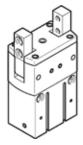
Radial gripper HGRT-25-A Part number: 563908







Data sheet

| Feature | values |
|---|--|
| Size | 25 |
| Max. replacement accuracy | <= 0.2 mm |
| Max. angular gripper jaw backlash ax,ay | <= 0.1 deg |
| Max. opening angle | 180 deg |
| Rotationally symmetrical | <= 0.2 mm |
| Repetition accuracy, gripper | <= 0.02 mm |
| Number of gripper fingers | 2 |
| Assembly position | Any |
| Mode of operation | double-acting |
| Gripper function | radial |
| Design structure | guided motion sequence |
| Position detection | For proximity sensor |
| | For inductive sensors |
| Working pressure | 3 8 bar |
| Max. operating frequency of gripper | <= 3 Hz |
| Min. opening time at 6 bar | 309 ms |
| Min. closing time at 6 bar | 343 ms |
| Operating medium | Compressed air in accordance with ISO8573-1:2010 [7:4:4] |
| Note on operating and pilot medium | Lubricated operation possible (subsequently required for further |
| | operation) |
| Corrosion resistance classification CRC | 2 |
| Ambient temperature | 5 60 °C |
| Total gripping torque at 6 bar, opening | 1,348 Ncm |
| Total gripping torque at 6 bar, closing | 1,208 Ncm |
| Mass moment of inertia | 2.1 kgcm2 |
| Max. force on gripper jaw Fz static | 180 N |
| Max. torque at gripper My static | 10 Nm |
| Max. torque at gripper Mz static | 1 Nm |
| Lubrication interval for guide components | 10 Mio SP |
| Product weight | 540 g |
| Mounting type | Internal thread and centering sleeve |
| Pneumatic connection | M5 |
| Materials note | Free of copper and PTFE |
| | Conforms to RoHS |
| Materials information, housing | Aluminum |
| | Smooth anodized |
| Materials information for gripper jaws | Steel |
| | Hardened |