Radial gripper DHRS-10-A Part number: 1310159







Data sheet

| Feature | values |
|---|---|
| Size | 10 |
| Max. replacement accuracy | <= 0.2 mm |
| Max. opening angle | 180 deg |
| Rotationally symmetrical | <= 0.2 mm |
| Repetition accuracy, gripper | <= 0.1 mm |
| Number of gripper fingers | 2 |
| Assembly position | Any |
| Mode of operation | double-acting |
| Gripper function | radial |
| Design structure | guided motion sequence |
| Position detection | For Hall sensors |
| Working pressure | 2 8 bar |
| Max. operating frequency of gripper | <= 4 Hz |
| Min. opening time at 6 bar | 35 ms |
| Min. closing time at 6 bar | 91 ms |
| Operating medium | Compressed air in accordance with ISO8573-1:2010 [7:4:4] |
| Note on operating and pilot medium | Lubricated operation possible (subsequently required for further operation) |
| Corrosion resistance classification CRC | 1 |
| Ambient temperature | 5 60 °C |
| Total gripping torque at 6 bar, opening | 21 Ncm |
| Total gripping torque at 6 bar, closing | 15 Ncm |
| Mass moment of inertia | 0.03 kgcm2 |
| Max. force on gripper jaw Fz static | 30 N |
| Max. torque at gripper Mx static | 0.8 Nm |
| Max. torque at gripper My static | 0.8 Nm |
| Max. torque at gripper Mz static | 0.8 Nm |
| Product weight | 44 g |
| Mounting type | Optional |
| | Internal thread and centering sleeve |
| | With through-hole and centering sleeve |
| Pneumatic connection | M3 |
| Materials note | Conforms to RoHS |
| Materials information for cover cap | PA |
| Materials information, housing | Wrought Aluminum alloy |
| | Hard anodized |
| Materials information for gripper jaws | High alloy steel |