Compax3

C3S - Low to Medium Power
C3H - High Power
C3M - Multi-Axis

Compact, Intelligent and Powerful Industrial Servo Drives & Drive/Controllers

With its high-performance and modular design, the Compax3 family of industrial servo drives and drive/controllers offers a new level of servo performance and flexibility. The modular structure of the Compax3 family allows options such as intelligent motion controllers, fieldbus interfaces and industry standard motor feedback. In addition, numerous expansion options can be added to the standard product in order to optimize the capabilities required for today's demanding servo applications. The family is offered in two variations: standalone (C3S and C3H) and a DC bussed multi-axis version (C3M). Both have all the same options and performance.

Compax3 Features

- Available in both 120/240 VAC and 480 VAC input versions
- Integrated safety: EN954-1 Category 3 technology

- Current output from 2.5 A (rms) continuous to 155 A (rms) continuous
- Resolver, encoder, high-resolution SinCos® or Stegmann Absolute rotary encoder feedback (single- or multi-turn) or Heidenhain Endat 2.1
- Internal regeneration circuitry; external resistor connections for additional power dissipation
- Easy-to-use wizards-based configuration and programming via C3 ServoManager™ software package
- Full diagnostic, tuning and 4-channel oscilloscope tools provided in the standard C3 ServoManager™ software
- Software input simulation
- Auto-load identification (auto-tuning)
- CE (EMC & LVD), UL and cUL recognized

T10 Features

- Base servo drive
- ±10 V analog
- Step and direction
- Torque/velocity control
- Position control
- Encoder tracking

T11 Features

- Servo positioning drive
- Up to 31 stored profiles
- Profile select via digtial inputs
- Multi-profile sequences
- Multiple homing routines
- Profibus
- CANopen
- DeviceNet
- ETHERNET Powerlink

T30 Features

- Full-featured programmable drive/controller
- IEC61131-3 programming flexibility
- PLCopen, Parker motion function blocks
- Complex motion
- Profibus
- CANopen
- DeviceNet
- ETHERNET Powerlink

T40 Features

- T30 programming capability
- Electronic cam control
- Superimpose motion
- Electronic gearing
- Position capture
- Profibus
- CANopen
- DeviceNet
- HEDA
- ETHERNET Powerlink

Parker Automation

Compax3 T10
Basic Drive

The Compax3 T10 technology level is a compact industrial digital servo drive available in 16 power levels producing up to 155 A (rms) continuous current and covering a broad range of input voltages. The T10 is the base Compax3 drive model and is designed for use with an external motion controller in centralized motion control systems.

Compax3 T10 drives are well-suited for combining with Parker's ACR or 6K motion controller products and together create a formidable multi-axis servo system. Parker also offers pre-made analog command cables for quick and efficient connectivity between any T10 drive and ACR or 6K controller.

The Compax3 T10 accepts both ±10 V analog command signals and step-and-direction command signals for operating as a torque, velocity or position control drive.

Compax3 products are easily configurable via RS232/485 using Parker's C3 ServoManager™ software running on a PC or by utilizing the optional BDM keypad interface module. Using the C3 ServoManager software could not be easier. All setup is accomplished via intuitive drive configuration wizards and basic application information. Commissioning is even faster with the addition of software input simulation and auto-tuning.

Compax3 T10 Features

- 120 - 480 VAC power input range
- Continuous current output from 2.5 A (rms) to 155 A (rms)
- Resolver, encoder or high-resolution SinCos® Hiperface™ and Endat 2.1 feedback
- ±10 V analog command signals
- 5V/24V step-and-direction command signals
- Torque, velocity or position control modes
- Encoder tracking capability
- CE (EMC & LVD), UL and cUL

Compax3 T10 Accessories

- Refer to the Compax3 Accessories section listed on page 15 of this catalog

Shown: Parker's ACR9000 multi-axis controller with Compax3 I10 T10 drives using ±10VDC command voltage

C3/ACR Analog Command Cable

71-021108-04

I10 T10   I10 T10   I10 T10   I10 T10

Parker Automation
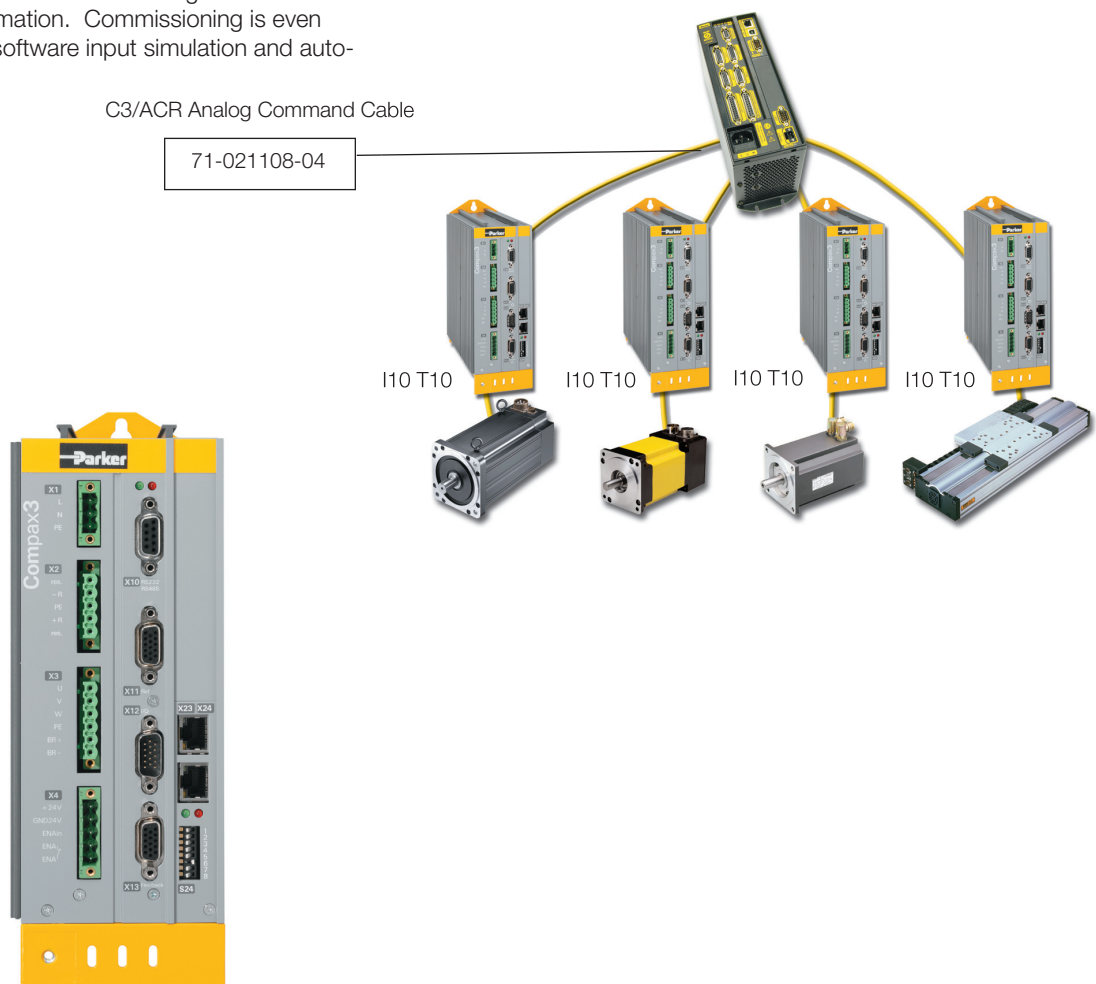
Compax3 T11
Servo Positioning Drive

The Compax3 T11 technology level intergrates simple position control capabilities into the standard Compax3 drive. The I11 T11 is a basic positioning drive capable of retaining up to 31 motion profiles in memory. Individual motion profiles are assigned a binary input mask and are triggered when the appropriate input pattern is set or via internal control bit manipulation from the optional fieldbus interfaces. Acceleration, deceleration, target speed, and target position are all user-configurable for each profile by entering values into a software table.

For more diverse applications, the Compax3 I12 T11 offers all the capabilities of the I11 T11, but also includes functionality such as electronic gearing and registration-based moves – all selectable via onboard I/O or serial interface (RS232/RS485). The I12 T11 also is compatible with Parker's HEDA high-speed following bus option.

Compax3 products are easily configurable via RS232/485 using Parker's C3 ServoManager™ PC software. All setup is accomplished via intuitive drive configuration wizards and basic application information. Commissioning is even faster with the addition of software input simulation and auto-tuning. If desired, customers can also copy existing T11 configuration files to/from other T11 units – without the need for a PC – using the optional BDM01/01 keypad interface module.

Although the Compax3 T11 uses standard resolver feedback, it can also be equipped with quadrature encoder or high-resolution Stegmann or SinCos® Hiperface™ encoders with multi-turn absolute feedback capability. The latest addition has Endat 2.1 support

Available with ETHERNET Powerlink
- Use in conjunction with ACR9040 as motion bus
- Use for TCP/IP communication
- Use with other EPL master units.

Compax3 I11 T11 Features
- 120 - 480 VAC power input range
- Continuous current output from 2.5 A (rms) to 155 A (rms)
- Resolver, encoder, high-resolution SinCos® or Stegmann Absolute rotary encoder feedback (single- or multi-turn) or Heidenhain Endat 2.1
- SSI encoder as a source for gearing, cam shapes and external position measurement
- Up to 31 move profiles storable in non-volatile flash memory
- Absolute or relative positioning via 8 digital inputs, 4 digital outputs
- Homing and jogging functionality
- Software travel limits
- "Dynamic positioning" – allows the changing of target position while a move is in progress
- Adjustable jerk (S-curve) limitation
- Optional fieldbus interfaces (CANopen, Profibus DP, DeviceNet and ETHERNET Powerlink)
- CE (EMC & LVD), UL and cUL

Compax3 I12 T11 Features
All I11 T11 capabilities, plus:
- Electronic gearing (following)
- Registration input (800 ns position-capture speed)
- Continuous velocity, registration-based moves
- 16 digital inputs, 8 digital outputs
- Hardware end-of-travel limit support
- Programmable pattern outputs
- Optional HEDA following bus option
- Requires M12 option

Compax3 T11 Accessories
- Refer to the Compax3 Accessories section listed on page 15 of this catalog

Parker Automation

Compax3 T30

IEC61131-3 Drive/Controller

The Compax3 T30 technology level is a compact industrial digital servo drive/controller available in six power levels producing up to 30 A (rms) continuous current and covering a broad range of input voltages. The T30 is a servo drive with fully programmable IEC61131-3 motion controller capability. The IEC61131-3 programming enivronment offers the ultimate in programming flexibility and power.

Compax3 T30 users may choose to develop their application code from any of six graphical, ladder or text-based IEC programming formats. Users have the freedom to develop their application in whichever programming style they are most comfortable; or, if desired, they may use any combination of these languages within the same application project. The motion capabilities of the Compax3 T30 are easily available to the user via PLCopen standard function blocks as well as more complex motion function blocks supplied by Parker Hannifin. Optional fieldbus interfaces allow simple and effective data exchange to higher-level systems.

The Compax3 is easily configurable via RS232/485 using Parker's C3 ServoManager™ software running on a PC or by downloading an existing configuration file from another T30 unit via the optional BDM01/01 keypad interface module. Using the C3 ServoManager software could not be easier. Commissioning is even faster with the addition of software input simulation and auto-tuning. All setup is accomplished via intuitive drive configuration wizards and basic application information. The CoDeSys IEC programming editor can also be launched directly from the C3 ServoManager software.

Although the Compax3 T30 uses standard resolver feedback, it can also be equipped with quadrature encoder, high-resolution Stegmann or SinCos® Hiperface™ encoder with single- or multi-turn absolute feedback capability or Heidenhain Endat 2.1.

Compax3 T30 Features

- 120 - 480 VAC power input range
- Continuous current output from 2.5 A (rms) to 30 A (rms)
- Resolver, encoder, high-resolution SinCos® or Stegmann Absolute rotary encoder feedback (single- or multi-turn) or Heidenhain Endat 2.1
- SSI encoder as a source for gearing, cam shapes and external position measurement
- Fully programmable IEC61131-3 single-axis drive/controller
- PLCopen and Parker motion function blocks
- 6 programming formats to choose from – CFC, LD, FBD, SFC, ST and IL
- Program memory – more than 5000 instruction lines
- High-level motion capability and machine control capability in one package
- 8 digital inputs/4 digital outputs
- Registration input (800 ns position-capture speed)
- Optional expansion I/O – additional 12 digital I/O points configurable for inputs or outputs, remote I/O with CANopen
- Optional fieldbus interfaces (CANopen, Profibus DP, DeviceNet and ETHERNET Powerlink)
- CE (EMC & LVD), UL and cUL

Compax3 T30 Accessories

- Refer to the Compax3 Accessories section listed on page 15 of this catalog

Parker Automation

Compax3 T40
IEC61131-3 Drive/Controller with Electronic Camming

The Compax3 T40 technology level is a compact industrial digital servo drive available in six power levels producing up to 30 A (rms) continuous current and covering a broad range of input voltages. The T40 is a servo drive with fully programmable IEC61131-3 motion controller and advanced electronic camming and gearing capabilities.

The Compax3 T40 represents the ultimate in programming flexiblity and power within the Compax3 drive family. In addition to all of the programming capabilities of the Compax3 T30, the T40 includes electronic gearing and cam control capabilities, position capture and programmable limit switch (PLS) functionality. Electronic cams are created graphically using the powerful, wizard-based Cam Designer tool built into the C3 ServoManager™ software package. All this can be combined with Parker's optional HEDA interface, a high-speed, real-time following bus specifically designed for line-shafting or multi-axis following applications. The motion capabilities of the Compax3 T40 are easily available to the user via PLCopen standard function blocks as well as more complex motion function blocks supplied by Parker Hannifin. Optional fieldbus interfaces allow simple and effective data exchange to higher-level systems.

The Compax3 is easily configurable via RS232/485 using Parker's C3 ServoManager™ software running on a PC or by downloading an existing configuration file from another T40 unit via the optional BDM keypad interface module. All setup is accomplished via intuitive drive configuration wizards and basic information of the application. Commissioning is even faster with the addition of software input simulation and auto-tuning. The CoDeSys IEC programming editor can also be launched directly from the C3 ServoManager software.

Compax3 T40 Features

- 120 - 480 VAC power input range
- Continuous current output from 2.5 A (rms) to 155 A (rms)
- Resolver, encoder, high-resolution SinCos® or Stegmann Absolute rotary encoder feedback (single- or multi-turn) or Heidenhain Endat 2.1
- SSI encoder as a source for gearing, cam shapes and external position measurement
- Fully programmable IEC61131-3 single-axis drive/controller
- 6 programming formats to choose from – CFC, LD, FBD, SFC, ST and IL
- Electronic camming, electronic gearing functionality
- Wide selection of master sources supported
- Virtual master
- Registration input (800 ns capture speed)
- Programmable limit switches (PLS)
- Optional HEDA following bus
- Optional expansion I/O – 12 digital I/O points configurable as inputs or outputs, remote I/O with CANopen
- Optional fieldbus interfaces (CANopen, Profibus DP, DeviceNet and ETHERNET Powerlink)
- CE (EMC & LVD), UL and cUL

Compax3 T40 Accessories

- Refer to the Compax3 Accessories section listed on page 15 of this catalog

Parker Automation

IEC61131-3
Programming Environment

IEC61131-3 is a manufacturer-independent programming enivronment for industrial automation devices. This programming interface brings tremendous flexibility to the user as well as worldwide recognition and support. The IEC61131-3 programmer may choose from five standard languages, both graphical and text-based, in order to develop the code for their application. Thus, users can program their device in the language or languages they are most comfortable with.

The graphical languages include:

- Ladder diagram (LD)
- Function block diagram (FBD)
- Continuous function chart (CFC)

The text-based languages include:

- Structured text (ST)
- Instruction list (IL)

An environment is also avaliable for structuring program flow:

- Sequential function chart (SFC)

The standard IEC61131-3 programming language has gone beyond establishing itself in PLC systems in the last few years. Today it is also frequency used for PCs, SCADA systems and also motion control systems. The intelligent drive/controller versions of the Compax3 family use the IEC61131-3 interface to give users new levels of flexibility and power when developing their application.

Motion Block Libraries for Compax3 T30 and T40

Parker makes IEC61131-3 programming for the Compax3 use even easier by providing motion-specific function block libraries, which are included with every Compax3 T30 and T40 product. These function block libraries allow users to insert pre-defined motion functions into their IEC project by selecting the desired function from a pull-down table, thus eliminating the need to program these functions manually. These libraries consist of function blocks created by both Parker and PLCopen™, a product- and company-independent organization that plays a significant role in supporting the IEC61131-3 programming language.

Some examples of the available Compax3 function modules include:

- Absolute motion
- Incremental (relative) motion
- Continuous motion

- Superimposed motion
- Homing
- Drive enable
- Stop motion
- Drive status / error clearing
- Ratio following
- Electronic cam selection
- Interchangable force-position control block
- P.I.D. block (i.e., temp control)
- And dozens more!

IEC61131-3 Features

- Five programming languages to choose from for ease of use
- Worldwide support for programming languages
- Program portability
- Multiple languages may be combined within a single project
- Minimal training and support effort
- Portability from one application project to another project
- IEC programming editor built into the standard C3 ServoManager™ software

Parker Automation
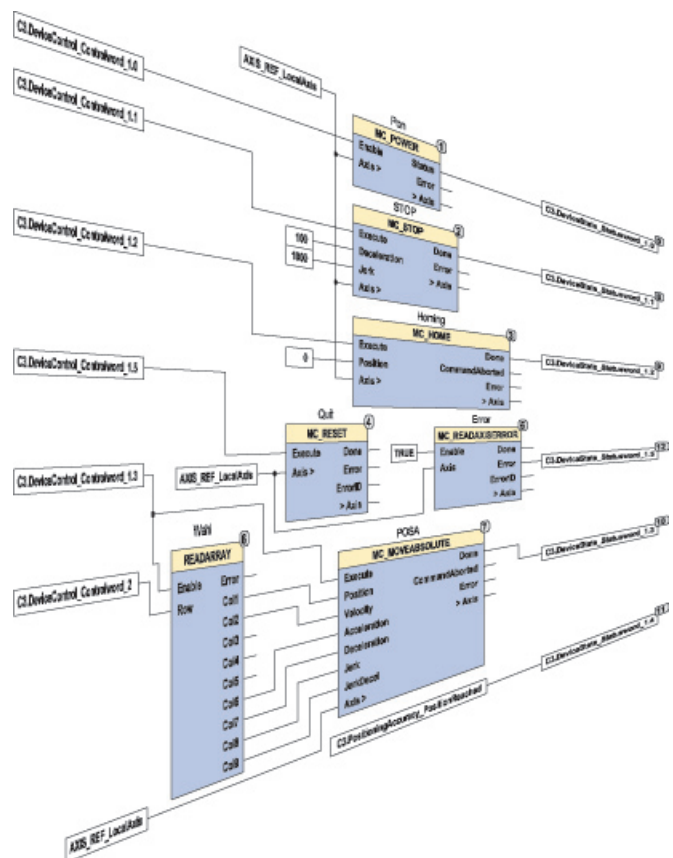
Compax3 Software Tools

C3 ServoManager™ Development Software
- User friendly, wizard-based drive configuration tool with navigation tree.
- Powerful online help system – accessible in any screen.
- MotorManager allows quick configuration of motors – automatically configures commutation settings.
- Multilingual support: English, German or French at the click of a button.
- C3 Profile Viewer – helps quantify S-curve acceleration.
- See Figure A.

Figure A
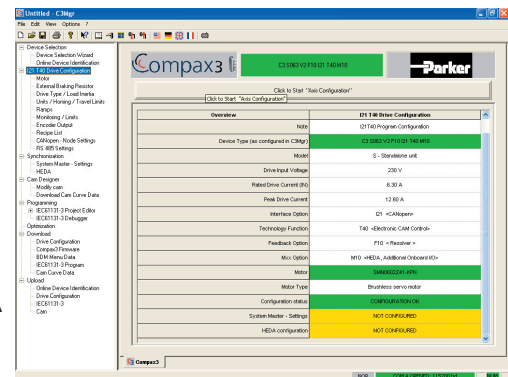
C3 Optimization Tool
- Powerful system diagnostic and troubleshooting tool.
- Numerical and graphical status displays.
- Error display with fault history.
- Four-channel oscilloscope with ASCII and CSV export capability.
- Commisioning feature allows motor jogging, preset moves, homing, drive enable and more.
- Launched directly from within the C3 ServoManager development software.
- Auto-tuning
- Input simulation
- See Figure B.

Figure B
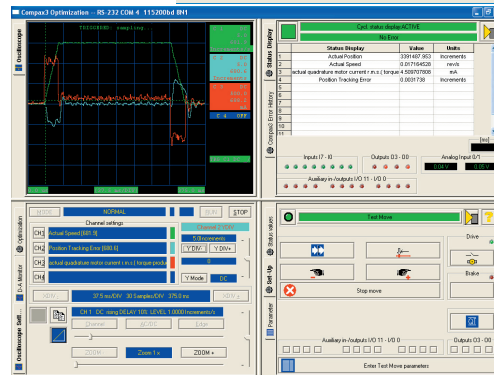
IEC61131-3 Project Development Editor
- IEC61131-3 programming environment for Compax3 T30 and T40.
- Graphics editor for LD, CFC, SFC and FBD; text editor for IL and ST.
- Syntax coloring, multi-level undo/redo and context-sensitive help.
- Library management for creating, accessing and selecting IEC function libraries.
- Launched directly from within the C3 ServoManager development software.
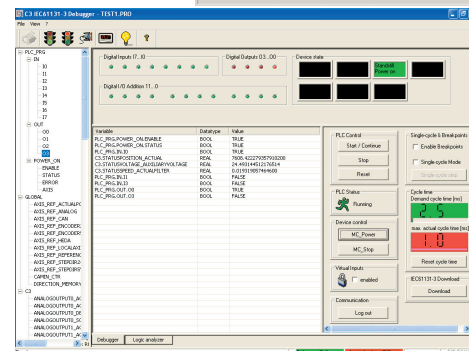- See Figure C.

Figure C
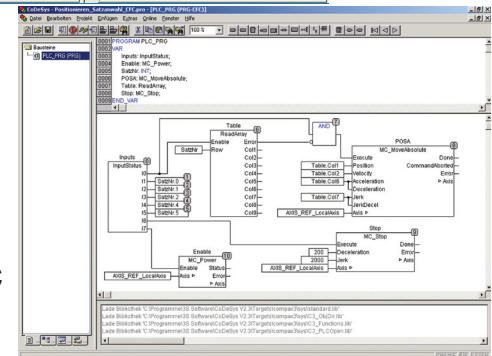
IEC Debugger
- Diagnostic tool specifically tailored for monitoring IEC program execution.
- All object variables within the IEC program can be viewed and modified online.
- Debugger and Logic analyzer screens.
- Input-forcing within the IEC program.
- Launched directly from within the C3 ServoManager development software.
- See Figure D.

Figure D
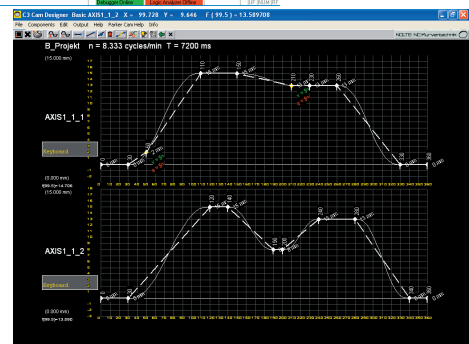
C3 Cam Designer
- Graphical electronic cam creation tool for Compax3 T40 applications.
- Wide selection of curve interpolation types.
- Real-time generation of displacement diagrams.
- Launched directly from within the C3 ServoManager development software.
- See Figure E.

Figure E

Parker Hannifin Corporation
Electromechanical Automation Division
parkermotion.com

Parker Automation

Compax3 Options

Feedback

F10 Option

F11 Option

F12 Option

Standard resolver feedback support,
Resolver position resolution: 19 bit; repeatability: ± 0.005°
SinCos® position resolution: 21 bit; SinCos® (Hiperface™) high-resolution encoder support; absolute accuracy:
± 0.002°; Stegmann
Quadrature rotary/linear encoder, sine-cosine linear, distance-coded encoder feedback support
Resolution, accuracy: dependent upon specification of encoder used; Endat 2.1 compatible feedback

Fieldbus

I20 Option

I21 Option

I22 Option

I30 Option

Profibus - DPV0 (slave)
Transmission speed: up to 12Mbd
Available on T11, T30, T40 units
CANopen - DS402 (slave)
Transmission speed: selectable (up to 1Mbd)
Available on T11, T30, T40 units
DeviceNet slave available on T11, T30 and T40 units
Transmission speed: 125, 250, 500 kBits/second
ETHERNET Powerlink: Use I30 T11 with ACR9030/9040

Additional

M10 Option

HEDA following bus and additional onboard I/O (available on T11, T30 and T40 units)
     HEDA:
         Real-time following bus for line-shafting or multi-axis following applications
         Configurable as master or slave; up to 19 units supported on network
         Bus transmission speed: 10 Mbaud
         Bus update rate: 500 microseconds (regardless of HEDA node count); 0.5 µs jitter
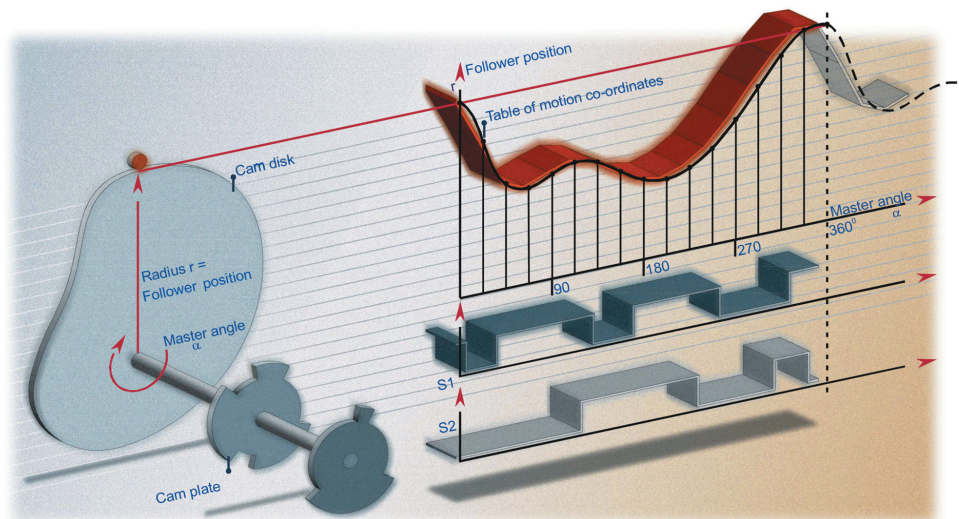   Additional Onboard I/O:
         12 I/O points, configurable as inputs or outputs in blocks of 4 (via software)
         User-defined functionality for all points

M11 Option
M12 Option

HEDA following bus only (available on T30 and T40 units)
Additional onboard I/O only (available on I12 T11, IxxT30 and IxxT40 units)

Parker Automation

Compax3 S0XX V2 Specifications

Specifications	S025 V2	S063 V2	S100 V2	S150 V2
Drive Input Power				
Voltage	80-253 VAC	80-253 VAC	80-253 VAC	80-253 VAC
Phase	1Ø	1Ø	3Ø	3Ø
Frequency	50/60 Hz	50/60 Hz	50/60 Hz	50/60 Hz
24 VDC Logic Power (Required)	24 VDC ±15%	24 VDC ±15%	24 VDC ±15%	24 VDC ±15%
Drive Output Power				
PWM	16/32 kHz (selectable)	16/32 kHz (selectable)	16/32 kHz (selectable)	8/16/32 kHz (selectable)
Continuous Current (RMS)	2.5 Amps	6.3 Amps	10 Amps	15 Amps
Peak Current (RMS)	5 Amps	12.6 Amps	20 Amps	30 Amps
Commutation	Sinusoidal	Sinusoidal	Sinusoidal	Sinusoidal

Performance
Torque Loop — 62.5 micro seconds
Velocity Loop — 125 micro seconds
Position Loop — 125 micro seconds

Command Inputs (T10 only)
Velocity and Torque Mode — 14 bit, ±10 VDC Analog
Position Mode — Step & Direction; 5V or 24 V level (300 kHz input frequency); differential signal

Onboard Digital Inputs
Type — Sinking type, 24 V nom. @ 10 mA, high = 9-32 V, low <8 V
Functions
Ixx T10 (4 dedicated) — Drive stage enable, control input enable, reset, motor brake open/close
Ixx T11 (8 dedicated) — Motion interrupt, Start, Drive Stage enable + 5 motion profile select inputs (or 4 inputs with a home input)
Ixx T30 (8 programmable*) — User definable via IEC61131-3 programming environment
Ixx T40 (8 programmable*) — User definable via IEC61131-3 programming environment

Analog Inputs (T11, T30, T40) — Two (dedicated); 14 bit

Onboard Digital Outputs
Type — Sourcing type, rated for 24 V @ 100 mA, short-circuit protected
Functions
Ixx T10 (4 dedicated) — No fault, drive enabled, in position window, at zero point
Ixx T11 (4 dedicated) — No fault, position reached, power stage active, at zero point
Ixx T30 (4 programmable*) — User definable via IEC61131-3 programming environment
Ixx T40 (4 programmable*) — User definable via IEC61131-3 programming environment
Encoder — Programmable up to 16,384 ppr (pre-quadrature)
Relay — Normally closed, dry contact (switching current: 10-300 mA, switching voltage [AC/DC]: 100 mV-60 V)

Analog Outputs (T11, T30, T40) — Two (dedicated); 8 bit; software configurable as monitor outputs

Communications
Type — RS232 (3-wire) on RS485 (2- or 4-wire); 8-bit word length, 1 stop bit, no parity
Baud Rate — Fixed at 115.8 Kbaud for RS232; adjustable for RS485
Multi-drop (RS485) — Up to 255 nodes
Profibus** — DPV0 supported; selectable Baud rate, 12 Mbd maximum transmission speed
CANopen** — DCiA, DS102 supported; selectable Baud rate, 1 Mbd maximum transmission speed
DeviceNet** — Polled, C05/cyclic I/O and bit strobe; 500 kBit/second max speed
ETHERNET Powerlink** — Interploated mask (ACR); fieldbus

Environmental
Temperature — Still air: 33-113°F (0-45°C); moving air: 33-122°F (0-50°C)
Humidity — 0-75%, non-condensing
IP Class — IP 20

Protection
Short Circuit — Phase-to-phase, phase-to-ground
Brownout — Below 70 VDC
Over Voltage — Will shut down when power dissipation capacity is exceeded
Over Temperature — Motor 330°F (170°C), Drive 221°F (105°C)
I²t — Error generated if peak current > 3 seconds
Safety Isolation — VDE0160

Standards — UL, cUL, CE (EMC), CE (LVD)

Internal Regeneration Capacities/Storable Energy
Compax3 S025 V2: 560 µF / 15Ws
Compax3 S063 V2: 1120 µF / 30Ws
Compax3 S100 V2: 780 µF / 21Ws
Compax3 S150 V2: 1,170 µF / 31Ws

	S025	S063	S100	S150
H	191	191	248	248
W	84	100	115	158
D	172	172	172	172

H
D (mm)
W

* 12 additional I/O points available as an option
** Applicable only to models supporting this option

Parker Automation

Compax3 SXXX V4 Specifications

Specifications	S038 V4	S075 V4	S150 V4	S300 V4
Drive Input Power				
Voltage	80-525 VAC	80-525 VAC	80-525 VAC	80-525 VAC
Phase	3Ø	3Ø	3Ø	3Ø
Frequency	50/60 Hz	50/60 Hz	50/60 Hz	50/60 Hz
24 VDC Logic Power (Required)	24 VDC ±15%	24 VDC ±15%	24 VDC ±15%	24 VDC ±15%
Drive Output Power				
PWM	16/32 kHz (selectable)	16/32 kHz (selectable)	8/16/32 kHz (selectable)	8/16/32 kHz (selectable)
Continuous Current (RMS)	3.8 Amps	7.5 Amps	15 Amps	30 Amps
Peak Current (RMS)	7.5 Amps	15 Amps	30 Amps	60 Amps
Commutation	Sinusoidal	Sinusoidal	Sinusoidal	Sinusoidal

Performance
Torque Loop — 62.5 micro seconds
Velocity Loop — 125 micro seconds
Position Loop — 125 micro seconds

Command Inputs (T10 only)
Velocity and Torque Mode — 14 bit, ±10 VDC Analog
Position Mode — Step & Direction; 5V or 24 V level (300 kHz input frequency); differential signal

Onboard Digital Inputs
Type — Sinking type, 24 V nom. @ 10 mA, high = 9-32 V, low <8 V
Functions
Ixx T10 (4 dedicated) — Drive stage enable, control input enable, reset, motor brake open/close
Ixx T11 (8 dedicated) — Motion interrupt, Start, Drive Stage enable + 5 motion profile select inputs (or 4 inputs with a home input)
Ixx T30 (8 programmable*) — User definable via IEC61131-3 programming environment
Ixx T40 (8 programmable*) — User definable via IEC61131-3 programming environment

Analog Inputs (T11, T30, T40) — Two (dedicated); 14 bit

Onboard Digital Outputs
Type — Sourcing type, rated for 24 V @ 100 mA, short-circuit protected
Functions
Ixx T10 (4 dedicated) — No fault, drive enabled, in position window, at zero point
Ixx T11 (4 dedicated) — No fault, position reached, power stage active, at zero point
Ixx T30 (4 programmable*) — User definable via IEC61131-3 programming environment
Ixx T40 (4 programmable*) — User definable via IEC61131-3 programming environment
Encoder — Programmable up to 16,384 ppr (pre-quadrature)
Relay — Normally closed, dry contact (switching current: 10-300 mA, switching voltage [AC/DC]: 100 mV-60 V)

Analog Outputs (T11, T30, T40) — Two (dedicated); 8 bit; software configurable as monitor outputs

Communications
Type — RS232 (3-wire) on RS485 (2- or 4-wire); 8-bit word length, 1 stop bit, no parity
Baud Rate — Fixed at 115.8 Kbaud for RS232; adjustable for RS485
Multi-drop (RS485) — Up to 255 nodes
Profibus** — DPV0 supported; selectable Baud rate, 12 Mbd maximum transmission speed
ETHERNET Powerlink** — DCiA, DS102 supported; selectable Baud rate, 1 Mbd maximum transmission speed
DeviceNet** — Polled, C05/cyclic I/O and bit strobe; 500 kBit/second max speed
CANopen** — Interploated mask (ACR); fieldbus

Environmental
Temperature — Still air: 33-113°F (0-45°C); moving air: 33-122°F (0-50°C)
Humidity — 0-75%, non-condensing
IP Class — IP 20

Protection
Short Circuit — Phase-to-phase, phase-to-ground
Brownout — Below 70 VDC
Over Voltage — Will shut down when power dissipation capacity is exceeded
Over Temperature — Motor 330°F (170°C), Drive 221°F (105°C)
I²t — Error generated if peak current > 3 seconds
Safety Isolation — VDE0160

Standards — UL, cUL, CE (EMC), CE (LVD)

Internal Regeneration Capacities/Storable Energy
Compax3 S038 V4: 235 µF / 37Ws
Compax3 S075 V4: 470 µF / 75Ws
Compax3 S150 V4: 690 µF / 110Ws
Compax3 S300 V4: 1,100 µF / 176Ws

	S038	S075	S150	S300
H	248	248	248	380
W	100	115	158	175
D	172	172	172	172
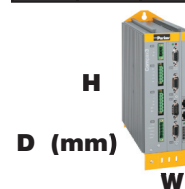
* 12 additional I/O points available as an option
** Applicable only to models supporting this option

Compax3 HXXX V4 Specifications

Specifications	H050 V4	H090 V4	H125 V4	H155 V4
Drive Input Power				
Voltage	350-528 VAC	350-528 VAC	350-528 VAC	350-528 VAC
Phase	3Ø	3Ø	3Ø	3Ø
Frequency	50/60 Hz	50/60 Hz	50/60 Hz	50/60 Hz
24 VDC Logic Power (Required)	24 VDC ±15%	24 VDC ±15%	24 VDC ±15%	24 VDC ±15%
Drive Output Power				
PWM	8 kHz	8 kHz	8 kHz	8 kHz
Continuous Current (RMS)	50 Amps @ 400 VAC	90 Amps @ 400 VAC	125 Amps @ 400 VAC	155 Amps @ 400 VAC
Peak Current (RMS)	75 Amps for 5 sec	135 Amps for 5 sec	187.5 Amps for 5 sec	232.5 Amps for 5 sec
Commutation	Sinusoidal	Sinusoidal	Sinusoidal	Sinusoidal

Performance
Torque Loop — 62.5 micro seconds
Velocity Loop — 125 micro seconds
Position Loop — 125 micro seconds

Command Inputs (T10 only)
Velocity and Torque Mode — 14 bit, ±10 VDC Analog
Position Mode — Step & Direction; 5V or 24 V level (300 kHz input frequency); differential signal

Onboard Digital Inputs
Type — Sinking type, 24 V nom. @ 10 mA, high = 9-32 V, low <8 V
Functions
  Ixx T10 (4 dedicated) — Drive stage enable, control input enable, reset, motor brake open/close
  Ixx T11 (8 dedicated) — Motion interrupt, Start, Drive Stage enable + 5 motion profile select inputs (or 4 inputs with a home input)
  Ixx T30 (8 programmable*) — User definable via IEC61131-3 programming environment
  Ixx T40 (8 programmable*) — User definable via IEC61131-3 programming environment

Analog Inputs (T11, T30, T40) — Two (dedicated); 14 bit

Onboard Digital Outputs
Type — Sourcing type, rated for 24 V @ 100 mA, short-circuit protected
Functions
  Ixx T10 (4 dedicated) — No fault, drive enabled, in position window, at zero point
  Ixx T11 (4 dedicated) — No fault, position reached, power stage active, at zero point
  Ixx T30 (4 programmable*) — User definable via IEC61131-3 programming environment
  Ixx T40 (4 programmable*) — User definable via IEC61131-3 programming environment
Encoder — Programmable up to 16,384 ppr (pre-quadrature)
Relay — Normally closed, dry contact (switching current: 10-300 mA, switching voltage [AC/DC]: 100 mV-60 V)

Analog Outputs (T11, T30, T40) — Two (dedicated); 8 bit; software configurable as monitor outputs

Communications
Type — RS232 (3-wire) on RS485 (2- or 4-wire); 8-bit word length, 1 stop bit, no parity
Baud Rate — Fixed at 115.8 Kbaud for RS232; adjustable for RS485
Multi-drop (RS485) — Up to 255 nodes
Profibus** — DPV0 supported; selectable Baud rate, 12 Mbd maximum transmission speed
CANopen** — DCiA, DS102 supported; selectable Baud rate, 1 Mbd maximum transmission speed
DeviceNet** — Polled, C05/cyclic I/O and bit strobe; 500 kBit/second max speed
ETHERNET Powerlink** — Interpoloated mask (ACR); fieldbus

Environmental
Temperature — Still air: 33-113°F (0-45°C); moving air: 33-122°F (0-50°C)
Humidity — 0-75%, non-condensing
IP Class — IP 20

Protection
Short Circuit — Phase-to-phase, phase-to-ground
Brownout — Below 70 VDC
Over Voltage — Will shut down when power dissipation capacity is exceeded
Over Temperature — Motor 330°F (170°C), Drive 221°F (105°C)
I^2t — Error generated if peak current > 3 seconds
Safety Isolation — VDE0160

Standards — UL, cUL, CE (EMC), CE (LVD)

Internal Regeneration Capacities/Storable Energy
Compax3 H050 V4: 2600 µF / 602Ws
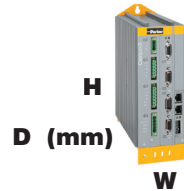Compax3 H090 V4: 3150 µF / 729Ws
Compax3 H125 V4: 5000 µF / 1158Ws
Compax3 H155 V4: 5000 µF / 1158Ws

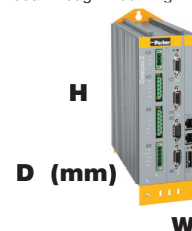|	H050	H090	H125	H155
H	453	668.6	720	720
W	252	257	257	257
D	245	312	355	355

(mm)

* 12 additional I/O points available as an option
** Applicable only to models supporting this option

Parker Automation

Compax3 M Specifications

Specifications	Power Supply Units		Axis Units			
	MP10 D6	MP20 D6***	M050 D6	M100 D6	M150 D6	M300 D6***
Drive Input Power						
Voltage	240/480 VAC	240/480 VAC	680 VDC	680 VDC	680 VDC	680 VDC
Phase	3-Ø	3-Ø	DC Bus	DC Bus	DC Bus	DC Bus
Frequency	50/60 Hz	50/60 Hz				
24 VDC Logic Power (Required)	24 VDC	24 VDC	Bussed 24 VDC	Bussed 24 VDC	Bussed 24 VDC	Bussed 24 VDC
Drive Output Power						
PWM	NA	NA	8/16/32 kHz	8/16/32 kHz	8/16/32 kHz	8/16/32 kHz
Continuous Current (RMS)	15A @ 480 VAC	30A @ 480 VAC	4A @ 480 VAC	8A @ 480 VAC	12.5A @ 480 VAC	24A @ 480 VAC
Peak Current (RMS)	30A @ 480 VAC	60A @ 480 VAC	8A @ 480 VAC	16A @ 480 VAC	25A @ 480 VAC	48A @ 480 VAC
Commutation	NA	NA	Sinusoidal	Sinusoidal	Sinusoidal	Sinusoidal

Performance
Torque Loop — 62.5 micro seconds
Velocity Loop — 125 micro seconds
Position Loop — 125 micro seconds

Command Inputs (T10 only)
Velocity and Torque Mode — 14 bit, ±10 VDC Analog
Position Mode — Step & Direction; 5V or 24 V level (300 kHz input frequency); differential signal

Onboard Digital Inputs
Type — Sinking type, 24 V nom. @ 10 mA, high = 9-32 V, low <8 V
Functions
Ixx T10 (4 dedicated) — Drive stage enable, control input enable, reset, motor brake open/close
Ixx T11 (8 dedicated) — Motion interrupt, Start, Drive Stage enable + 5 motion profile select inputs (or 4 inputs with a home input)
Ixx T30 (8 programmable*) — User definable via IEC61131-3 programming environment
Ixx T40 (8 programmable*) — User definable via IEC61131-3 programming environment

Analog Inputs (T11, T30, T40) — Two (dedicated); 14 bit

Onboard Digital Outputs
Type — Sourcing type, rated for 24 V @ 100 mA, short-circuit protected
Functions
Ixx T10 (4 dedicated) — No fault, drive enabled, in position window, at zero point
Ixx T11 (4 dedicated) — No fault, position reached, power stage active, at zero point
Ixx T30 (4 programmable*) — User definable via IEC61131-3 programming environment
Ixx T40 (4 programmable*) — User definable via IEC61131-3 programming environment
Encoder — Programmable up to 16,384 ppr (pre-quadrature)
Relay — Normally closed, dry contact (switching current: 10-300 mA, switching voltage [AC/DC]: 100 mV-60 V)

Analog Outputs (T11, T30, T40) — Two (dedicated); 8 bit; software configurable as monitor outputs

Communications
Type — RS232 (3-wire) on RS485 (2- or 4-wire); 8-bit word length, 1 stop bit, no parity
Baud Rate — Fixed at 115.8 Kbaud for RS232; adjustable for RS485
Multi-drop (RS485) — Up to 255 nodes
Profibus** — DPV0 supported; selectable Baud rate, 12 Mbd maximum transmission speed
CANopen** — DCiA, DS102 supported; selectable Baud rate, 1 Mbd maximum transmission speed
DeviceNet** — Polled, C05/cyclic I/O and bit strobe; 500 kBit/second max speed
ETHERNET Powerlink** — Interploated mask (ACR); fieldbus

Environmental
Temperature — Still air; 33-113°F (0-45°C); moving air; 33-122°F (0-50°C)
Humidity — 0-75%, non-condensing
IP Class — IP 20

Protection
Short Circuit — Phase-to-phase, phase-to-ground
Brownout — Below 70 VDC
Over Voltage — Will shut down when power dissipation capacity is exceeded
Over Temperature — Motor 330°F (170°C), Drive 221°F (105°C)
I^2t — Error generated if peak current > 3 seconds
Safety Isolation — VDE0160

Standards — UL, cUL, CE (EMC), CE (LVD)

Internal Regeneration Capacities/Storable Energy
Compax3 M050 V6: 110 µF / 10Ws @ 480 Volts
Compax3 M100 V6: 220 µF / 21Ws @ 480 Volts
Compax3 M150 V6: 220 µF / 21Ws @ 480 Volts

	MP10	MP20	M050, M100 M1050	M300
H	360	360	360	360
W	50	100	50	100
D	263*	263*	263*	263*

* Depth can be reduced to 190mm (7.5") with feed-through mounting.

H

D (mm)

W

* 12 additional I/O points available as an option
** Applicable only to models supporting this option
*** To be released in Fall 2008

Parker Automation

BDM 01/01
Interface Module

BUS07/01 plug
71-017635-01 cable

HEDA Interface
(Optional)

VM15–PM
Breakout Module

Analog
Input/Output
Interface

SSK 1/02

Additional
Digital I/O Interface
(Optional)

VM15–PF
Breakout Module

Compax3
SEE TABLE A

Motors & Cables
SEE TABLE B

Fieldbus Interface
(Optional)

Digital I/O
Interface

BUS08/01 plug (Profibus)
BUS10/01 plug (CANopen)
71-028656-xx (ETHERNET Powerlink)

VM15–PF
Breakout Module

All Compax3 units include:
- AC power connector
- Braking resistor connector
- Motor power connector
- 24 VDC logic power connector
- Motor power shield spring clip

Connector

X11	Analog I/O, step-and-direction input, aux encoder	VM15-PM
X12	Digital I/O	VM15-PF
X13	Feedback	VM15-PM
X22	Expansion I/O	VM15-PF

Parker Automation

Ordering a Compax3 System

Table A – Compax3 Order Code

Continuous Current/Input Voltage
S025 V2 - 2.5 A (rms) / 120 - 240 VAC
S063 V2 - 6.3 A (rms) / 120 - 240 VAC
S100 V2 - 10 A (rms) / 120 - 240 VAC 3Ø
S150 V2 - 15 A (rms) / 120 - 240 VAC 3Ø
S038 V4 - 3.8 A (rms) / 208 - 480 VAC 3Ø
S075 V4 - 7.5 A (rms) / 208 - 480 VAC 3Ø
S150 V4 - 15 A (rms) / 208 - 480 VAC 3Ø
S300 V4 - 30 A (rms) / 208 - 480 VAC 3Ø
H050 V4 - 50 A (rms) / 400 - 480 VAC 3Ø
H090 V4 - 90 A (rms) / 400 - 480 VAC 3Ø
H125 V4 - 125 A (rms) / 400 - 480 VAC 3Ø
H155 V4 - 155 A (rms) / 400 - 480 VAC 3Ø
M050 D6 - 4 A (rms) / 240 - 480 VAC 3Ø
M100 D6 - 8 A (rms) / 240 - 480 VAC 3Ø
M150 D6 - 12.5 A (rms) / 240 - 480 VAC 3Ø

Motor Feedback
F10 - Resolver
F11 - Absolute encoder/SinCos®/
　　　Stegmann/Hiperface
F12 - Quadrature encoder/
　　　SineCosine linear/Endat 2.1

Options
M00 - No options
M10 - Additional I/O
　　　with HEDA
M11 - HEDA
M12 - Additional I/O

Interface/Technology (Control) Level
I10 T10 - Drive only
I11 T11 - Basic positioning via digital inputs
　　　(requires M00)
I12 T11 - Advanced positioning via inputs
　　　and RS232/485 (requires M12)
I20 T11 - Positioning via Profibus DP
I21 T11 - Positioning via CANopen
I22 T11 - Positioning via DeviceNet
I30 T11 - Positioning/Interpolation via EPL
I11 T30 - IEC with digital I/O
I20 T30 - IEC with Profibus DP
I21 T30 - IEC with CANopen
I22 T30 - IEC with DeviceNet
I30 T30 - IEC with EPL
I11 T40 - IEC Cam control w/ digital I/O
I20 T40 - IEC Cam control w/ Profibus DP
I21 T40 - IEC Cam control w/ CANopen
I22 T40 - IEC Cam control w/ DeviceNet
I30 T40 - IEC Cam control w/ EPL

Table B – Servo Motor Power/Feedback Cables – *As Easy As 1-2-3!*

Compax3 PS Motor-Drive Cables

PS Feedback Cables

1. Choose Your Feedback Type	2. Choose Your Motor Family	3. Your Part Number is:
Resolver	• BE 23, 34 • NeoMetric/ J Series 34, 70, 92 • MaxPlus 72 - 190 • M Series 105 - 205 • SMN 60 - 142 • MaxPlusPlus (MPP)	**F-2B1-xx**
SinCos/Stegmann/ Hiperface	• BE 34 • NeoMetric/ J Series 34, 70, 92 • MaxPlus 72 - 190 • M Series 105 - 205 • SMN 60 - 142 • MaxPlusPlus (MPP)	**F-2B1-xx**
Encoder	• BE 23, 34 • NeoMetric/ J Series 34, 70, 92 • MaxPlus 72 - 190 • M Series 105 - 205 • SMN 60 - 142 • MaxPlusPlus (MPP)	**F-2C1-xx**

PS Motor Power Cables

1. Choose Your Motor Current	2. Choose Your Motor Family	3. Your Part Number is:
Up to 6A RMS continuous (240VAC only)	• BE 23 • NeoMetric, J Series • MaxPlusPlus (MPP)	**P-1A1-xx**
Up to 20A RMS continuous (240 or 480V)	• BE 34 • NeoMetric, J Series • MaxPlus • M Series • SMN Series • MaxPlusPlus (MPP)	**P-3B1-xx**
20A to 30A RMS (240 or 480V)	• M Series • MaxPlusPlus (MPP)	**P-4B1-xx**
20A to 30A RMS (240 or 480V)	• M Series • MaxPlus • MaxPlusPlus (MPP)	**P-4B2-xx**
30A to 50A RMS (240 or 480V)	• M Series • MaxPlus • MaxPlusPlus (MPP)	**P-6B2-xx**
> 50A RMS	Contact factory	**Custom product**

-XX denotes cable length in feet; motor power and feedback cables available in standard lengths of 10, 25 and 50 feet (other lengths also available).

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Compax3 Accessories

Part Number	Product Description
Power Supply**	
C3MP10USBM000	10kW power supply for Compax3M axis units; 240/480 3-phase
C3MP20USBM000	20kW power supply for Compax3M axis units; 240/480 3-phase
Breakout Modules	
VM15-PM	15-pin breakout module and 2' cable to Compax3 feedback or analog encoder
VM15-PF	15-pin breakout module and 2' cable to Compax3 digital I/O
VM15-PM-05	15-pin breakout module and 5' cable to Compax3 feedback or analog encoder
VM15-PF-05	15-pin breakout module and 5' cable to Compax3 digital I/O
VM15-PM-10	15-pin breakout module and 10' cable to Compax3 feedback or analog encoder
VM15-PF-10	15-pin breakout module and 10' cable to Compax3 digital I/O
Connector Kits	
ZBH02/01	Replacement connector kit for Compax3 S025 V2, S063 V2 products
ZBH02/02	Replacement connector kit for Compax3 S038 V4, S075 V4, S150 V4 products
ZBH02/03	Replacement connector kit for Compax3 S300 V4 products
ZBH04/01	Replacement connector kit for Compax3 M050D6, M100D6, M150D6
ZBH04/02	Replacement connector kit for Compax3 M300D6
ZBH04/03	Replacement connector kit for Compax3 MP10D6 and MP20D6 (power supply)
Communication Cable	
SSK1/02	8' cable, RS232 serial communication cable (PC to Compax3)
SSK32/20	Communications dongle for C3Hxxx; one unit ships with drive - replacement only
VBK17/01	X10 to X10 jumper - replacement only for C3H
Braking Resistors	
BRM08/01	Braking resistor for Compax3 S025, S038 units (60 W continuous, 250 W peak)
BRM05/01	Braking resistor for Compax3 S063, S075 units (180 W continuous, 2300 W peak)
BRM05/02	Braking resistor for Compax3 S150 units (570 W continuous, 6900 W peak)
BRM04/01	Braking resistor for Compax3 S300 units (570 W continuous, 6900 W peak)
BRM04/02	Braking resistor for Compax3 S300 units (740 W continuous, 8900 W peak)
BRM04/03	Braking resistor for Compax3 S300 amd MP20D6 units (1500 W continuous, 18000 W peak)
BRM09/01	Braking resistor for Compax3 S100 units (570 W continuous, 6900 W peak)
BRM10/01	Braking resistor for Compax3 S150V4 units (570 W continuous, 6900 W peak)
BRM11/01	Braking resistor for Compax3 H0xx units (3500 W continuous, 19.3 kW peak)
BRM12/01	Braking resistor for Compax3 H1xx units (4500 W continuous, 24.8 kW peak)
BRM13/01	Braking resistor for Compax3 MP10D6 (500 W continuous)
BRM14/01	Braking resistor for Compax3 MP20D6 (500 W continuous, two 15ohm in series)
EMC Accessories	
MDR01/04	Compax3 motor output filter (rated up to 6.3 A continuous current motors)
MDR01/01	Compax3 motor output filter (rated up to 16 A continuous current motors)
MDR01/02	Compax3 motor output filter (rated up to 30 A continuous current motors)
NFI01/01	Mains Filter* for Compax3 S025, S063 units
NFI01/02	Mains Filter* for Compax3 S038, S075, S150 units
NFI01/03	Mains Filter* for Compax3 S300 units
NFI02/01	Mains Filter* for Compax3, 50A
NFI02/02	Mains Filter* for Compax3, 90A
NFI02/03	Mains Filter* for Compax3, 125A & 155A
NFI03/01	Mains Filter* for Compax3, 25A for C3MP10D6 power supply
NFI03/02	Mains Filter* for Compax3, 25A for C3MP20D6 power supply
Fieldbus & HEDA Accessories	
71-028656-xx	Shielded ETHERNET Powerlink cable (from ACR to Compax3/Aries)
71-017635-01	5' cable, HEDA bus cable
BUS07/01	HEDA bus termination plug AND termination for C3M axis module communication bus
BUS08/01	Profibus cable connector with integral bus terminal switch (plug only)
BUS10/01	CANopen cable connector with integral bus terminal switch (plug only)
Compax3 I10 T10 Drive Command Cables	
71-021625-XX	Compax3 I10 T10 drive-to-6K analog command cable (torque, velocity mode only)
71-021108-XX	Compax3 I10 T10 drive-to-ACR analog command cable (torque, velocity mode only)

-XX denotes cable length in feet; available in 4' and 10' lengths.
* For Class A (EMC) compliance for commercial or residential applications where motor cable lengths exceed 33 feet (10 m).
** Required for C3M; not used for C3S/H.

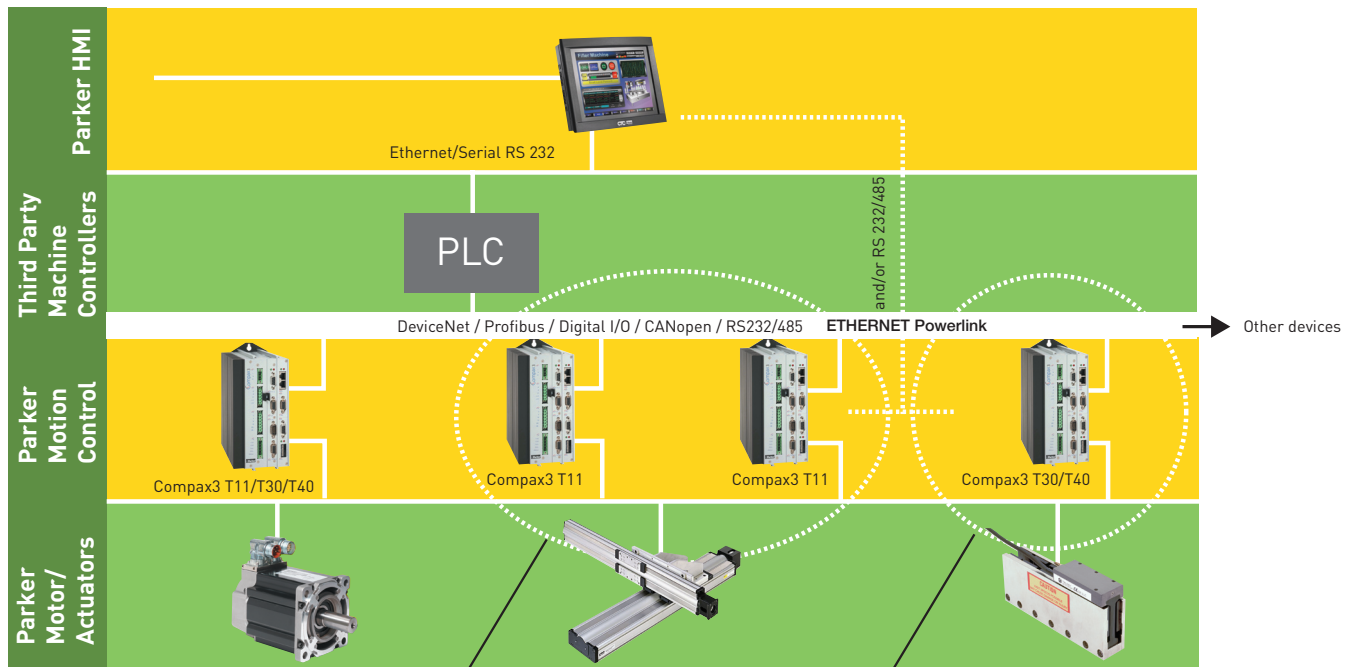## BDM01/01

Compax3 diagnostic interface module

The BDM01/01 is a palm-sized, transportable diagnostic module that can be used to transmit drive configuration data to/from multiple Compax3 units, without the need for using a PC. BDM01/01 features include:
- Upload/download transfer of drive configuration files to other Compax3 units*
- Online display of drive, error status
- Online modification of drive parameters, such as error reset, jogging, motor brake open/close, tuning gains, etc.**
- Plugs into RS232 port; hot-swappable
- Multi-language capable – English, German, French
- Modification of up to 15 user-defined program variables when used with Compax3 T30 or T40 units

* Identical control level
** Features depend on control level

Compax3 System Architecture

Parker HMI

Ethernet/Serial RS 232

Third Party Machine Controllers

PLC

and/or RS 232/485

DeviceNet / Profibus / Digital I/O / CANopen / RS232/485   ETHERNET Powerlink   → Other devices

Parker Motion Control

Compax3 T11/T30/T40   Compax3 T11   Compax3 T11   Compax3 T30/T40

Parker Motor/Actuators

T11
1. Fast, Easy Setup - No code to learn
2. 31 unique motion profiles
3. PLC maintains all motion control execution, conditional, and math tasks
4. Requires external logic to make all control decisions

T30/T40
1. Simple to Complex Motion
2. Fully programmable, IEC61131-3 controller
   - Access to all internal data/status registers (i.e., current, velocity)
   - Make motion-related decisions based on values and conditions
3. Stand-alone or PLC controlled
4. Fully programmable and expandable I/O

Online Training

I11T30

I12T11

I11T11

I10T10

Optimization

Location parkermotion.com

Compax3 Video Training Series
Short, Easy-to-understand, step-by-step video tutorials for:

1) Software navigation
2) Drive selection
3) Drive commissioning
4) Motion profile configuration
5) Making motion
6) Oscilloscope and optimization

Parker Automation