

Sample Edition

Beyond the Exam

Understanding IT
Beyond Knowledge



Think
Deeper



Understand
Systems



Learn from
Mistakes



Work with
Humans & AI

50 EPISODES

to Build Real Understanding,
Stronger Thinking,
and Lasting Skills

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30 Years in IT. A Lifelong Journey of
Learning and Teaching.



Preface

I have spent more than 30 years in the IT industry. Today, I work as an instructor at a technical college, sharing what I have learned with the next generation.

My journey with computers began in high school. At that time, I built an **8-bit microcomputer** by soldering it together myself. I had always enjoyed electronics, so I already had some basic knowledge of digital circuits.

But what truly fascinated me was **what came next**.

After the machine started working, I began writing software for it. Every day was filled with excitement—experimenting, creating, and discovering what computers could do.

Those days were not just educational. **They were simply fun.**

Since then, technology has continued to evolve at an incredible pace. Both hardware and software have advanced far beyond what we could have imagined. And there is no sign that this progress will slow down.

However, there is something I sometimes feel.

A quiet sense of loss.

Many of the ideas and constraints that once shaped how we learned computers are now considered outdated or unnecessary.

Before dismissing them, I invite you to pause—and read this book.

If you are involved in IT, I believe you will encounter ideas that change how you see things. Not because they are new, but because they **reveal what has always been there.**

For me, computers have never been just a tool. They have been **a lifelong companion.**

From that first machine I built as a student to the systems I work with today, they have given me curiosity, challenge, and joy.

Even now, I continue to feel that same excitement.

Every day.

So, here's to a life of learning, and to the journey that continues.

And most of all,

thank you—for picking up this book.

1. Under the Hood

Episode 1. Why reset signals are often active-low

This topic will not help you pass any exam. Honestly, it probably won't help you answer a single test question. I just always found it interesting.

When you first hear that a **reset signal** works when it is low, it feels backward. If "1" means ON and "0" means OFF, shouldn't reset be ON when the signal is high?

If you grew up with early microcomputers, this question may feel strange in a different way. There was a reset button. You pressed it, and the system restarted. No theory needed. This physical experience is important. It makes reset feel like a human action, not a signal level. Here is what really happened in those 8-bit microcomputers: RESET pin high → CPU runs normally. Press RESET button → pin is forced low, CPU stops, **program counter resets**, internal registers clear. Release button → pin returns to high, CPU starts executing from the **known starting address**.

In other words, the human pressing the button was temporarily holding the CPU in a **safe state** until everything was ready. The "action" of reset was just keeping the system low.

Modern computers don't have humans pressing buttons at startup. The environment—power, signals, and circuitry—performs the same role: ensuring the system stays in a **known, safe state** before normal operation begins.

This idea is not limited to hardware. Think about what "reset" means in software. Clearing memory. Returning variables to known values. Going back to a **clean state**. Conceptually, reset is not an action. It is the **absence of normal operation**.

That is why "**active-low**" makes sense in a quiet, practical way. Normal operation begins only after the system becomes stable. Reset stays active until that moment arrives.

Modern computers are incredibly complex. Operating systems, virtual machines, containers, frameworks — they hide these details from us. But they are still built on the same assumption: before anything clever can happen, the system must first reach a **known, safe state**.

You may never need to remember that reset signals are often active-low. But knowing why they are designed that way makes computers feel a little less magical — and a little more honest.

Some ideas don't disappear. They just become invisible.

Episode2. Why computers use two's complement

This topic, like the previous one, probably won't appear on any exam. Still, it's fascinating, especially if you've ever wondered how computers represent **negative numbers**.

At first glance, the idea seems strange. How can a bunch of 0s and 1s represent both positive and negative numbers without any sign symbol?

Here's the trick: **two's complement**.

Imagine an 8-bit microcomputer from the early days. Memory is precious. Circuits are simple. Adding a special **sign bit** for negative numbers? Too complicated. Computers needed a clever way to use the same circuits for addition and subtraction, no exceptions.

Two's complement does exactly that. Positive numbers stay as they are. Negative numbers are **flipped and incremented by one**. Adding them with positive numbers just works—no extra logic required.

Example: 8-bit numbers

+5 = 00000101

-5 = 11111011

Add them together:

```
  00000101
+ 11111011
= 00000000 (ignoring the carry)
```

It just works. The CPU doesn't need to know whether the number is positive or negative—it only adds bits.

This was brilliant in the early days. Simple hardware. **Same adder for everything**. No extra sign handling. Elegant, practical, and efficient.

Here's a funny thought: if you ever learned this in school as "**invert all bits and add one**," it may have felt arbitrary. But it solves a deep problem effortlessly, and early engineers must have laughed when they realized it worked universally.

Even today, every computer on the planet still uses this trick. Nothing has changed. That tiny invention from decades ago still runs our modern world.

Episode3. Pull-up and pull-down resistors explained

In digital electronics, signals are usually described in a simple way: a signal is either HIGH (1) or LOW (0). This clear definition makes digital systems easy to understand. However, real circuits are not always so clean. Sometimes, a signal line is not actively driven by any device.

When this happens, the voltage becomes uncertain. This state is called a **floating input**.

A floating input can lead to **unpredictable behavior**. The voltage may fluctuate due to electrical noise, interference from nearby circuits, or even the physical properties of the wire itself. As a result, a digital input may randomly be interpreted as HIGH or LOW. In real systems, this can cause unstable operation or bugs that are difficult to identify.

To solve this problem, engineers use **pull-up resistors** and **pull-down resistors**.

A **pull-up resistor** connects the signal line to the positive voltage supply, often called **Vcc**.

When no device is actively driving the signal, the resistor gently pulls the voltage up to HIGH. If another device needs to drive the signal LOW, it can safely connect the line to ground. The resistor limits the current, preventing a **short circuit**.

A **pull-down resistor** works in the opposite way. It connects the signal line to ground, ensuring that the line stays at LOW when no device is driving it. If another device drives the signal HIGH, the voltage rises, and the resistor again limits the current safely.

In simple terms, these resistors provide a **default state** for the signal line.

This idea is especially important when using switches or buttons with **microcontrollers**.

When a switch is open, the input would otherwise be floating. By adding a pull-up or pull-down resistor, the system ensures that the input always has a **defined logic level**.

Many modern microcontrollers include **internal pull-up resistors** that can be enabled by software. This reduces the need for external components and simplifies circuit design.

Although pull-up and pull-down resistors are small and inexpensive, they play a critical role in reliable digital systems. They show that behind the clean concept of 1 and 0, there is always an **analog world** of voltages, currents, and noise.

Understanding these details helps engineers build systems that behave predictably in the real world.

Episode4. High voltage does not always mean “1”

In our very first lessons in IT, we are taught a simple rule: "High voltage is 1. Low voltage is 0." It's easy to remember and logical. But in the real world of hardware design, this rule is broken all the time.

As we discussed in the episode about reset signals, many systems use "**Active-Low**" logic. In these systems, the "Action" happens when the voltage drops to zero. In other words, Low = 1 (True) and High = 0 (False).

Why would engineers choose to flip the world upside down? It's not to make things difficult for students. It's about **reliability and safety**.

Imagine a wire that connects two parts of a computer. If that wire accidentally breaks or gets disconnected, what happens to the signal? Usually, it "floats" or is pulled up to a high voltage by a resistor. If "High" meant "Start the Motor" or "Delete the Data," a broken wire could trigger a disaster.

By making the important actions **Active-Low**, engineers ensure that a disconnected cable won't accidentally trigger a critical command. The system stays in a "safe" high state until someone **intentionally pulls it down to ground**.

There is also a historical reason related to electricity itself. In the early days of transistors (like **TTL logic**), it was much easier and faster for a circuit to "**sink**" current to the ground (Low) than to "**source**" it from the power supply (High). Engineers followed the path of least resistance—literally.

Modern technology has improved, but the philosophy remains. We don't just assign "1" to the highest voltage. We assign "1" to the state that represents the **intent of the action**. Sometimes, silence (High voltage) is the normal state, and the signal (Low voltage) is the message.

When you look at a circuit board, don't just see electricity. See the cautious wisdom of the engineers who built it. They designed it so that even if things go wrong, the system stays quiet. High voltage doesn't always mean "1." Sometimes, it just means "everything is okay, and I'm waiting for your command."

Episode 5. What “floating” really means in hardware

In everyday English, the word “floating” sounds peaceful—a boat floating on a lake, or a cloud floating in the sky. It feels light, free, and calm. But in the world of digital circuits, floating” is a nightmare. It is one of the most common causes of mysterious bugs and **erratic behavior**.

In a digital circuit, a pin should be either High (1) or Low (0). When a pin is “floating,” it is neither. It is disconnected, hanging in the air, caught in a state of indecision. Why is this a problem? Because a floating pin acts like a **tiny antenna**.

It picks up **electromagnetic noise** from the air, from nearby wires, or even from the static electricity on your finger. The voltage on a floating pin doesn't stay still; it bounces up and down. The CPU looks at this pin and sees: 0... 1... 0... 0... 1... 1... The computer starts reacting to signals that don't exist. It's like a ghost is pressing buttons inside your machine.

To prevent this, engineers use **Pull-up or Pull-down resistors**. These are like “safety ropes” that tie the floating pin to a **known state** (High or Low) so it doesn't drift away.

If you are a software engineer, you might think this doesn't affect you. But have you ever seen a variable that wasn't initialized? A pointer that points to “nowhere” in memory? In the world of code, an **uninitialized variable** is exactly like a floating pin. It contains “garbage”—random data left behind by whatever was there before.

The lesson from hardware is clear: **Nature abhors a vacuum, and digital systems abhor an undefined state.**

Whether you are designing a circuit board or writing a high-level application, never leave a door swinging in the wind. Tie it down. Give it a **default value**. In the digital world, “floating” isn't peaceful—it's chaos.

Episode6. Why timing matters more than speed

In computing, speed is often considered the most important factor. Faster processors and quicker algorithms are usually seen as improvements. However, in many real systems, **timing matters more than speed**.

Imagine a digital circuit processing signals. Even if a processor is very fast, it still has to wait for signals to arrive at the correct moment. If a signal comes too early or too late, the result may be incorrect. In this situation, being fast does not help—being **properly timed** does.

This is especially true in **synchronous systems** controlled by a clock. Each component must complete its task within a specific **time window**. If one part is late, it can disrupt the entire system. Finishing early does not necessarily help either, since the system often waits for the next clock cycle.

Timing is also important in network communication. Data packets must arrive in the correct order and within expected time intervals. If packets are delayed or out of order, extra processing is needed, reducing efficiency. **Consistent timing** is often more valuable than raw speed.

Real-time systems show this even more clearly. In areas like automotive control or medical devices, tasks must be completed within **strict deadlines**. Missing a deadline—even slightly—can cause serious problems. In these systems, **predictability** is more important than maximum speed.

Even in everyday software, timing affects user experience. A system that responds consistently feels smooth and reliable. On the other hand, **inconsistent timing** can feel uncomfortable, even if the system is technically fast.

These examples show that performance is not just about speed. A fast but poorly timed system can be unstable, while a slightly slower system with **proper timing** can be reliable and efficient.

For engineers, this means optimization is not only about making things faster. It is about making sure things happen **at the right time**. Understanding **when** is often more important than **how fast**.

Episode 7. Why clocks control everything

In digital systems, many operations appear to happen instantly. Data is processed, signals change, and results are produced in what seems like no time at all. However, behind this apparent simplicity lies a strict mechanism that controls when things happen: the **clock**.

A clock in computing is not a device that tells time in the usual sense. Instead, it is a signal that repeatedly switches between HIGH and LOW at a constant rate. Each cycle of this signal defines a small unit of time in which operations can occur. In this way, the clock acts as a **metronome** for the entire system.

Without a clock, different parts of a system would operate at unpredictable times. One component might send data before another is ready to receive it. Signals could overlap, or arrive too early or too late, causing incorrect behavior. The clock prevents this by providing a **shared rhythm** that all components follow.

In synchronous systems, every operation is coordinated by the clock. Data is typically read, processed, and written at specific moments, often on the **rising or falling edge** of the clock signal. This ensures that all parts of the system move forward in a controlled and predictable manner.

Interestingly, the clock does not make the system faster by itself. Instead, it defines the **pace** at which the system can safely operate. If the clock is too fast, some components may not finish their tasks in time, leading to errors. If it is too slow, the system becomes inefficient. Designing a system often involves finding the right **balance between speed and stability**.

The influence of the clock extends beyond simple coordination. It also determines how data flows through **pipelines**, how memory is accessed, and how processors execute instructions. In modern CPUs, billions of clock cycles occur every second, and each cycle represents an opportunity to move the computation forward.

However, clocks also introduce challenges. As systems become faster and more complex, distributing the clock signal evenly across all components becomes difficult. Small delays, known as **clock skew**, can cause parts of the system to become slightly out of sync. Engineers must carefully design circuits to minimize these effects.

Despite these challenges, the clock remains a **fundamental element** of digital design. It provides order in a system that would otherwise be chaotic. It ensures that operations happen not just quickly, but at the right time.

Understanding the role of the clock reveals an important truth: computers are not just fast—they are **carefully synchronized systems** where timing is everything.

This is sample edition