

MLFB-Ordering data

6SL3210-1KE23-2UF1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

ltem no. :
Consignment no. :
Project :

Rated data		General tech. specifications		
Input		Power factor λ	0.7	70 0.85
Number of phases	3 AC	Offset factor cos φ	0.9	95
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.9	97
Line frequency	47 63 Hz	Sound pressure level (1m)	66	dB
Rated current (LO)	40.60 A	Power loss	0.4	13 kW
Rated current (HO)	36.40 A	Filter class (integrated)	Un	filtered
Output		Ambion	t conditio	nc
Number of phases	3 AC	Ambient conditions		
Rated voltage	400 V	Cooling	Air coolin	ig using an integrated fan
Rated power IEC 400V (LO)	15.00 kW	Cooling air requirement	0.010 m3	(0 () () (1 3/2)
Rated power NEC 480V (LO)	20.00 hp	Cooling air requirement		/s (0.636 ft ³ /s)
Rated power IEC 400V (HO)	11.00 kW		1000 m (3280.84 ft)
Rated power NEC 480V (HO)	15.00 hp	Ambient temperature		
Rated current (IN)	32.00 A	Operation	-10 40	°C (14 104 °F)
Rated current (LO)	31.00 A	Transport		°C (-40 158 °F)
Rated current (HO)	25.00 A	Storage	-40 70	°C (-40 158 °F)
Max. output current	50.00 A	Relative humidity		
Pulse frequency	4 kHz	95 % At 40 °C (104 °F), condo Max. operation and icing not permissible		
Output frequency for vector control	0 240 Hz			
output inequency for vector control	0 2 10 112	Closed-loop control techniques		hniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parame	terizable	Yes
		V/f with flux current control (FC	C)	Yes
Overload capability		V/f ECO linear / square-law		Yes
Low Overload (LO)		Sensorless vector control		Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time		Vector control, with sensor		No
		Encoderless torque control		No
High Overload (HO)				

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Torque control, with encoder

No



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Mechanical data		Com	Figure similar Communication		
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP		
Size	FSC	Connections			
Net weight	4.40 kg (9.70 lb)	Signal cable			
Width	140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Height	295 mm (11.61 in)	Line side			
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals		
Inputs / out	tputs	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)		
itandard digital inputs		Motor end			
Number	6	Version	Plug-in screw terminals		
Switching level: 0→1	11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)		
Switching level: 1→0	5 V	DC link (for braking resistor)			
Max. inrush current	15 mA	Version	Plug-in screw terminals		
ail-safe digital inputs			-		
Number	1	Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)		
Digital outputs		Line length, max.	15 m (49.21 ft)		
Number as relay changeover contact	1	PE connection Max. motor cable length	On housing with M4 screw		
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)		
Number as transistor	1	Unshielded	150 m (492.13 ft)		
Output (resistive load)	DC 30 V, 0.5 A	Standards			
Analog / digital inputs					
Number	1 (Differential input)	Compliance with standards	UL, cUL, CE, C-Tick (RCM)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltag Directive 2006/95/EC		
witching threshold as digital in	put				
0→1	4 V				
1→0	1.6 V				
Analog outputs					
Number	1 (Non-isolated output)				
PTC/ KTY interface					

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\mathrm{C}$



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The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values