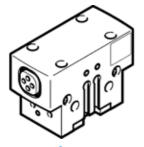
## Parallel gripper HGPD-16-A Part number: 1132936







## **Data sheet**

Feature	values
Size	16
Stroke per gripper jaw	3 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. gripper jaw backlash Sz	<= 0.02 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.03 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Design structure	Inclined plane
	guided motion sequence
Position detection	For proximity sensor
Total force at 6 bar, opening	107 N
Total force at 6 bar, closing	94 N
Working pressure	3 8 bar
Working pressure, sealing air	0 0.5 bar
Max. operating frequency of gripper	<= 3 Hz
Min. opening time at 6 bar	15 ms
Min. closing time at 6 bar	17 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	54 N
Gripping force per gripper jaw at 6 bar, closing	47 N
Mass moment of inertia	0.22 kgcm2
Max. force on gripper jaw Fz static	150 N
Max. torque at gripper Mx static	8 Nm
Max. torque at gripper My static	4 Nm
Max. torque at gripper Mz static	3 Nm
Lubrication interval for guide components	5,000,000 Mio SP
Max. ground per external gripper finger	25 g
Product weight	100 g
Mounting type	Optional
	Internal thread and centering sleeve
	With through-hole and centering sleeve
	With through-hole and dowel pin
	With internal thread and dowel pin
Pneumatic connection, sealing air	M3
Pneumatic connection	M5
Materials note	Free of copper and PTFE
	Conforms to RoHS
Materials information for cover cap	High alloy steel, non-corrosive
Materials information, housing	Aluminum
	Anodized
Materials information for gripper jaws	Steel
	Hardened