1$	$D_1$	$D_5$	$H$	$H_3$	$I$	$K$	$K_1$		
	inch	inch	inch	inch	inch						inch	
14	0.197 - 0.630	0.197 - 0.630	0.433	1.181	1.181	1.260	0.512	0.197	0.433	0.354	3.346 - 118.110	
19	0.236 - 0.787	0.236 - 0.787	1.004	1.575	1.575	1.811	0.630	315.000	0.571	0.748	5.748 - 118.110	
24	0.394 - 1.260	0.394 - 1.260	1.181	2.165	1.969	2.244	0.709	0.413	0.787	0.827	7.087 - 118.110	
28	0.394 - 1.496	0.394 - 1.496	1.378	2.559	2.362	2.795	0.787	0.433	0.965	0.925	8.504 - 118.110	
38	0.472 - 1.890	0.472 - 1.890	1.772	3.150	3.150	3.268	0.945	0.610	1.181	1.299	10.472 - 118.110	
42	0.551 - 2.126	0.551 - 2.126	1.969	3.740	3.543	3.740	1.024	0.709	1.280	1.378	11.024 - 118.110	
48	0.591 - 2.362	0.591 - 2.362	2.264	4.134	3.937	4.114	1.102	0.827	1.457	1.614	11.654 - 118.110	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.

### Characteristics

- Hubs made of aluminum
- Standard elastomeric spider with 98 SH A (red spider), optional with through bore hole see page 54/55
- Precision line shaft made of aluminum
- Fail-safe design
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

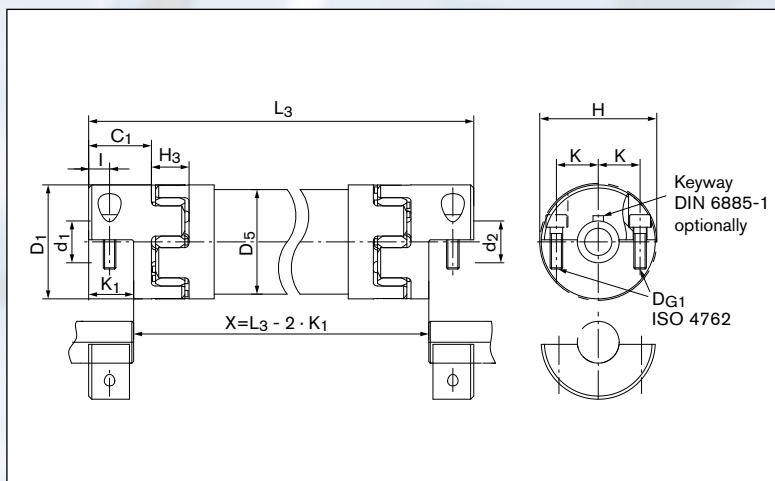
### Ordering example: GWZ 5106.1

Series Size	Total length $L$	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWZ 5106.1-14	7.874	0.394	0.551	*

\* Keyway



# GERWAH® GWZ 5106.1



Sectional view GWZ 5106.1

## Technical Data

- T** = Transmissible torque at given  $T_A$
- H<sub>es</sub>** = Hardness of the elastomeric spider
- C<sub>m</sub>** = Torsional stiffness of extension tube per meter
- D<sub>G1</sub>** = Thread
- T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

## Technical Data

	Size	T	H <sub>es</sub>	C <sub>m</sub>	D <sub>G1</sub>	T <sub>A1</sub>
		ft-lbs		ft-lbs/rad	mm	ft-lbs
	14	9	98 SH A	1126	2 x M3	1.5
	19	13	98 SH A	2393	2 x M6	8
	24	44	98 SH A	4891	2 x M6	11
	28	118	98 SH A	8714	2 x M8	24
	38	240	98 SH A	33138	2 x M8	28
	42	332	98 SH A	55905	2 x M10	62
	48	387	98 SH A	67235	2 x M12	107

## Transmissible torque T [Nm]

Ø mm Ø inch																					
Size	5 0.197	6 0.236	8 0.315	9 0.354	10 0.394	12 0.472	14 0.551	15 0.591	16 0.630	18 0.707	20 0.787	22 0.866	24 0.945	25 0.984	30 1.181	35 1.378	40 1.575	44 1.732	48 1.890	50 1.989	58 2.283
14	3	3	4	5	5	6	8	8	9	---	---	---	---	---	---	---	---	---	---	---	---
19	---	9	13	13	13	13	13	13	13	13	13	---	---	---	---	---	---	---	---	---	---
24	---	---	---	---	21	25	30	32	34	38	42	44	44	44	44	---	---	---	---	---	---
28	---	---	---	---	---	41	48	51	55	61	68	75	82	86	103	119	---	---	---	---	---
38	---	---	---	---	---	49	57	60	65	73	81	89	97	101	122	142	162	182	---	---	---
42	---	---	---	---	---	---	103	110	117	132	146	161	176	183	220	256	293	329	---	---	---
48	---	---	---	---	---	---	---	---	172	193	215	237	258	190	322	376	387	387	387	387	387

## Dimensions

$d_1, d_{2min}$	= Min. bore diameter
$d_1, d_{2max}$	= Max. bore diameter
$d_{1k}, d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}, d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
A	= Max. outer diameter
C	= Pitch circle diameter
$C_1$	= Guided length in hub boring $d_1$
$D_1$	= Outer diameter hub
$D_5$	= Tube diameter
H	= Clearance diameter
I	= Distance between center screw hole and hub end
K	= Distance shaft axis - clamping screw axis
$K_1$	= Clamping length
$L_1$	= Length of coupling
$L_{3min}$	= Min. length of inside shaft
$L_{3max}$	= Max. length of inside shaft
$L_6$	= Length of basic part



## Dimensions

Size	$d_1, d_2$ min-max	$d_{1k}, d_{2k}$ min-max													
	Without keyway	With keyway	A	C	$C_1$	$D_1$	$D_5$	H	I	K	$K_1$	$L_1$	$L_3$ min-max	$L_6$	
	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	inch	
18	0.315 - 0.984	0.315 - 0.866	2.283	1.969	0.768	1.772	1.575	1.890	0.236	0.689	0.027	2.067	5.709 - 118.110	1.732	
30	0.394 - 0.984	0.394 - 0.866	2.756	2.441	0.965	2.165	1.969	2.205	0.315	0.787	0.031	2.067	5.827 - 118.110	1.614	
60	0.472 - 1.378	0.472 - 1.142	3.150	2.835	1.142	2.520	2.362	2.638	0.394	0.945	0.037	2.461	7.165 - 118.110	1.969	
150	0.551 - 1.575	0.551 - 1.417	4.055	3.622	1.299	3.150	3.149	3.307	0.472	1.102	0.042	3.346	9.094 - 118.110	2.244	
200	0.866 - 1.732	0.866 - 1.496	4.409	3.976	1.476	3.543	3.543	3.661	0.512	1.220	0.048	3.110	9.331 - 118.110	2.441	
300	0.945 - 1.890	0.945 - 1.654	5.394	4.803	1.476	4.331	4.252	4.331	0.512	1.535	0.060	3.248	9.606 - 118.110	2.598	
500	1.378 - 2.441	1.378 - 2.126	5.827	5.276	1.614	4.685	4.488	4.803	0.591	1.693	0.067	3.484	10.629 - 118.110	2.756	

Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings <  $d_{min}$ . Types with borings <  $d_{min}$ , however, can be supplied.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- Precision line shaft made of aluminum
- Optional line shaft made of CFK
- Backlash-free and torsionally rigid
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

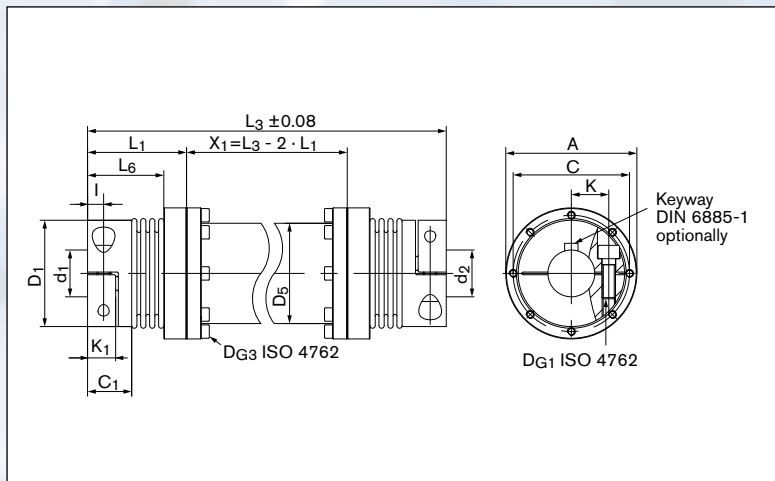
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: GWZ 5116

Series Size	Total length	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWZ 5116 18	19.685	0.394	0.984	*

\* Keyway or stainless steel

# GERWAH® GWZ 5116



Sectional view GWZ 5116

## Technical Data

- T** = Transmissible torque at given  $T_A$
- $C_m$**  = Torsional stiffness of extension tube per meter
- D<sub>G1</sub>** = Thread
- T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>
- D<sub>G3</sub>** = Thread of the flange screws
- T<sub>A3</sub>** = Tightening torque of the flange bolts D<sub>G3</sub>

## Technical Data

Size	T	$C_m$	D <sub>G1</sub>	T <sub>A1</sub>	D <sub>G3</sub>	T <sub>A3</sub>
	ft-lbs	ft-lbs/rad	mm	ft-lbs	mm	ft-lbs
18	22	2392	1 x M5	4	4 x M4	2.2
30	36	4892	1 x M6	9	6 x M4	3.0
60	75	8714	1 x M8	22	6 x M5	5.2
150	180	33138	1 x M10	63	8 x M6	7.0
200	240	55906	1 x M12	74	8 x M6	9.0
300	360	137714	1 x M12	89	8 x M8	22.0
500	600	149876	1 x M14	140	8 x M8	22.0

## Transmissible torque T [Nm]

Ø mm Ø inch																					
Size	8 0.315	9 0.354	10 0.394	11 0.433	12 0.472	13 0.512	15 0.591	16 0.630	18 0.707	20 0.787	22 0.866	25 0.984	28 1.102	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	64 2.520
18	13	15	16	16	16	16	16	16	16	16	16	16		---			---	---	---	---	---
30	---	---	27	27	27	27	27	27	27	27	27	27	27	27	---	---	---	---	---	---	---
60	---	---	---	---	55	55	55	55	55	55	55	55	55	55	55	---	---	---	---	---	---
150	---	---	---	---	---	---	133	133	133	133	133	133	133	133	133	133	---	---	---	---	---
200	---	---	---	---	---	---	---	---	---	---	177	177	177	177	177	177	177	---	---	---	---
300	---	---	---	---	---	---	---	---	---	---	---	266	266	266	266	266	266	266	266	266	---
500	---	---	---	---	---	---	---	---	---	---	---	---	---	---	443	443	443	443	443	443	443



## Dimensions

$d_1; d_{2min}$	= Min. bore diameter
$d_1; d_{2max}$	= Max. bore diameter
$d_{1k}; d_{2kmin}$	= Min. bore diameter with keyway acc. to DIN 6885-1
$d_{1k}; d_{2kmax}$	= Max. bore diameter with keyway acc. to DIN 6885-1
$C_1$	= Guided length in hub boring $d_1$
$D_1$	= Outer diameter hub
$D_5$	= Tube diameter
$H$	= Clearance diameter
$I$	= Distance between center screw hole and hub end
$K$	= Distance shaft axis - clamping screw axis
$K_1$	= Clamping length
$L_{3min}$	= Min. length of inside shaft
$L_{3max}$	= Max. length of inside shaft
$L_6$	= Length of basic part



## Dimensions

Size	$d_1; d_2$ min-max	$d_{1k}; d_{2k}$ min-max										
	Without keyway	With keyway	$C_1$	$D_1$	$D_5$	H	I	K	$K_1$	$L_3$ min-max	$L_6$	
	inch	inch	inch	inch	inch		inch			inch	inch	
18	0.315 - 0.984	0.315 - 0.866	0.787	1.772	1.575	1.870	0.236	0.689	0.433	5.276 - 118.110	2.087	
30	0.394 - 0.984	0.394 - 0.866	0.965	2.165	1.969	2.205	0.315	0.787	0.591	5.236 - 118.110	2.047	
60	0.472 - 1.378	0.472 - 1.142	1.142	2.520	2.362	2.618	0.394	0.925	0.748	6.496 - 118.110	2.520	
150	0.551 - 1.575	0.551 - 1.417	1.299	3.150	3.149	3.268	0.472	1.102	0.827	8.071 - 118.110	2.835	
200	0.866 - 1.732	0.866 - 1.496	1.476	3.543	3.543	3.622	0.512	1.220	0.945	8.583 - 118.110	3.150	
300	0.945 - 1.890	0.945 - 1.654	1.476	4.331	3.937	4.331	0.512	1.535	0.945	8.937 - 118.110	3.268	
500	1.378 - 2.441	1.378 - 2.126	1.614	4.685	4.488	4.803	0.591	1.693	1.083	9.882 - 118.110	3.543	

Transmission of the couplings transmissible torque  $T$  can not longer be guaranteed for certain with borings  $< d_{min}$ . Types with borings  $< d_{min}$ , however, can be supplied.

## Characteristics

- Metal bellows made of stainless steel, hubs made of aluminum
- Precision line shaft made of aluminum
- Optional line shaft made of CFK
- Backlash-free and torsionally rigid
- The shaft tolerance should be within the fit tolerance "g6" or "h7"
- The contact surfaces have to be free from oil and grease

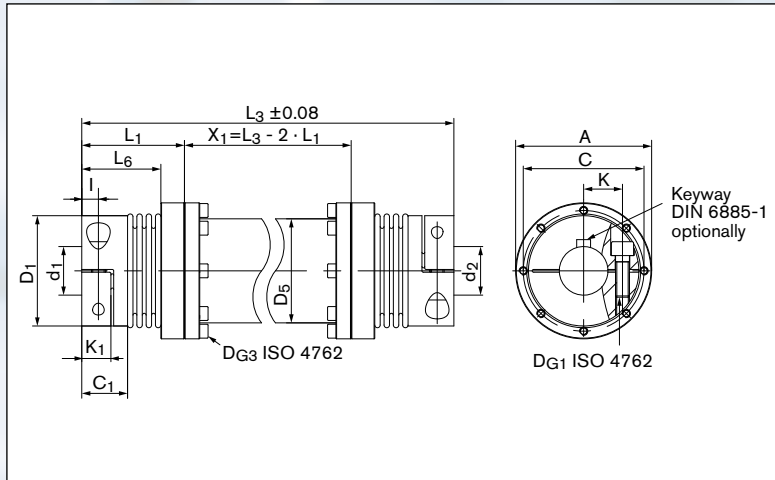
The torque values shown in the technical data tables can only be safely transmitted if all instructions are followed.

## Ordering example: GWZ 5106

Series Size	Total length $L$	Bore diameter $d_1$	Bore diameter $d_2$	Further details*
GWZ 5106 18	19.685	0.394	0.984	*

\* Keyway or stainless steel

# GERWAH® GWZ 5106



Sectional view GWZ 5106

## Technical Data

- T** = Transmissible torque at given  $T_A$   
**C<sub>m</sub>** = Torsional stiffness of extension tube per meter  
 $\Delta K_w$  = Max. permissible angular misalignment  
**D<sub>G1</sub>** = Thread  
**T<sub>A1</sub>** = Tightened torque of clamping screw D<sub>G1</sub>

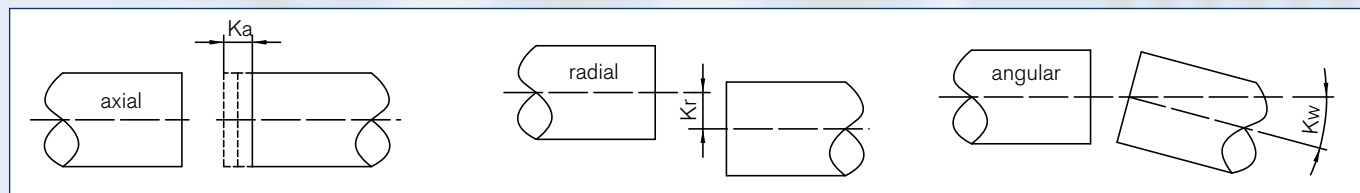
## Technical Data

	Size	T	C <sub>m</sub>	$\Delta K_w$	D <sub>G1</sub>	T <sub>A1</sub>
		ft-lbs	ft-lbs/rad	degree	mm	ft-lbs
	18	16	2393	1	1 x M5	4.4
	30	27	4892	1	1 x M6	9
	60	55	8714	1	1 x M8	22
	150	133	36826	1	1 x M10	63
	200	177	55905	1	1 x M12	74
	300	266	67235	1	1 x M12	89
	500	443	149876	1	1 x M14	140

## Transmissible torque T [Nm]

Ø mm Ø inch																						
Size	8 0.315	9 0.354	10 0.394	11 0.433	12 0.472	14 0.551	15 0.591	18 0.707	20 0.787	22 0.866	Ø24 0.945	25 0.984	28 1.102	30 1.181	35 1.378	40 1.575	45 1.772	50 1.989	55 2.165	60 2.362	64 2.520	
18	10	11	13	14	15	16	16	16	16	16	16	16	---	---	---	---	---	---	---	---	---	
30	---	---	21	22	24	27	27	27	27	27	27	27	27	27	---	---	---	---	---	---	---	
60	---	---	---	---	46	54	55	55	55	55	55	55	55	55	55	---	---	---	---	---	---	
150	---	---	---	---	---	123	133	133	133	133	133	133	133	133	133	133	---	---	---	---	---	
200	---	---	---	---	---	---	---	---	---	177	177	177	177	177	177	177	177	---	---	---	---	
300	---	---	---	---	---	---	---	---	---	---	252	252	252	252	252	252	252	252	252	252	---	
500	---	---	---	---	---	---	---	---	---	---	---	---	---	---	443	443	443	443	443	443	443	

# Backlash-free Metal Bellows Couplings · Mounting Instructions



## Mounting

Clean and degrease shaft ends and bores in hubs and check the tolerances. Insert both shaft ends into the hubs of the metal bellows coupling. Firmly tighten the screws after examining the axial installation dimensions. The tightening torque of the screws and the maximum approved misalignment should not be exceeded (refer to the list of technical data).

## Removal

After loosening the backlash-free shaft hub connections, the drive can be pulled apart and the metal bellows coupling can be removed. Conical bushings of series AK are forced off with a hexagonal socket screw.

## Alignment

If several types of misalignment occur simultaneously, none of them must reach the maximal value but must be adjusted. The sum of all actual misalignments must not exceed 100% (percentage of the maximum value). The diagram shows how to adjust. The more precise the alignment, the more reserves are available to handle additional misalignments during the operation. This will have an advantageous effect on the durability, quietness and the accuracy of transmission.

**Please ask for our detailed mounting instructions.**

## Design example

### Application:

A bellows coupling CKN 80/2.441 has to be installed. The following misalignment values result from the installation situation:

$\Delta K_r = 0.00394$  mm

$\Delta K_a = 0.00394$  mm

$\Delta K_w = 0.2^\circ$

Are the misalignment values for the CKN 80/2.441 acceptable?

### Selection:

The tolerable misalignment values are: (cp. data sheet Series CKN):

$\Delta K_r = 0.008$  in

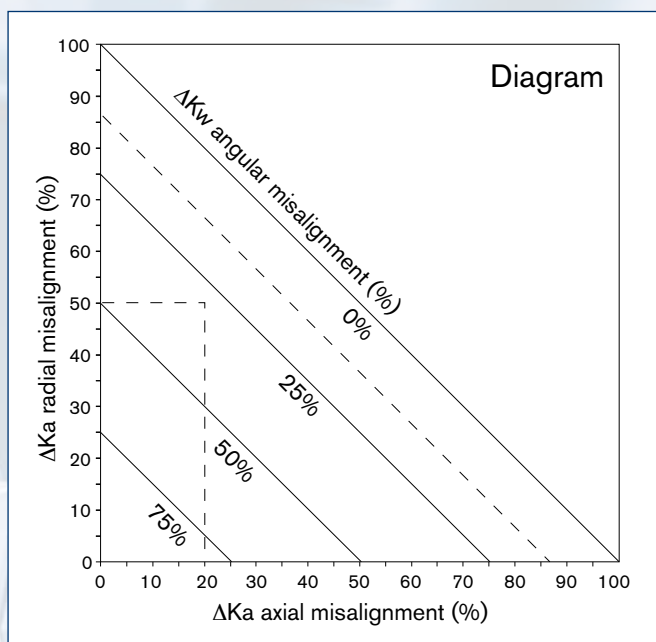
$\Delta K_a = 0.02$  in

$\Delta K_w = 1.5^\circ$

The reached radial misalignment  $\Delta K_r = 0.00394$  in corresponds to 50% of the max. tolerable value.

The value  $\Delta K_a = 0.00394$  in corresponds to 20% of the max. tolerable axial misalignment.

The angular misalignment with  $\Delta K_w = 0.2^\circ$  corresponds to 13% of the overall view.



### Interpretation by means of the diagram:

Enter the calculated values in the diagram on the right side (dashed line). The combination of the different misalignment values is within the tolerable area.

### Interpretation by means of the empirical formula:

$50\% + 20\% + 13\% < 100\%$

The coupling can be installed.

**Empirical formula:** 
$$\frac{\text{(Installation situation)}}{\text{(Data sheet)}} \cdot \frac{\Delta K_r}{\Delta K_r} \cdot 100\% + \frac{\Delta K_a}{\Delta K_a} \cdot 100\% + \frac{\Delta K_w}{\Delta K_w} \cdot 100\% < 100\%$$



# Backlash-free Servo-Insert Couplings · Mounting Instructions

## Mounting

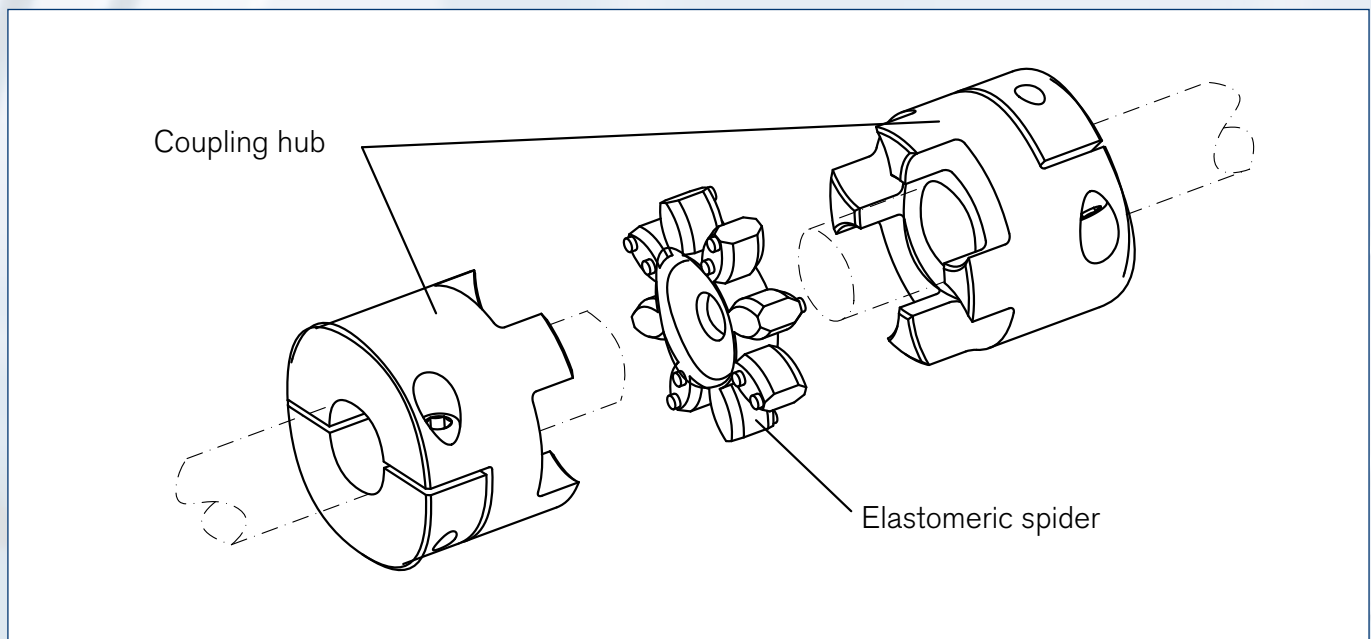
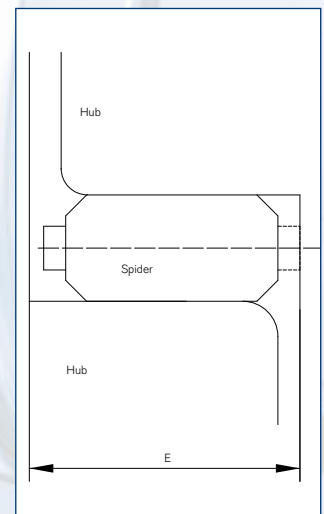
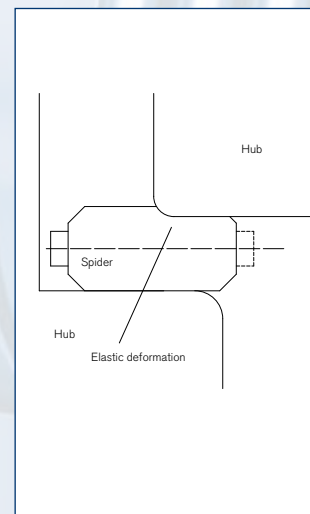
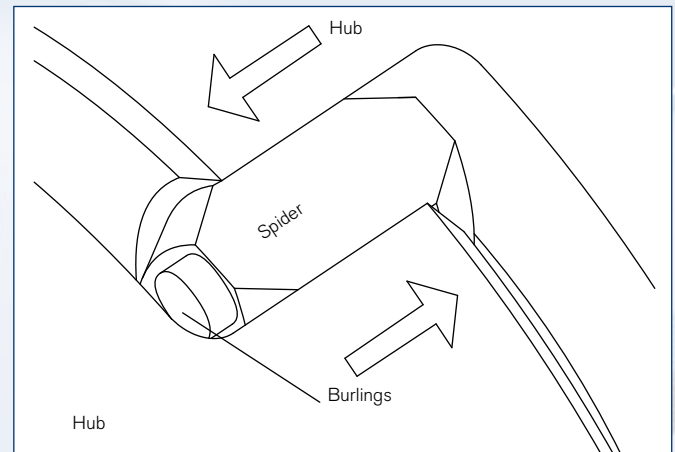
Clean and degrease both shaft surface and hub bores. The shaft tolerance should be within the fit tolerance "g6" or "h7".

Slide a coupling hub onto each shaft end and tighten the screws after checking the axial dimensions. Refer to the list of technical data to get the correct tightening torque for the screws.

Firmly press the elastomeric spider into one of the two hubs. A PU compatible grease such as Vaseline may be applied to ease assembly. The edges of the spider and the jaws of the coupling hubs are both chamfered for an easier or – if applicable – blind assembly. The burlings sidewise alternate on the edges, ease the assembly and prevent from an too tight installation. Now push in the second hub. Always keep within the clearance, so that the elastomeric spider will not be tensed up axial. Therefore a longer durability and electrical isolation will be guaranteed.

### IMPORTANT: For application with high dynamics

For application with high dynamics (frequent acceleration and reversion of rotating) or high impact load (applications like presses and shredders) we recommend to use the support of the Engineering-Team in doing the dimensioning and choosing the appropriated coupling.

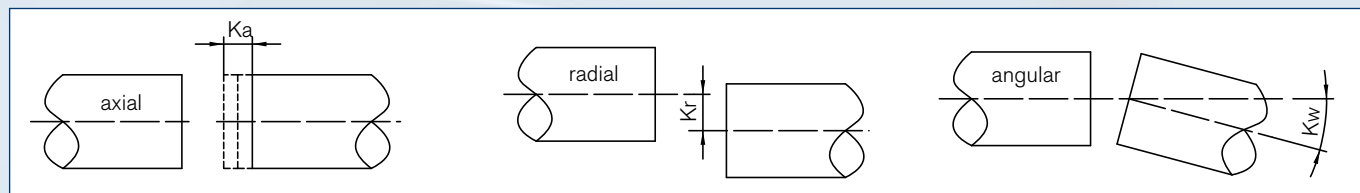
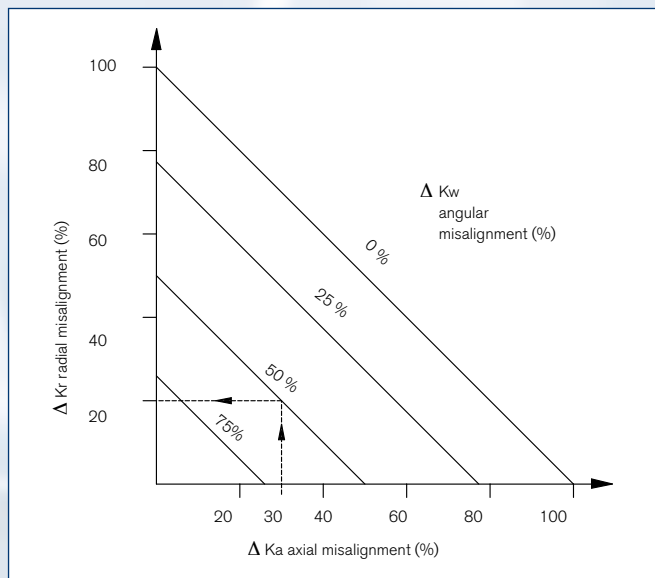


# Backlash-free Servo-Insert Couplings · Mounting Instructions

## Alignment

The picture above shows the three types of misalignment. The mounted coupling needs to be aligned. The more accurate the initial alignment, the better the coupling can absorb additional misalignments during operation. Durability and quietness are favourably influenced. If all three types of misalignment occur simultaneously, each type must not reach the maximum allowable value, but has to be adjusted.

The total amount of the actual misalignment types, expressed as a percentage of the maximum allowable value, must not exceed 100%. The diagram on the right side shows such an adjustment.

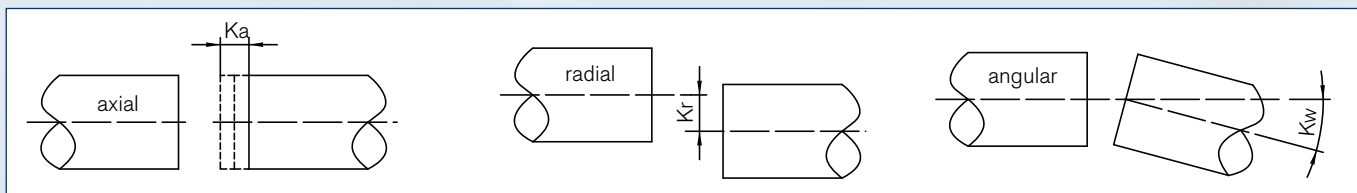


## Removal

Remove the fastening screws, e.g. on the motor. Pull the drive unit, including the Servo-Insert Coupling apart. A new spider or a spider with a different shore hardness can now be installed. After loosening the backlash-free shaft-hub-connection the hubs can be disassembled.

**Please ask for a detailed instruction sheet.**

# GERWAH Line Shafts · Mounting Instructions



## Alignment of the shafts:

The picture shows the several types of misalignment. It is necessary to adjust the shafts before assembly. The more accurate the initial alignment, the better the shaft can absorb additional misalignments during operation. Durability of the line shafts and quietness of the drive are favourably influenced.

In case all three types of misalignment occur simultaneously, each type must not reach the maximum allowable value, but have to be aligned.

## Mounting:

Slide the clamping hubs on the clean and degreased shafts (or fit it when half-shell variant).

After checking the axial dimensions tighten the screws according to the technical data (Ma) for wrench torque listed in the catalogue.

The dimension on the shaft distance X (see technical drawing) should be kept.

## Removal:

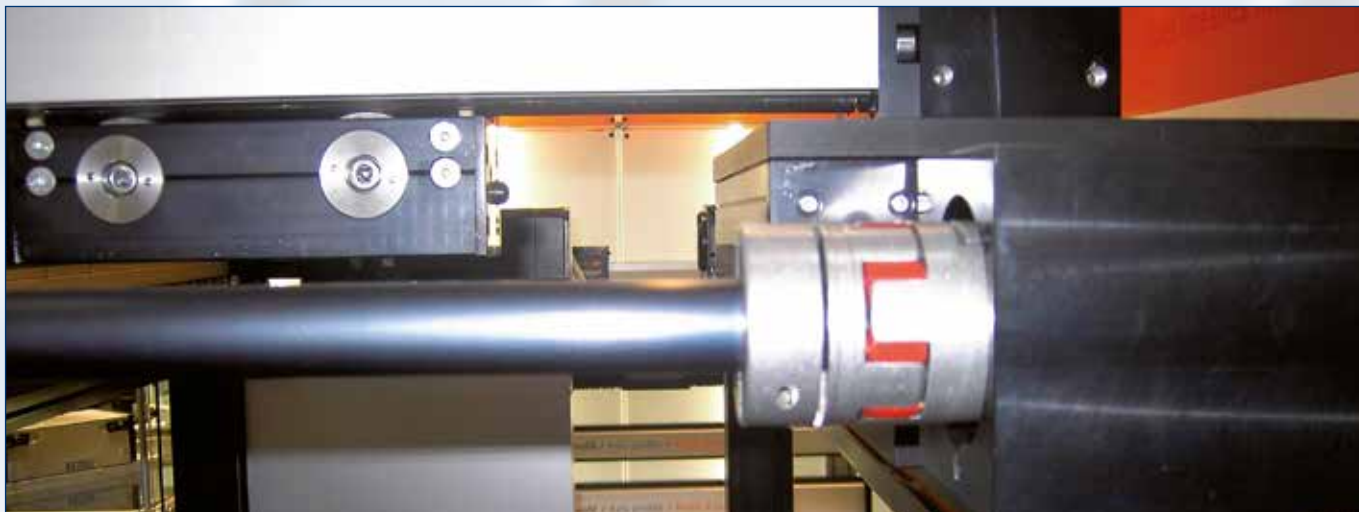
Remove the locking screws of the hubs. Line Shafts in split hub designs GWZ 5106 and GWZ 5106.1 lift up. For an easy removing of the GWZ 5116 intermediate pipe, shift the unfastened clamping hubs outwards (on GWZ 5104.1 to the center).

**Please ask for detailed mounting instructions or find information on [www.ringfeder.com](http://www.ringfeder.com)!**

## Misalignments Servo-Insert Line Shafts

Size	Shifting		
	mm radial* $\Delta Kr$	mm axial $\Delta Ka$	Degree angular $\Delta Kw$
14	0,197 in	$\pm 0,039$ in	1,5°
19	0,197 in	$\pm 0,039$ in	1,5°
24	0,197 in	$\pm 0,039$ in	1,5°
28	0,197 in	$\pm 0,039$ in	1,5°
38	0,197 in	$\pm 0,039$ in	1,5°
42	0,197 in	$\pm 0,039$ in	1,5°
48	0,197 in	$\pm 0,039$ in	1,5°

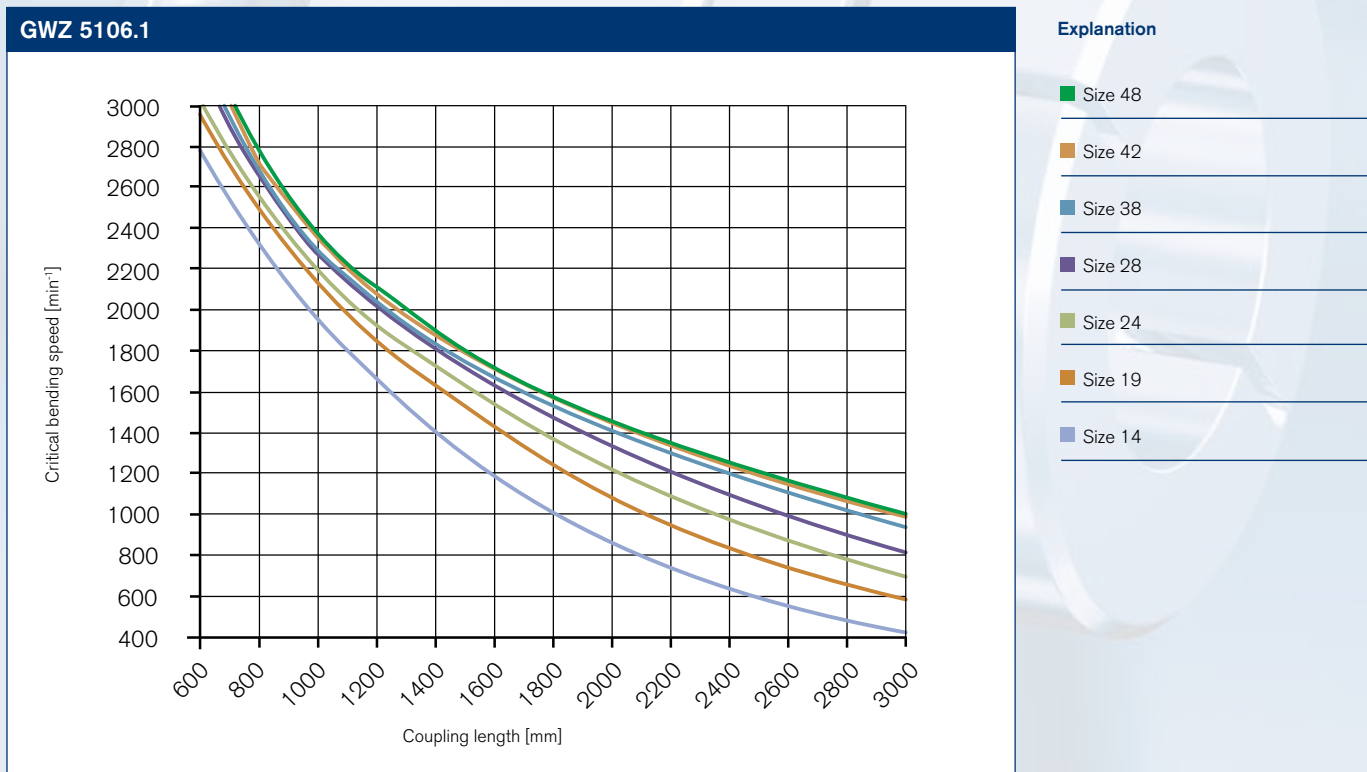
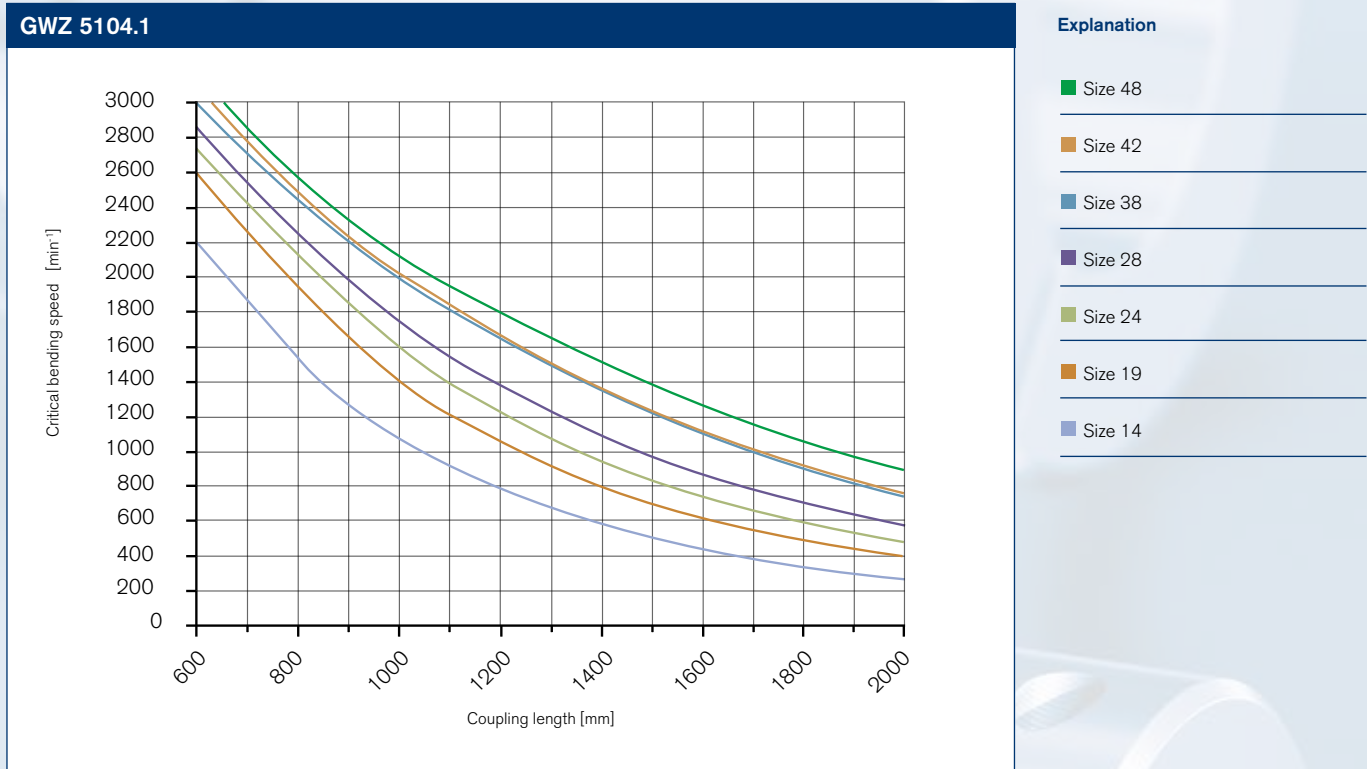
\*Radial/parallel misalignment depends on the length of the tube.





# Critical bending speed

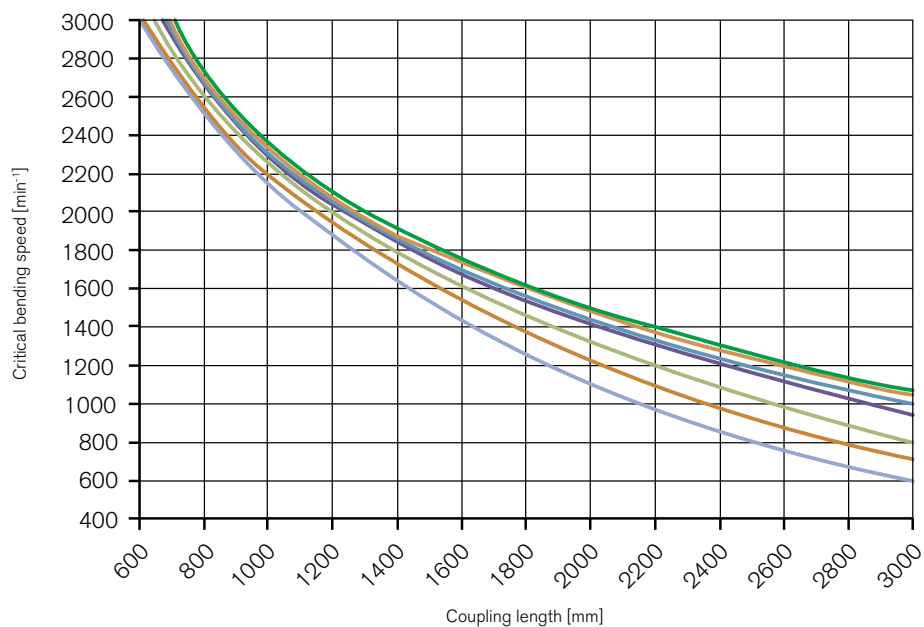
Critical bending speed for line shafts (operating speed = critical bending speed / 1,4)



# Critical bending speed

Critical bending speed for line shafts (operating speed = critical bending speed / 1,4)

GWZ 5106



## Explanation

Size 48

Size 42

Size 38

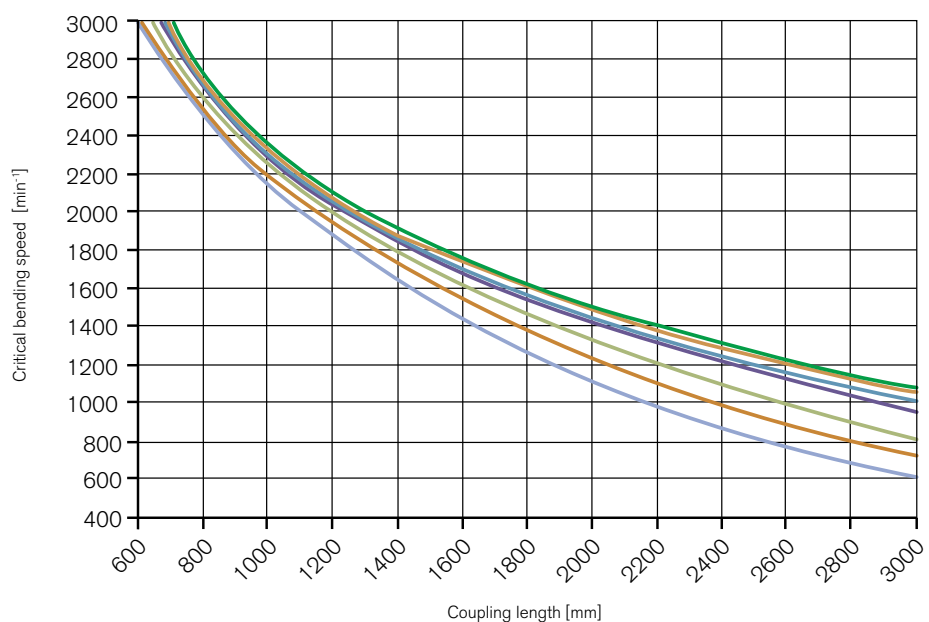
Size 28

Size 24

Size 19

Size 14

GWZ 5116



## Explanation

Size 48

Size 42

Size 38

Size 28

Size 24

Size 19

Size 14

# Fax Inquiry Couplings

On this page please explain the planned application of a GERWAH® coupling and we will propose our solution. Please send this page to:

**RINGFEDER POWER TRANSMISSION USA CORPORATION**

**FAX: +1 201 664 6053**

## 1. Application

Planned use of the coupling (machine, machine group or plant):

## 2. Type of attachment (please tick/check)

- |                                       |                                     |  |  |
|---------------------------------------|-------------------------------------|--|--|
| <input type="checkbox"/> Clamping hub | <input type="checkbox"/> Cone hub   | <input type="checkbox"/> Expanding hub | <input type="checkbox"/> Hub with set screw    |
| <input type="checkbox"/> Flange mount | <input type="checkbox"/> Outer cone | <input type="checkbox"/> Fanuc         | <input type="checkbox"/> Acc. customer request |

## 3. Dimensions

- |  |   |                             |
|--|---|-----------------------------|
| <input type="text"/> Length (Inches)         | <input type="text"/> Bore D <sub>1</sub> (Inches) | <input type="text"/> Keyway |
| <input type="text"/> Outer diameter (Inches) | <input type="text"/> Bore D <sub>2</sub> (Inches) | <input type="text"/> Keyway |

## 4. Shaft misalignment

- |                                     |                                      |                                       |
|-------------------------------------|--------------------------------------|---------------------------------------|
| <input type="text"/> Axial (Inches) | <input type="text"/> Radial (Inches) | <input type="text"/> Angular (Degree) |
|-------------------------------------|--------------------------------------|---------------------------------------|

## 5. Drive

- |             |  |                             |   |
|-------------|--|-----------------------------|---|
| Drive power | <b>P =</b> <input type="text"/> <b>HP</b>  | Nominal torque of the drive | <b>Mt<sub>nom</sub> =</b> <input type="text"/> <b>lb-in</b> |
| Input speed | <b>n =</b> <input type="text"/> <b>rpm</b> | Peak torque of the drive    | <b>Mt<sub>max</sub> =</b> <input type="text"/> <b>lb-in</b> |

## 6. Mass moment of inertia

- |                   |  |                    |  |
|-------------------|--|--------------------|--|
| On the drive side | <b>J<sub>A</sub> =</b> <input type="text"/> <b>lb-in<sup>2</sup></b> | On the driven side | <b>J<sub>L</sub> =</b> <input type="text"/> <b>lb-in<sup>2</sup></b> |
|-------------------|--|--------------------|--|

## 7. Environmental influences

- |   |  |  |                                 |                                |
|---|--|--|---------------------------------|--------------------------------|
| Temperature in the area of the coupling | <b>Temp =</b> <input type="text"/> <b>°F</b> | Special materials (e.g. stainless steel) | <input type="text"/>            |                                |
| Are there any impacts on the load side? | <input type="checkbox"/> No                  | <input type="checkbox"/> Slight          | <input type="checkbox"/> Medium | <input type="checkbox"/> Heavy |
| Other, special influences               | <input type="text"/>                         |  |                                 |                                |

## 8. Estimated demand

## 9. Target price

- |                                 |                                  |                                 |   |                                     |
|---------------------------------|----------------------------------|---------------------------------|---|-------------------------------------|
| <input type="checkbox"/> Series | <input type="checkbox"/> Project | <input type="checkbox"/> Repair | <input type="checkbox"/> Number of items/p.a. | <input type="text"/> <b>\$/Each</b> |
|---------------------------------|----------------------------------|---------------------------------|---|-------------------------------------|

Please send your offer to:

- |         |                      |           |                      |
|---------|----------------------|-----------|----------------------|
| Company | <input type="text"/> | Attention | <input type="text"/> |
| Address | <input type="text"/> |           |                      |
| Phone   | <input type="text"/> | Fax       | <input type="text"/> |
| E-mail  | <input type="text"/> |           |                      |



# Fax Inquiry Line Shafts

On this page please explain the planned application of a GERWAH® line shaft and we will propose our solution. Please send this page to:

**RINGFEDER POWER TRANSMISSION USA CORPORATION**

**FAX: +1 201 664 6053**

## 1. Application

Planned use of the coupling (machine, machine group or plant):

## 2. Type of attachment (please tick/check)

- ☐ Clamping hub ☐ Cone hub ☐ Flange mount ☐ Hub with half-shell  
☐ Outer cone ☐ Acc. customer request

## 3. Dimensions

Total length (Inches)  Bore D<sub>1</sub> (Inches)  Keyway  
 Dimension shafts distance (Inches)  Bore D<sub>2</sub> (Inches)  Keyway

## 4. Shaft misalignment

Axial (Inches)  Radial (Inches)  Angular (Degree)

## 5. Drive

Drive power  $P =$   HP Nominal torque of the drive  $Mt_{nom} =$   lb-in  
Input speed  $n =$   rpm Peak torque of the drive  $Mt_{max} =$   lb-in

## 6. Mass moment of inertia

On the drive side  $J_A =$   lb-in<sup>2</sup> On the driven side  $J_L =$   lb-in<sup>2</sup>

## 7. Environmental influences

Temperature in the area of the coupling  $Temp =$   °F Special materials (e.g. stainless steel)

Are there any impacts on the load side? ☐ No ☐ Slight ☐ Medium ☐ Heavy

Other, special influences

## 8. Estimated demand

## 9. Target price

☐ Series ☐ Project ☐ Repair ☐ Number of items/p.a.  \$/Each

Please send your offer to:

Company  Attention   
Address   
Phone  Fax   
E-mail

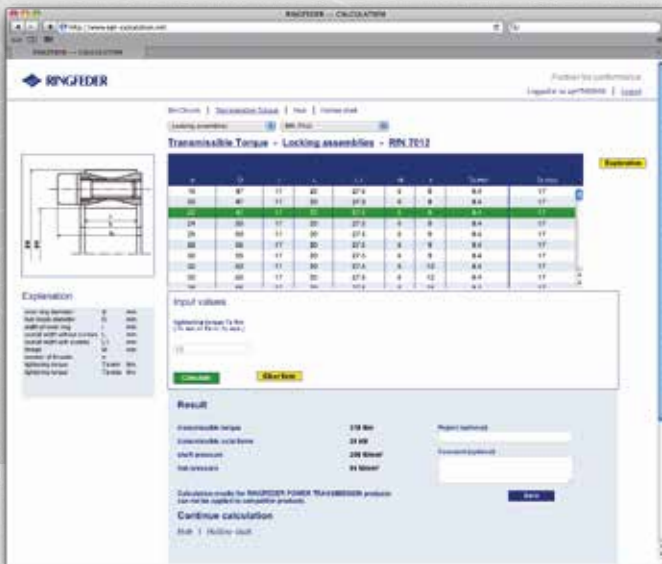
## Calculation program for Locking Assemblies and Locking Elements

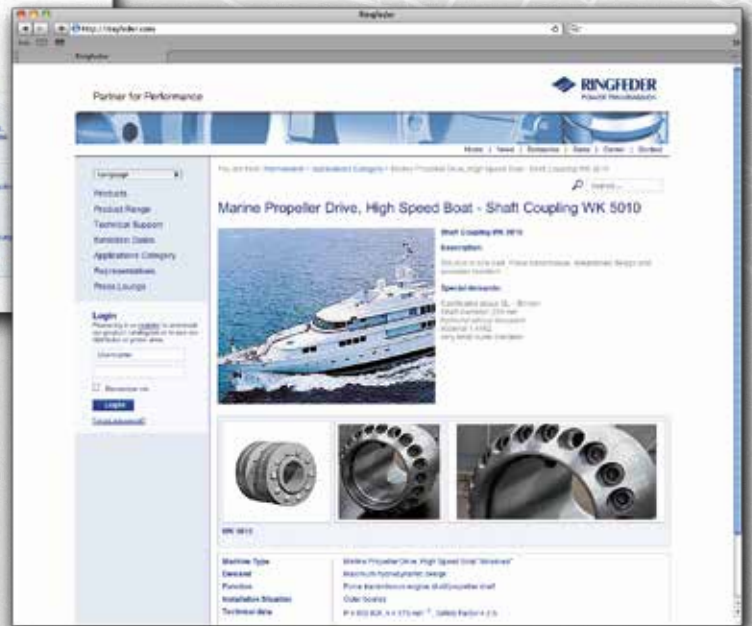
In order to meet the complex requirements on the correct design and selection of RINGFEDER products under practise-relevant demands, RINGFEDER POWER TRANSMISSION has developed a calculation program.

This calculation program offers the engineer a valuable aid in his or her daily work and simplifies the calculation of a wide range of tasks.

Once a product and the desired product size have been selected the program carries out the calculation, taking into account additional user input e.g. **transmissible torque and axial forces, resulting hub and shaft pressure, the outer diameter of the hub, the inner diameter of the hollow shaft** and for special tasks even the **forces and loads under bending moment loads**.

Interested? Visit our Website at [www.ringfeder.com!](http://www.ringfeder.com!)





## Our Website

### Easily accessible information.

RINGFEDER POWER TRANSMISSION – one of the top addresses for drive and damping technology in mechanical engineering. You can find first-hand service details and information on our website. It contains both details on our entire range

of products and numerous documents such as product catalogues, data sheets and assembly instruction for you to download.

Visit **www.ringfeder.com** to get right up to date.



Download area Product Range and catalogues



Available Instructions for Installation, Removal and Maintaining





Locking Devices



Locking Assemblies



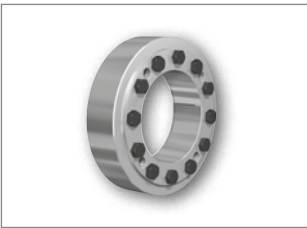
Locking Assemblies for bending moments



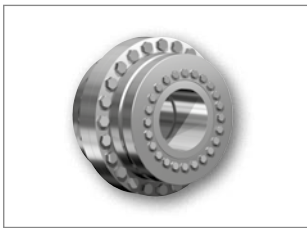
Locking Assemblies – Stainless steel



Locking Elements



Shrink Discs



Flange Couplings

Damping Technology



Friction Springs



DEFORM plus®



DEFORM plus® R



Couplings



Torsionally Flexible Couplings



Torsionally Flexible Couplings



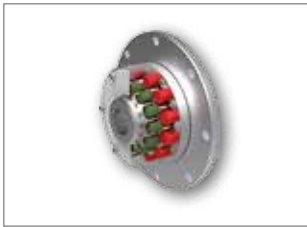
Torsionally Flexible Couplings



Torsionally Rigid Gear Couplings



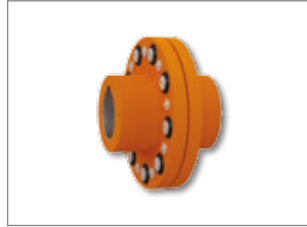
Torsionally Rigid Barrel Coupling



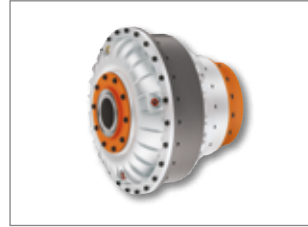
Couplings with variable Stiffness



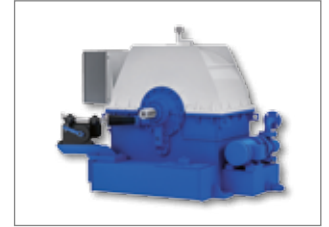
## Couplings



Flexible Couplings Henflex

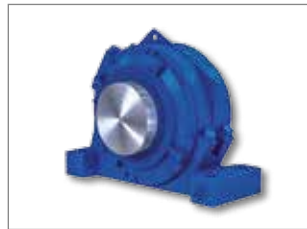


Hydrodynamic Couplings Henfluid



Hydrodynamic Couplings with variable speed

## Bearing Housings



Bearing Housings

### Remark:

HENFEL products are only available in South America and selected markets.



## Couplings



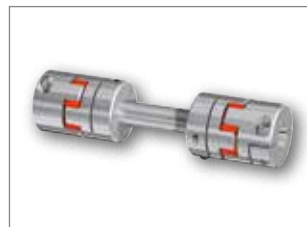
Metal Bellows Couplings



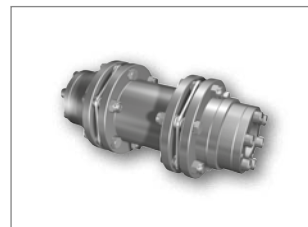
Servo-Insert Couplings



Safety Couplings



Line Shafts



Torsionally Rigid Disc Couplings



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