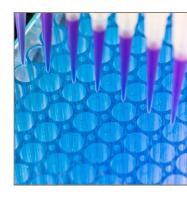




ZFA SeriesOptomechanical Focusing Nano Positioner





Achieve nanometer level stability in milliseconds

For instrument builders who require nanometer level stability and ultra low settling times, the Parker ZFA offers industry leading performance

The Parker ZFA is a precision machined, crossed roller guided, voice coil driven positioner utilizing the latest in linear encoder technology, with selectable integration features to match the application need.



With industry leading natural frequencies, the ZFA provides stabilities on the nanometer scale. These, combined with single digit nanometer resolutions, allow for rapid step and settle moves, increasing image quality and throughput.

Precision Objective Bracket Alignment

Integral carriage datum features allow factory alignment of objective bracket to travel path. Base datum features allow for easy integration of the ZFA into instruments. Datum features are present with or without an included objective bracket for alignment in the field.



Features

- 95 x 90 x 36 form factor
- Up to 9 mm of usable travel
- Up to 1 kg objective mass with internal magnetic counterbalance
- Up to 2 kg objective mass with optional external counterbalance
- Included encoder reference mark
- Adjustable hard stops
- Non-moving cable design
- CE and RoHS Compliance



Selectable Levels of Integration

Included Objective Mounting Bracket

- M25-M32, SM1, and RMS mounting
- · Custom brackets available

Configurable Internal Magnetic Counterbalance

- Objective masses up to 1 kg
- · Non-contact design
- Internal mounting

Optional Additional External Magnetic Counterbalance

- Objective masses from 1 to 2 kg
- External mounting
- · Non-contact design



ZFA Series - Basic Specifications

	Units	ZFA
Travel Range	mm	9
Travel (Hard Stop to Hard Stop)	mm	9.5
Resolution (Digital Encoder)	nm	2.5
Positional Accuracy over full travel (1),(2)	μm	+/- 4
Positional Accuracy over 1mm travel (1),(2)	μm	1
Positional Repeatability over full travel (1),(2)	nm	+/- 250
Standstill Stability (1),(2),(3),(4)	nm (rms)	5
Step and Settle Capability (1),(2),(3),(4)	nm	100nm step and settle within +/-15nm <15ms
Max Velocity (2.5nm digital encoder) Requires minimum of 20 Mhz encoder input	mm/ sec	32
Continuous Motor Force	N	4
Peak Motor Force	N	10
Stage Mass (No bracket)	kg	0.96
Overall Dimension (excluding bracket)	LxWx H (mm)	95 x 90 x 36 101 x 90 x 36 (Includes cable clearance)

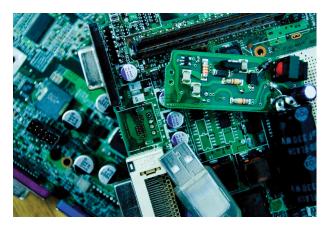
⁽¹⁾ Stage mounted to granite surface, 2.5 micron optical encoder.

⁽²⁾ Measurements taken at 35 mm above the center of the carriage.

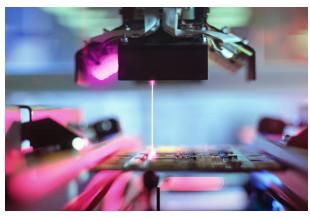
⁽³⁾ Please see tables on page 7-11 for more details.

⁽⁴⁾ Possible performance highly dependent on other system design factors, including drive and control. Contact factory for details.

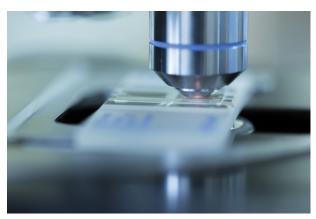
ZFA Application Solutions



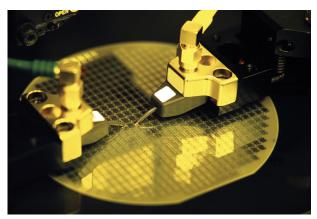
Electronics Manufacturing



Metrology



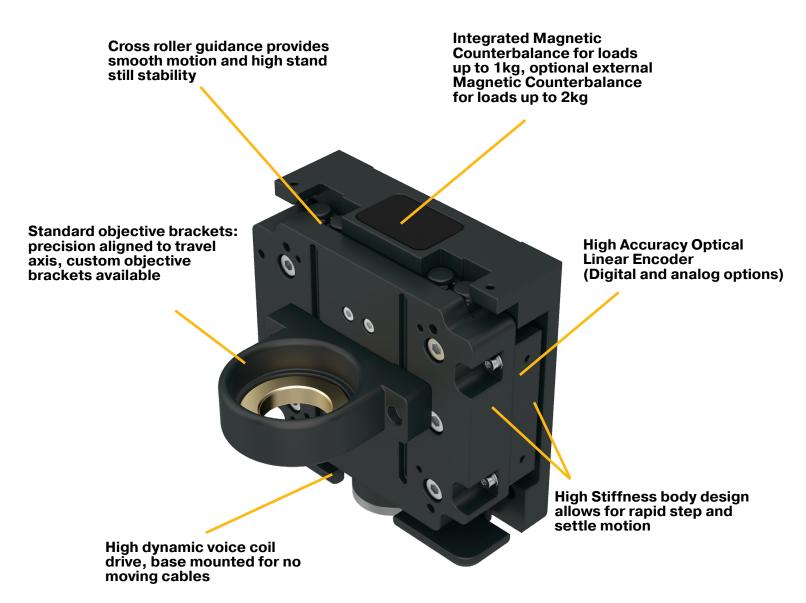
Life Sciences



Semiconductor

For the fields of digital pathology, Next-Generation Sequencing dynamic metrology, and laser processing, the ZFA provides high bandwidth critical to in motion imaging applications. Rapid step and settle response reduces device cycle times contributing to reduced costs per run. The non-contact voice coil drivetrain provides consistent performance across instrument life, greatly increasing performance and reducing total cost of ownership. High degrees of stand still stability allow for never before seen image quality and resolution. Industry leading load capacities allow for larger than typical objective lenses, increasing field of view and reducing travel requirements on scan axes. In some cases, two axis scanning can be reduced to a single axis of motion, accelerating instrument design cycles, reducing footprint, and reducing cost.

ZFA Design Overview



CE and RoHS Compliance

The ZFA conforms to both CE and RoHS directives as standard.







Performance Specifications

ParameterUnitsSpecificationTravel Range (Usable)mm9Travel (Min. Hard Stop to Hard Stop)mm9.5Max Travel (Hard Stop to Hard Stop)mm10.5	
Travel (Min. Hard Stop to Hard Stop) mm 9.5	
Max Travel (Hard Stop to Hard Stop) mm 10.5	
Top Hard Stop to Index Location mm 4.9 to 5.1	
Index to Bottom Hard Stop Location mm 4.4 to 5.6	
Resolution (Digital Encoder) nm 2.5	
Resolution (1 V p-p) Sin/Cos Encoder) Divided by controllers A/D resolution	
Positional Accuracy over full travel (1)(2) μm +/-4	
Positional Accuracy over 1 mm travel (1)(2) μm +/-1	
Positional Repeatability over full travel (1)(2)(4) μm +/-0.25	
Angular Pitch per mm (1)(3) Arcsec +/-2	
Angular Roll per mm (1)(3) Arcsec +/-2	
Angular Yaw per mm (1)(3) Arcsec +/-2	
Index (Home) Repeatability (1)(2)(3)	
Standstill Stability (1)(2)(3)(4) nm (rms) 5 to 15	
Max Velocity (2.5nm digital encoder, 20 Mhz clock frequency capability required) mm/sec 32	
Max Acceleration / Deceleration g's Load Dependent	
Continuous Motor Force N 4.19	
Peak Motor Force N 10	
Moving Mass (No bracket) Kg 0.39	
Moving Mass (with std Objective bracket) Kg 0.455	
Stage Mass (no bracket) Kg 1.15	
Overall Dimension (excluding bracket) L x W x H (mm) 95 x 90 x 36 101 x 90 x 36 (includes cable clearance)	e)
Payload Capacity - With Internal Counterbalance (5) g 1,050	
Payload Capacity - With Optional External g Counterbalance (5)	

^{(1).} Measured at optical center line.

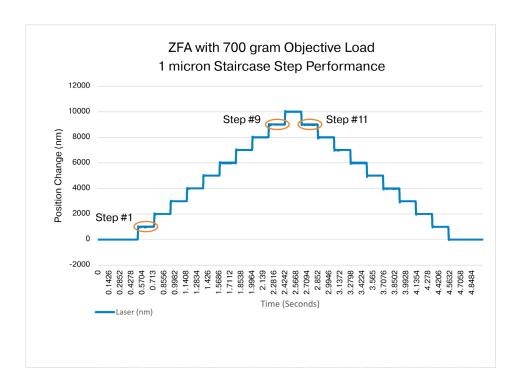
^{(2).} With 2.5 nm resolution encoder.

^{(3).} Mounting to a frame with a Minimum Natural Frequency >1 KHz and mounting surface flatness of 8 microns or better.

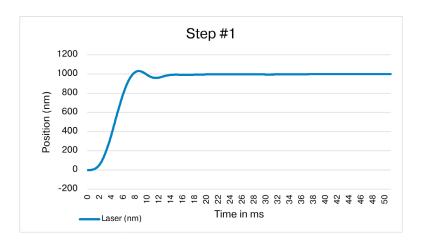
^{(4).} Possible performance highly dependent on other system design factors, including drive and control. Contact factory for details.

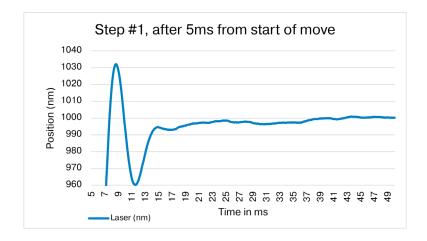
^{(5).} Total payload mass including any mounting brackets.

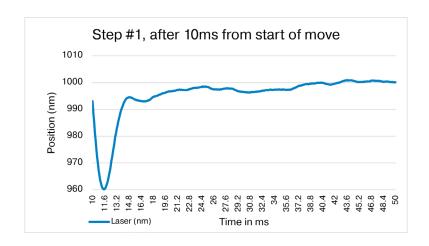
Step and Settle Response



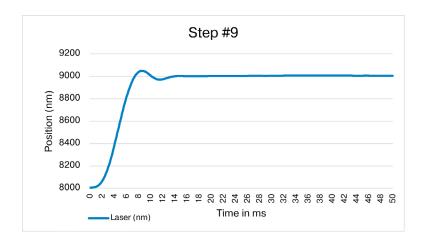
Step and Settle Response: Step One

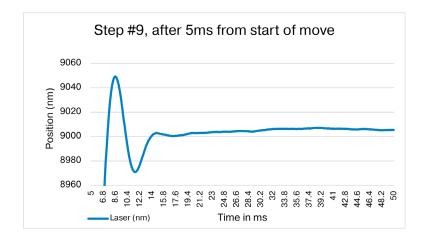


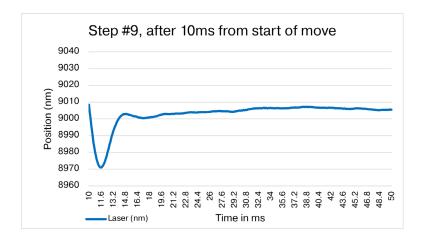




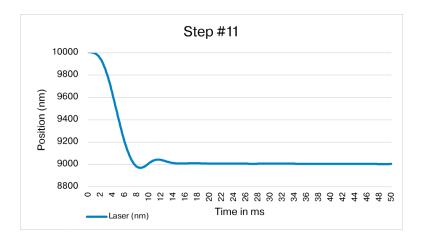
Step and Settle Response: Step Nine

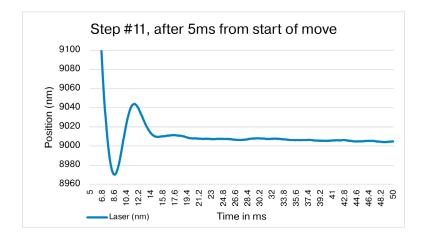


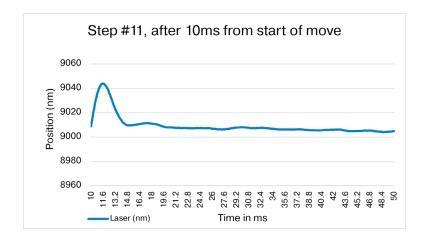




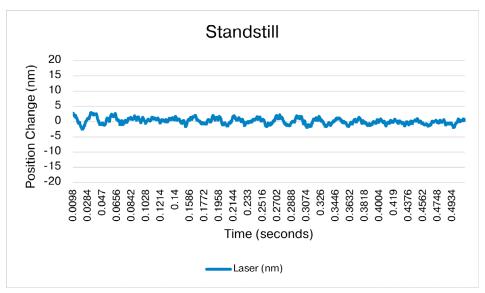
Step and Settle Response: Step Eleven







Standstill Stability



Note: Possible performance highly dependent on other system design factors, including drive and control. Contact factory for details.

Motor Specifications

	Units	
Stall Force Continuous ¹	N	4.19
Stall Curret Continuous 1	Amps	1.35
Peak Force ⁴	N	10.00
Peak Current ⁴	Amps	3.23
Voltage Constant ²	Volts/m/s	3.10
Force Constant ²	N/ Amps	3.10
Resistance ⁸	Ohms	3.50
Inductance ³	mH	1.05
Maximum Bus Voltage	Volts DC	50
Thermal Resistance Winding-Ambient	°C/watt	9.43
Thermal Resistance Winding-Case	°C/watt	3.30
Thermal Resistance Case-Ambient	°C/watt	6.13
Motor Thermal Time Constant ⁶	Minutes	1.80
Winding Thermal Time Constant ⁷	Minutes	1.20
Electrical Time Constant ⁵	Millisecs	0.30
Rated Winding Temperature	°C	100
Rated Ambient Temperature	°C	25

- 1. @ 25°C ambient, 100°C winding temperature
- 2. Measured Line to Line, +/- 10%
- 3. Inductance measurement @1Khz (Coil fully inside magnet stator housing)
- 4. Initial winding temperature must be 60°C or less before Peak Current is Applied
- 5. Time for motor value to reach 63% of its final current after a step change in voltage $\,$
- 6. Time the motor takes to reach 63% of its final temperature, given constant power
- 7. Time for the winding to reach 63% of its final temperature rise above the rest of the motor, given constant power
- 8. Measured between motor leads at 25°C. At 100°C, multiply resistance by 1.295 (75°C rise * 0.393%/°C)

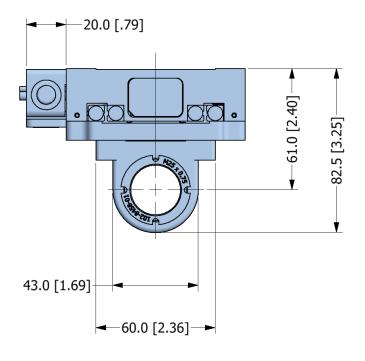


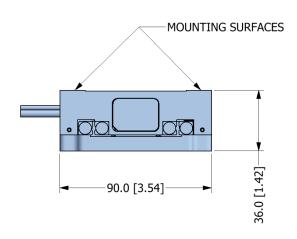


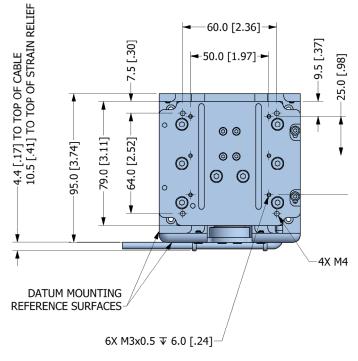
Encoder Specifications

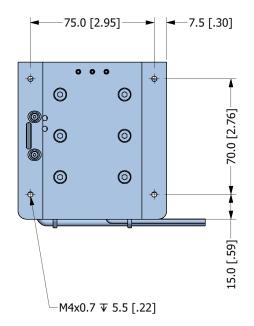
Encod	er Type	Resolution	Scale Accuracy, un-mapped (+/-µm/m)	Clock Speed (MHz)	Supply Voltage (V)	Current (mA)	Scale Thermal Expansion (µm/m/°C)
E 5	Digital Incremental (Differential)	2.5 nm	5	20	5 -5%/+10%	200	10.1
sc	1V P-P Sin/Cos Incremental (Differential)	20 µm / Controller DAC	5	n/a	5 +/-10%	100	10.1

Dimensions - mm [in]

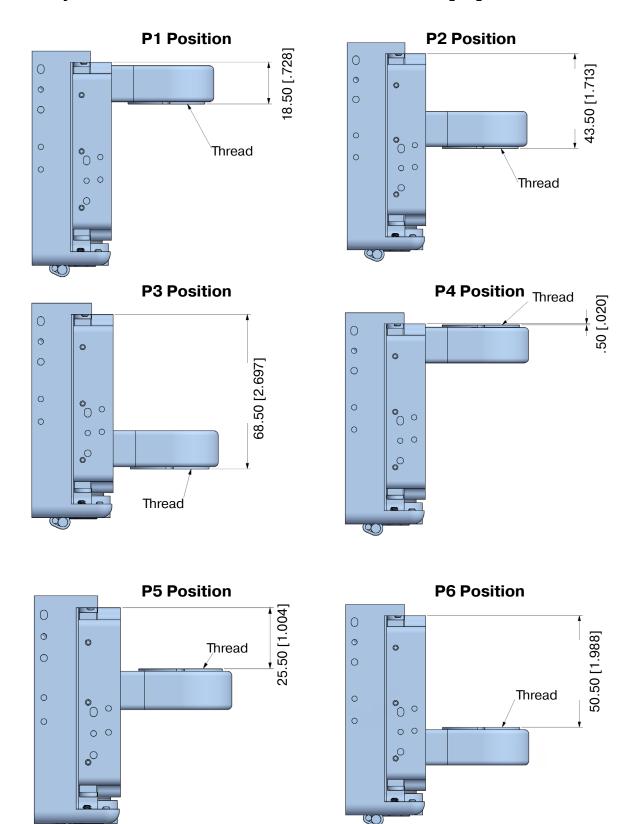






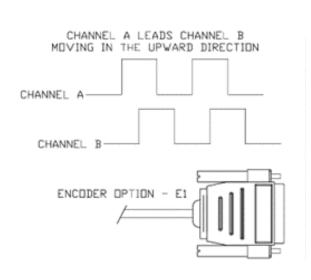


Objective Positions Dimensions - mm [in]



ZFA Feedback Cable Specifications

ZFA E1 Encoder Option - Digital Encoder Connector Pinout

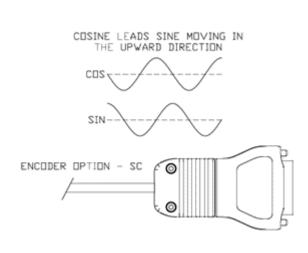


Digital Encoder With 15 Pin Male D-SUB				
Color	AWG	PIN#	Function	
BRN	32	7, 8	5V	
WHT	32	2, 9	0V	
RED	32	14	A+	
BLU	32	6	A-	
YEL	32	13	B+	
GRN	32	5	B-	
VLT	32	12	Z+	
GRY	32	4	Z-	
PNK	32	11	NO CONNECT	
BLK	32	10	NO CONNECT	
ORG	32	3	E	
CLR	32	1	CAL	
SHLD		CASE	SHLD	

ZFA E1 Encoder Option - Specification

Description	Specification
+5VDC Supply Voltage	-5%/+10% with a maximum current of 200mA

ZFA SC Encoder Option - Analog Encoder Connector Pinout



Digital Encoder With 15 Pin Male D-SUB				
Color	AWG	PIN#	Function	
BRN	32	4, 5	5V	
WHT	32	12, 13	0V	
RED	32	9	COS+	
BLU	32	1	COS-	
YEL	32	10	SIN+	
GRN	32	2	SIN-	
VLT	32	3	Z+	
GRY	32	11	Z-	
PNK	32	7	NO CONNECT	
BLK	32	8	NO CONNECT	
ORG	32	14	CAL	
CLR	32	6	SETUP	
SHLD			INNER SHLD	
SHLD		CASE	OUTER SHLD	

ZFA SC Encoder Option - Specification

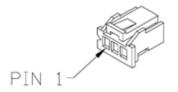
•	
Description	Specification
+5VDC Supply Voltage	+/-10% with a maximum current of 100mA

ZFA Power Cable Specifications

Stage Direction



Motor Connector Input

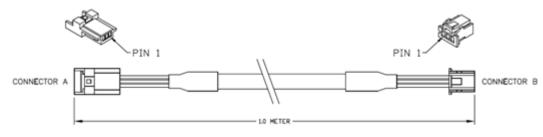


Motor Power Connector			
Color	AWG	PIN#	Function
BLK	24	3	PHASE N
RED	24	2	PHASE P
DRAIN	24	1	DRAIN

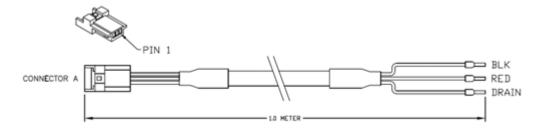
Feedback Extension Cable - 15 Pin D-Sub Male to Female

Parker Part Number	L-Com Part Number	Description
003-5430-1	CSM15MF-1	Cable, DB15M/F Molded, 1.0Ft
003-5430-2.5	CSM15MF-2.5	Cable, DB15M/F Molded, 2.5Ft
003-5430-5	CSM15MF-5	Cable, DB15M/F Molded, 5.0Ft

Motor Extension Cable Male to Female - 006-2983-01.00



Motor Extension Cable Flying Leads - 006-2982-01.00



Ordering Information

Fill in an order code from each of the numbered fields to create a complete part number

Order Example:

1 2 3 4 5 6 7 8 ZFA 090 - 09 - E5 - V - P3 - T5 - 1000

- (1) Series
 - **ZFA** Series
- (2) Base Size (width in mm)
 - **090** 90 mm Base
- Travel
 - **09** 9 mm Travel
- (4) Encoder Option
 - E5dits Digital 2.5 nm resolution
 - SC Sine / Cosine
- Travel Orientation
 - H HorizontalV Vertical
- 6 Objective Bracket Position
 - P0 None
 - P1 Bracket Top/ Objective Down
 - P2 Bracket Middle/ Objective
 - Down
 - P3 Bracket Bottom/ Objective
 - Down
 - P4 Bracket Top/ Objective Up
 - P5 Bracket Middle/ Objective Up
 - P6 Bracket Bottom/ Objective
 - Up

Objective Thread

- **T0** M32 X 0.75 No Adapter
- **T1** M25 X 0.75
- **T2** M26 X 0.706
- **T3** M27 X 0.75
- **T4** M27 X 1
- **T5** SM1 (1.035 40 / UNS 2B)
- **T6** RMS (0.800" 36 / UNS 2B)
- Objective Mass
 - XXXX Objective Mass in Grams

FM Sales Offices

Australia

Parker Hannifin (Australia) Pty Ltd. 9 Carrington Road Castle Hill NSW 2154 Australia

Tel: +61 (0) 2 9842 5111

Brazil

Parker Hannifin Ind. Com Ltda. Estrada Municipal Joel De Paula 900 São Josã Dos Campos 12247-015 São Paulo Brazil Tel: 0800 727 5375

Email: automation.brazil@parker.com

Canada

Parker Hannifin (Canada) Inc. 160 Chisholm Dr Milton, Ontario L9T 3G9 Tel: 905-693-3000

Email: miltoncustservice@parker.com

China

Parker Hannifin Motion & Control (Shanghai) Co., Ltd 280 Yunqiao Rd. Jin Qiao Export Processing Zone Shanghai 201206, China Tel: 86-21 28995000

France

Sales Company France 142 Rue De La Foret Contamine-Sur-Arve France 74130 Tel: +33 (4) 5025 8025

Germany

Electromechanical Europe Parker Hannifin GmbH & Co KG Robert-Bosch-Strasse 22 D-77656 Offenburg Germany Tel: +49 (0) 7815090

Email: em-motion@parker.com

India

Parker Hannifin India PVT, LTD. Plot El-26, Midc Ttc Industrial Area Mahape Navi Mumbai, 400709 India Tel: 91-22-41242500

Italy

Sales Company Italy Via Caboto 1 Corsico Corsico (Milano) 20094 Italy Tel: 0039 02 451921

Email: parker.italy@parker.com

Korea

Parker Hannifin Korea 9th Floor KAMCO Yangjae Tower 949-3 Dogok 1-dong Gangnam-gu Seoul 135-860, Korea Tel: 82-2-559-0454

Mexico

Antiguo Camino A San Lorenzo 338 Zona Industrial Toluca, Mexico 54963 Tel: +52 722 275-4200 Email: contacto@parker.com

Singapore

Parker Hannifin Singapore Pte Ltd 11 Fourth Chin Bee Road Singapore 619702 Tel: +65 6887 6300

Taiwan

Parker Hannifin Taiwan Co., Ltd 8F No 22 Wuquan 7th Road Wuku District New Taipei City, Taiwan 24890 Tel: +886 2 2298 8987 enquiry.taiwan@parker.com

Thailand

Parker Hannifin (Thailand) Co., Ltd. 1265 Rama 9 Road, Pattanakarn Suanluang, Bangkok 10250 Thailand Tel: +66 2186 7000

Email: infoTH OTH@parker.com

UK

Tachbrook Park Drive Tachbrook Park Warwick CV34 6TU Tel: +44 (0) 1926 317878 Email: parker.uk@parker.com

Parker Hannifin Ltd.

USA

EMC Division HQ 850 Arthur Avenue Elk Grove Village, IL 60007 Tel: 800-221-9257 emn.service@support.parker.com

EMC Electromechanical Products 1140 Sandy Hill Road Irwin, PA 15642 Tel: 800-358-9070

emn.service@support.parker.com

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ZFA Series Catalog

November 2024



Parker Hannifin Corporation **Electronic Motion and Controls Division** 1140 Sandy Hill Road Irwin, PA 15642 parker.com/emc