



K SERIES FRAMELESS KIT MOTORS

The Reliable and Compact Approach to Building
Your Own High-Performance Servo Motor



***WARNING - USER RESPONSIBILITY***

FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS AND/OR SYSTEMS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

- This document and other information from Parker Hannifin Corporation, its subsidiaries and authorized distributors provide product and/or system options for further investigation by users having technical expertise.
- The user, through its own analysis and testing, is solely responsible for making the final selection of the system and components and assuring that all performance, endurance, maintenance, safety, and warning requirements of the application are met. The user must analyze all aspects of the application, follow applicable industry standards, and follow the information concerning the product in the current product catalog and in any other materials provided from Parker or its subsidiaries or authorized distributors.
- To the extent that Parker or its subsidiaries or authorized distributors provide component or system options based on data or specifications provided by the user, the user is responsible for determining that such data and specifications are suitable and sufficient for all applications and reasonably foreseeable uses of the components or systems.
- The products described herein, including without limitation, product features, specifications, designs, availability and pricing, are subject to change by Parker Hannifin Corporation and its subsidiaries at any time without notice.

Table of Contents

K Series Kit Motors..... 4
 Direct drive motion construction 4
 Advantages of Direct Drive Frameless Motors 5

Frameless Motor Kit Selection 6

Design Considerations 7

Speed-Torque Performance 8

Model-Specific Performance 9
 Frame Size 032 (32 mm O.D.) 9
 Frame Size 044 (44 mm O.D.) 10
 Frame Size 064 (64 mm O.D.) 11
 Frame Size 089 (89 mm O.D.) 12
 Frame Size 178 (178 mm O.D.) 13

Dimensions 14

Signal Timing 15



If you have questions about the products contained in this catalog, or their applications, please contact:
Parker Hannifin Hydraulic Pumps and Motors Division
parker.com/hps

K SERIES KIT MOTORS

The Reliable and Compact Approach to Building Your Own High Performance Servo Motor

Direct drive motion construction gives equipment designers the advantages of lower costs, increased reliability and improved performance.

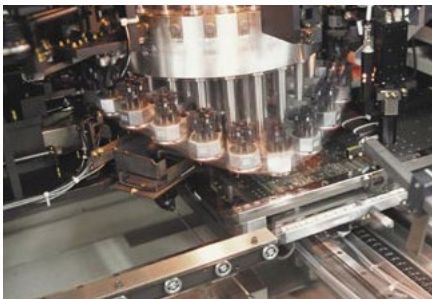
Frameless kit motors are the ideal solution for machine designs that require high performance in small spaces. Kit motors allow for direct integration with a mechanical transmission device, eliminating parts that add size and compliance. Use of frameless kit motors results in a smaller, more reliable motor package.

Lower costs, increased reliability and improved performance are benefits you will enjoy when designing in frameless kit motors like the Parker K-Series.



Applications:

- Automotive
- Machine tool
- Material handling
- Packaging
- Robotics
- Semiconductor



Features & Benefits:

- High torque from 0.5 in-lb (0.06 Nm) to 85.6 in-lb (9.7 Nm)
- High speeds up to 50,000 RPM
- Superior performance – high stiffness and better response
- High reliability – no mechanical transmission devices (couplings, flanges)
- Compact design – minimizes product size
- Low cogging - unique magnetic circuit design decreases cogging

When to Use:

- A significant cost savings
- Reduced mechanical complexity
- Greater design flexibility
- High performance in a compact package
- Improved dynamic response and settling
- Minimum motor size per application space
- Low cogging for smooth operation
- Low inertia for high acceleration

Advantages of Direct Drive Frameless Motors Compared to Traditional Coupled Motors

Parker direct drive brushless kit motors consist of three components:

- The stator and winding
- The rotor with high energy product neodymium magnets
- Hall sensor device for motor commutation

The couplings, motor mounting brackets and extra bearings used in coupled-drive construction can create reliability and performance problems.

Direct drive motors provide higher dynamic stiffness by eliminating the compliance of shaft attachments.

Direct drive motor construction gives equipment designers the advantages of lowered costs, increased reliability and improved performance.

Frameless Kit Motors are the most cost effective direct drive motor solutions available.

Kit motors save space in applications because the couplings, motor mounting brackets and extra bearings you would find in coupled drive construction are eliminated. Since there are fewer moving parts, the direct drive kit motor approach allows for a more reliable and compact design.



Design Features

- 1 Pre-installed integral commutation board with Hall effects is prealigned for easy assembly. Motor and feedback as integrated unit.
- 2 Rare earth magnets provide high-flux in a small volume, high resistance to thermal demagnetizing.
- 3 Rotor assembly for easy mounting directly on the drive shaft with or without keyway.
- 4 Machined grooves to securely lock magnets to rotor and ensures optimized radial location.
- 5 Class H insulation for high temperature operation (up to 155°C) meeting UL approved requirements.
- 6 High-density copper winding for low thermal resistance and consistent performance across all motors.
- 7 Minimized end turns to maximize performance. Formed to minimize motor size.
- 8 Skewed laminations with odd slot counts reduce cogging for precise rotary motion with drastically reduced torque ripple even at low speeds.
- 9 Optimized slot fill for maximum torque-to size ratio; hand inserted to obtain highest slot fill possible maximizing ampere-turns.

Frameless Motor Kit Selection

The selection of a particular frame size and winding for an application is dependent on:

- Volume (diameter and length) requirement
- Power (torque and speed) requirement
- Voltage and current available or required

The first two items are dependent on the load and performance specifications of the application. They result in the selection of a particular frame size (032 through 178) and stack length. The winding to be used will then be determined by voltage and current available or required.

Voltage: The bus voltage and maximum speed will approximately determine the required voltage constant (K_E).

Current: The maximum load and acceleration will determine the amount of current required, determined by the torque constant (KT) associated with the selected voltage constant.

Example: Assume a requirement of 1,000 RPM at 50 oz-in. If a motor with a particular winding having $KE = 18.24$ V/1,000 RPM and $KT = 24.62$ oz in/amp is chosen, it will now require a voltage (BEMF) of 18 volts and current of 2 amp.

NOTE: KE and KT are directly proportional to each other. Increasing KE will also increase KT ; decreasing KE will also decrease KT . The result is that as the voltage requirement changes, the current requirement changes inversely.

Parker has a range of 3 windings that are available for each stack length within a particular frame size to meet the majority of your application requirements. Parker does have additional windings that are available upon request from Parker's Application Engineering Department.

Use the performance specifications and speed torque curves on the following pages to help determine the best solution for your specific application requirements.

Detailed information for all these windings can also be found on our web site at www.parkermotion.com. Please contact Parker application engineers if you need assistance in selecting the proper motor size and power.

Frame Size	Stack Length Range		Continuous Stall Torque		Peak Torque		Rotor Inertia		Core Loss	Winding Amb Thermal Resist	Pole Count	Motor Weight	
	mm	in	Nm	in-lbs	Nm	in-lbs	Kg-m ²	lb-in-sec ²	Pc	°C/W	#	kg	lb
K032	12.7	0.5	0.08	0.7	0.26	2.3	3.2 ⁻⁷	2.8 ⁻⁶	0.06	3.44	4	0.07	0.15
	25.4	1	0.14	1.2	0.45	3.9	6.3 ⁻⁷	5.6 ⁻⁶	0.12	3.44	4	0.12	0.27
	50.8	2	0.23	2.0	0.73	6.4	1.3 ⁻⁶	1.1 ⁻⁵	0.25	3.44	4	0.26	0.57
K044	12.7	0.5	0.21	1.8	0.66	5.8	1.412 ⁻⁶	1.25 ⁻⁵	0.24	2.36	6	0.1	0.3
	25.4	1	0.36	3.2	1.16	10.2	2.9 ⁻⁶	2.6 ⁻⁵	0.49	2.36	6	0.22	0.49
	50.8	2	0.59	5.2	1.88	16.5	5.8 ⁻⁶	5.1 ⁻⁵	1.11	2.36	6	0.4	0.88
K064	12.7	0.5	0.59	5.1	1.86	16.3	9.0 ⁻⁶	8.0 ⁻⁵	0.78	1.68	8	0.29	0.63
	25.4	1	1.03	9.1	3.28	28.9	1.8 ⁻⁵	1.6 ⁻⁴	1.6	1.68	8	0.57	1.26
	50.8	2	1.73	15.2	5.48	48.2	3.6 ⁻⁵	3.2 ⁻⁴	3.23	1.68	8	1.13	2.49
K089	12.7	0.5	1.47	12.9	4.67	41.1	3.7 ⁻⁵	3.3 ⁻⁴	2.14	1.02	12	0.5	1.1
	25.4	1	2.59	22.8	8.23	72.4	7.8 ⁻⁶	6.5 ⁻⁵	4.42	1.02	12	1	2.2
	50.8	2	4.31	37.9	13.69	120.5	1.5 ⁻⁴	1.3 ⁻³	8.95	1.02	12	1.99	4.39
K178	12.7	0.5	8.44	74.2	26.77	235.5	4.7 ⁻⁴	4.1 ⁻³	9.1	0.5	18	2.4	5.29
	25.4	1	15.16	133.4	48.12	423.5	9.2 ⁻⁴	8.1 ⁻³	18.7	0.5	18	3.71	8.18
	50.8	2	25.74	226.5	81.74	719.3	1.8 ⁻³	1.6 ⁻²	37.4	0.5	18	6.34	13.98

Other stack lengths, windings and frame sizes are available. Contact Parker application engineering for more information.

Design Considerations

A number of methods are used to mount the stator and rotor assemblies to the customer product. The method chosen largely depends on the product design, performance requirements (torque, velocity, temperature, etc.) and the manufacturing capabilities of the user.

The following are some brief design consideration notes for your kit motor. Please contact our application engineering group if you require any assistance.

Stator

The stator is typically mounted into a cylindrically shaped hole in the product. It is recommended that a banking step be incorporated at the bottom of the hole to assure accurate and repeatable location of the stator. Alternately, a non-ferrous "plug" can be used to provide a banking surface, which can be removed once the stator is fixed in place. The stator is typically held in position with adhesive for a permanent assembly or with set screws for a removable assembly.

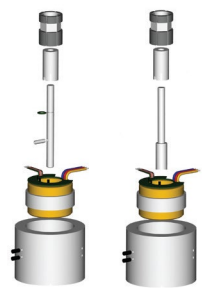
Housing

In designing the housing, provide a means for the stator lead wires (three) and the commutation Hall sensor PCB wires (five) to extend outside of the housing without interfering with the rotor/shaft assembly.

For volume production, a jig should be fabricated that will assure that the stator is located in the same position for each assembly. The yellow dot on the stator provides an index point for accomplishing this. This will eliminate the need to perform mechanical commutation alignment at final assembly.

Rotor

Except for the smaller motors (K032 and K044), the ID of the rotor is usually larger than the shaft diameter. An adapter sleeve allows the rotor to be mounted to the shaft. The rotor/sleeve assembly must be positioned on the shaft such that the magnets are located in line with the stator laminations.



Spring pin/retaining ring method (left); shoulder/adhesive method (right)

If the version in which the commutation PCB assembly is bonded to the end turns is being used, the commutation magnets must be located in proper proximity to the Hall sensors on the PCB. shows two methods for holding the rotor / sleeve on the shaft, either with adhesive or by using a spring pin and retaining ring. When using the adhesive method, a shoulder should be provided on the shaft to properly locate the rotor/sleeve assembly. When using the spring pin/retaining ring method, a slot must be provided in the sleeve that will engage the spring pin in the shaft, thus properly locating the rotor/sleeve assembly.

Use our value added service to integrate your motor design



Half Housed Stator

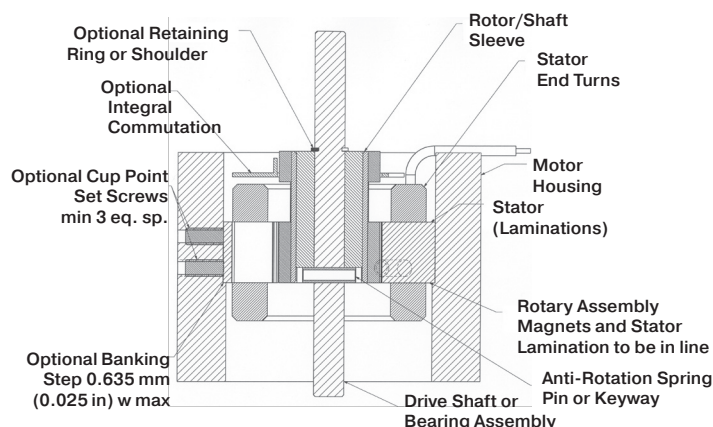
Clamp-on Rotor

With our on-site design and manufacturing capabilities, Parker can offer value added solutions to assist with the integration of your frameless motor and provide "plug and play" solutions to your custom application requirements.

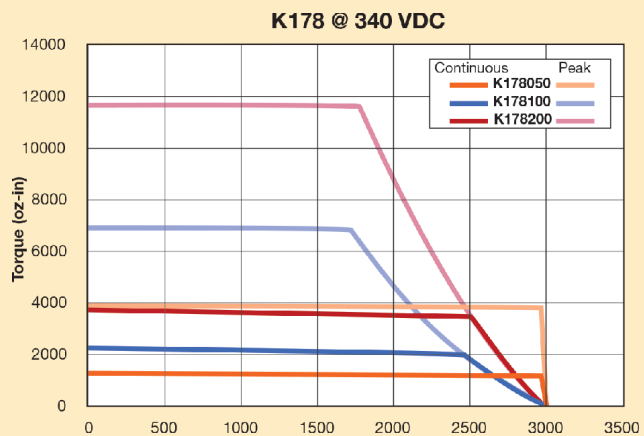
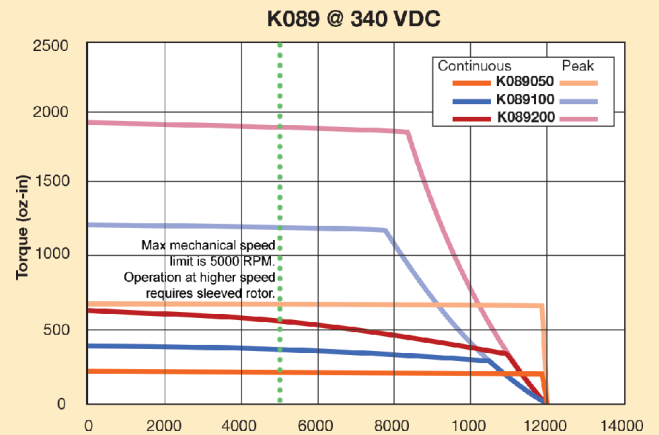
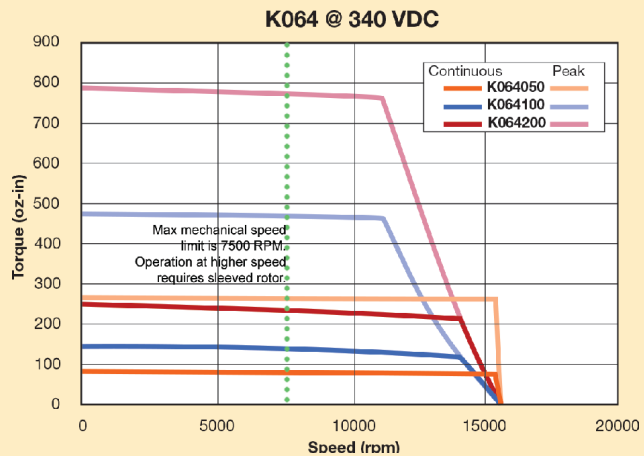
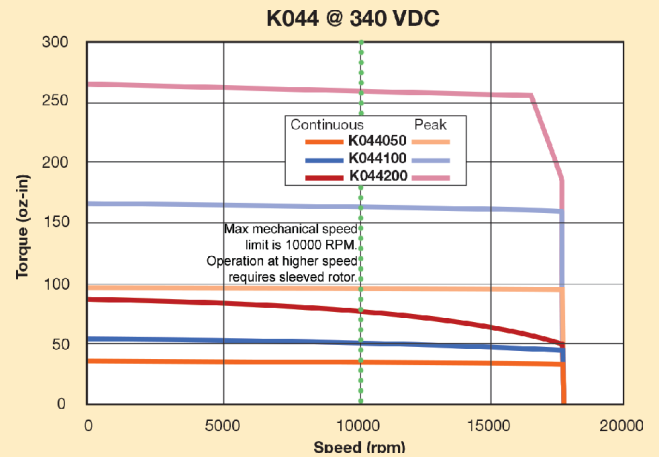
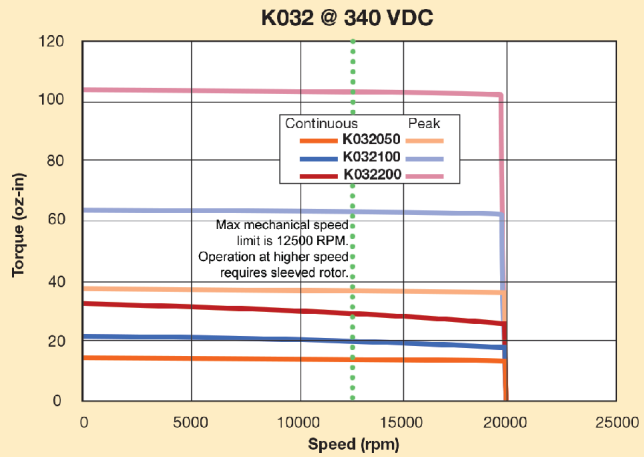
Please contact a Parker Application Engineer to discuss your needs.

Examples of our added design options are illustrated below. Value added capabilities include:

- Aluminum end caps
- Clamp-on rotors
- Kevlar roving or stainless steel sleeve for ultimate reliability & speed
- Potting/encapsulation (including windings) to improve thermal performance and overall robustness



Speed-Torque Performance



Notes:

Please contact the factory for performance at voltages other than 340 VDC.

Parker has numerous additional frame sizes, stack lengths, and windings available to meet virtually any practical combination of voltage and current requirement. Please contact us if you do not find a unit that meets your specific application performance, electrical and mechanical requirements.

Parker MotionSizer sizing software available for free download at: www.parkermotion.com

Frame Size 032 (32 mm O.D.) Model-Specific Performance*

	Symbol	Units	K032050-	K032100-	K032200-
Stall Torque Continuous ^(1,2,3)	T_{cs}	Nm	0.08	0.14	0.23
		in-lb	0.73	1.25	2.04
		oz-in	12	20	33
Peak Torque	T_{pk}	Nm	0.16	0.28	0.46
		in-lb	1.4	2.5	4.1
		oz-in	22.7	39.6	65.1
Max Mechanical Speed**		RPM	12,500	12,500	12,500
Rated Torque ^(1,2,3)	T_r	Nm	0.08	0.12	0.18
		in-lb	0.68	1.10	1.56
		oz-in	11	18	25
Rated Shaft Output Power ^(1,2,3)	P_{out}	kW	0.160	0.259	0.372
DC Bus Voltage ⁽⁴⁾	V_{mbus}	VDC	340	340	340
AC Voltage ⁽⁴⁾	V_s	VAC	240	240	240
Winding-Amb Thermal Resist ⁽⁴⁾	R_{thw-a}	°C/W	3.44	3.44	3.44
Ambient Temp at Rating	T_{amb}	°C	25	25	25
Max Winding Temp	T_{max}	°C	155	155	155
Motor Thermal Time Constant ⁽⁴⁾	t_{th}	minutes	9.74	1.4	9.74
Rotor Shaft Viscous Damping ⁽⁴⁾	B	Nm/krpm	0.0001	0.0002	0.0004
Rotor Shaft Dynamic Friction ⁽⁴⁾	T_f	Nm	0.0003	0.0007	0.0013
Rated Inertia ⁽⁴⁾	J	kg-m ²	3.2 ⁻⁷	6.3 ⁻⁷	1.3 ⁻⁶
		in-lb-sec ²	2.8 ⁻⁶	5.6 ⁻⁶	1.1 ⁻⁶
Number of rotor magnet poles	N_p	# poles	4	4	4
Motor Weigh ⁽⁴⁾		kg	0.07	0.12	0.26
		lb	0.15	0.27	0.57
Motor Weight	F	UL class	H	H	H

Winding Constants			7Y	8Y	EY	7Y	8Y	EY	7Y	8Y	EY
Stall Torque Continuous ^(1,2,3)	$I_{cs(ms)}$	Arms	3.55	2.78	1.75	3.06	3.06	3.06	2.49	1.95	1.23
	$I_{cs(trap)}$	Amps DC	4.35	3.41	2.14	3.75	2.94	1.85	3.05	2.39	1.50
Peak Current ^(1,2,3)	$I_{ck(ms)}$	Arms	11.23	8.79	1.75	3.06	3.06	3.06	2.49	1.95	1.23
	$I_{ck(trap)}$	Amps DC	13.76	10.77	2.14	3.75	2.94	1.85	3.05	2.39	1.50
Voltage Constant ^(6,8)	K_b	V/rad/s	0.02	0.02	0.04	0.04	0.05	0.08	0.07	0.10	0.15
	K_e	Vms/krpm	1.40	1.81	2.87	2.77	3.58	5.70	5.56	7.20	11.45
Torque Constant ^(6,8)	$K_{t(sine)}$	Nm/Arms	0.02	0.03	0.05	0.05	0.06	0.09	0.09	0.12	0.19
	$K_{t(trap)}$	oz-in/Amp DC	2.57	3.45	5.50	5.30	6.85	10.90	10.63	13.76	21.90
Resistance ^(6,8)	R	ohm	1.3	2.2	5.4	1.8	2.9	7.3	2.7	4.4	11.1
Motor Weight	L	mH	0.7	1.1	2.8	1.3	2.2	5.6	2.6	4.4	11.2

* K032 housed in a motor frame, typically an aluminum cylinder with 0.250 in thick walls, mounted to a 6 in x 6 in x 0.5 in aluminum plate.

Parker MotionSizer sizing software available for free download at parker-motion.com.

** Higher rpm possible with sleeved rotor. See speed/torque curves in this brochure or contact Parker Application Engineer for assistance.

(1) Assumes motor is mounted to an aluminum plate with dimensions of 10" X 10" X 1/4" aluminum plate

(2) Maximum winding temperature is 155°C. Optional thermal protection device may be at a lower temperature. No thermal switch provided with kit motors as standard (typically integrated into motor housing); can be provided as custom.

(3) These ratings are valid for Parker Hannifin drives. Other drives may not achieve the same ratings.

(4) Reference only

(6) ±10%

(7) ±30% @ 1kHz

(8) Measured Lead to Lead

Frame Size 044 (44 mm O.D.) Model-Specific Performance*

	Symbol	Units	K044050-	K044100-	K044200-
Stall Torque Continuous ^(1,2,3)	T_{cs}	Nm	0.21	0.36	0.59
		in-lb	1.8	3.22	5.24
		oz-in	29.5	52	84
Peak Torque	T_{pk}	Nm	0.42	0.72	1.2
		in-lb	3.7	6.4	10.6
		oz-in	59.5	102	169.9
Max Mechanical Speed**		RPM	10,000	10,000	10,000
Rated Torque ^(1,2,3)	T_r	Nm	0.18	0.29	0.40
		in-lb	1.6	2.55	3.52
		oz-in	26.2	41	56
Rated Shaft Output Power ^(1,2,3)	P_{out}	kW	0.3	0.539	0.648
DC Bus Voltage ⁽⁴⁾	V_{mbus}	VDC	340	340	340
AC Voltage ⁽⁴⁾	V_s	VAC	240	240	240
Winding-Amb Thermal Resist ⁽⁴⁾	R_{thw-a}	°C/W	2.36	2.36	2.36
Ambient Temp at Rating	T_{amb}	°C	25	25	25
Max Winding Temp	T_{max}	°C	155	155	155
Motor Thermal Time Constant ⁽⁴⁾	t_{th}	minutes	11.0	11	11
Rotor Shaft Viscous Damping ⁽⁴⁾	B	Nm/krpm	0.0004	0.0007	0.0014
Rotor Shaft Dynamic Friction ⁽⁴⁾	T_f	Nm	0.0010	0.0019	0.0039
Rated Inertia ⁽⁴⁾	J	kg-m ²	1.412 ⁻⁶	2.9 ⁻⁶	5.8 ⁻⁶
		in-lb-sec ²	1.250 ⁻⁵	2.6 ⁻⁵	5.1 ⁻⁵
Number of rotor magnet poles	N_p	# poles	6	6	6
Motor Weigh ⁽⁴⁾		kg	0.1	0.22	0.40
		lb	0.3	0.49	0.88
Motor Weight	F	UL class	H	H	H

Winding Constants			7Y	8Y	EY	7Y	8Y	EY	7Y	8Y	EY
Stall Torque Continuous ^(1,2,3)	$I_{cs(ms)}$	Arms	4.63	3.7	2.31	4.01	3.19	1.60	3.28	2.61	1.64
	$I_{cs(trap)}$	Amps DC	5.67	4.5	2.83	4.91	3.91	1.95	4.01	3.20	2.00
Peak Current ^(1,2,3)	$I_{ck(ms)}$	Arms	14.63	11.7	7.31	12.67	10.09	5.04	10.35	8.24	5.17
	$I_{ck(trap)}$	Amps DC	17.92	14.3	8.95	15.52	12.36	6.17	12.68	10.10	6.33
Voltage Constant ^(6,8)	K_b	V/rad/s	0.04	0.05	0.07	0.07	0.09	0.19	0.15	0.19	0.30
	K_e	Vms/krpm	2.75	3.44	5.50	5.54	6.93	13.86	11.04	13.80	22.08
Torque Constant ^(6,8)	$K_{t(sine)}$	Nm/Arms	0.04	0.06	0.09	0.09	0.11	0.23	0.18	0.23	0.36
	$K_{t(trap)}$	oz-in/Amp DC	5.26	6.57	10.51	10.60	13.25	26.51	21.11	26.39	42.23
Resistance ^(6,8)	R	ohm	1.1	1.79	4.5	4.5	2.4	9.5	2.3	3.6	9.1
Motor Weight	L	mH	0.8	1.3	3.2	1.6	2.5	10.0	3.2	5.0	12.8

* K044 housed in a motor frame, typically an aluminum cylinder with 0.250 in thick walls, mounted to a 6 in x 6 in x 0.5 in aluminum plate.

Parker MotionSizer sizing software available for free download at parkermotion.com.

** Higher rpm possible with sleeved rotor. See speed/torque curves in this brochure or contact Parker Application Engineer for assistance.

(1) Assumes motor is mounted to an aluminum plate with dimensions of 10" X 10" X 1/4" aluminum plate

(2) Maximum winding temperature is 155°C. Optional thermal protection device may be at a lower temperature. No thermal switch provided with kit motors as standard (typically integrated into motor housing); can be provided as custom.

(3) These ratings are valid for Parker Hannifin drives. Other drives may not achieve the same ratings.

(4) Reference only

(6) ±10%

(7) ±30% @ 1kHz

(8) Measured Lead to Lead

Frame Size 064 (64 mm O.D.) Model-Specific Performance*

	Symbol	Units	K064050-	K064100-	K064200-
Stall Torque Continuous ^(1,2,3)	T_{cs}	Nm	0.59	1.03	1.73
		in-lb	5.18	9.16	15.28
		oz-in	83	147	244
Peak Torque	T_{pk}	Nm	1.6	2.9	5.1
		in-lb	14.2	25.7	45.1
		oz-in	226.6	410.6	722.2
Max Mechanical Speed**		RPM	7,500	7,500	7,500
Rated Torque ^(1,2,3)	T_r	Nm	0.49	0.86	1.56
		in-lb	4.30	7.58	13.77
		oz-in	69	121	220
Rated Shaft Output Power ^(1,2,3)	P_{out}	kW	0.783	0.964	0.866
DC Bus Voltage ⁽⁴⁾	V_{mbus}	VDC	340	340	340
AC Voltage ⁽⁴⁾	V_s	VAC	240	240	240
Winding-Amb Thermal Resist ⁽⁴⁾	R_{thw-a}	°C/W	1.68	1.68	1.68
Ambient Temp at Rating	T_{amb}	°C	25	25	25
Max Winding Temp	T_{max}	°C	155	155	155
Motor Thermal Time Constant ⁽⁴⁾	t_{th}	minutes	22	22	22
Rotor Shaft Viscous Damping ⁽⁴⁾	B	Nm/krpm	0.0010	0.0021	0.0042
Rotor Shaft Dynamic Friction ⁽⁴⁾	T_f	Nm	0.0030	0.0060	0.0120
Rated Inertia ⁽⁴⁾	J	kg-m ²	9.0 ⁻⁶	1.8 ⁻⁵	3.6 ⁻⁵
		in-lb-sec ²	8.0 ⁻⁵	1.6 ⁻⁴	3.2 ⁻⁴
Number of rotor magnet poles	N_p	# poles	8	8	8
Motor Weigh ⁽⁴⁾		kg	0.29	0.57	1.13
		lb	0.63	1.26	2.49
Motor Weight	F	UL class	H	H	H

Winding Constants			8Y	9Y	EY	8Y	9Y	EY	8Y	9Y	EY
Stall Torque Continuous ^(1,2,3)	$I_{cs(ms)}$	Arms	4.43	3.53	2.78	3.92	3.13	2.46	3.28	2.61	2.05
	$I_{cs(trap)}$	Amps DC	5.43	4.33	3.41	4.81	3.83	3.01	4.01	3.20	2.52
Peak Current ^(1,2,3)	$I_{ck(ms)}$	Arms	14.02	11.16	8.79	12.40	9.88	7.77	10.36	8.25	6.49
	$I_{ck(trap)}$	Amps DC	17.17	13.67	10.76	15.19	12.10	9.52	12.68	10.10	7.95
Voltage Constant ^(6,8)	K_b	V/rad/s	0.11	0.14	0.17	0.22	0.27	0.35	0.43	0.54	0.70
	K_e	Vms/krpm	8.05	10.07	12.88	16.10	20.13	25.77	32.21	40.26	51.54
Torque Constant ^(6,8)	$K_{t(sine)}$	Nm/Arms	0.13	0.17	0.21	0.27	0.33	0.43	0.53	0.67	0.85
	$K_{t(trap)}$	oz-in/Amp DC	15.40	19.25	24.64	30.80	38.50	49.28	61.60	76.99	98.55
Resistance ^(6,8)	R	ohm	1.7	2.7	4.4	2.2	3.5	5.6	3.2	5.0	8.1
Motor Weight	L	mH	2.0	3.1	5.1	4.0	6.3	10.2	8.0	12.5	20.4

* K064 housed in a motor frame, typically an aluminum cylinder with 0.250 in thick walls, mounted to a 6 in x 6 in x 0.5 in aluminum plate.

Parker MotionSizer sizing software available for free download at parkermotion.com.

** Higher rpm possible with sleeved rotor. See speed/torque curves in this brochure or contact Parker Application Engineer for assistance.

(1) Assumes motor is mounted to an aluminum plate with dimensions of 10" X 10" X 1/4" aluminum plate

(2) Maximum winding temperature is 155°C. Optional thermal protection device may be at a lower temperature. No thermal switch provided with kit motors as standard (typically integrated into motor housing); can be provided as custom.

(3) These ratings are valid for Parker Hannifin drives. Other drives may not achieve the same ratings.

(4) Reference only

(6) ±10%

(7) ±30% @ 1kHz

(8) Measured Lead to Lead

Frame Size 089 (89 mm O.D.) Model-Specific Performance*

	Symbol	Units	K089050-	K089100-	K089200-
Stall Torque Continuous ^(1,2,3)	T_{cs}	Nm	1.47	2.59	4.31
		in-lb	13.01	22.94	38.12
		oz-in	208	367	610
Peak Torque	T_{pk}	Nm	3.5	6.6	11.7
		in-lb	31.0	58.4	103.5
		oz-in	495.6	934.6	1,656.7
Max Mechanical Speed**		RPM	5,000	5,000	5,000
Rated Torque ^(1,2,3)	T_r	Nm	1.16	2.07	3.77
		in-lb	10.23	18.35	33.32
		oz-in	164	294	533
Rated Shaft Output Power ^(1,2,3)	P_{out}	kW	1.443	1.716	1.590
DC Bus Voltage ⁽⁴⁾	V_{mbus}	VDC	340	340	340
AC Voltage ⁽⁴⁾	V_s	VAC	240	240	240
Winding-Amb Thermal Resist ⁽⁴⁾	R_{thw-a}	°C/W	1.02	1.02	1.02
Ambient Temp at Rating	T_{amb}	°C	25	25	25
Max Winding Temp	T_{max}	°C	155	155	155
Motor Thermal Time Constant ⁽⁴⁾	t_{th}	minutes	28	28	28
Rotor Shaft Viscous Damping ⁽⁴⁾	B	Nm/krpm	0.0034	0.0068	0.0136
Rotor Shaft Dynamic Friction ⁽⁴⁾	T_f	Nm	0.0097	0.0193	0.0387
Rated Inertia ⁽⁴⁾	J	kg-m ²	3.7 ⁻⁵	7.8 ⁻⁶	1.5 ⁻⁴
		in-lb-sec ²	3.3 ⁻⁴	6.9 ⁻⁵	1.3 ⁻³
Number of rotor magnet poles	N_p	# poles	12	12	12
Motor Weigh ⁽⁴⁾		kg	0.50	1.00	1.99
		lb	1.1	2.2	4.39
Motor Weight	F	UL class	H	H	H

Winding Constants			6Y	7Y	9Y	6Y	7Y	9Y	4Y	7Y	9Y
Stall Torque Continuous ^(1,2,3)	$I_{cs(ms)}$	Arms	8.44	6.77	4.30	7.44	5.97	3.79	9.96	4.97	3.15
	$I_{cs(trap)}$	Amps DC	10.33	8.30	5.26	9.12	7.32	4.64	12.19	6.09	3.89
Peak Current ^(1,2,3)	$I_{ck(ms)}$	Arms	26.66	21.40	13.58	23.52	18.88	11.98	31.46	15.71	9.97
	$I_{ck(trap)}$	Amps DC	32.66	26.21	16.63	28.81	23.12	14.67	38.53	19.24	12.21
Voltage Constant ^(6,8)	K_b	V/rad/s	0.14	0.18	0.28	0.29	0.36	0.56	0.36	0.71	1.11
	K_e	Vms/krpm	10.73	13.21	20.64	21.47	26.42	41.28	26.42	52.84	82.56
Torque Constant ^(6,8)	$K_{t(sine)}$	Nm/Arms	0.18	0.22	0.34	0.35	0.44	0.68	0.44	0.87	1.37
	$K_{t(trap)}$	oz-in/Amp DC	20.52	25.26	39.47	41.05	50.52	78.94	50.52	101.05	157.88
Resistance ^(6,8)	R	ohm	0.8	1.2	3.0	1.0	1.6	3.9	0.6	2.3	5.7
Motor Weight	L	mH	1.2	1.8	4.5	2.4	3.7	8.9	1.8	7.3	17.9

* K089 housed in a motor frame, typically an aluminum cylinder with 0.250 in thick walls, mounted to a 8 in x 8 in x 0.5 in aluminum plate.

Parker MotionSizer sizing software available for free download at parker-motion.com.

** Higher rpm possible with sleeved rotor. See speed/torque curves in this brochure or contact Parker Application Engineer for assistance.

(1) Assumes motor is mounted to an aluminum plate with dimensions of 12" X 12" X 1/2" aluminum plate

(2) Maximum winding temperature is 155°C. Optional thermal protection device may be at a lower temperature. No thermal switch provided with kit motors as standard (typically integrated into motor housing); can be provided as custom.

(3) These ratings are valid for Parker Hannifin drives. Other drives may not achieve the same ratings.

(4) Reference only

(6) ±10%

(7) ±30% @ 1kHz

(8) Measured Lead to Lead

Frame Size 178 (178 mm O.D.) Model-Specific Performance*

	Symbol	Units	K0178050-	K0178100-	K0178200-
Stall Torque Continuous ^(1,2,3)	T_{cs}	Nm	8.44	15.16	25.74
		in-lb	74.67	134.18	277.75
		oz-in	1195	2147	3644
Peak Torque	T_{pk}	Nm	15.7	29.8	55.3
		in-lb	138.9	263.7	489.4
		oz-in	2,223.1	4,219.7	7,830.5
Max Mechanical Speed**		RPM	3000	3000	3000
Rated Torque ^(1,2,3)	T_r	Nm	7.44	13.94	24.35
		in-lb	65.83	123.37	215.50
		oz-in	1,053	1,974	3,448
Rated Shaft Output Power ^(1,2,3)	P_{out}	kW	2.321	2.372	2.099
DC Bus Voltage ⁽⁴⁾	V_{mbus}	VDC	340	340	340
AC Voltage ⁽⁴⁾	V_s	VAC	240	240	240
Winding-Amb Thermal Resist ⁽⁴⁾	R_{thw-a}	°C/W	0.5	0.5	0.5
Ambient Temp at Rating	T_{amb}	°C	25	25	25
Max Winding Temp	T_{max}	°C	155	155	155
Motor Thermal Time Constant ⁽⁴⁾	t_{th}	minutes	108	108	108
Rotor Shaft Viscous Damping ⁽⁴⁾	B	Nm/krpm	0.0561	0.1123	0.2246
Rotor Shaft Dynamic Friction ⁽⁴⁾	T_f	Nm	0.0485	0.0970	0.1940
Rated Inertia ⁽⁴⁾	J	kg-m ²	4.7 ⁻⁴	9.2 ⁻⁴	1.8 ⁻³
		in-lb-sec ²	4.1 ⁻³	8.1 ⁻³	1.6 ⁻²
Number of rotor magnet poles	N_p	# poles	18	18	18
Motor Weigh ⁽⁴⁾		kg	2.40	3.71	6.34
		lb	5.29	8.18	13.98
Motor Weight	F	UL class	H	H	H

Winding Constants			7Y	8Y	EY	7Y	8Y	EY	7Y	8Y	EY
Stall Torque Continuous ^(1,2,3)	$I_{cs(ms)}$	Arms	16.94	10.68	6.74	9.60	7.60	6.06	8.15	6.46	5.15
	$I_{cs(trap)}$	Amps DC	20.75	13.08	8.26	11.75	9.31	7.42	9.98	7.91	6.30
Peak Current ^(1,2,3)	$I_{ck(ms)}$	Arms	53.54	33.75	21.30	30.32	24.03	19.14	25.76	20.41	16.26
	$I_{ck(trap)}$	Amps DC	65.58	41.33	26.09	37.14	29.43	23.44	31.55	25.00	19.91
Voltage Constant ^(6,8)	K_b	V/rad/s	0.41	0.65	1.02	1.30	1.64	2.05	2.59	3.28	4.10
	K_e	Vms/krpm	30.34	48.04	75.85	96.06	121.34	151.67	192.12	242.67	303.34
Torque Constant ^(6,8)	$K_{t(sine)}$	Nm/Arms	0.50	0.79	1.25	1.59	2.01	2.51	3.18	4.01	5.02
	$K_{t(trap)}$	oz-in/Amp DC	58.02	91.86	145.05	183.69	232.03	290.03	367.38	464.06	580.08
Resistance ^(6,8)	R	ohm	0.4	1.0	2.5	1.2	2.0	3.1	1.7	2.7	4.3
Motor Weight	L	mH	1.5	3.8	9.6	7.7	12.2	19.1	15.3	24.5	38.2

* K178 housed in a motor frame, typically an aluminum cylinder with 0.250 in thick walls, mounted to a 8 in x 8 in x 0.5 in aluminum plate.

Parker MotionSizer sizing software available for free download at parker-motion.com.

** Higher rpm possible with sleeved rotor. See speed/torque curves in this brochure.

(1) Assumes motor is mounted to an aluminum plate with dimensions of 12" X 12" X 1" aluminum plate

(2) Maximum winding temperature is 155°C. Optional thermal protection device may be at a lower temperature. No thermal switch provided with kit motors as standard (typically integrated into motor housing); can be provided as custom.

(3) These ratings are valid for Parker Hannifin drives. Other drives may not achieve the same ratings.

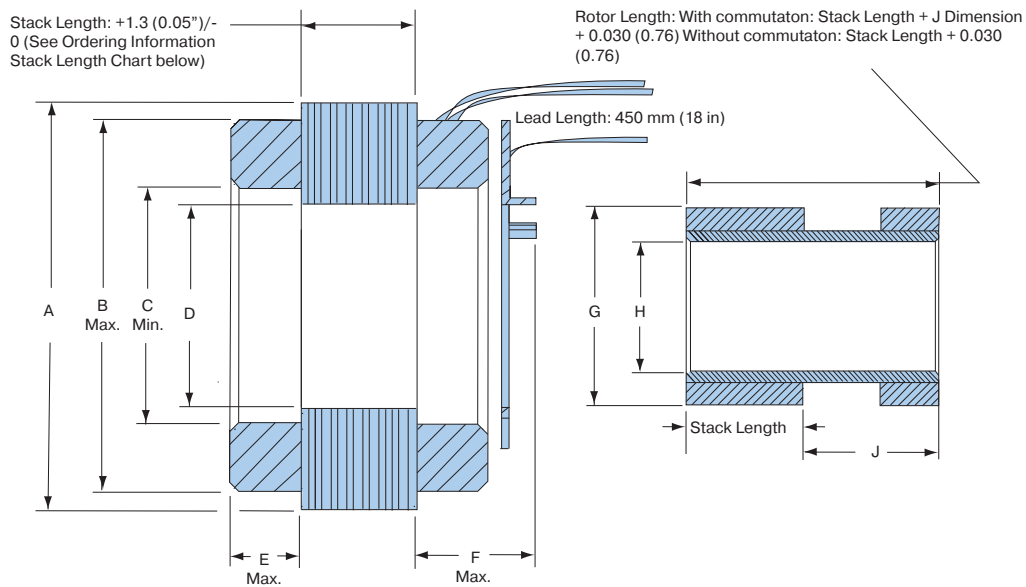
(4) Reference only

(6) ±10%

(7) ±30% @ 1kHz

(8) Measured Lead to Lead

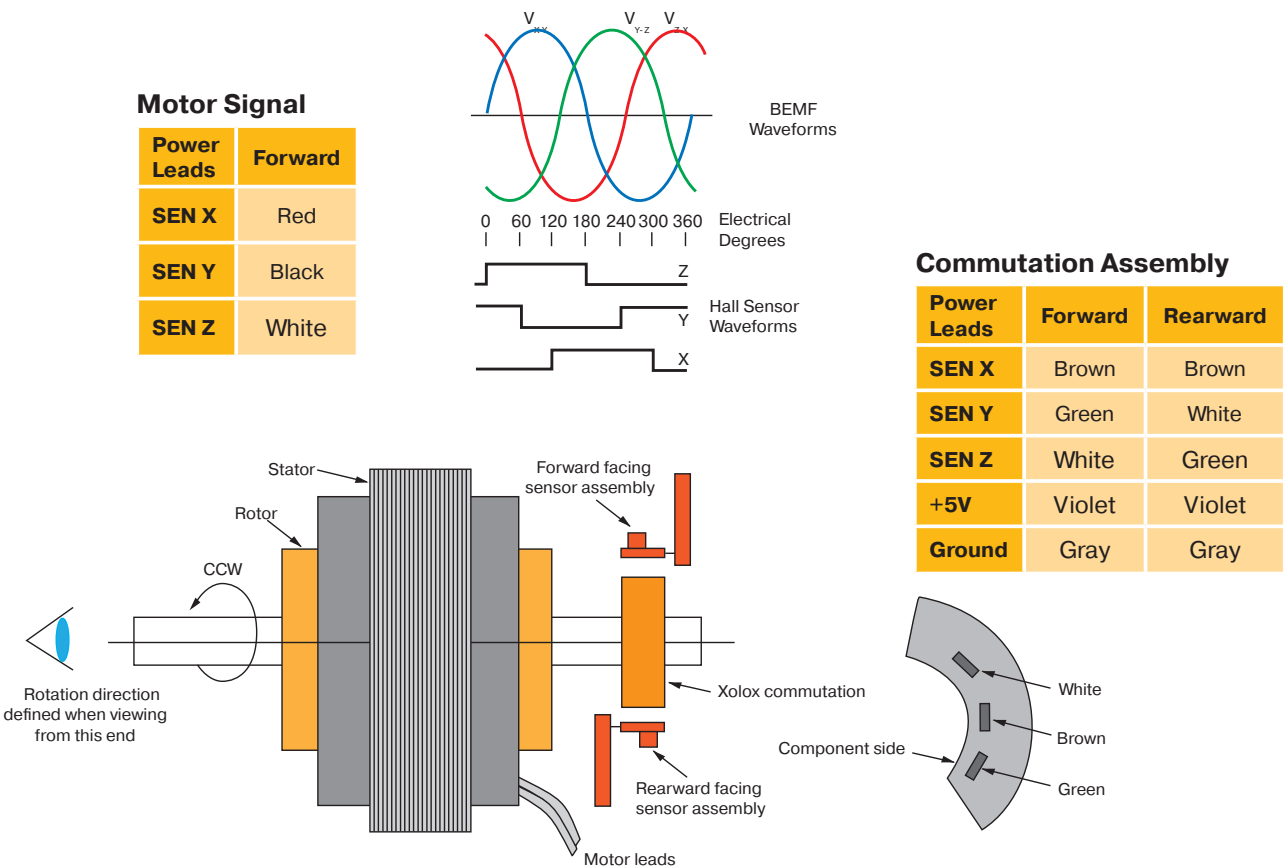
Dimensions



Frame Size	A	B	C	D	E	F	G	H	J
	O.D.	End Turns O.D. Max	End Turns I.D. Min	I.D.	End Turns Length Max	Commutation Length	Rotor O.D. Max	Rotor I.D.	Commutation Length
K032	1.251 (31.78)	1.17	0.65	0.593 (15.06)	0.25	0.57 (14.5)	0.559	0.301 (7.65)	0.52 (13.2)
	1.249 (31.72)	(29.7)	(16.5)	0.583 (14.80)	(6.4)		(14.20)	0.299 (7.60)	
K044	1.751 (44.48)	1.65	1.02	0.880 (22.35)	0.31	0.65 (16.5)	0.845	0.551 (14.00)	0.58 (14.7)
	1.748 (44.40)	(42.0)	(25.9)	0.870 (22.10)	(7.9)		(21.46)	0.549 (13.95)	
K064	2.501 (63.53)	2.39	1.50	1.385 (35.18)	0.38	0.69 (17.5)	1.350	0.927 (23.55)	0.62 (15.7)
	2.498 (63.45)	(60.7)	(38.1)	1.375 (34.92)	(9.7)		(34.29)	0.925 (23.50)	
K089	3.501 (88.93)	3.38	2.15	2.105 (53.47)	0.39	0.69 (17.5)	2.050	1.601 (40.67)	0.66 (16.7)
	3.498 (88.85)	(85.9)	(54.6)	2.095 (53.21)	(9.9)		(52.07)	1.599 (40.61)	
K178	7.003 (177.88)	6.80	4.39	4.356 (110.65)	0.60	*	4.319	3.771 (95.78)	*
	6.997 (177.72)	(172.7)	(111.5)	4.346 (110.39)	(15.3)		(109.70)	3.769 (95.73)	

*Integral commutation not available

Signal Timing



Ordering Information

	①	②	③	④	⑤	⑥
Order Example:	K	044	100	E	Y	2

Fill in an order code from each of the numbered fields to create a complete model order code.

- ① **Series**

K Frameless Kit Motor
- ② **Frame Size (Stator O.D.)**

032 32 mm

044 44 mm

064 64 mm

089 89 mm

178 178 mm
- ③ **Stack Length**

055 0.50 in

100 1.00 in

200 2.00 in
- ④ **Windings**

Refer to "Winding Constants" for selected frame size for winding performance and selection (pages 5-9)
- ④ **Connection Options***

Y Wye

*Consult factory for special connection options
- ④ **Commutation***

1 Without

2 With integral

*Integral commutation is not available for the K178



Parker Hannifin Corporation
**Hydraulic Pumps and
Motors Division**
14249 Industrial Pkwy
Marysville, OH 43040 USA
phone 937 644 4435
fax 937 642 3639
www.parker.com/hps

3/2025

Your Local Authorized Parker Distributor

© 2025 Parker Hannifin Corporation

