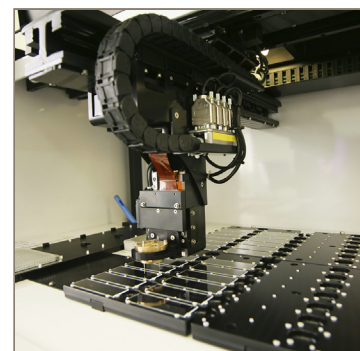


## XLM Series

Linear Motor Stages for Positioning with  
Ultra-High Precision



ENGINEERING YOUR SUCCESS.

# XLM Series Linear Motor Stages

Maximize your accuracy while keeping a low profile

For machinery or instrument builders who need smooth motion and high precision, Parker offers the XLM series. The XLM is a linear positioner that provides micron level precision in three different profile widths from 125mm to 200 mm. Its modular design allows for easy assembly of multi-axis systems.

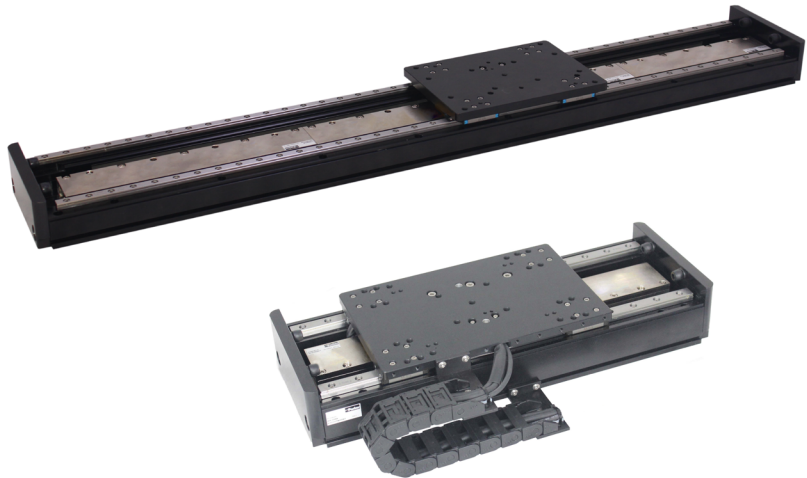
The XLM series is a precision machined, profiled guide linear positioner which is driven with linear servo motor technology, and utilizes selectable levels of linear encoder technology that are configured to match the application need.

Within each form factor, Parker offers three options:

- Open Design for the most cost effective and lowest profile solution
- Covered Design for protection where an open design is not practical
- Sealed Design for additional environmental protection

The XLM family of positioners are ideal for a variety of applications, ranging from imaging systems in digital pathology equipment to metrology instruments in semiconductor or electronics manufacturing. Designed with low Abbe error, consistently accurate positioning is provided.

Know that the XLM has been designed with typical instrument regulations and certifications in mind as all versions meet CE and RoHS requirements.



One of the biggest advantages offered by the XLM series is its modular design, allowing multiple axis systems to be assembled easily. Whether the application calls for a relatively simple X-Y configuration or a more complex multi-axis gantry. Integrated cable management helps to provide a clean and easy to install package, saving on the cost of additional components and the time to install them.

Finally, the XLM provides ease of connectivity. Parker's proven range of servo drives and controls are available for a complete solution from a single, trusted source, but the flexibility of the XLM allows the use of a wide range of drives and controls provided by others.

## Features

- **Three form factors: 125mm, 145mm, and 200mm width**
- **Three enclosure options**
- **Six different linear encoder options**
- **Ironless linear motor technology**
- **Standard travel options ranging from 40mm to 1500mm stroke**
- **Efficient cable management system**
- **Integrated and adjustable limit sensing**
- **Complete error mapping on each unit with linear slope correction value provided**
- **CE and RoHS Compliance**



# XLM Series Linear Motor Stages

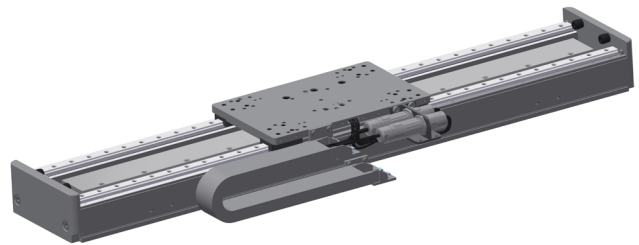
## Configurations for a variety of environments

Applications for precision machinery and instruments can vary from factory floor to clean room. In some cases the stage is protected inside machinery where an open design allows for maximum use of space, while in others it is subject to adverse conditions requiring integrated protection. These variables were taken into account in the design of the XLM family, resulting in three distinct product configurations to cover the gamut of possibilities.

### Open Design - Type UA/UB

- **Lower profile**
- **Narrower width**
- **Less operating friction**

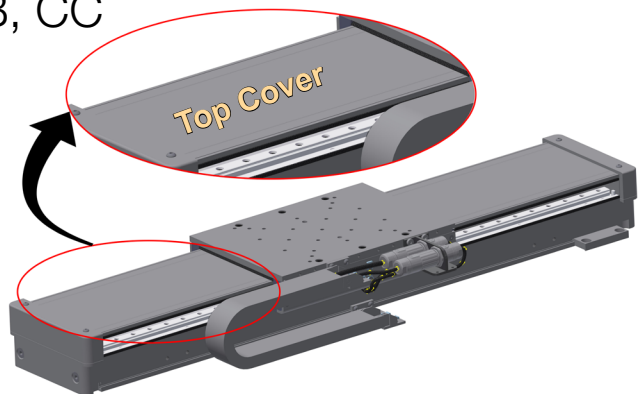
If the XLM will be installed in a protected area, the economical open design can be an attractive option. Lightest in weight and physically smallest of the three styles, the open design also operates with less friction for higher efficiency.



### Covered Design - Type CA, CB, CC

- **Solid top cover**
- **Protection against falling materials**
- **No increase in friction**

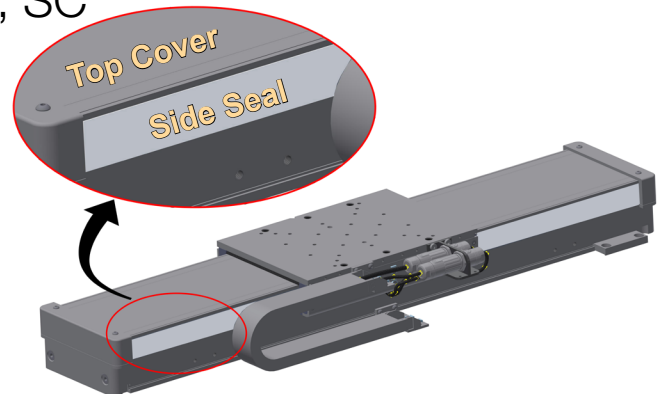
The covered design incorporates a solid **top cover** which provides effective protection against material or objects that may drop onto the stage. Friction is not increased by the cover, so operating efficiency is not affected.



### Sealed Design - Type SA, SB, SC

- **IP30 environmental protection**
- **Protection against objects >2.5mm**

The sealed version of the XLM takes the covered version a step further with **side seals** in addition to a solid top cover. This provides ingress protection to IP30, preventing entry of foreign objects 2.5mm and larger.



# XLM Series Linear Motor Stages

Maximize  
Instrument  
Performance —  
Not Its Size

The XLM linear positioner offers instrument builders optimized packaging of a linear motor, guidance and encoder, as well as limits in one complete solution. In addition, the XLM has been designed with typical instrument regulations and certification in mind, and is both CE and RoHS compliant for all standard products.

Best of Breed  
Encoder  
Technology

The XLM positioner offers instrument builders a variety of different encoding technologies and resolutions to select from.

Standard incremental optical resolutions range from one micron all the way down to ten nanometers. This optical encoder offers exceptionally low sub-divisional errors, allowing for very tight control over velocity ripple.

The analog (sine/cosine) encoder option is an ideal way to reach high resolution when paired with controls using interpolating technology to achieve high precision and high speed.

The BiSS-C encoder option provides feedback for applications requiring absolute positional information eliminating the needs for end of travel sensors.

## XLM Series - Basic Specifications

	Units	XLM125	XLM145	XLM200
Size - Open style (W x H)	mm	125 x 55	145 x 65	200 x 77
Travel (Max)	mm	1010	1225	1500
Normal Load (Max)	kg	170	300	630
Thrust (Max, less friction) <sup>3</sup>				
Continuous	N	27.47	79.35	127.35
Peak	N	98.42	262.06	414.04
Acceleration (Max – no load)	G	3	3	3
Speed (Max – no load)	m/s	3	3	3
Rated Bus Voltage	VDC	330	330	330
Repeatability <sup>1</sup>	µm	+/- 0.5	+/- 0.5	+/- 0.5
Accuracy <sup>1,2</sup>	µm	+/- 4	+/- 4	+/- 8
Straightness & Flatness <sup>1</sup>	µm	+/- 3	+/- 3	+/- 4
Feedback Compatibility				
1 µm Optical (incremental)		•	•	•
0.1 µm Optical (incremental)		•	•	•
0.01 µm Optical (incremental)		•	•	•
Analog Sine/Cosine		•	•	•
0.05 µm BiSS-C (absolute)		•	•	•
0.005 µm BiSS-C (absolute)		•	•	•

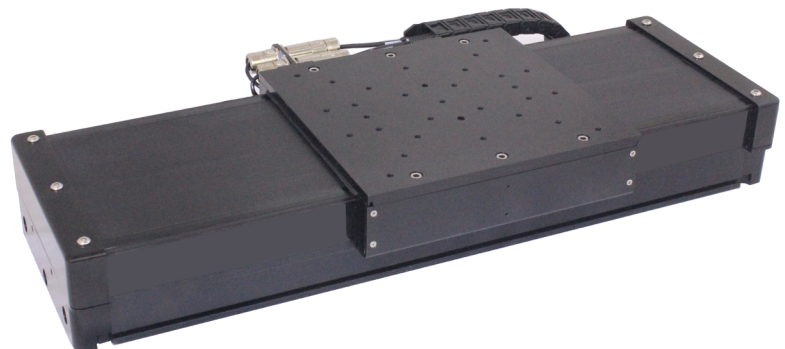
<sup>1</sup> Stage mounted to granite surface, 0.01 micron optical encoder

<sup>2</sup> Measurements taken at 35 mm above the center of the carriage, with linear slope correction.

<sup>3</sup> Please see tables on page 8 - 13 for more details.

## Laser Grade Precision

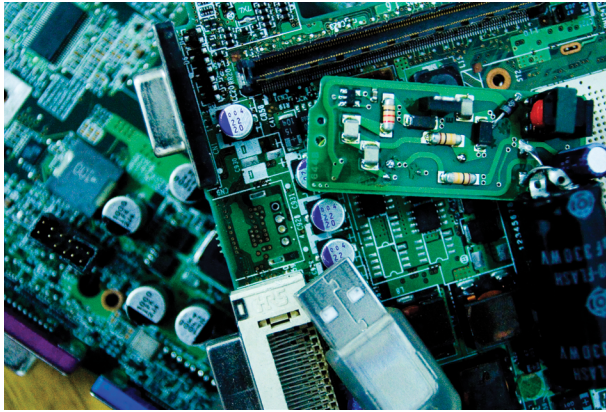
Every XLM stage is thoroughly tested with a laser interferometer to ensure that it meets product specification. Parker also provides test data, which when used with controller compensation, can yield higher stage accuracy.





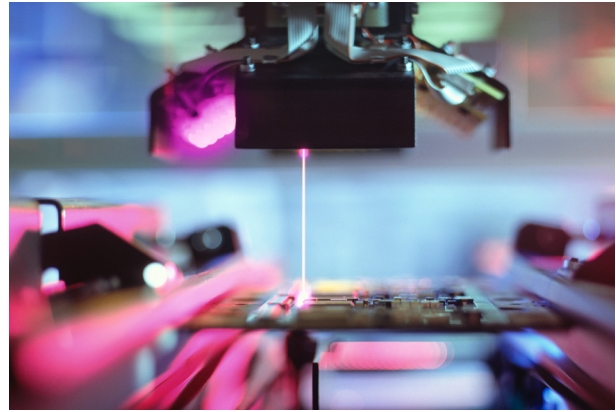
# XLM Series Linear Motor Stages

## XLM Application Solutions



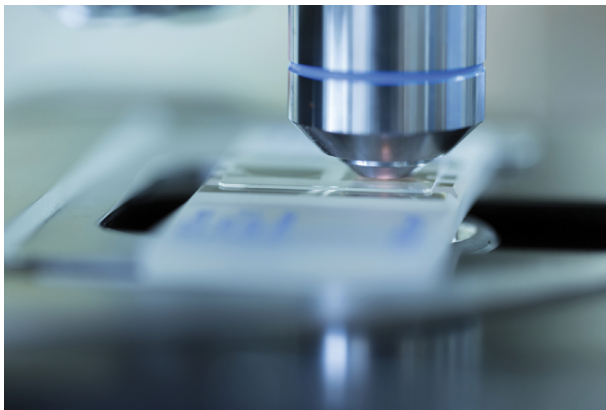
### Electronics Manufacturing

The XLM is an ideal positioner for high throughput electronics manufacturing equipment, as its design combines high performance linear motor technology with a variety of high resolution feedback devices for quick, precise placement of miniature components. The XLM provides a robust solution for inspection systems, as its direct drive technology has been designed to stand the test of time.



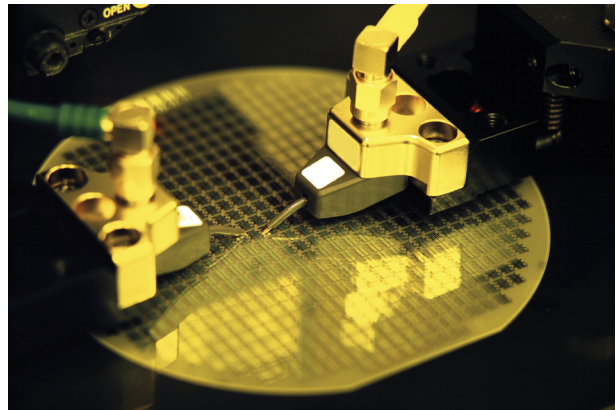
### Metrology

Dynamic metrology applications where measurement data is collected while either the measurement sensor or the unit under measure are in motion have a low margin of tolerance for errors in positioning. The XLM offers a reliable and accurate platform for these as well as static metrology and focusing applications found in inspection, optical and laser profilometry, microscopy, and more.



### Life Sciences

For the fields of digital pathology and cellular therapeutics, the XLM provides a high precision, miniature means of picking and placing cells for cell therapy instruments. These instruments require highly repeatable positioning to pick cells of interest and incubate them for future cell based therapies.

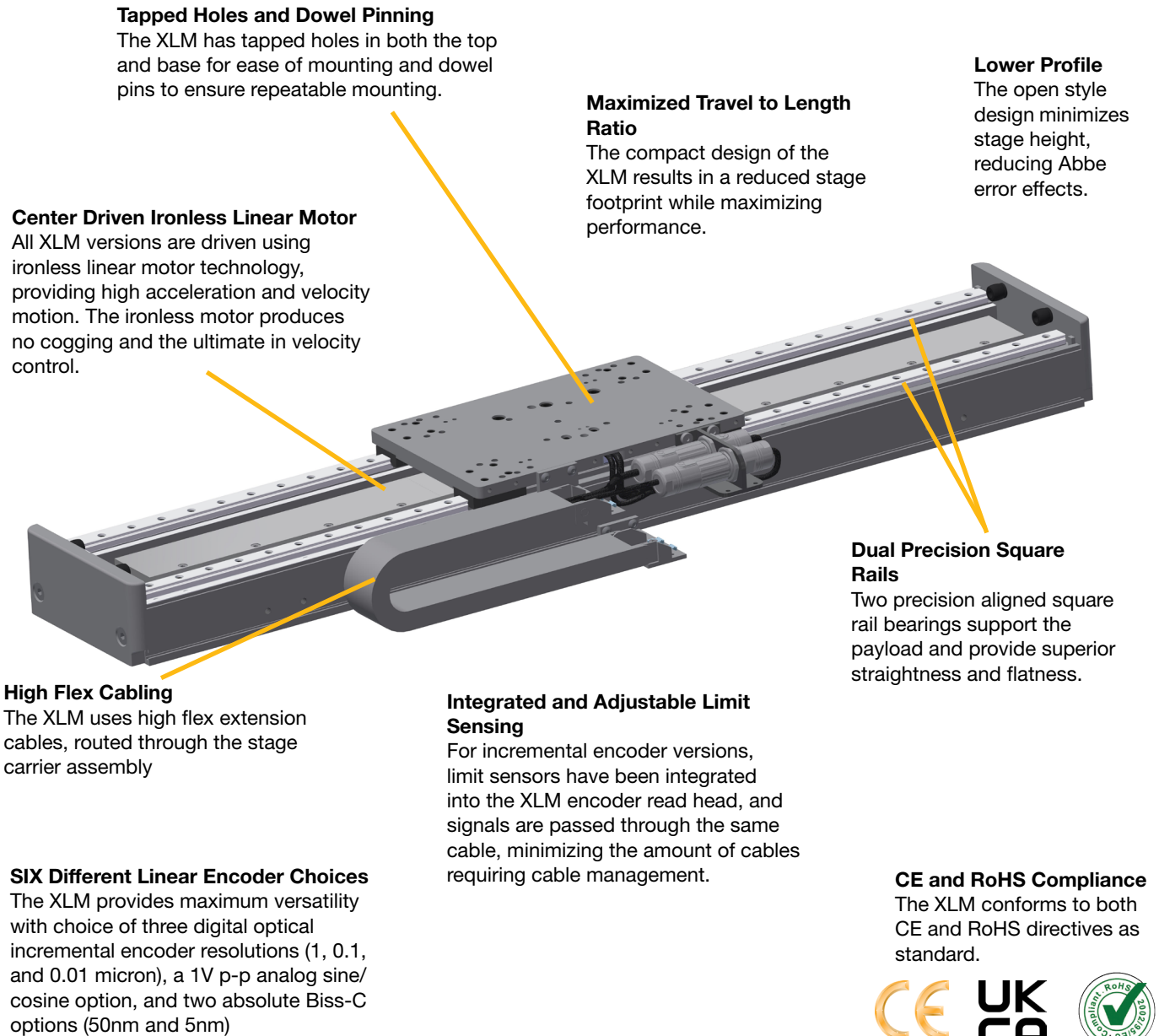


### Semiconductor

Given the combination of its superior geometric performance and compact packaging, the XLM series positioner is ideal for semiconductor handling and metrology applications. Regardless of whether you are examining features on the micro or nano-scale, the XLM can be adapted to meet the need with its wide array of encoder options.

# XLM Series Linear Motor Stages

## XLM Design Advantages Open Style (U Version)



# XLM Series Linear Motor Stages

## XLM Design Advantages Covered/Sealed Style (C, S Versions)

### Tapped Holes and Dowel Pinning

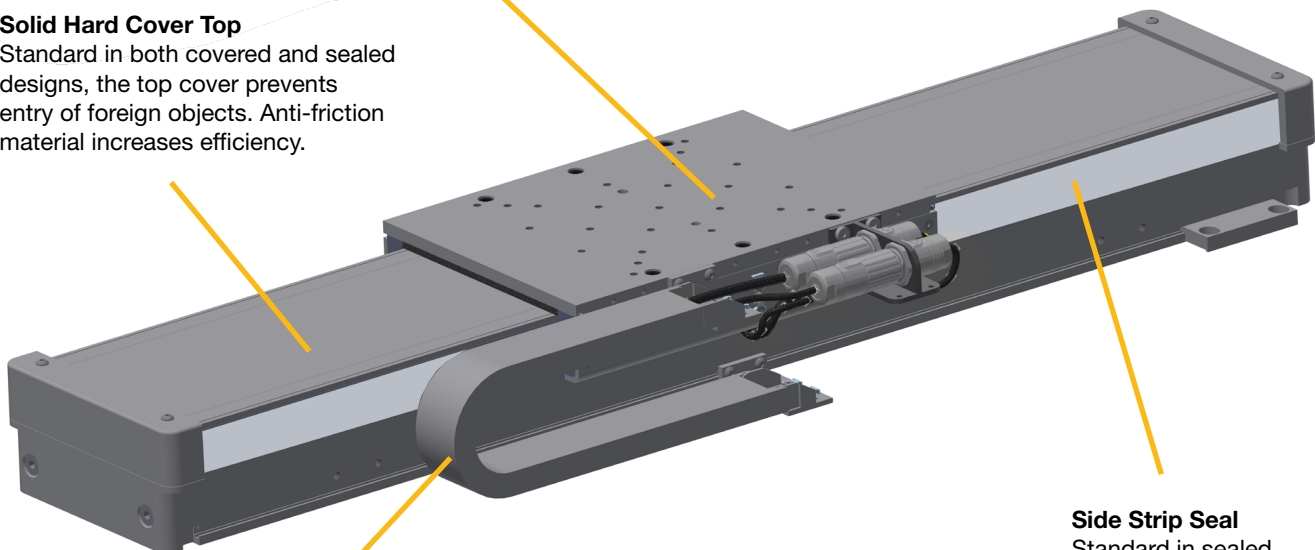
The XLM has tapped holes in both the top and base for ease of mounting and dowel pins to ensure repeatable mounting.

### Solid Hard Cover Top

Standard in both covered and sealed designs, the top cover prevents entry of foreign objects. Anti-friction material increases efficiency.

### Center Driven Ironless Linear Motor

All XLM versions are driven using ironless linear motor technology, providing high acceleration and velocity motion. The ironless motor produces no cogging and the ultimate in velocity control.



### High Flex Cabling

The XLM uses high flex extension cables, routed through the stage carrier assembly

### Integrated and Adjustable Limit Sensing

For incremental encoder versions, limit sensors have been integrated into the XLM encoder read head, and signals are passed through the same cable, minimizing the amount of cables requiring cable management.

### Side Strip Seal

Standard in sealed version, these provide enhanced ingress protection to IP30 standard.

### SIX Different Linear Encoder Choices

The XLM provides maximum versatility with choice of three digital optical incremental encoder resolutions (1, 0.1, and 0.01 micron), a 1V p-p analog sine/cosine option, and two absolute Biss-C options (50nm and 5nm)

### CE and RoHS Compliance

The XLM conforms to both CE and RoHS directives as standard.



# XLM Series Linear Motor Stages

## Performance Specifications - XLM125

Specification	Units												
Travel (U Version)	mm	110	160	210	260	310	410	510	610	710	810	910	1010
Travel (C, S Versions)	mm	100	150	200	250	300	400	500	600	700	800	900	1000
Accuracy <sup>1</sup>	+/-µm	4	6	8	9	10	12	14	16	18	20	22	24
Resolution	µm	Encoder Dependent (See Encoder Specification)											
Bidirectional Repeatability (Resolution Dependant) <sup>1</sup>	+/-µm	0.5 + Encoder Resolution											
Horizontal Straightness <sup>1</sup>	+/-µm	3	4	4	5	6	8	9	10	12	13	14	15
Vertical Straightness <sup>1</sup>	+/-µm	3	4	4	5	6	8	9	10	12	13	14	15
Pitch <sup>1</sup>	arc sec	≤ 30											
Yaw <sup>1</sup>	arc sec	≤ 30											
Total Stage Mass (U Version) <sup>3</sup>	Kg	5.3	5.9	6.2	6.8	7.3	8.5	9.3	10.5	11.6	12.5	13.7	14.8
Total Stage Mass (C, S Versions) <sup>3</sup>	Kg	8.3	8.9	9.4	10	10.7	12	13	14.4	15.7	16.8	18	19.4

Motor Type		P2											
Moving Mass	Kg	0.8 (U), 2.4 (C,S)											
Continuous Force <sup>2</sup>	N	27.47 (U, C), 19.47 (S)											
Peak Force <sup>2</sup>	N	98.42 (U, C), 90.42 (S)											
Max Speed	m/s	Feedback and Load Dependent (Max 3m/sec)											
Max Acceleration	g's	Feedback and Load Dependent (Max 3g)											

<sup>1</sup> Specifications based on following conditions: Single axis, fully bolted or clamped to AA granite mounting surface, ambient and stage temperature at 20° C, point of measurement centered in carriage, 35mm above the carriage mounting surface.

<sup>2</sup> Continuous and Peak forces shown equal the motor Continuous or Peak force less the RMS frictional resistance of the stage.

<sup>3</sup> Masses include cable management assembly

## Mechanical Specifications - XLM125

Specification	Units	P2 Motor
Maximum Load	Kg	170 <sup>1</sup>
Maximum Pitch Moment Load	Nm	88
Maximum Roll Moment Load	Nm	70
Maximum Yaw Moment Load	Nm	75
Pitch Torsional Spring Rate (C, S Versions)	arc-sec/Nm	1.14
Yaw Torsional Spring Rate (C, S Versions)	arc-sec/Nm	0.60
Roll Torsional Spring Rate (C, S Versions)	arc-sec/Nm	1.62
Pitch Torsional Spring Rate (U Version)	arc-sec/Nm	0.40
Yaw Torsional Spring Rate (U Version)	arc-sec/Nm	0.73
Roll Torsional Spring Rate (U Version)	arc-sec/Nm	1.34
Base Moment of Inertia (Narrow dimension)	kg-mm <sup>2</sup>	28,400
Base Moment of Inertia (Wide dimension)	kg-mm <sup>2</sup>	32,400
Running Friction RMS value over travel (U, C Versions)	N	8
Running Friction Peak value over travel (U, C Versions)	N	12
Running Friction RMS value over travel (S Version)	N	16
Running Friction Peak value over travel (S Version)	N	24
IP Rating		U (Uncovered) version: IP00 C (Covered) version: IP10 S (Sealed) version: IP30 <sup>2</sup>

<sup>1</sup> Normal load centered on carriage with stage in horizontal orientation

<sup>2</sup> IP30 rating requires user to seal all unused mounting holes in carriage and base



# XLM Series Linear Motor Stages

## Motor Specifications - XLM125

	Units	P2
<b>Stall Force Continuous</b> <sup>1</sup>	N	35.47
<b>Stall Current Continuous</b> <sup>1, 4, 8</sup>	Amps (Peak of sine)	5.19
<b>Stall Current Continuous</b> <sup>1, 7</sup>	Amps (DC)	4.49
<b>Stall Current Continuous</b> <sup>1</sup>	Amps (RMS)	3.67
<b>Peak Force</b> <sup>6</sup>	N	106.42
<b>Peak Current</b> <sup>4, 6, 8</sup>	Amps (Peak of sine)	15.56
<b>Peak Current</b> <sup>6, 7</sup>	Amps (DC)	13.47
<b>Peak Current</b> <sup>6</sup>	Amps (RMS)	11
<b>Voltage Constant</b> <sup>3, 4</sup>	Volts/m/s	7.9
<b>Force Constant</b> <sup>9</sup>	N/ Amps (Peak of sine)	6.84
<b>Force Constant</b> <sup>3, 4</sup>	N/Amps (DC)	7.9
<b>Force Constant</b> <sup>3</sup>	N/Amps (RMS)	9.68
<b>Resistance</b> <sup>14</sup>	Ohms	1.71
<b>Inductance</b> <sup>5</sup>	mH	0.5
<b>Maximum Bus Voltage</b>	Volts DC	330
<b>Thermal Resistance Winding-Ambient</b>	°C/watt	1.68
<b>Thermal Resistance Winding-Case</b>	°C/watt	1.04
<b>Thermal Resistance Case-Ambient</b>	°C/watt	0.64
<b>Motor Thermal Time Constant</b> <sup>12</sup>	Minutes	25
<b>Winding Thermal Time Constant</b> <sup>13</sup>	Minutes	1.2
<b>Electrical Time Constant</b> <sup>11</sup>	Millisecs	0.29
<b>Electrical Pitch</b> <sup>10</sup>	mm	60.96
<b>Rated Winding Temperature</b>	°C	100

<sup>1</sup> @ 25°C ambient, 100°C winding temperature

<sup>2</sup> Measured with a 0.76 mm gap

<sup>3</sup> Measured Line to Line, +/- 10%

<sup>4</sup> Value is measured peak of sine wave

<sup>5</sup> +/-30%, Line-to-Line, inductance bridge measurement @1 KHz

<sup>6</sup> Initial winding temperature must be 60°C or less before Peak Current is Applied

<sup>7</sup> DC current through a pair of motor phases of a trapezoidal (six state) commutated motor

<sup>8</sup> Peak of the sinusoidal current in a phase for a sinusoidal commutated motor

<sup>9</sup> Total motor torque per peak of the sinusoidal amps measured in any phase, +/-10%

<sup>10</sup> The distance from the leading edge of a north pole to the leading edge of the next north pole

<sup>11</sup> Time for motor value to reach 63% of its final current after a step change in voltage

<sup>12</sup> Time the motor takes to reach 63% of its final temperature, given constant power

<sup>13</sup> Time for the winding to reach 63% of its final temperature rise above the rest of the motor, given constant power

<sup>14</sup> Measured between any 2 motor leads with delta connection at 25°C. At 100°C, multiply resistance by 1.295 (75°C rise\* 0.393%/°C)



# XLM Series Linear Motor Stages

## Performance Specifications - XLM145

Specification	Units														
Travel (U Version, P3 Motor)	mm	125	175	225	275	325	425	525	625	725	825	925	1025	1225	
Travel (C, S Versions, P3 Motor)	mm	100	150	200	250	300	400	500	600	700	800	900	1000	1200	
Travel (U Version, P4 Motor)	mm	65	115	165	215	265	365	465	565	665	765	865	965	1165	
Travel (C, S Versions, P4 Motor)	mm	40	90	140	190	240	340	440	540	640	740	840	940	1140	
Accuracy <sup>1</sup>	+/-µm	4	6	8	9	10	12	14	16	18	20	22	24	26	
Resolution	µm	Encoder Dependent (See Encoder Specification)													
Bidirectional Repeatability (Resolution Dependant) <sup>1</sup>	+/-µm	0.5 + Encoder Resolution													
Horizontal Straightness <sup>1</sup>	+/-µm	3	4	4	5	6	8	9	10	12	13	14	15	20	
Vertical Straightness <sup>1</sup>	+/-µm	3	4	4	5	6	8	9	10	12	13	14	15	20	
Pitch <sup>1</sup>	arc sec	≤ 30													
Yaw <sup>1</sup>	arc sec	≤ 30													
Total Stage Mass (U, P3 Motor) <sup>3</sup>	Kg	9.9	11	11.5	12.7	13.7	15.8	17.4	19.6	21.7	23.4	25.5	27.1	31.3	
Total Stage Mass (C, S, P3 Motor) <sup>3</sup>	Kg	14.6	15.1	15.8	16.9	18.1	20.4	22.2	24.6	26.9	28.7	31	32.8	37.5	
Total Stage Mass (U, P4 Motor) <sup>3</sup>	Kg	10.2	11.2	11.8	12.7	13.9	16	17.7	19.8	22	23.6	25.7	27.4	31.6	
Total Stage Mass (C, S, P4 Motor) <sup>3</sup>	Kg	15.2	16.3	17	18.2	19.3	21.6	23.5	25.8	28.1	29.9	32.2	34.1	38.7	

Motor Type		P3	P4
Moving Mass	Kg	1.3 (U), 4.0 (C, S)	1.5 (U), 4.5 (C, S)
Continuous Force <sup>2</sup>	N	58.60 (U, C), 50.60 (S)	79.35 (U, C), 71.35 (S)
Peak Force <sup>2</sup>	N	199.81 (U, C), 191.81 (S)	262.06 (U, C), 254.06 (S)
Max Speed	m/s	Feedback and Load Dependent (Max 3m/sec)	
Max Acceleration	g's	Feedback and Load Dependent (Max 3g)	

<sup>1</sup> Specifications based on following conditions: Single axis, fully bolted or clamped to AA granite mounting surface, ambient and stage temperature at 20° C, point of measurement centered in carriage, 35mm above the carriage mounting surface.

<sup>2</sup> Continuous and Peak forces shown equal the motor Continuous or Peak force less the RMS frictional resistance of the stage.

<sup>3</sup> Masses include cable management assembly.

## Mechanical Specifications - XLM145

Specification	Units	P3 Motor	P4 Motor
Maximum Load	Kg	300 <sup>1</sup>	300 <sup>1</sup>
Maximum Pitch Moment Load	Nm	230	310
Maximum Roll Moment Load	Nm	140	140
Maximum Yaw Moment Load	Nm	190	250
Pitch Torsional Spring Rate (C, S Versions)	arc-sec/Nm	0.71	0.62
Yaw Torsional Spring Rate (C, S Versions)	arc-sec/Nm	0.30	0.20
Roll Torsional Spring Rate (C, S Versions)	arc-sec/Nm	1.82	2.22
Pitch Torsional Spring Rate (U Version)	arc-sec/Nm	0.36	0.31
Yaw Torsional Spring Rate (U Version)	arc-sec/Nm	0.32	0.21
Roll Torsional Spring Rate (U Version)	arc-sec/Nm	2.09	2.53
Base Moment of Inertia (Narrow dimension)	kg-mm <sup>2</sup>	71,800	71,800
Base Moment of Inertia (Wide dimension)	kg-mm <sup>2</sup>	81,900	81,900
Running Friction RMS value over travel (U, C Versions)	N	12	12
Running Friction Peak value over travel (U, C Versions)	N	16	16
Running Friction RMS value over travel (S Version)	N	20	20
Running Friction Peak value over travel (S Version)	N	28	28
IP Rating		U (Uncovered) version: IP00 C (Covered) version: IP10 S (Sealed) version: IP30 <sup>2</sup>	

<sup>1</sup> Normal load centered on carriage with stage in horizontal orientation

<sup>2</sup> IP30 rating requires user to seal all unused mounting holes in carriage and base.

# XLM Series Linear Motor Stages

## Motor Specifications - XLM145

	Units	P3	P4
<b>Stall Force Continuous</b> <sup>1</sup>	N	70.60	91.35
<b>Stall Current Continuous</b> <sup>1, 4, 8</sup>	Amps (Peak of sine)	4.31	4.19
<b>Stall Current Continuous</b> <sup>1, 7</sup>	Amps (DC)	3.74	3.63
<b>Stall Current Continuous</b> <sup>1</sup>	Amps (RMS)	3.05	2.96
<b>Peak Force</b> <sup>6</sup>	N	211.81	274.06
<b>Peak Current</b> <sup>4, 6, 8</sup>	Amps (Peak of sine)	12.94	12.56
<b>Peak Current</b> <sup>6, 7</sup>	Amps (DC)	11.21	10.88
<b>Peak Current</b> <sup>6</sup>	Amps (RMS)	9.15	8.88
<b>Voltage Constant</b> <sup>3, 4</sup>	Volts/m/s	18.9	25.2
<b>Force Constant</b> <sup>9</sup>	N/ Amps (Peak of sine)	16.37	21.82
<b>Force Constant</b> <sup>3, 4</sup>	N/Amps (DC)	18.90	25.20
<b>Force Constant</b> <sup>3</sup>	N/Amps (RMS)	23.15	30.86
<b>Resistance</b> <sup>14</sup>	Ohms	4.03	5.51
<b>Inductance</b> <sup>5</sup>	mH	1.80	2.40
<b>Maximum Bus Voltage</b>	Volts DC	330	330
<b>Thermal Resistance Winding-Ambient</b>	°C/watt	1.03	0.80
<b>Thermal Resistance Winding-Case</b>	°C/watt	0.52	0.28
<b>Thermal Resistance Case-Ambient</b>	°C/watt	0.51	0.52
<b>Motor Thermal Time Constant</b> <sup>12</sup>	Minutes	41.67	36.67
<b>Winding Thermal Time Constant</b> <sup>13</sup>	Minutes	1.00	1.00
<b>Electrical Time Constant</b> <sup>11</sup>	Millisecs	0.45	0.44
<b>Electrical Pitch</b> <sup>10</sup>	mm	60.96	60.96
<b>Rated Winding Temperature</b>	°C	100	100

<sup>1</sup> @ 25°C ambient, 100°C winding temperature

<sup>2</sup> Measured with a 0.76 mm gap

<sup>3</sup> Measured Line to Line, +/- 10%

<sup>4</sup> Value is measured peak of sine wave

<sup>5</sup> +/-30%, Line-to-Line, inductance bridge measurement @1 KHz

<sup>6</sup> Initial winding temperature must be 60°C or less before Peak Current is Applied

<sup>7</sup> DC current through a pair of motor phases of a trapezoidal (six state) commutated motor

<sup>8</sup> Peak of the sinusoidal current in a phase for a sinusoidal commutated motor

<sup>9</sup> Total motor torque per peak of the sinusoidal amps measured in any phase, +/-10%

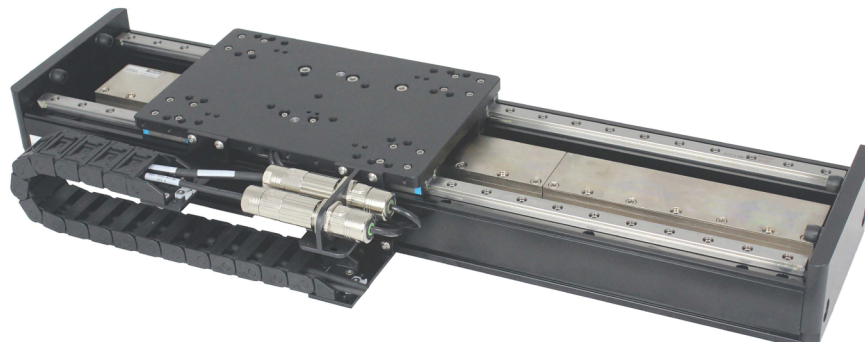
<sup>10</sup> The distance from the leading edge of a north pole to the leading edge of the next north pole

<sup>11</sup> Time for motor value to reach 63% of its final current after a step change in voltage

<sup>12</sup> Time the motor takes to reach 63% of its final temperature, given constant power

<sup>13</sup> Time for the winding to reach 63% of its final temperature rise above the rest of the motor, given constant power

<sup>14</sup> Measured between any 2 motor leads with delta connection at 25°C. At 100°C, multiply resistance by 1.295 (75°C rise\* 0.393%/°C)



# XLM Series Linear Motor Stages

## Performance Specifications - XLM200

Specification	Units												
Travel (U, C, S Versions, P3 Motor)	mm	200	300	400	500	600	700	800	900	1000	1200	1350	1500
Travel (C, S Versions, P4 Motor)	mm	140	240	340	440	540	640	740	840	940	1140	1290	1440
Travel (U Version, P4 Motor)	mm	160	260	360	460	560	660	760	860	960	1160	1310	1460
Accuracy <sup>1</sup>	+/-µm	8	10	12	14	16	17	18	19	20	24	26	30
Resolution	µm	Encoder Dependent (See Encoder Specification)											
Bidirectional Repeatability (Resolution Dependant) <sup>1</sup>	+/-µm	0.5 + Encoder Resolution											
Horizontal Straightness <sup>1</sup>	+/-µm	4	6	6	7	7	8	9	10	10	12	13	15
Vertical Straightness <sup>1</sup>	+/-µm	4	6	6	7	7	8	9	10	10	12	13	15
Pitch <sup>1</sup>	arc sec	≤ 30											
Yaw <sup>1</sup>	arc sec	≤ 30											
Total Stage Mass (U, P3 Motor) <sup>3</sup>	Kg	19.8	22.3	25.5	28	31.3	34.5	37	40.2	42.7	49	53.2	58
Total Stage Mass (C, S, P3 Motor) <sup>3</sup>	Kg	26.7	29.5	33	35.8	39.4	42.9	45.7	49.2	52	59.1	63.7	69
Total Stage Mass (U, P4 Motor) <sup>3</sup>	Kg	20.2	22.7	25.9	28.4	31.6	34.8	37.3	40.5	43	49.4	53.5	58.3
Total Stage Mass (C, S, P4 Motor) <sup>3</sup>	Kg	28.1	31	34.5	37.3	40.8	44.3	47.2	50.7	53.5	60.6	65.1	70.4

Motor Type		P3	P4
Moving Mass	Kg	2.9 (U), 6.1 (C, S)	3.2 (U), 7.5 (C, S)
Continuous Force <sup>2</sup>	N	102.53 (U, C), 88.53 (S)	127.35 (U, C), 113.35 (S)
Peak Force <sup>2</sup>	N	339.60 (U, C), 325.60 (S)	414.04 (U, C), 400.04 (S)
Max Speed	m/s	Feedback and Load Dependent (Max 3m/sec)	
Max Acceleration	g's	Feedback and Load Dependent (Max 3g)	

<sup>1</sup> Specifications based on following conditions: Single axis, fully bolted or clamped to AA granite mounting surface, ambient and stage temperature at 20° C, point of measurement centered in carriage, 35mm above the carriage mounting surface.

<sup>2</sup> Continuous and Peak forces shown equal the motor Continuous or Peak force less the RMS frictional resistance of the stage.

<sup>3</sup> Masses include cable management assembly.

## Mechanical Specifications - XLM200

Specification	Units	P3 Motor	P4 Motor
Maximum Load	Kg	630 <sup>1</sup>	630 <sup>1</sup>
Maximum Pitch Moment Load	Nm	450	600
Maximum Roll Moment Load	Nm	400	400
Maximum Yaw Moment Load	Nm	360	485
Pitch Torsional Spring Rate (C, S Versions)	arc-sec/Nm	0.85	0.74
Yaw Torsional Spring Rate (C, S Versions)	arc-sec/Nm	0.25	0.17
Roll Torsional Spring Rate (C, S Versions)	arc-sec/Nm	0.71	0.86
Pitch Torsional Spring Rate (U Version)	arc-sec/Nm	0.51	0.45
Yaw Torsional Spring Rate (U Version)	arc-sec/Nm	0.20	0.15
Roll Torsional Spring Rate (U Version)	arc-sec/Nm	0.48	0.61
Base Moment of Inertia (Narrow dimension)	kg-mm <sup>2</sup>	151,600	151,600
Base Moment of Inertia (Wide dimension)	kg-mm <sup>2</sup>	181,200	181,200
Running Friction RMS value over travel (U, C Versions)	N	16	16
Running Friction Peak value over travel (U, C Versions)	N	24	24
Running Friction RMS value over travel (S Version)	N	30	30
Running Friction Peak value over travel (S Version)	N	48	48
IP Rating		U (Uncovered) version: IP00 C (Covered) version: IP10 S (Sealed) version: IP30 <sup>2</sup>	

<sup>1</sup> Normal load centered on carriage with stage in horizontal orientation

<sup>2</sup> IP30 rating requires user to seal all unused mounting holes in carriage and base.



# XLM Series Linear Motor Stages

## Motor Specifications - XLM200

	Units	P3	P4
<b>Stall Force Continuous</b> <sup>1</sup>	N	118.53	143.35
<b>Stall Current Continuous</b> <sup>1, 4, 8</sup>	Amps (Peak of sine)	5.80	5.25
<b>Stall Current Continuous</b> <sup>1, 7</sup>	Amps (DC)	5.02	4.55
<b>Stall Current Continuous</b> <sup>1</sup>	Amps (RMS)	4.10	3.72
<b>Peak Force</b> <sup>6</sup>	N	355.60	430.04
<b>Peak Current</b> <sup>4, 6, 8</sup>	Amps (Peak of sine)	17.40	15.76
<b>Peak Current</b> <sup>6, 7</sup>	Amps (DC)	15.07	13.65
<b>Peak Current</b> <sup>6</sup>	Amps (RMS)	12.30	11.15
<b>Voltage Constant</b> <sup>3, 4</sup>	Volts/m/s	23.60	31.50
<b>Force Constant</b> <sup>9</sup>	N/ Amps (Peak of sine)	20.44	27.28
<b>Force Constant</b> <sup>3, 4</sup>	N/Amps (DC)	23.60	31.50
<b>Force Constant</b> <sup>3</sup>	N/Amps (RMS)	28.90	38.58
<b>Resistance</b> <sup>14</sup>	Ohms	2.67	3.78
<b>Inductance</b> <sup>5</sup>	mH	2.30	3.00
<b>Maximum Bus Voltage</b>	Volts DC	330	330
<b>Thermal Resistance Winding-Ambient</b>	°C/watt	0.86	0.74
<b>Thermal Resistance Winding-Case</b>	°C/watt	0.50	0.40
<b>Thermal Resistance Case-Ambient</b>	°C/watt	0.36	0.34
<b>Motor Thermal Time Constant</b> <sup>12</sup>	Minutes	48.33	53.33
<b>Winding Thermal Time Constant</b> <sup>13</sup>	Minutes	2.17	2.17
<b>Electrical Time Constant</b> <sup>11</sup>	Millisecs	0.86	0.79
<b>Electrical Pitch</b> <sup>10</sup>	mm	60.96	60.96
<b>Rated Winding Temperature</b>	°C	100	100

<sup>1</sup> @ 25°C ambient, 100°C winding temperature

<sup>2</sup> Measured with a 0.76 mm gap

<sup>3</sup> Measured Line to Line, +/- 10%

<sup>4</sup> Value is measured peak of sine wave

<sup>5</sup> +/-30%, Line-to-Line, inductance bridge measurement @1 KHz

<sup>6</sup> Initial winding temperature must be 60°C or less before Peak Current is Applied

<sup>7</sup> DC current through a pair of motor phases of a trapezoidal (six state) commutated motor

<sup>8</sup> Peak of the sinusoidal current in a phase for a sinusoidal commutated motor

<sup>9</sup> Total motor torque per peak of the sinusoidal amps measured in any phase, +/-10%

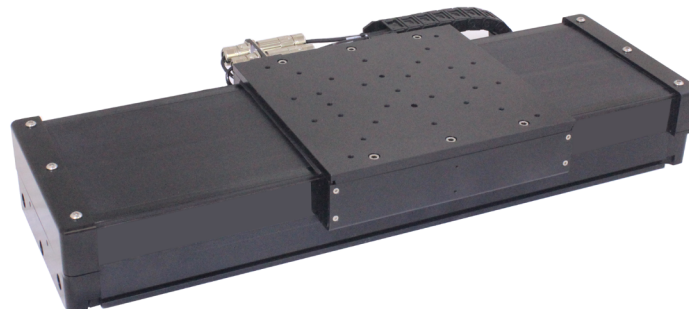
<sup>10</sup> The distance from the leading edge of a north pole to the leading edge of the next north pole

<sup>11</sup> Time for motor value to reach 63% of its final current after a step change in voltage

<sup>12</sup> Time the motor takes to reach 63% of its final temperature, given constant power

<sup>13</sup> Time for the winding to reach 63% of its final temperature rise above the rest of the motor, given constant power

<sup>14</sup> Measured between any 2 motor leads with delta connection at 25°C. At 100°C, multiply resistance by 1.295 (75°C rise\* 0.393%/°C)



# XLM Series Linear Motor Stages

## Encoder Specifications - XLM Series

Encoder	Type	Resolution (μm)	Word Length (bit)	Scale Accuracy, un-mapped (+/- μm/m)	Max Speed (m/sec)	Clock Speed (MHz)	Supply Voltage (V)	Current (mA)	Scale Thermal Expansion (μm/m/°C)
<b>E1</b>	Digital Incremental (Differential)	1	n/a	5	> 3	8	5 +/- 5%	230	10.1
<b>E2</b>	Digital Incremental (Differential)	0.1	n/a	5	0.6	8	5 +/- 5%	230	10.1
<b>E3</b>	Digital Incremental (Differential)	0.01	n/a	5	0.06	8	5 +/- 5%	230	10.1
<b>SC</b>	1V P-P Sin/Cos Incremental (Differential)	20 / Controller DAC	n/a	5	> 3	n/a	5 +/- 5%	120	10.1
<b>R1 / R3</b>	Absolute (Biss-C)	0.05	32	5	> 3	n/a	5 +/- 5%	280	10.1
<b>R2 / R4</b>	Absolute (Biss-C)	0.005	32	5	> 3	n/a	5 +/- 5%	280	10.1

# XLM Series Linear Motor Stages

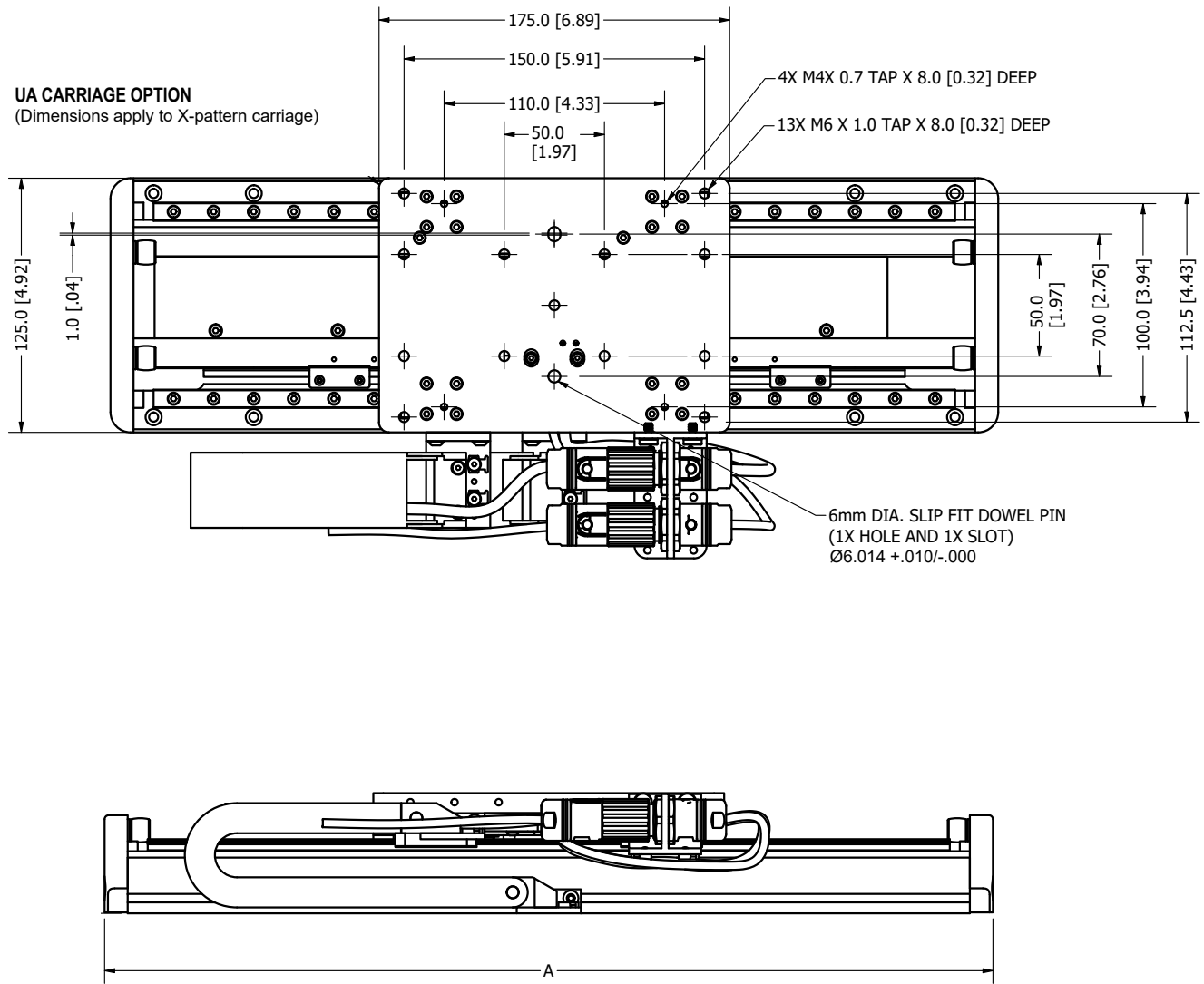
## Sensor Specifications - XLM Series

Sensor Type	Supply Voltage (V)	Current (mA)	Output Type	Signal Voltage Range (V)	Max Current per Output (mA)
Hall	5	50	Single ended, NPN Open Collector	5 +/- 5%	15
End of Travel Limit (NPN output) Not available with Absolute Encoder options. <sup>1</sup>	5 (powered by encoder supply)	Sames as encoder supply	Single ended, NPN Open Collector	5 to 24 +/- 5%	20
End of Travel Limit (PNP output) Not available with Absolute Encoder options. <sup>1</sup>	5 (powered by encoder supply)	Sames as encoder supply	Single ended, PNP Open Emitter	24 +/- 5%	20

<sup>1</sup> PNP output only available with C3, C4, C5, and C6 cable options. Not available with C1 or C2, direct-from-carriage cabling.

# XLM Series Linear Motor Stages

## XLM125 Dimensions (Open) – mm [in]

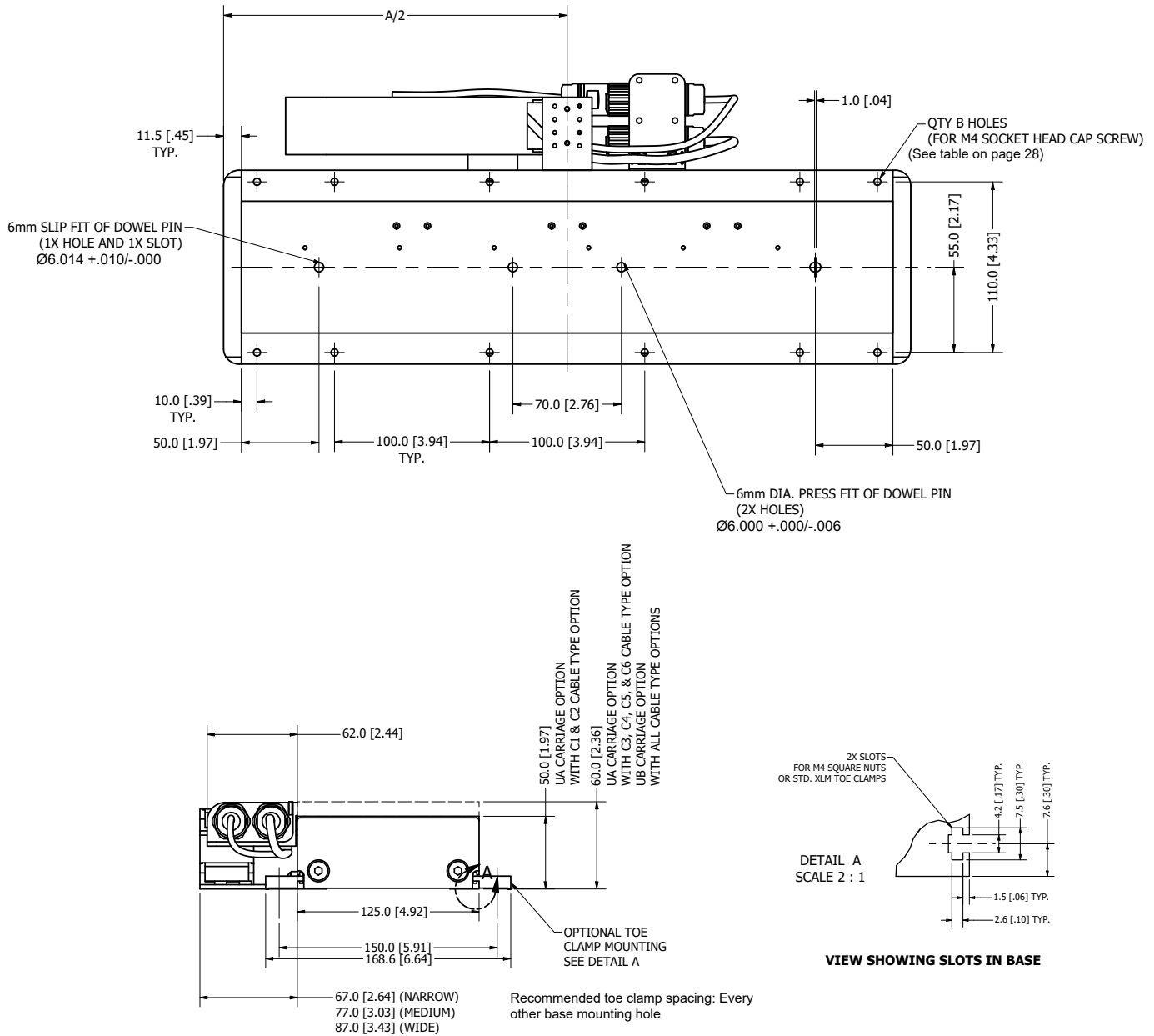


See table on page 28 for "A" dimension



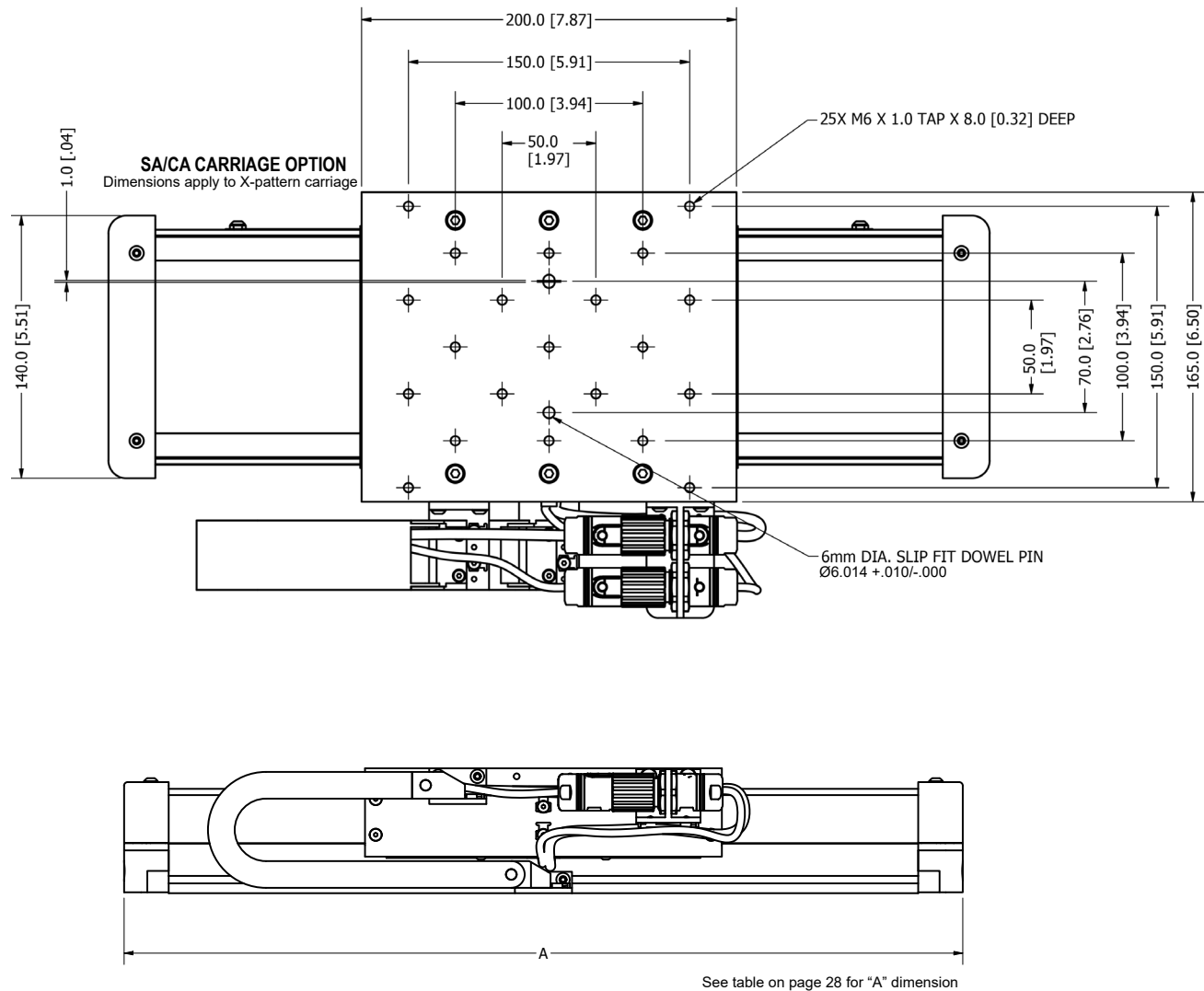
# XLM Series Linear Motor Stages

## XLM125 Dimensions (Open) – mm [in]



# XLM Series Linear Motor Stages

XLM125 Dimensions (Covered/Sealed) – mm [in]

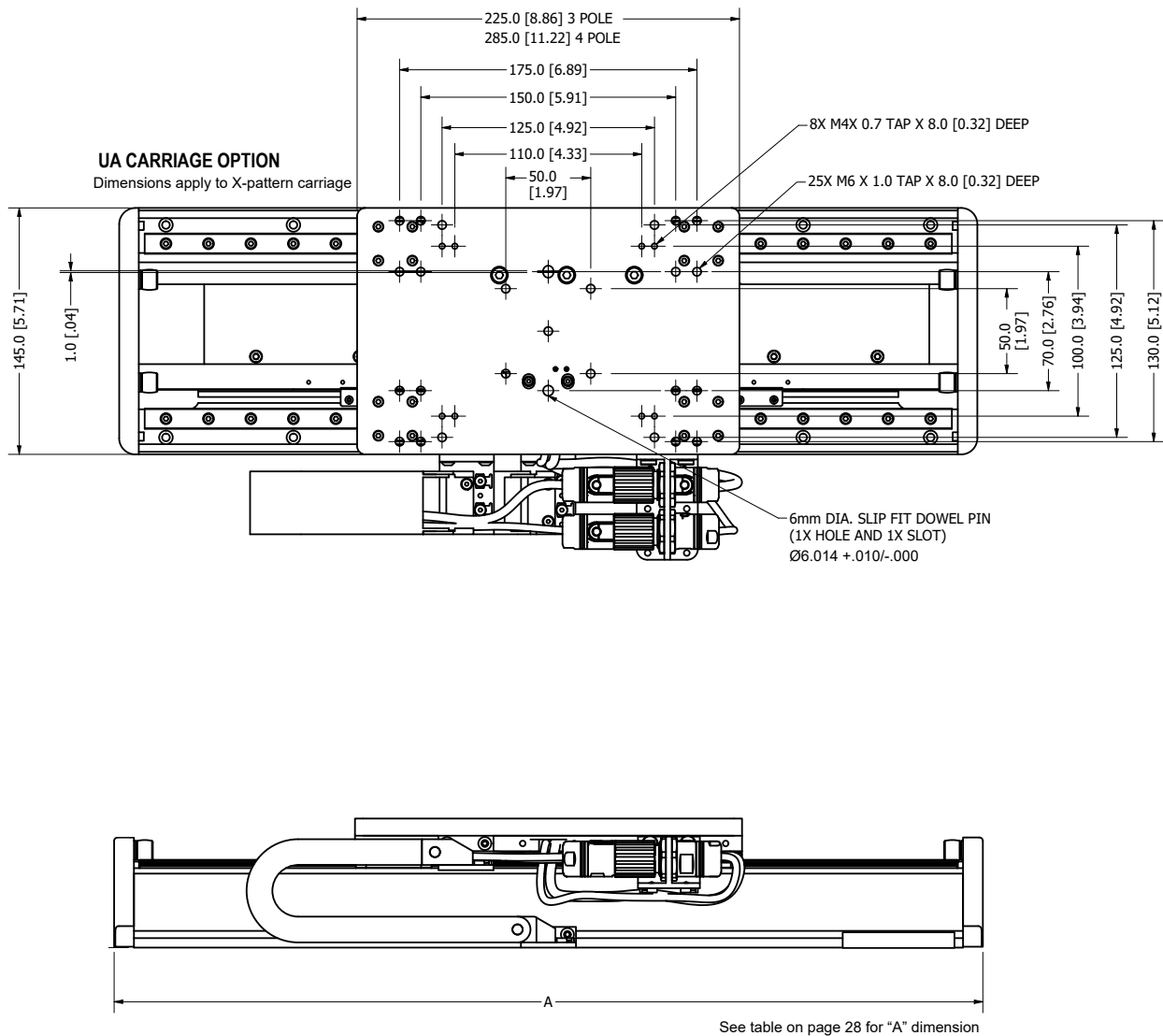


### XLM125 Dimensions (Covered/Sealed) – mm [in]



# XLM Series Linear Motor Stages

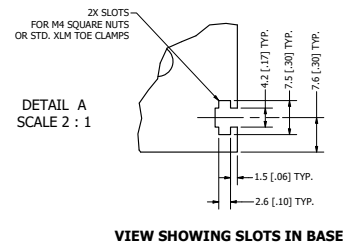
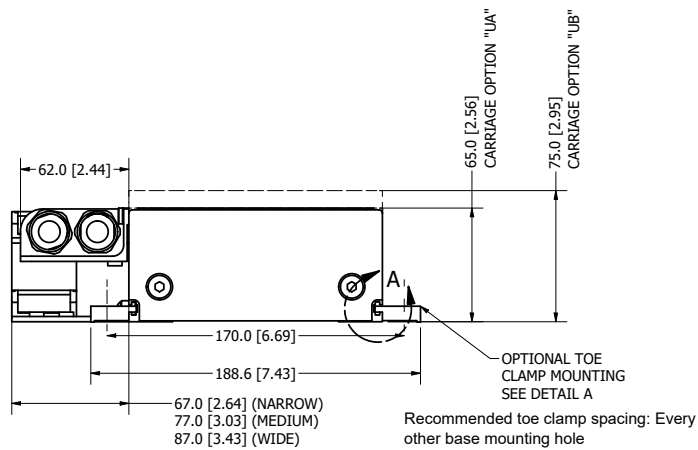
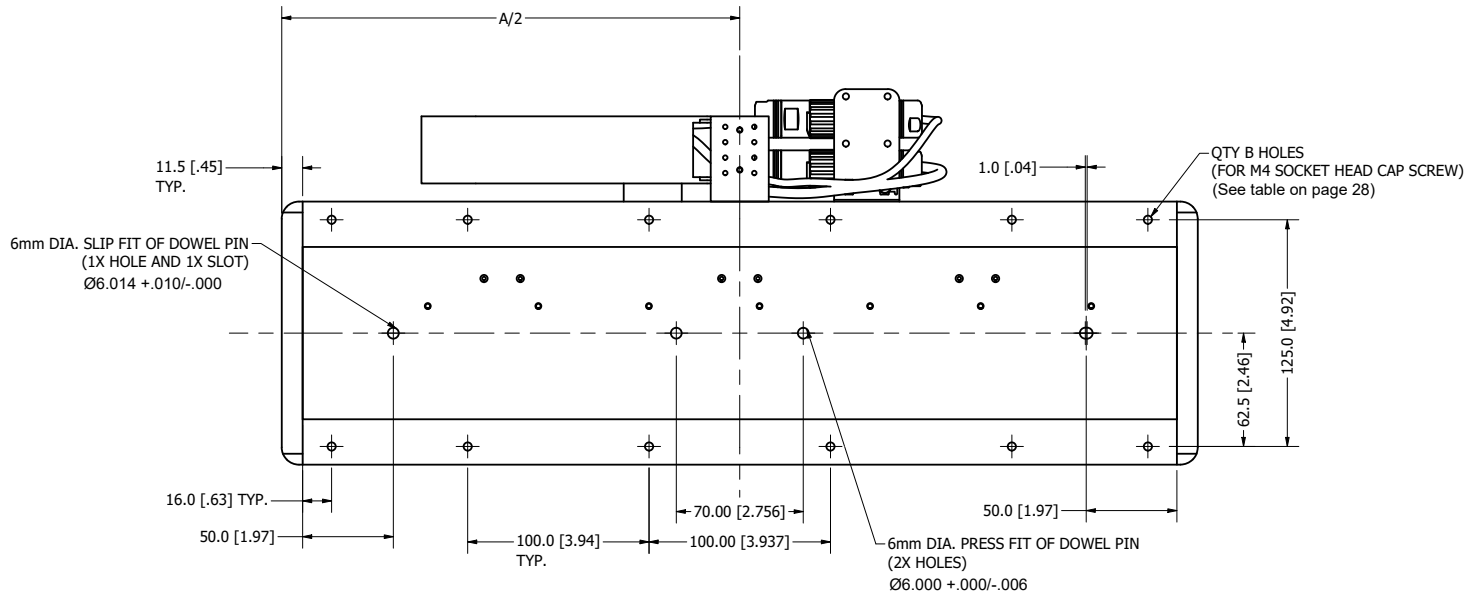
## XLM145 Dimensions (Open) – mm [in]





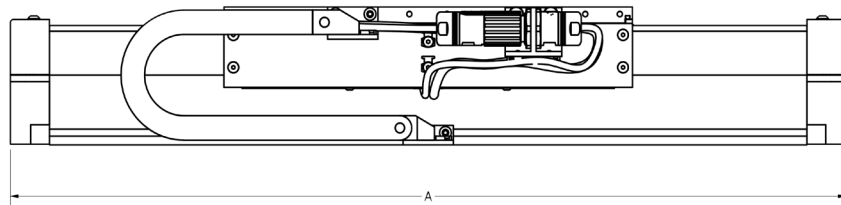
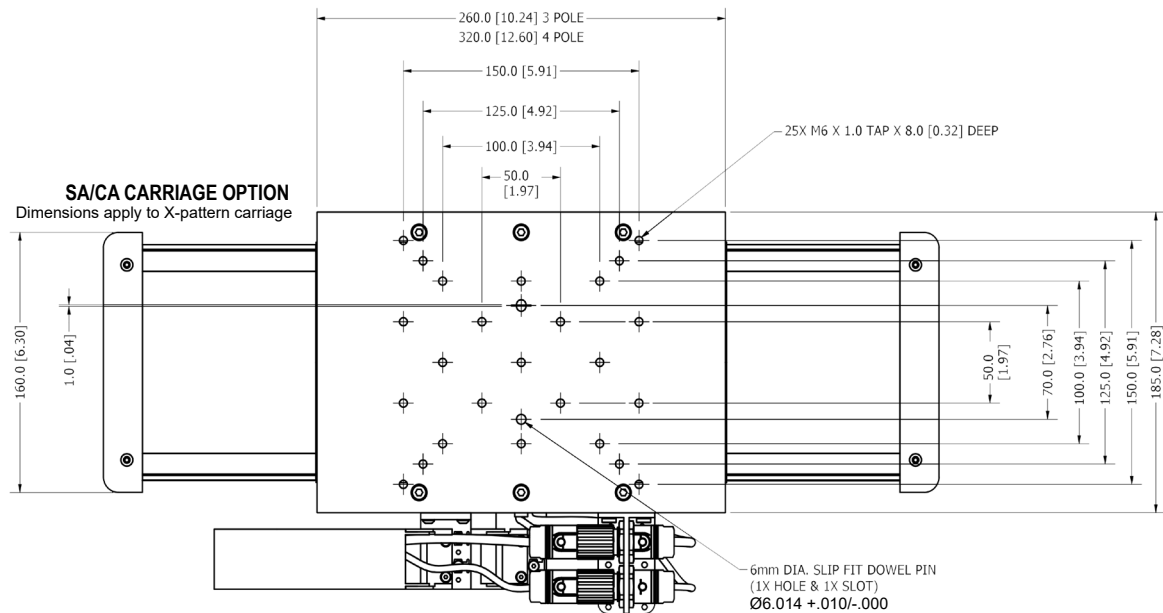
# XLM Series Linear Motor Stages

## XLM145 Dimensions (Open) – mm [in]



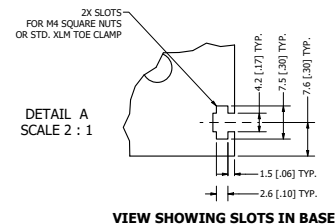
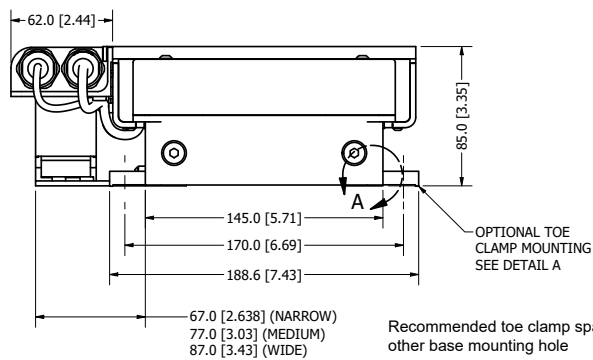
# XLM Series Linear Motor Stages

XLM145 Dimensions (Covered/Sealed) – mm [in]



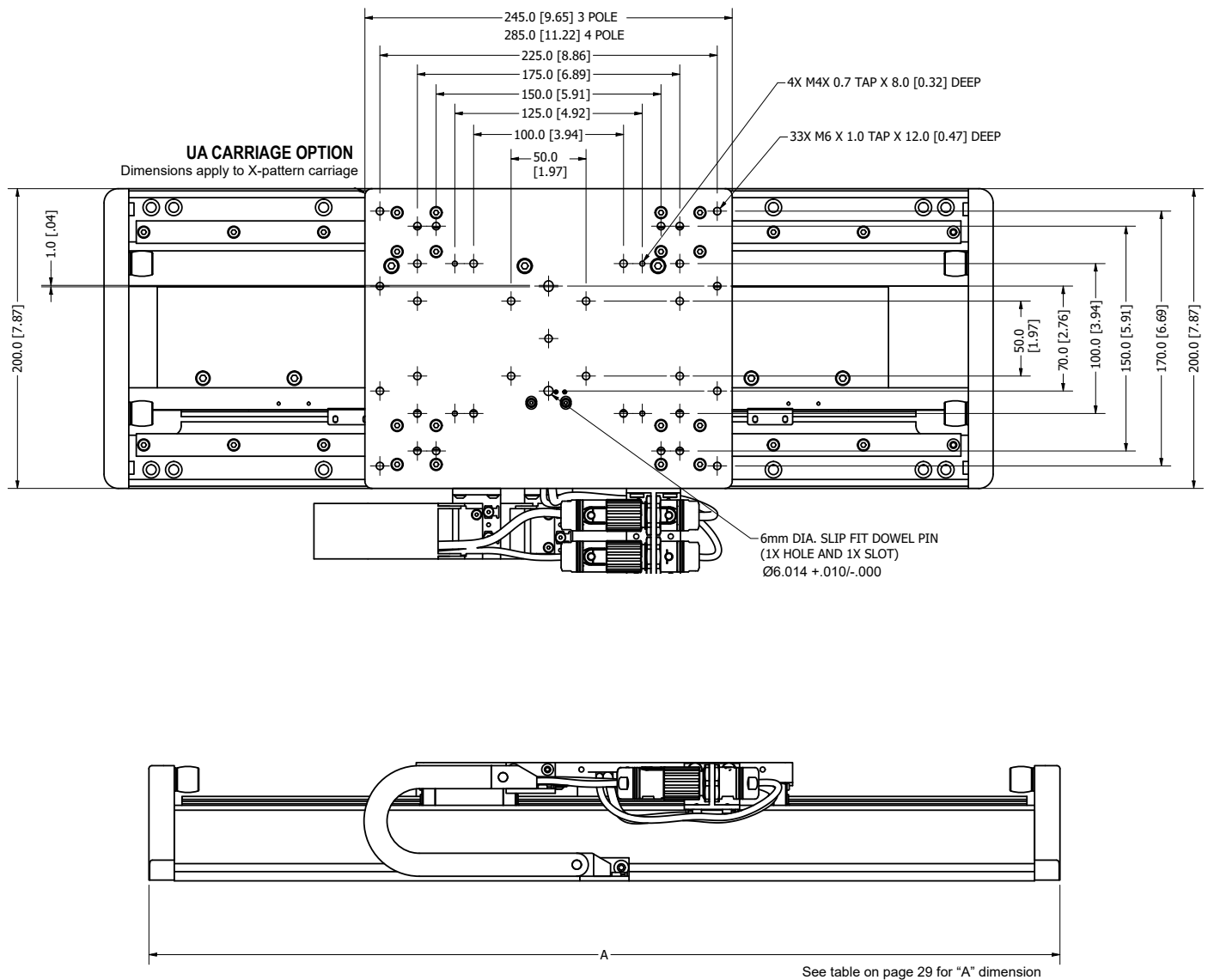
See table on page 28 for "A" dimension

## XLM145 Dimensions (Covered/Sealed) – mm [in]

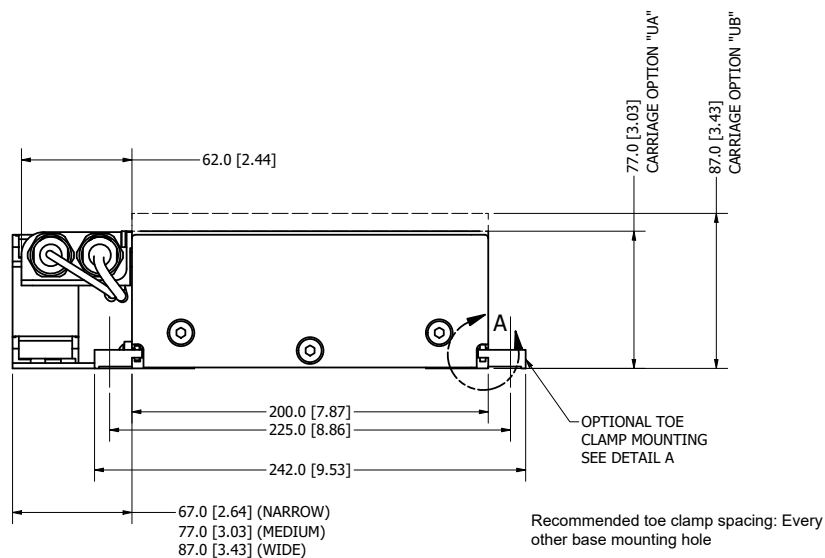


# XLM Series Linear Motor Stages

XLM200 Dimensions (Open) – mm [in]

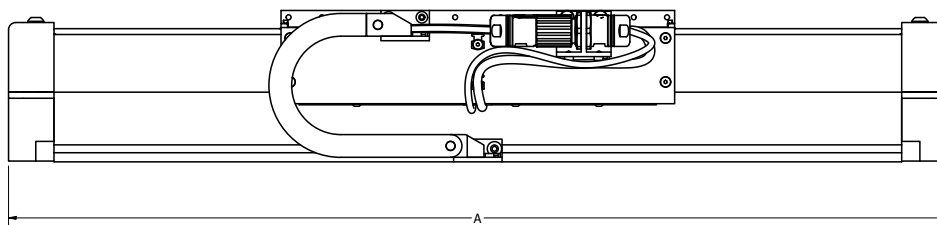
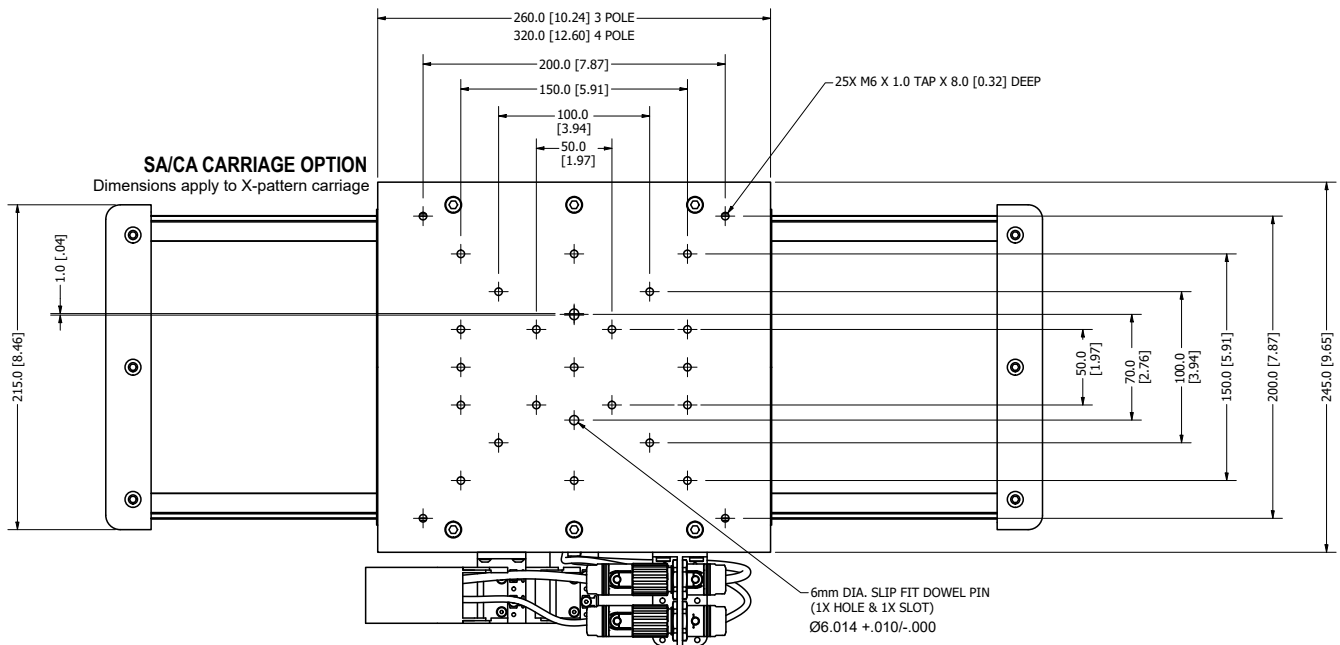


## XLM200 Dimensions (Open) – mm [in]



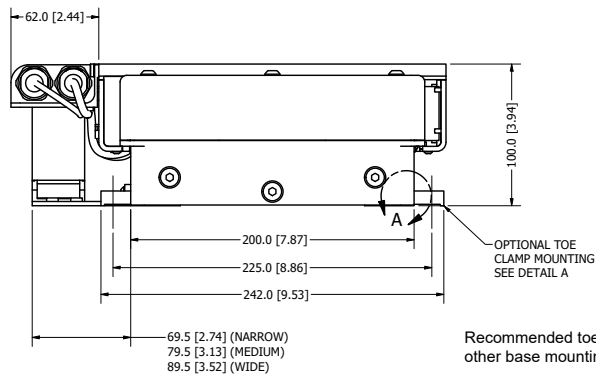
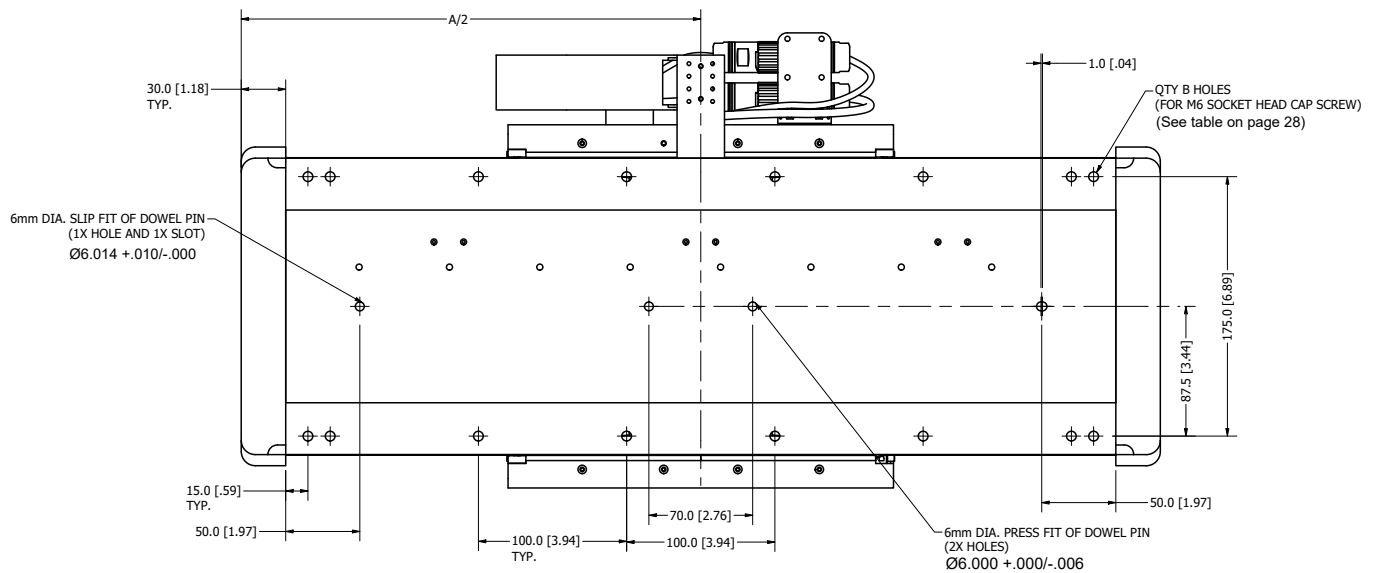
# XLM Series Linear Motor Stages

XLM200 Dimensions (Covered/Sealed) – mm [in]

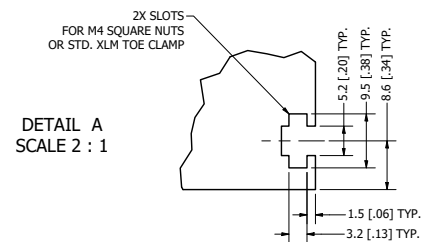


See table on page 29 for "A" dimension

## XLM200 Dimensions (Covered/Sealed) – mm [in]



Recommended toe clamp spacing: Every other base mounting hole



**VIEW SHOWING SLOTS IN BASE**



# XLM Series Linear Motor Stages

## XLM125 Nominal Travel Lengths/Base Holes

XML125 - Open (U)			
Nominal Travel (mm)		A (mm)	B
110		343	8
160		393	12
210		443	12
260		493	12
310		543	12
410		643	16
510		743	16
610		843	20
710		943	20
810		1043	24
910		1143	24
1010		1243	28
<b>C (mm):</b> 71.1 Carriage: UA with Cable Type: C3, C4, C5, or C6			
60.0 Carriage: UB with Cable Type: C1, or C2			

XML125 - Covered and Sealed (C, S)			
Nominal Travel (mm)		A (mm)	B
100		370	8
150		420	12
200		470	12
250		520	12
300		570	12
400		670	16
500		770	16
600		870	20
700		970	20
800		1070	24
900		1170	24
1000		1270	28

B = Number of Base Holes

## XLM145 Nominal Travel Lengths/Base Holes

XML145 - Open (U)			
Nominal Travel (mm)			
3-Pole	4-Pole	A (mm)	B
125	65	405	12
175	115	455	12
225	165	505	12
275	215	555	12
325	265	605	16
425	365	705	16
525	465	805	20
625	565	905	20
725	665	1005	24
825	765	1105	24
925	865	1205	28
1025	965	1305	28
1225	1165	1505	32

XML145 - Covered and Sealed (C, S)			
Nominal Travel (mm)			
3-Pole	4-Pole	A (mm)	B
100	40	432	12
150	90	482	12
200	140	532	12
250	190	582	12
300	240	632	16
400	340	732	16
500	440	832	20
600	540	932	20
700	640	1032	24
800	740	1132	24
900	840	1232	28
1000	940	1332	28
1200	1140	1532	32

B = Number of Base Holes

# XLM Series Linear Motor Stages

## XLM200 Nominal Travel Lengths/Base Holes

XLM200 - Open (U)			
Nominal Travel (mm)			
3-Pole	4-Pole	A (mm)	B
200	160	543	12
300	260	643	16
400	360	743	16
500	460	843	20
600	560	943	20
700	660	1043	24
800	760	1143	24
900	860	1243	28
1000	960	1343	28
1200	1160	1543	32
1350	1310	1693	36
1500	1460	1843	40

XLM200 - Covered and Sealed (C, S)			
Nominal Travel (mm)			
3-Pole	4-Pole	A (mm)	B
200	140	570	12
300	240	670	16
400	340	770	16
500	440	870	20
600	540	970	20
700	640	1070	24
800	740	1170	24
900	840	1270	28
1000	940	1370	28
1200	1140	1570	32
1350	1290	1720	36
1500	1440	1870	40

B = Number of Base Holes

# XLM Series Linear Motor Stages

## XLM Ordering Information

Fill in an order code from each of the numbered fields to create a complete part number

	①	②	③	④	⑤	⑥	⑦	⑧	⑨
<b>Order Example:</b>	<b>XLM</b>	<b>200</b>	<b>-</b>	<b>P3</b>	<b>UA</b>	<b>-</b>	<b>0300</b>	<b>-</b>	<b>E3 S - C1 K0</b>

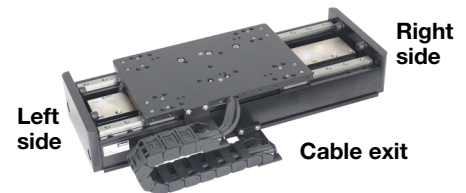
- ① **Series**  
**XLM** Series
- ② **Base Size (width in mm)**  
**125** 125 mm wide profile  
**145** 145 mm wide profile  
**200** 200 mm wide profile
- ③ **Winding & Pole Length**  
**P2** Parallel, 2 pole length  
**P3** Parallel, 3 pole length  
**P4** Parallel, 4 pole length
- ④ **Sealing and Carriage Type**  
**UA** Uncovered with Carriage A Mount  
**UB** Uncovered with Carriage B Mount  
**CA** Covered with Carriage A Mount  
**CB** Covered with Carriage B Mount  
**CC** Covered with Carriage C Mount  
**SA** Sealed with Carriage A Mount  
**SB** Sealed with Carriage B Mount  
**SC** Sealed with Carriage C Mount
- ⑤ **Travel (mm)** - See table on page 31 for available travel lengths by base size and features.

- ⑥ **Encoder**  
**E1** 1μ optical incremental  
**E2** 0.1μ optical incremental  
**E3** 0.01μ optical incremental  
**SC** Sine/Cosine 1V p-p  
**R1** Absolute BiSS-C 50 nm, 32 Bit, value increases right to left  
**R2** Absolute BiSS-C 5 nm, 32 Bit, value increases right to left  
**R3** Absolute BiSS-C 50 nm, 32 Bit, value increases left to right  
**R4** Absolute BiSS-C 5 nm, 32 Bit, value increases left to right

- ⑦ **Scale**  
**S** Steel

- ⑧ **Cable Type**  
**C1** 3 meter cable direct from carriage, no connectors  
**C2** 5 meter cable direct from carriage, no connectors, Sine/Cosine and Absolute ONLY (SC, R1, R2, R3, & R4)  
**C3** Carriage-mounted connectors with 3m universal extension cables  
**C4** Carriage-mounted connectors with 5m universal extension cables  
**C5** Carriage-mounted connectors with 3m P-Drive extension cables (Not available with SC, R1, R2, R3, and R4 configurations)  
**C6** Carriage-mounted connectors with 5m P-Drive extension cables (Not available with SC, R1, R2, R3, and R4 configurations)

- ⑨ **Cable Carrier**  
**K0** None  
**K1** Side carrier, narrow, cable exit to right  
**K2** Side carrier, medium, cable exit to right  
**K3** Side carrier, wide, cable exit to right  
**K4** Side carrier, narrow, cable exit to left  
**K5** Side carrier, medium, cable exit to left  
**K6** Side carrier, wide, cable exit to left



# XLM Series Linear Motor Stages

## XLM Standard Travel Lengths

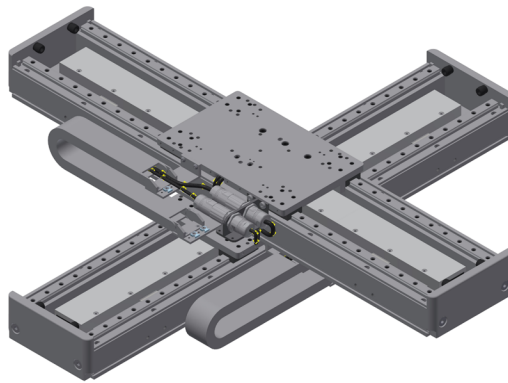
Use the following four-digit travel lengths for position ⑤ in the part number.

Series	XLM125		XLM145				XLM200			
Winding & Pole Length	P2		P3		P4		P3		P4	
Sealing	UA,UB	CA,CB,CC SA,SB,SC	UA,UB	CA,CB,CC SA,SB,SC	UA,UB	CA,CB,CC SA,SB,SC	UA,UB	CA,CB,CC SA,SB,SC	UA,UB	CA,CB,CC SA,SB,SC
Travel (mm) ⑤	0110	0100	0125	0100	0065	0040	0200	0200	0160	0140
	0160	0150	0175	0150	0115	0090	0300	0300	0260	0240
	0210	0200	0225	0200	0165	0140	0400	0400	0360	0340
	0260	0250	0275	0250	0215	0190	0500	0500	0460	0440
	0310	0300	0325	0300	0265	0240	0600	0600	0560	0540
	0410	0400	0425	0400	0365	0340	0700	0700	0660	0640
	0510	0500	0525	0500	0465	0440	0800	0800	0760	0740
	0610	0600	0625	0600	0565	0540	0900	0900	0860	0840
	0710	0700	0725	0700	0665	0640	1000	1000	0960	0940
	0810	0800	0825	0800	0765	0740	1200	1200	1160	1140
	0910	0900	0925	0900	0865	0840	1350	1350	1310	1290
	1010	1000	1025	1000	0965	0940	1500	1500	1460	1440
			1225	1200	1165	1140				

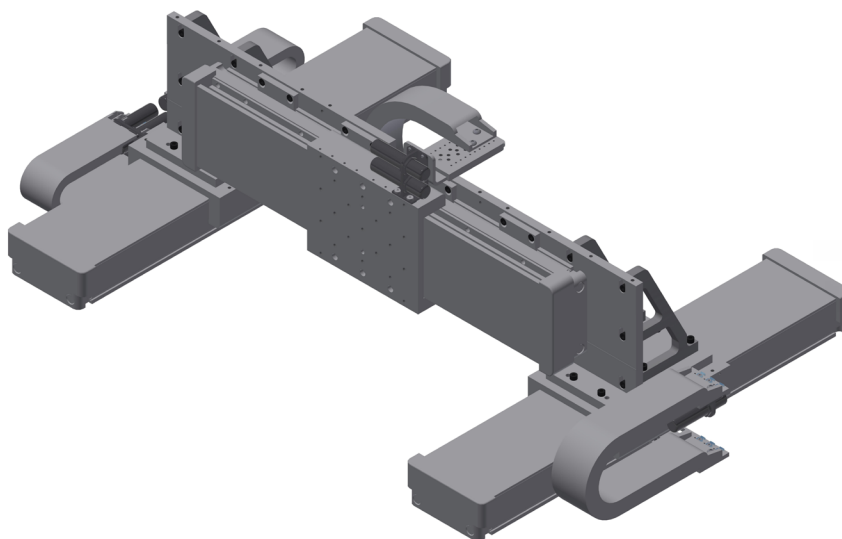
# XLM Series Linear Motor Stages

## XLM Modular Connectivity for Multi-Axis Systems

The XLM series was designed to be highly modular such that it can easily be configured into multi-axis systems made out of other XLM positioners or mSR as the XLM uses the same bolt pattern. Since the entire series was designed with this common hole pattern in mind, X-Y systems can be developed without the need for an additional transition plate.



**X-Y configuration using standard open version XLM stages**



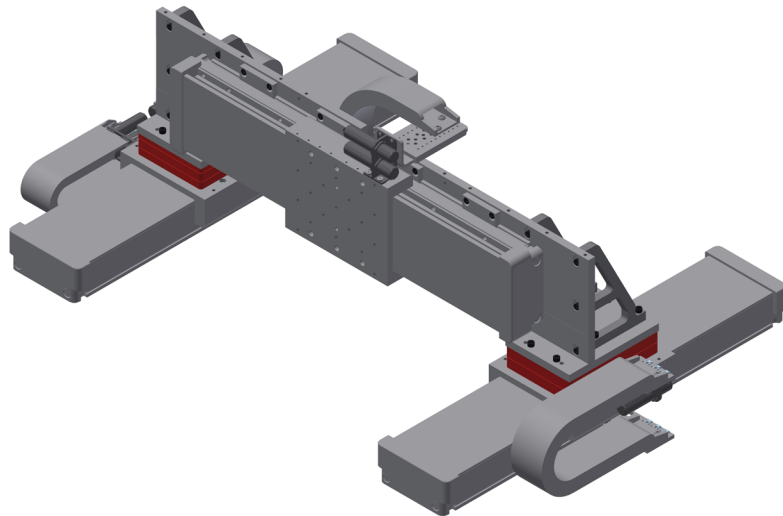
**Three-axis X-X-Y system**

# XLM Series Linear Motor Stages

XLM Modular Connectivity for Multi-Axis Systems



**X-Z configuration using open version XLM and Parker 404XR stage on universal Z-bracket**



**Multi-axis system using RTR Modules**

# XLM Series Linear Motor Stages

## Multi-axis Compatibility Table

One of the key features of the XLM series is the capability to build multi-axis systems by coupling additional XLM or other selected Parker stages. This table indicates which secondary axis and accessories can be mounted to the base XLM axis by size, enclosure style, and motor type.

			Second Axis (Y)										
			XLM125 and Accessories			XLM145 and Accessories				XML200 and Accessories			
			XLM125 (Base Holes) (XY Only)	Toe Clamps (XY Only)	Gantry Brackets	XLM145 (Base Holes) (XY Only)	Toe Clamps (XY Only)	Z-Brackets	Gantry Brackets	XML200 (Base Holes) (XY Only)	Toe Clamps (XY Only)	Z-Brackets	Gantry Brackets
Base Axis (X)	XLM125	SA/CA			✓			✓					
		SB/CB	✓	✓									
		SC/CC											
		UA	✓	✓	✓			✓					
		UB											
	XLM145	SA/CA			✓			✓	✓				
		SB/CB	✓	✓		✓	✓						
		SC/CC											
		UA	✓	✓	✓	✓	✓	✓	✓				
		UB											
	XML200	SA/CA			✓				✓			✓	✓
		SB/CB				✓	✓			✓	✓		
		SC/CC		✓									
		UA			✓	✓	✓		✓	✓	✓	✓	✓
		UB	✓										

How to use the compatibility chart:

Select the size and style of the base axis (X) from leftmost column.

Items with check marks can be mounted to the base axis selected to add a second (Y) axis.



# XLM Series Linear Motor Stages

## Multi-axis Compatibility Table

One of the key features of the XLM series is the capability to build multi-axis systems by coupling additional XLM or other selected Parker stages. This table indicates which secondary axis and accessories can be mounted to the base XLM axis by size, enclosure style, and motor type.

			Second Axis (Y)											
			Customer "X" Pattern	RTR Modules			XE Series			XR Series			mSR	mPR
				RTR 125	RTR 145	RTR 200	402XE Center Mounting Holes (XY Only)	403XE Center Mounting Holes (XY Only)	Z-Brackets	404XR Toe Clamps	406XR Toe Clamps	Z-Brackets	mSR100 Base Holes	mPR100
Base Axis (X)	XLM125	SA/CA	✓	✓					✓			✓		
		SB/CB												
		SC/CC				✓	✓		✓	✓		✓	✓	
		UA	✓	✓				✓			✓			
		UB				✓	✓		✓			✓	✓	
	XLM145	SA/CA	✓	✓	✓			✓			✓			
		SB/CB												
		SC/CC				✓	✓		✓	✓		✓	✓	
		UA	✓	✓	✓			✓			✓			
		UB				✓	✓		✓	✓		✓	✓	
	XLM200	SA/CA	✓	✓	✓	✓								
		SB/CB												
		SC/CC					✓		✓	✓			✓	
		UA	✓	✓	✓	✓								
		UB						✓		✓	✓		✓	

How to use the compatibility chart:

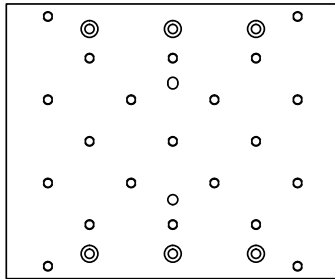
Select the size and style of the base (X) axis from leftmost column.

Items with check marks can be mounted to the base axis selected to add a second (Y) axis.

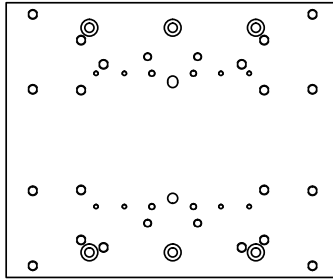
# XLM Series Linear Motor Stages

## Carriage Options

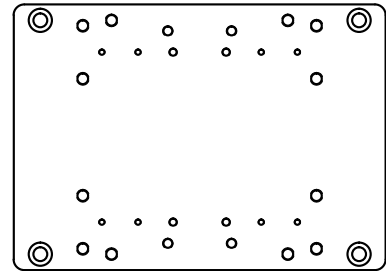
A number of standard and optional carriage choices are available for each XLM size. Carriages are available with standard "X" pattern holes to accommodate XLM Z-brackets, toe clamps, or RT/R adapters, with base holes for additional XLMs in a multi-axis configuration, and with hole patterns for other Parker positioners. These include the mSR100 and mPR100, the 402/403XE, and 404/406XR, some examples of which are shown below.



X Pattern



XE/XR Pattern



mSR/mPR Pattern

Easily couple the XLM with these Parker positioners:



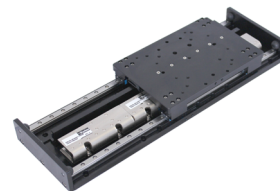
XE Series Positioner



XR Series Positioner



mPR100 Rotary Positioner

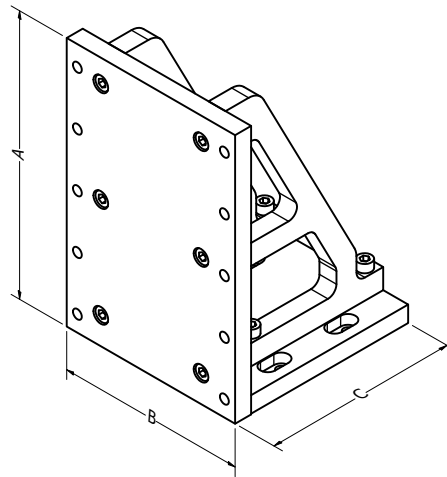


mSR100 Miniature Positioner

# XLM Series Linear Motor Stages

## XLM Accessories - Z-Brackets

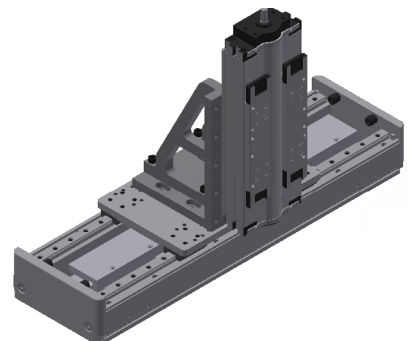
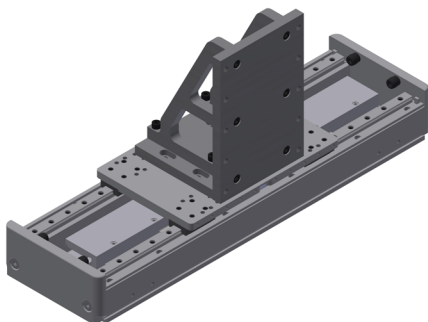
Multiple styles of Z-Brackets are available for additional flexibility of carriage configuration or building multi-axis systems. The brackets can mount at 3, 6, 9, and 12 o'clock positions, and can mount directly to XLM125 and XLM145 open, closed, and sealed versions. Z-Brackets can accept Parker 401XE, 402XE, 403XE, 404XE, and 404XR stages. See tables on pages 34 and 35 for compatibility.



Part #	A (mm)	B (mm)	C (mm)	X Axis	Z Axis
002-4280-02	187	126	130	XLM125, XLM145	404XR, 404XE
002-4280-03					401XE, 402XE, 403XE
002-4280-12	337	126	130	XLM125, XLM145	404XR, 404XE
002-4280-13					401XE, 402XE, 403XE
002-4281-02	187	187	202	XLM200	404XR, 404XE
002-4281-03					406XR
002-4281-12	337	187	202	XLM200	404XR, 404XE
002-4281-13					406XR

Note: Z-Brackets can be mounted every 90 degrees on X axis. All brackets include mounting hardware.

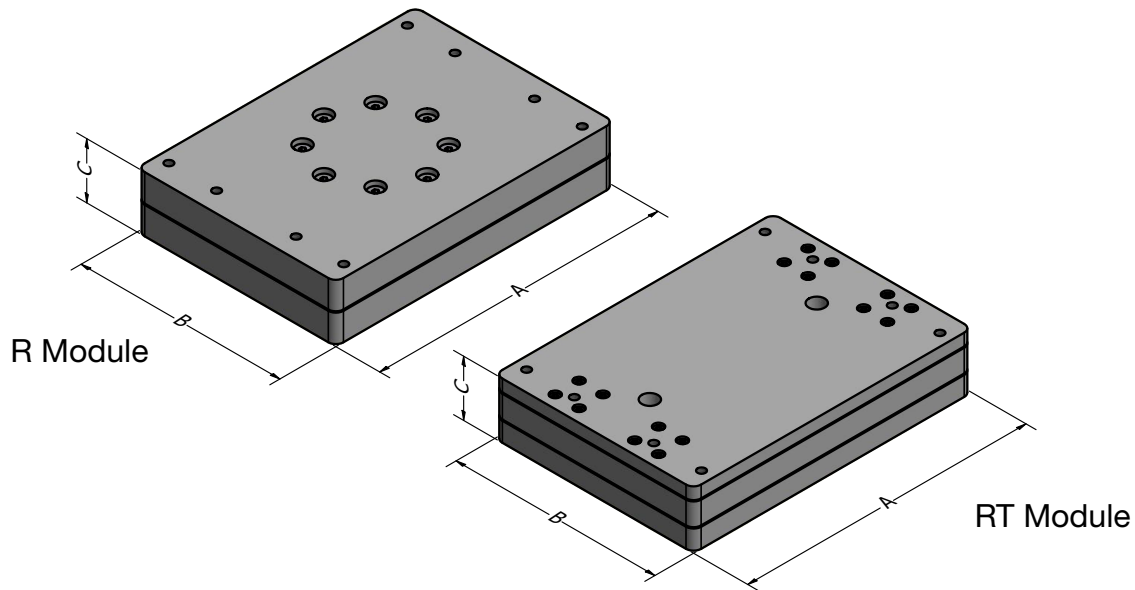
002-4280-03 and 002-4280-13 also include adjustable adapter plate to mount to XE.



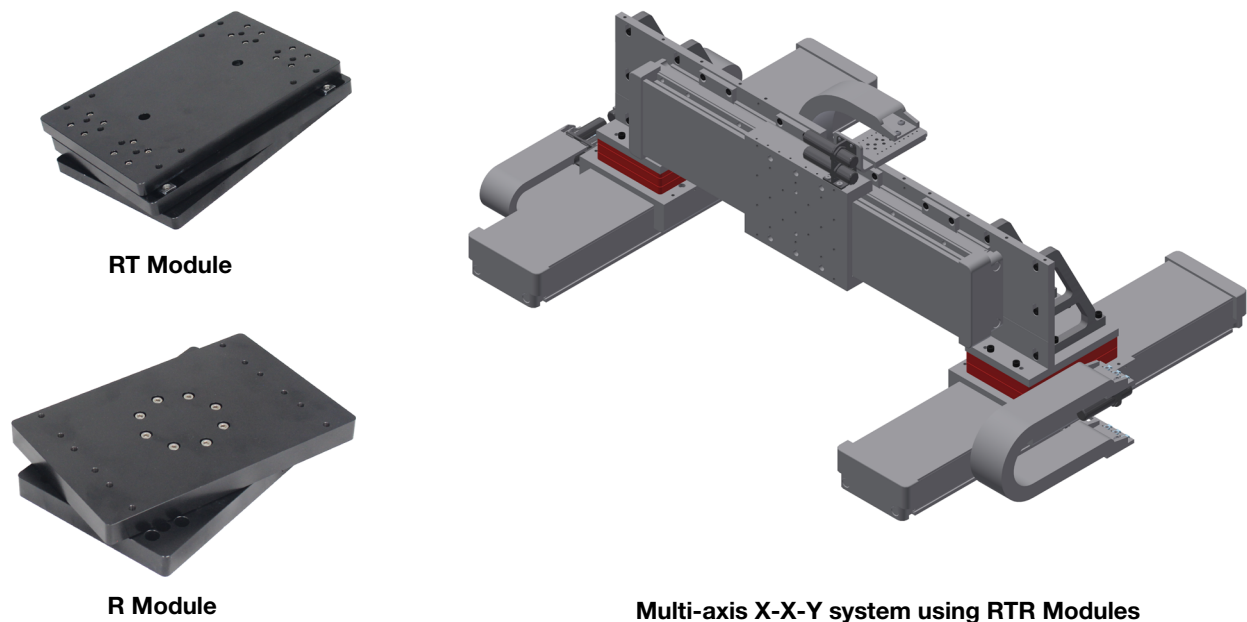
# XLM Series Linear Motor Stages

## XLM Accessories - RTR Modules

These accessory assemblies are used to mechanically couple multiple XLM units and allow for flexibility in the geometry of the system. The “R” module allows for rotation between axes, while the “RT” incorporates both rotation and translation. Compatibility of the RTR modules is shown in the table below.



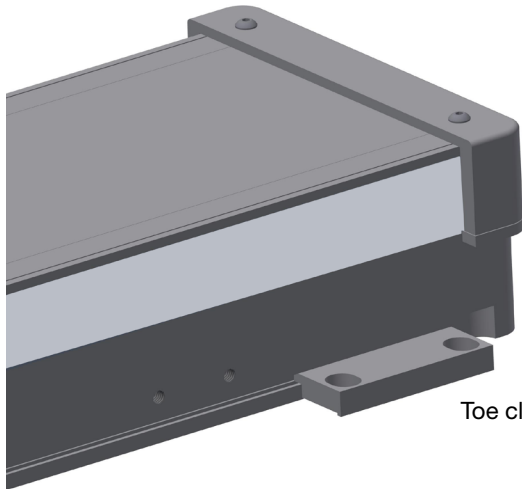
RTR Size	Part #	A (mm)	B (mm)	C (mm)	Angular Travel (deg)	Mounts onto	XLMS that mount onto RTR
125	002-4214-01	175	125	35	7.5	XLM125, 145, 200	XLM125
145	002-4234-01	225	145	40	7.5	XLM145, 200	XLM145
200	002-4254-01	245	200	60	6.25	XLM200	XLM200



# XLM Series Linear Motor Stages

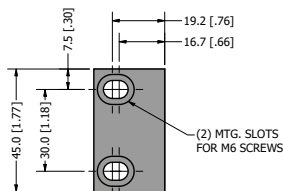
## XLM Accessories - Toe Clamps

A range of Toe Clamps can be used to connect multiple XLM units together to create a multi-axis system. They are also recommended for covered and sealed versions to eliminate the need to open the unit for mounting. All hardware is included with Toe Clamps.



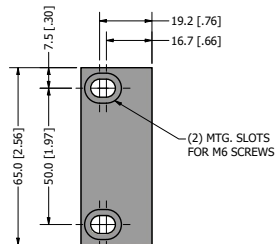
Toe clamps fit into slots in base of XLM.

**XLM125 & 145**  
**002-4283-01**



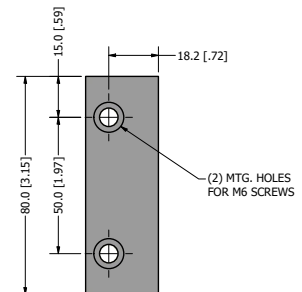
USE WHEN:  
MOUNTING XLM125 & 145 Y AXIS TO  
XLM125 & 145 OPEN VERSION X AXIS

**XLM125 & 145**  
**002-4283-10**



USE WHEN:  
MOUNTING XLM125 & 145 Y AXIS TO  
XLM125 & 145 SEALED/COVERED VERSION X AXIS  
MOUNTING ALL XLM125 & 145 X AXIS

**XLM200**  
**002-4283-20**



USE WHEN:  
ALL VERSIONS OF XLM200

It is recommended that a toe clamp be installed every other base mounting hole.

# XLM Series Linear Motor Stages

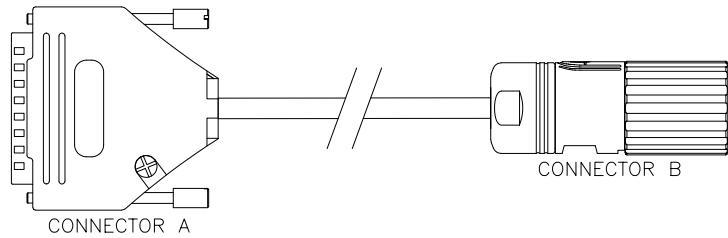
## XLM Feedback Extension Cable Specifications

Type **C3** **C4** **C5** **C6**

006-2862-03.00

006-2862-05.00

Digital Encoder (E1, E2, E3)  
or Absolute Encoder (R1, R2, R3, R4)



### Connector A

Male 25 Pin D-SUB	
Function	Pin #
24VDC PNP Supply	1
Reserved	2
LIMIT- PNP-NC (Digital only)	3
LIMIT+ PNP-NC (Digital only)	4
+5 Volts DC	5
Reserved	6
A+ /MA+	7
A- / MA-	8
B+	9
B-	10
Z+ / SLO+	11
Z- / SLO-	12
CAL (Digital only)	13
Reserved	14
LIMIT- NPN-NC (Digital only)	15
LIMIT+ NPN-NC (Digital only)	16
GND Encoder/Halls	17
GND NPN / PNP	18
TEMP+	19
TEMP-	20
HALL 1	21
HALL 2	22
HALL 3	23
Reserved	24
Reserved	25
SHLD	SHLD

### Connector B

17 Pin Series 617 Connector	
Function	Pin #
+5 Volts DC	1
GND	2
A+ /MA+	3
A- / MA-	4
B+	5
B-	6
Z+ / SLO+	7
Z- / SLO-	8
LIMIT+ (Digital only)	9
LIMIT- (Digital only)	10
Reserved	11
CAL	12
HALL 1	13
HALL 2	14
HALL 3	15
TEMP+	16
TEMP-	17
SHLD	SHLD

### XLM Feedback Extension Cables Electrical Specifications

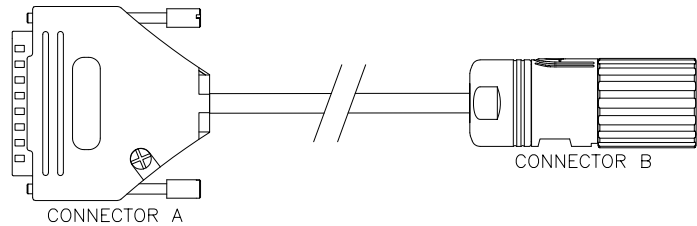
Description	Specification
+5VDC Supply Voltage	+/-5% with a maximum current of 300mA (Encoder Dependent)
PNP 24VDC Supply Voltage	+5% / -20% with a maximum current of 100mA
NPN Output	Normally Closed, Current Sinking, Open Collector +5 to +24 VDC, 20mA Max
PNP Output	Normally Closed, Current Sourcing, 20mA Max
Hall Output	See Phase-Hall Alignment Diagrams

# XLM Series Linear Motor Stages

## XLM Feedback Extension Cable Specifications

Type **C3** **C4** **C5** **C6**

006-2863-03.00  
006-2863-05.00  
Analog Encoder (SC)



### Connector A

Male 25 Pin D-SUB	
Function	Pin #
24VDC PNP Supply	1
Reserved	2
LIMIT- PNP-NC	3
LIMIT+ PNP-NC	4
+5 Volts DC	5
Reserved	6
SIN+	7
SIN-	8
COS+	9
COS-	10
Z+	11
Z-	12
CAL	13
Reserved	14
LIMIT- NPN-NC	15
LIMIT+ NPN-NC	16
GND Encoder/Halls	17
GND NPN / PNP	18
TEMP+	19
TEMP-	20
HALL 1	21
HALL 2	22
HALL 3	23
SETUP	24
Reserved	25
SHLD	SHLD

### Connector B

17 Pin Series 617 Connector	
Function	Pin #
+5 Volts DC	1
GND	2
SIN+	3
SIN-	4
COS+	5
COS-	6
Z+	7
Z-	8
LIMIT+	9
LIMIT-	10
SETUP	11
CAL	12
HALL 1	13
HALL 2	14
HALL 3	15
TEMP+	16
TEMP-	17
SHLD	SHLD

### XLM Feedback Extension Cables Electrical Specifications

Description	Specification
+5VDC Supply Voltage	+/-5% with a maximum current of 300mA (Encoder Dependent)
PNP 24VDC Supply Voltage	+5% / -20% with a maximum current of 100mA
NPN Output	Normally Closed, Current Sinking, Open Collector +5 to +24 VDC, 20mA Max
PNP Output	Normally Closed, Current Sourcing, 20mA Max
Hall Output	See Phase-Hall Alignment Diagrams

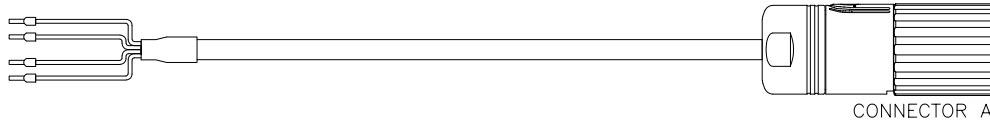


# XLM Series Linear Motor Stages

## XLM Cable Specifications - Type **C3** **C4** **C5** **C6**

006-2865-03.00

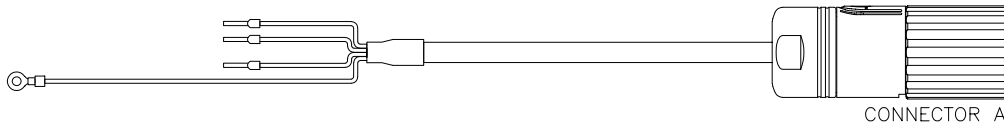
006-2865-05.00 - XLM Power Extension Cable, Flying Leads, Universal



**C3** **C4**

006-2877-03.00

006-2877-05.00 - XLM Power Extension Cable, Flying Leads, P Series Drive



**C5** **C6**

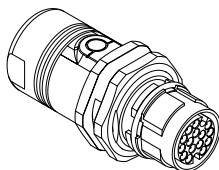
### 4-Position Series 917 Connector A

Function	AWG	Color	Pin #
U*	20	Red/Yellow	1
V*	20	Brown/Yellow	2
W	20	Orange/Yellow	3
GND	20	Green/Yellow	E
Shield	Shield	Shield	Case

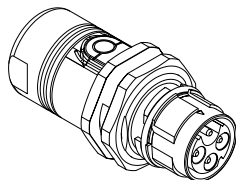
\*For R3/R4 options U = Brown/Yellow, V = Red/Yellow

## XLM Table Side Connector Pinouts

**C3** **C4** **C5** **C6**



MOTOR FEEDBACK



MOTOR POWER

### Motor Power Connector

4 Position Series 917 Connector	
Function	Pin #
U	1
V	2
W	3
PE GND	E
SHLD	SHLD

### Motor Feedback: Digital & Absolute

17 Pin Series 617 Connector	
Function	Pin #
+5 Volts DC	1
GND	2
A+ / MA+	3
A- / MA-	4
B+	5
B-	6
Z+ / SLO+	7
Z- / SLO-	8
LIMIT+ (Digital only)	9
LIMIT- (Digital only)	10
Reserved	11
CAL	12
HALL 1	13
HALL 2	14
HALL 3	15
TEMP+	16
TEMP-	17
SHLD	SHLD

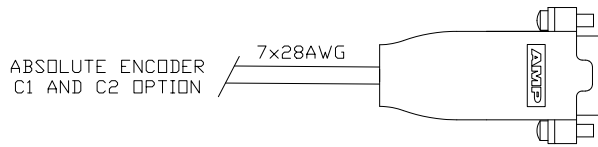
### Motor Feedback: Analog

17 Pin Series 617 Connector	
Function	Pin #
+5 Volts DC	1
GND	2
SIN+	3
SIN-	4
COS+	5
COS-	6
Z+	7
Z-	8
LIMIT+	9
LIMIT-	10
SETUP	11
CAL	12
HALL 1	13
HALL 2	14
HALL 3	15
TEMP+	16
TEMP-	17
SHLD	SHLD

# XLM Series Linear Motor Stages

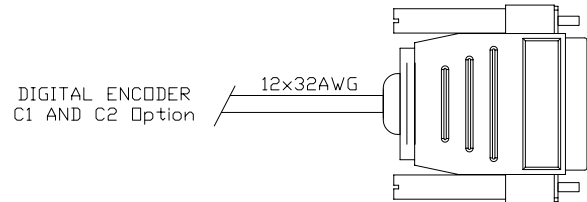
## XLM Feedback Cable Specifications - Type **C1** **C2**

### XLM C1, C2 OPTIONS ABSOLUTE ENCODER PINOUT



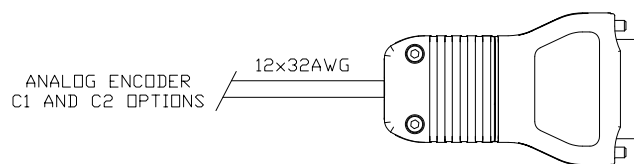
Absolute Encoder with 9-Pin Male D-SUB			
Function	AWG	Color	Pin #
5VDC	28	Brown	4, 5
0V	28	White	8
0V	28	Green	9
MA+	28	Violet	2
MA-	28	Yellow	3
SLO+	28	Gray	6
SLO-	28	Pink	7
Inner Shield		Shield	1
Outer Shield		Shield	Case

### XLM C1, C2 OPTIONS DIGITAL ENCODER PINOUT



Digital Encoder with 15-Pin Male D-SUB			
Function	AWG	Color	Pin #
5VDC	32	Brown	7, 8
0V	32	White	2, 9
A+	32	Red	14
A-	32	Blue	6
B+	32	Yellow	13
B-	32	Green	5
Z+	32	Violet	12
Z-	32	Gray	4
Limit+	32	Pink	11
Limit-	32	Black	10
E	32	Orange	3
CAL	32	Clear	1
SHLD		SHLD	Case

### XLM C1, C2 CABLES – ANALOG ENCODER PINOUT

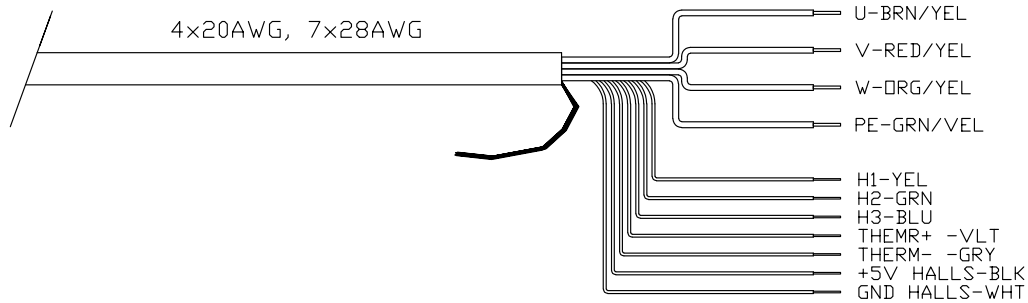


Analog Encoder with 15-Pin Male D-SUB			
Function	AWG	Color	Pin #
5 VDC	32	Brown	4, 5
0V	32	White	12, 13
SIN+	32	Red	9
SIN-	32	Blue	1
COS+	32	Yellow	10
COS-	32	Green	2
Z+	32	Violet	3
Z-	32	Gray	11
LIMIT+	32	Pink	7
LIMIT-	32	Black	8
CAL	32	Orange	14
SETUP	32	Clear	6
Inner Shield		Shield	
Outer Shield		Shield	Case

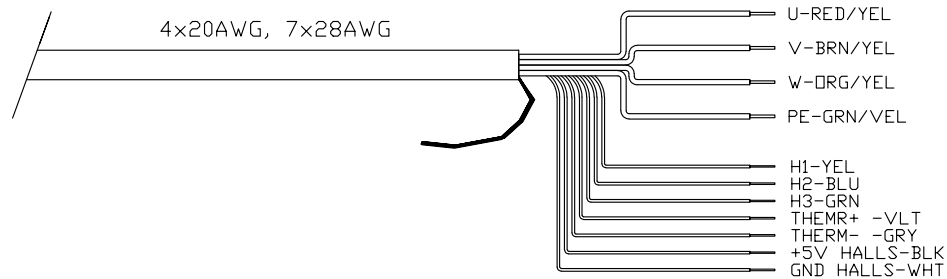
# XLM Series Linear Motor Stages

## XLM Motor Cable Specifications - Type **C1** **C2**

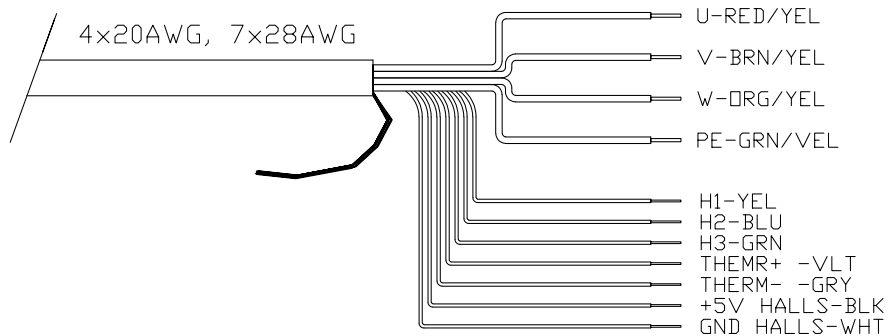
### XLM125 P2 AND XLM200 P3 & P4 - R3 & R4 Options - MOTOR/HALLS/TEMP



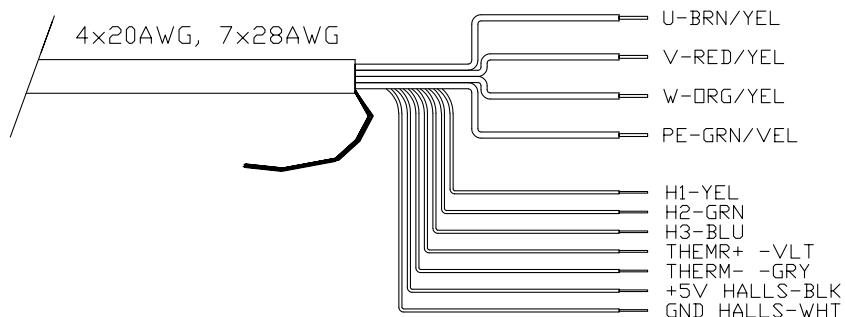
### XLM125 P2 AND XLM200 P3 & P4 - E1, E2, E3, SC, R1 & R2 Options - MOTOR/HALLS/TEMP



### XLM145 P3 & P4 - R3 & R4 Options - MOTOR/HALLS/TEMP



### XLM145 P3 & P4 - E1, E2, E3, SC, R1 & R2 Options - MOTOR/HALLS/TEMP

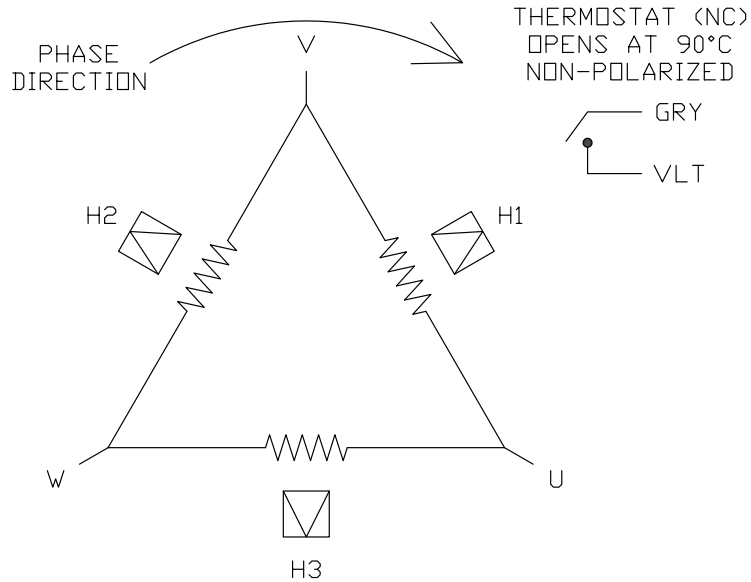


# XLM Series Linear Motor Stages

## XLM Cable Specifications

### PHASE-HALL ALIGNMENT DIAGRAM

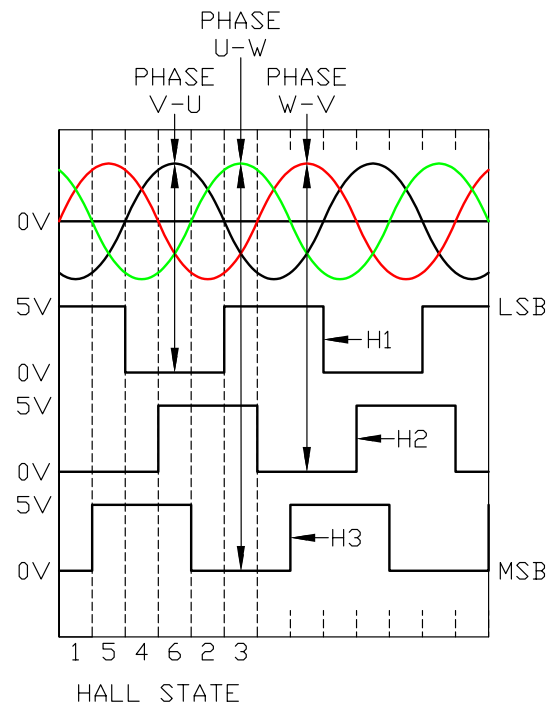
XLM145-P3/P4, XLM125-P2 AND XLM200-P3/P4  
DELTA WOUND WITH THERMOSTAT  
DIGITAL HALL EFFECT DEVICES



HALL EFFECT DEVICES  
SYMMETRICAL RESPONSE  
4.5V TO 18V OPERATION  
OPEN COLLECTOR OUTPUT  
I<sub>out</sub> CONTINUOUS 15mA

PHASE/HALL ALIGNMENT DIAGRAM  
WITH POSITIVE ENCODER DIRECTION

H1 IS LSB  
H2 IS MSB

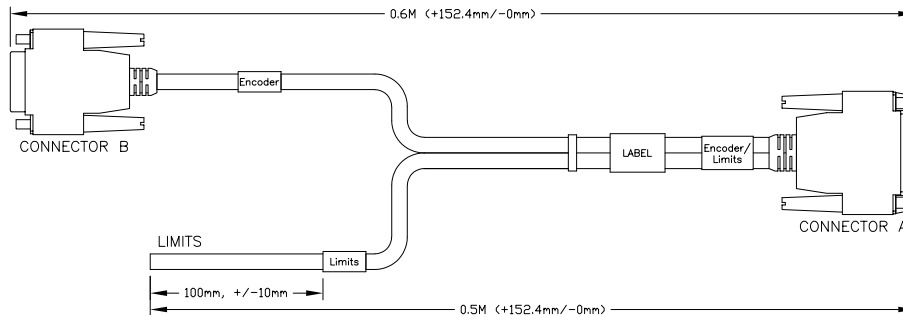


FOR R3 & R4 OPTIONS THE ENCODER DIRECTION IS NEGATIVE

# XLM Series Linear Motor Stages

## XLM Adaptor Cables - ACR7xV and IPA Drives

### 006-2866-01 - XLM to ACR7xV/IPA Adaptor Cable, Digital (E1, E2, E3) or Analog Encoder (SC)



To be used with

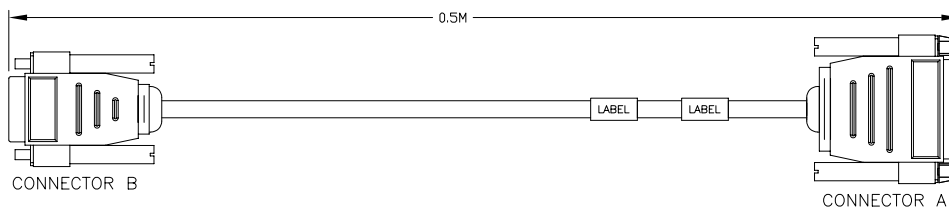


CONNECTOR B - Male 15 Pin HD-SUB		
ACR7xV/IPA		
Function		Pin #
Z+		1
Z-		2
GND Encoder/Halls		3
+5V		5
TEMP-		6
A-/SIN-		7
A+/SIN+		8
HALL 1		9
TEMP+		10
B-/COS-		11
B+/COS+		12
HALL 2		13
HALL 3		14
SHIELD		SHIELD

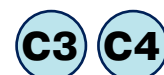
LIMITS	
Function	Color
24VDC PNP Supply	Red
RESERVED	Blue
LIMIT- PNP-N. C.	Brown
LIMIT+ PNP-N. C.	Green
RESERVED	Yellow
LIMIT- NPN-N. C.	Gray
LIMIT+ NPN-N. C.	Pink
GND NPN/PNP	White
SHIELD	SHIELD

CONNECTOR A - Female 25 Pin D-SUB		
Encoder/Limits		
Function		Pin #
24VDC PNP Supply		1
LIMIT- PNP-N. C.		3
LIMIT+ PNP-N. C.		4
+5V		5
A+/SIN+		7
A-/SIN-		8
B+/COS+		9
B-/COS-		10
Z+		11
Z-		12
LIMIT- NPN-N. C.		15
LIMIT+ NPN-N. C.		16
GND Encoder/Halls		17
GND NPN/PNP		18
TEMP+		19
TEMP-		20
HALL 1		21
HALL 2		22
HALL 3		23
SHIELD		SHIELD

### 006-2878-01 - XLM to ACR7xV/IPA Adaptor Cable, Absolute Encoder (R1, R2, R3, R4)



To be used with



CONNECTOR B - Male 15 Pin HD-SUB		
IPA/ACR7 Absolute Encoder		
Function	Color	Pin #
SLO+	Green	1
SLO-	Orange	2
GND	White	3
+5V	Brown	5
MA+	Red	9
TEMP+	Yellow	10
MA-	Blue	13
TEMP-	Black	15
SHIELD	SHIELD	SHIELD

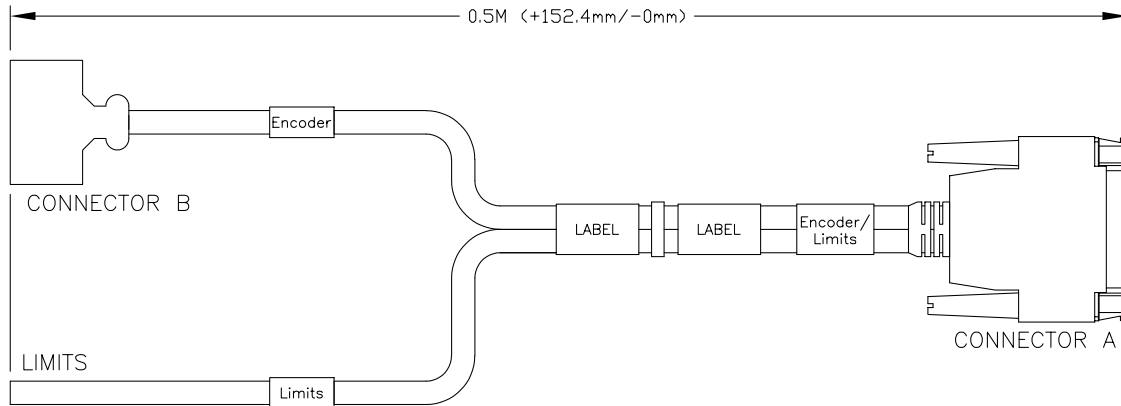
CONNECTOR A - Female 25 Pin D-SUB		
Absolute Encoder		
Function	Color	Pin #
+5V	Brown	5
MA+	Red	7
MA-	Blue	8
SLO+	Green	11
SLO-	Orange	12
GND	White	17
TEMP+	Yellow	19
TEMP-	Black	20
SHIELD	SHIELD	SHIELD

# XLM Series Linear Motor Stages

## XLM Adaptor Cables - P-Series Drive

### 006-2867-01 - XLM to P Series Adaptor Cable, Digital Encoder (E1, E2 & E3)

To be used with



P-SERIES DIGITAL ENCODER 006-2867-01	
CONNECTOR B - 14 POS MINI D RIBBON	
Function	Pin #
HALL 3	1
HALL 2	3
HALL 1	5
GND	7
Z-	8
Z+	9
B-	10
B+	11
A-	12
A+	13
+5V	14
SHIELD	SHIELD

LIMITS	
Function	Color
24VDC PNP Supply	Red
RESERVED	Blue
LIMIT- PNP-N. C.	Brown
LIMIT+ PNP-N. C.	Green
RESERVED	Yellow
LIMIT- NPN-N. C.	Gray
LIMIT+ NPN-N. C.	Pink
GND NPN/PNP	White

P-SERIES ENCODER CONNECTOR A - Female 25 Pin D-SUB	
Encoder/Limits	
Function	Pin #
24VDC PNP Supply	1
LIMIT- PNP-N. C.	3
LIMIT+ PNP-N. C.	4
+5V	5
A+/MA+	7
A-/MA-	8
B+	9
B-	10
Z+/ SLO+	11
Z-/ SLO-	12
LIMIT- NPN-N. C.	15
LIMIT+ NPN-N. C.	16
GND Encoder/Halls	17
GND NPN/PNP	18
HALL 1	21
HALL 2	22
HALL 3	23
SHIELD	SHIELD



# XLM Series Linear Motor Stages

## Drive/Control Solutions



The Intelligent Parker Amplifier or IPA, is an versatile servo drive/controller based on the ACR control platform.

The IPA provides a dual port Ethernet interface which gives the machine builder the flexibility needed to create cost effective motion control solutions.

The IPA operates as a fully programmable stand-alone motion controller with on-board I/O and virtual axis capability or can be integrated into a PLC or PC-based machine control solution.

Software tools are included to optimize motion performance and efficiently monitor and manage the application.

EtherNet/IP gives IPA users a popular connectivity option to PLCs for easy integration of servo motion in larger machine control application. The IPA is an EtherNet/IP adapter device supporting both I/O and Explicit Messaging. Add-On Instructions are available for seamless integration with Logix controllers.



The P-Series drives operate with a variety of machine control architectures and offer sophisticated servo functionality. Accurate and easy to use inertia detection leads to fast set-up of tuning parameters and minimal settling time.

Advanced filtering and gain switching features can be used to increase throughput and improve positioning performance.

For high speed, real-time network applications, the

P-Series is available with, EtherCAT, the fastest growing, most flexible industrial Ethernet protocol. Ideal for use with the Parker Automation Controller, the P-Series also follows the open standards for EtherCAT.

The Pulse version can be configured for step and direction control input and includes analog inputs for torque or velocity control. Select Indexer mode to create up to 64 position table entries triggered via inputs or over a RS422 interface.

# EM Sales Offices

## Australia

Parker Hannifin (Australia) Pty Ltd.  
9 Carrington Road  
Castle Hill NSW 2154  
Australia  
Tel: +61 (0) 2 9842 5111

## India

Parker Hannifin India PVT, LTD.  
Plot El-26, Midc  
Ttc Industrial Area  
Mahape Navi Mumbai,  
400709 India  
Tel: 91-22-41242500

## Thailand

Parker Hannifin (Thailand) Co., Ltd.  
1265 Rama 9 Road, Pattanakarn  
Suanluang, Bangkok 10250  
Thailand  
Tel: +66 2186 7000  
Email: infoTH\_OTH@parker.com

## Brazil

Parker Hannifin Ind. Com Ltda.  
Estrada Municipal Joel De Paula  
900 São Josã Dos Campos  
12247-015 São Paulo Brazil  
Tel: 0800 727 5375  
Email: automation.brazil@parker.com

## Italy

Sales Company Italy Via Caboto 1  
Corsico Corsico (Milano)  
20094 Italy  
Tel: 0039 02 451921  
Email: parker.italy@parker.com

## UK

Parker Hannifin Ltd.  
Tachbrook Park Drive  
Tachbrook Park  
Warwick CV34 6TU  
Tel: +44 (0) 1926 317878  
Email: parker.uk@parker.com

## Canada

Parker Hannifin (Canada) Inc.  
160 Chisholm Dr  
Milton, Ontario L9T 3G9  
Tel: 905-693-3000  
Email: miltoncustservice@parker.com

## Korea

Parker Hannifin Korea  
9th Floor KAMCO Yangjae Tower  
949-3 Dogok 1-dong Gangnam-gu  
Seoul 135-860, Korea  
Tel: 82-2-559-0454

## USA

EMC Division HQ  
850 Arthur Avenue  
Elk Grove Village, IL 60007  
Tel: 800-221-9257  
emn.service@support.parker.com

## China

Parker Hannifin Motion & Control  
(Shanghai) Co., Ltd  
280 Yunqiao Rd. Jin Qiao Export  
Processing Zone  
Shanghai 201206, China  
Tel: 86-21 28995000

## Mexico

Antiguo Camino A San Lorenzo 338  
Zona Industrial  
Toluca, Mexico 54963  
Tel: +52 722 275-4200  
Email: contacto@parker.com

EMC Electromechanical Products  
1140 Sandy Hill Road  
Irwin, PA 15642  
Tel: 800-358-9070  
emn.service@support.parker.com

## France

Sales Company France  
142 Rue De La Foret  
Contamine-Sur-Arve  
France 74130  
Tel: +33 (4) 5025 8025

## Singapore

Parker Hannifin Singapore Pte Ltd  
11 Fourth Chin Bee Road  
Singapore 619702  
Tel: +65 6887 6300

## Germany

Electromechanical Europe  
Parker Hannifin GmbH & Co KG  
Robert-Bosch-Strasse 22  
D-77656 Offenburg  
Germany  
Tel: +49 (0) 7815090  
Email: em-motion@parker.com

## Taiwan

Parker Hannifin Taiwan Co., Ltd  
8F No 22 Wuquan 7th Road  
Wuku District  
New Taipei City, Taiwan 24890  
Tel: +886 2 2298 8987  
enquiry.taiwan@parker.com

