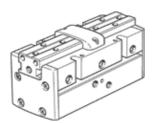
Parallel gripper HGPP-25-A-G1 Part number: 525662



Precise, for position sensing via hall effect sensor or inductive sensors. With gripping force retention when opening ...-G1.





Data sheet

Feature	values
Size	25
Stroke per gripper jaw	10 mm
Max. replacement accuracy	0.1 mm
Repetition accuracy, gripper	<= 0.02 mm
Number of gripper fingers	2
Mode of operation	double-acting
Gripper function	Parallel
Gripper force back-up	On opening
Design structure	Rack and pinion
Position detection	For Hall sensors
	For inductive sensors
Working pressure	5 8 bar
Max. operating frequency of gripper	4 Hz
Min. opening time at 6 bar	58 ms
Min. closing time at 6 bar	164 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2
Ambient temperature	5 60 °C
Max. force on gripper jaw Fz static	380 N
Max. torque at gripper Mx static	21 Nm
Max. torque at gripper My static	21 Nm
Max. torque at gripper Mz static	21 Nm
Max. ground per external gripper finger	250 g
Product weight	910 g
Mounting type	with internal (female) thread
Pneumatic connection	M5
Materials note	Free of copper and PTFE
Materials information for cover cap	POM
Materials information, housing	Wrought Aluminum alloy
	Hard anodized
Materials information for gripper jaws	Wrought Aluminum alloy
	Nickel plated