

Continuing Education Course #208 Future Highways - Automated Vehicles

1. Automated vehicles have effect: a. Decreased greenhou b. Increased productivi c. Decreased energy co d. Improved quality of e. All of the above	onsumption
2. The U.S. Interstate High a. 20,000 b. 45,000 c. 60,000 d. 100,000	away System is comprised of approximately how many miles?
3. Approximately how man conditions in 2017? a. 5.8 b. 6.8 c. 7.8 d. 8.8	ny additional billions of hours did Americans spend traveling due to congested traffic
4. Trucks contribute what p a. 7 b. 8 c. 10 d. 11	percent to urban congestion?
5. How many billions of do a. 100 b. 125 c. 166 d. 200	ollars in time and fuel did commuters spend due to congestion in 2017?
6. Transportation contribut a. 15 b. 25 c. 29 d. 32	ed what percentage of the U.S. Greenhouse Gas Emissions in 2019?

7. There were approximately how many millions of injuries due to automobile crashes in the U.S. in 2019?

○ a. 1.5○ b. 2.74○ c. 2.5○ d. 3.0
What is the biggest reason for automobile crashes? a. Poor pavement condition b. Adverse weather c. Human error d. Vehicle mechanical failure
Automated highway systems could achieve reductions in crash frequency, energy consumption, vehicle emissions, ad a. Personal travel mobility b. Total person-miles of travel c. Travel times d. Pavement maintenance
0. The future advances of automated vehicles, according to NHTSA research, could prevent 50 percent of crashes avolving non-impaired vehicles. a. True b. False
1. V2X is a more general term for vehicle-to-vehicle and vehicle-to-infrastructure communication technologies. a. True b. False
2. The NHTSA-defined level of vehicle automation that involves automation where the vehicle can itself perform all spects of the driving task under some circumstances and the human driver must be ready to take back control at any me when the ADS requests the human driver to do so. a. Level 1 b. Level 2 c. Level 3 d. Level 4 e. Level 5
3. Which of the following is LIDAR not used for, directly or indirectly, in autonomous vehicles? a. 3D mapping of the surrounding environment b. Detecting traffic signs and signals c. Identifying the fastest travel route between an origin and destination d. Detecting obstacles within the roadway e. Identifying valid travel paths
4. Radar sensors provide vehicle route mapping in real time. a. True b. False
5. Autonomous vehicles have the potential to save millions of dollars by reducing a. Car repairs b. Insurance claims

○ c. Medical bills○ d. All of the above
 16. A potential disadvantage to autonomous vehicles includes an increase in needed parking spaces. a. True b. False
17. V2X could utilize real time vehicle data to deploy maintenance crews and emergency vehicles, as well as let driver know to move aside for emergency vehicles to pass. O a. True O b. False
18. DSRC stands for ○ a. Digital Short Range Communications ○ b. Dedicated Short Range Cars ○ c. Dedicated Short Range Communications ○ d. Digital Signal Reflection Compression
19. Basic Safety Messages (BSM) are typically transmitted at what rate? ○ a. 5 Hz ○ b. 8 Hz ○ c. 10 Hz ○ d. 12 Hz
20. Which state has not passed legislation specific to automated vehicles? ○ a. Florida ○ b. Montana ○ c. Michigan ○ d. Nevada
21. Interrupted-flow facilities are considered to be roadways in which external controls, such as traffic signals and stop signs, are present. a. True b. False
 22. Only one factor, queue discharge rate, influences the capacity of traffic movements at a signalized intersection. a. True b. False
23. Geometric design is largely predicated on three factors: vehicle performance as a function of physics, sight distance (human) for safe stopping, and vehicle dimensions. a. True b. False
24 generally refers to the issue of how far in advance a vehicle driver can detect a potential obstacle in the roadway. ○ a. Horizontal curve ○ b. Vertical curve ○ c. Sight triangles ○ d. Sight distance 25. Sight distance is a critical factor in designing the rate of change of slope for a vertical curve.
20. 215111 distance to a critical factor in acciding the face of change of slope for a vertical curve.

\bigcirc	a.	True
\bigcirc	b.	False

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