SIEMENS

Technical Instructions

Document No. 155-760
EA GQD
June 23, 2008

OpenAir™

Spring Return, 20 lb-in (2 Nm), Rotary
GQD Series, Electronic Damper Actuators

Description	The OpenAir GQD Series direct-coupled spring return electronic actuator is designed for modulating, two-position, and floating control of building HVAC dampers.
Features	• Bi-directional spring return (fail-safe) • Pre-cabled • Plenum-rated models available • Fast run time • Available in 20 lb-in (2 Nm) torque • Signal inversion capability on modulating types (2 to 10 Vdc or 10 to 2 Vdc) • UL and cUL listed, CE certified • Compact footprint • Low voltage models are 24 Vac/dc compatible • 120 Vac model with 1/2" NPT conduit connection
Application	Used in constant or variable air volume installations for the control of return air, mixed air, exhaust, and face and bypass, and residential zone dampers requiring up to 20 lb-in (2 Nm) torque. Designed for applications that require the damper to return to a fail-safe position when there is a power failure.

Product Numbers

Table 1.

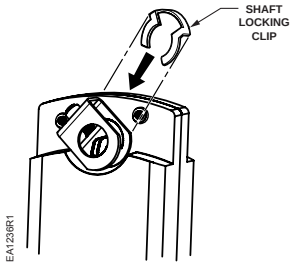
Product Number*	Voltage		Control Signals			Plenum Cabling
	24 Vac/dc	120 Vac	2-Position	Floating	Modulating 2 to 10 Vdc/ 10 to 2 Vdc	
GQD121.1P	●	—	●	—	—	●
GQD131.1P	●	—	—	●	—	●
GQD151.1P	●	—	—	—	●	●
GQD221.1U	—	●	●	—	—	—

*Add /B to part numbers to order bulk pack of 10 each.

Warning/Caution Notations

WARNING:		Personal injury/loss of life may occur if you do not perform a procedure as specified.
CAUTION:		Equipment damage may occur if you do not perform a procedure as specified.

Actuator Components



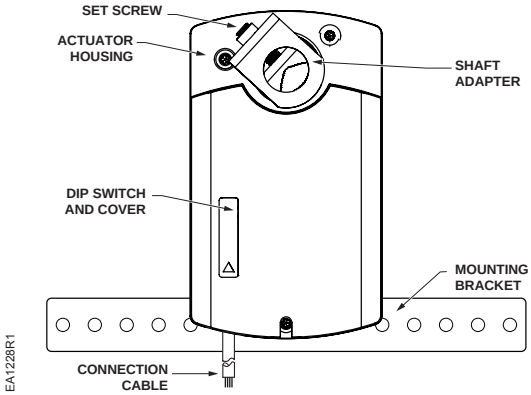


Figure 1. Components of the GQD Spring Return Actuator.

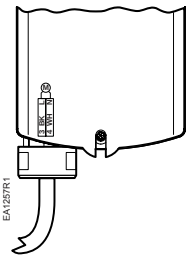


Figure 2. GQD221.1U Only, Conduit Adapter.

Specifications

Power Supply	Operating voltage			24 Vac ±20%; 24 Vdc ±15% 120 Vac ± 15%
	Frequency			50/60 Hz
	Power consumption			
	24 Vac/24 Vdc	running		
			GQD121.1P	6.5 VA (4.5W)
			GQD131.1P	4 VA (2.5W)
			GQD151.1P	4.5 VA (3W)
		holding		
			GQD121.1P	4 VA (2.5W)
			GQD131.1P	3 VA (1.5W)
			GQD151.1P	3.5 VA (2W)
	120 Vac	running	GQD221.1U	10 VA
		holding		7 VA
Equipment Rating		24 Vac		Class 2, in accordance with UL/CSA Class III per IEC 60536
		120 Vac		Double insulation
Control Signal	Input signal (wires 8–2)			
	voltage input signal GQD151			2 to 10 Vdc (max. 35 Vdc)
	input resistance			>100K ohms
Feedback Signal	Position output signal (wires 9–2)			
	voltage output signal GQD151			2 to 10 Vdc
	maximum output current			+1 mA, -0.5 mA
Function	Running/spring return torque			20 lb-in (2 Nm)
	Maximum torque			53 lb-in (6 Nm)
	Runtime for 90°			
	operating with motor			30 seconds
	closing (on power loss) with spring return			15 seconds typical
Mounting	Nominal angle of rotation			90°
	Maximum angular rotation			95°
	Shaft size			3/8 to 1/2-inch (8 to 13 mm) dia.
				1/4 to 7/16-inch (6 to 11 mm) square
	Minimum shaft length			3/4-inch (20 mm)
Housing	Enclosure			NEMA 1 IP40
	Material			Plenum rated rugged plastic
	Gear lubrication			Silicone-free
Ambient Conditions	Ambient temperature			
	operation			–25°F to 130°F (–32°C to 55°C)
	storage and transport			–40°F to 158°F (–40°C to 70°C)
	Ambient humidity (non-condensing)			95% rh

Agency Certification			UL listed per UL873
		24 Vac	cUL to CSA C22.2 No. 24-93
			C-Tick conformity per AS/NZS3548
CE **Conformity**		120 Vac	EMC and Low Voltage Directives
Miscellaneous	Pre-cabled connection		18 AWG (0.75 mm^2)
	Cable length		3 feet (0.9 m) length
	Life cycle		Designed for minimum of 60,000 full stroke cycles and a minimum of 1.5 million repositions at rated torque and temperature
	Dimensions		4-23/32" H × 2-22/32" W × 2-15/32" D (120 mm H × 69 mm W × 63 mm D)
		GQD221.1U (only)	5 1/2" H × 2-22/32"W × 2-15/32" D (138.5 mm H × 69 mm W × 63 mm D)
	Weight		1.06 lbs (0.48 kg)

Service Parts

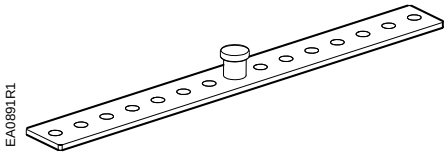


Figure 3.
985-055P24
Anti-rotation Bracket (mounting).

Figure 4. 985-124
499-ohm Resistor Assembly Kit for 4 to 20 mA Applications.

Operation

GQD151
Apply a continuous 2 to 10 Vdc control signal between wire 8 (Y) and wire 2 (G0) to operate the damper actuator. The angle of rotation is proportional to the control signal.

A 2 to 10 Vdc position feedback output signal is available between wire 9 (U) and wire 2 (G0) to monitor the position of the damper motor.

In the event of a power failure or when the operating voltage is shut off, the actuator returns to the "0" position.

GQD121/GQD221.1U
When power is applied, the actuator coupling moves toward the open position "90°". In the event of a power failure or when the operating voltage is shut off, the actuator returns to the "0" position.

GQD131
A floating control signal controls the damper actuator. The actuator's angle of rotation is proportional to the length of time the signal is applied. A 24 Vac/dc control signal to wire 6 (Y1) causes the actuator coupling to rotate clockwise. A 24 Vac/dc control signal to wire 7 (Y2) causes the actuator coupling to rotate counterclockwise.

With no control voltage, the damper actuator holds its position. In the event of a power failure, the actuator will return to the "0" position.

Overload Protection

In the event of a blockage in the damper, the actuator is overload protected over the full range to prevent damage to the actuator.

Life Expectancy

An improperly tuned loop will cause excessive repositioning that will shorten the life of the actuator.

Sizing

The type of actuator required depends on several factors:

1. Obtain damper torque ratings (lb-in/ft^2 or Nm/m^2) from the damper manufacturer.
2. Determine the area of the damper.
3. Calculate the total torque required to move the damper:

$$\text{Total Torque} = \frac{\text{Torque Rating} \times \text{Damper Area}}{SF^{1}}$$

4. Select a spring return actuator using Table 1.

[1] Safety Factor: When calculating the total torque required, a safety factor should be included for unaccountable variables such as slight misalignments, aging of the damper, etc. A suggested safety factor is 0.80.

Table 2. Sizing.

Total Torque	Actuator
≤20 lb-in (2Nm)	GQD
>20 lb-in ≤62 lb-in (>2Nm ≤7 Nm)	GMA
>62 lb-in ≤142 lb-in (7 Nm ≤ 16 Nm)	GCA
>142 lb-in ≤ 248 lb-in (>16 Nm ≤ 28 Nm)	Tandem GCA **ASK73.2U***: Tandem mounting bracket with any combination of GCA16x. **ASK73.1U*:** Tandem mounting bracket for all other GCAx actuators.

***NOTE:** Mechanically coupled actuators must be of the exact same type. Use the correct mounting bracket.

Mounting and Installation

- The shaft adapter can be mounted on either side of the actuator. The actuator mounting orientation and shaft length determine how they will be mounted on the actuator.
- The minimum damper drive shaft length is 3/4-inch (20 mm).
- See *Specifications* for the minimum and maximum damper shaft dimensions.
- A mounting bracket is included with the actuator.
- See the detailed installation instructions included with each actuator.

DIP Switch Functionality GQD151

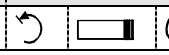
Description	Label	Description	Function
Inverse Acting		Direct-Acting	Input Signal Inversion

Figure 5. DIP Switch.

Input Signal Inversion

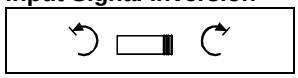


Figure 6.

Allows inverting the control input signal

The arrow direction indicates opening or closing (closing or opening) when operating an actuator with a given control signal. See **Error! Reference source not found.**.

↻ = Direct acting (Factory setting)
Input signal 2 Vdc ► fail-safe position

↺ = Inverse acting
Input signal 10 Vdc ► fail-safe position

Wiring

All wiring must conform to NEC and local codes and regulations.

Use earth ground isolating step-down Class 2 transformers. Do not use autotransformers.

The maximum rating for a Class 2 step-down transformer is 100 VA. Determine the supply transformer rating by summing the VA ratings of all actuators and all other components used. It is recommended that one transformer power no more than 10 actuators (or 80% of its VA).

WARNING:

Installations requiring CE Conformance:

- All wiring for 24 Vac/dc actuators must only be safety extra-low voltage (SELV) or protective extra-low voltage (PELV) per HD384.
- Use safety transformers per EN61558 with double isolation, designed for 100% duty-cycle for supplying SELV or PELV circuits.
- Over-current protection for supply lines is maximum 10A.

Wire Designations

Each wire has the standard symbol printed on it. See Table 3.

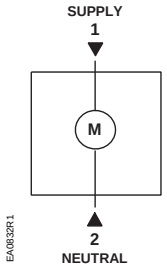
Table 3. Wire Designations.

Applicable Actuator	Standard Symbol	Function	Terminal Designations	Color
24 Vac/dc	1	Supply (SP)	G	Red
	2	Neutral (SN)	G0	Black
	6	Control signal clockwise (CW)	Y1	Violet
	7	Control signal counterclockwise (CCW)	Y2	Orange
	8	Input signal: 2 to 10 Vdc or 10 to 2 Vdc	Y	Gray
	9	Position output: 2 to 10 Vdc	U	Pink
120 Vac	3	Supply	L	Black
	4	Neutral	N	White

Wiring Diagrams

GQD121.1P

24 Vac/dc
2-Position Control

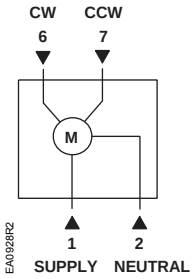


Class III

Figure 7.

GQD131.1P

24 Vac/dc
Floating Control

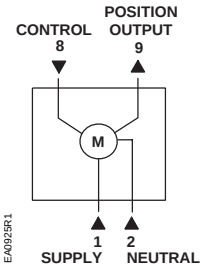


Class III

Figure 8.

GQD151.1P

24 Vac/dc
Modulating Control



Class III

Figure 9.

GQD221.1U

120 Vac

2-Position Control

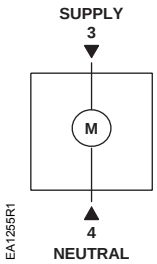


Figure 10.

Wiring Diagrams, continued

Special Applications

GQD151

4 to 20 mA

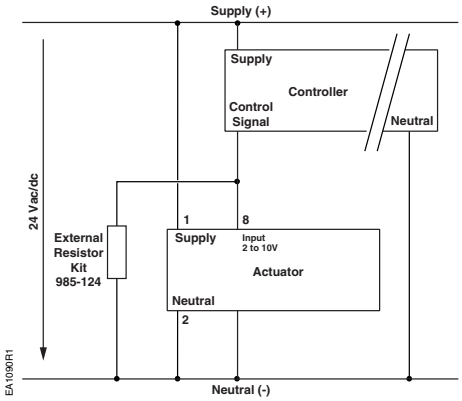


Figure 11. GQD151 4 to 20 mA Applications.

Start-Up/ Commissioning

GQD151

Spring Return Modulating Control 24 Vac/dc

1. Check Operation:
   a. Connect wires 1 (red) and 2 (black) to the 24 Vac/dc power supply.

      NOTE: With no input signal present, the GQD151 actuator with input signal inversion switch set to Inverse Acting, will start driving towards 90°.

   b. Use a Digital Multimeter (DDM) and set the dial to Vdc for the actuator input signal.
   c. Connect wires 2 (black) and 8 (gray) to the DMM.
   d. Apply to input signal wire 8 (gray):
      Y = 10 Vdc (GQD151 with input signal inversion switch set to Direct Acting).
      Y = 2 Vdc (GQD151 with input signal inversion switch set to Inverse Acting).

   Allow the actuator shaft coupling to rotate from 0° to 90°.

   e. Apply to input signal wire 8 (gray):
      Y = 2 Vdc (GQD151 with input signal inversion switch set to Direct Acting).
      Y = 10 Vdc (GQD151 with input signal inversion switch set to Inverse Acting).

   The shaft coupling returns to the "0" position.

2. Check Spring Return:
   a. Set the DMM dial to Vdc.
   b. Connect wires 2 (black) and 8 (gray) to the DMM.
   c. Apply to input signal wire 8 (gray):
      Y = 6 Vdc (GQD151)

   Allow the actuator shaft coupling to rotate halfway.

   d. Disconnect wire 1 (red).

   The spring returns the actuator shaft coupling to the fail-safe "0" position.

   e. Connect wire 1 (red) and the actuator moves.

3. Check Feedback:
   a. Set the DMM dial to Vdc.
   b. Attach wires 2 (black) and 9 (pink) to the DMM.
   c. Apply the input signal as in *Step 1d,* to wire 8 (gray).
      - The reading at the DMM should increase (decrease for GQD151 with output signal inversion switch set to Inverse Acting Feedback).
      - The reading at the DMM should decrease (increase for GQD 151 with output signal inversion switch set to Inverse Acting Feedback) and the actuator shaft coupling returns to the fail-safe "0" position.

GQD121.1P

Spring Return 2-Position 24 Vac/dc

1. Check Operation:
   a. Connect wires 1 (red) and 2 (black) to 24 Vac/dc power supply.

   Allow the actuator shaft coupling to rotate from 0° to 90°.

   b. Disconnect wire 1 (red) and the actuator shaft coupling returns to the "0" position.

2. Check Spring Return:
   a. Connect wire 1 (red).

   Allow the actuator shaft coupling to rotate halfway.

   b. Disconnect wire 1 (red).

   The spring returns the actuator shaft coupling to the fail- safe "0" position.

Start-Up/ Commissioning, Continued

GQD131

Spring Return Floating 24 Vac/dc

1. Check Operation:
   a. Connect wires 1 (red) and 2 (black) to a 24 Vac/dc power supply.
   b. Apply a control signal (24 Vac/dc) to wire 6 (violet).

Allow the actuator shaft coupling to rotate from 0 to 90°.

   c. Stop the control signal to wire 6 (violet).
   d. Apply a control signal (24 Vac/dc) to wire 7 (orange).

Allow the actuator shaft coupling to rotate from 90° to 0°.

2. Check Spring Return:
   a. Apply a control signal (24 Vac/dc) to wire 6 (violet).

Allow the actuator shaft coupling to rotate half way.

   b. Disconnect wire 1 (red).
   The spring returns the actuator shaft coupling to the fail-safe "0" position.
   c. Connect wire 1 (red).
   The actuator shaft coupling begins to move.

GQD221.1U Two-Position 120 Vac

1. Check Operation:
   a. Switch on 120 Vac power.
   b. Allow the actuator shaft coupling to rotate from 0 to 90°.
2. Switch off power.
   The actuator shaft coupling will return to the "0" position.
3. Check Spring Return:
   a. Switch on 120 Vac power.
   b. Allow the actuator shaft coupling to rotate halfway.
   c. Switch off 120 Vac power.
   The spring returns the actuator shaft coupling to the fail "0" position.

Service

WARNING:
Do not open the actuator.
If the actuator is inoperative, replace the unit.

Troubleshooting

WARNING:

To avoid injury or loss of life, pay attention to any hazardous voltage (For example, 120 Vac) when performing checks.

- Check that the wires are connected correctly.
- Check that DIP switch is set correctly, if used.
- Use a Digital Multimeter (DMM) to verify that the operating voltage is within range.
- If the actuator is not working, check the damper for blockage.
- If blocked, remove the obstacle and cycle the actuator power off and on. The actuator should resume normal operating mode.

Dimensions

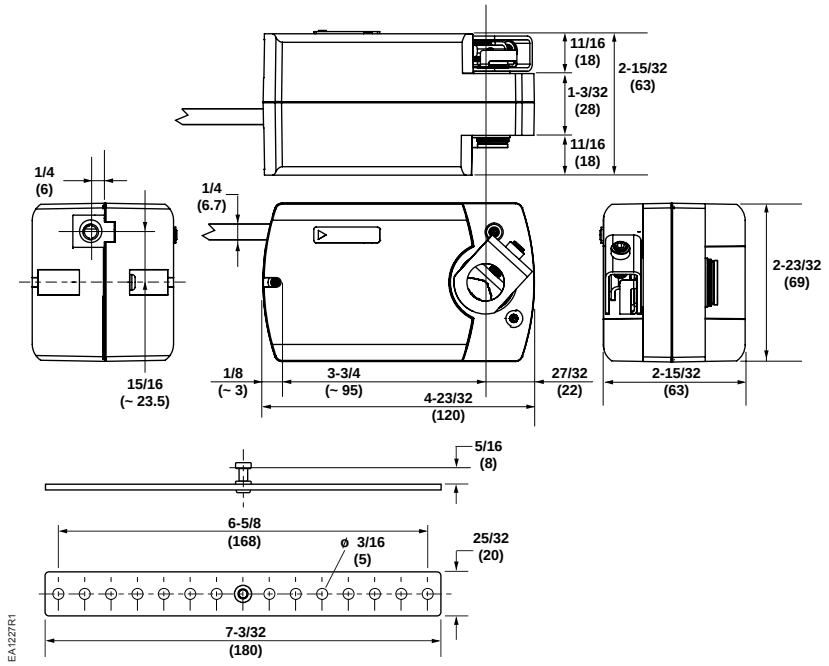


Figure 12. GQD Actuator and Mounting Bracket Dimensions in Inches (Millimeters).

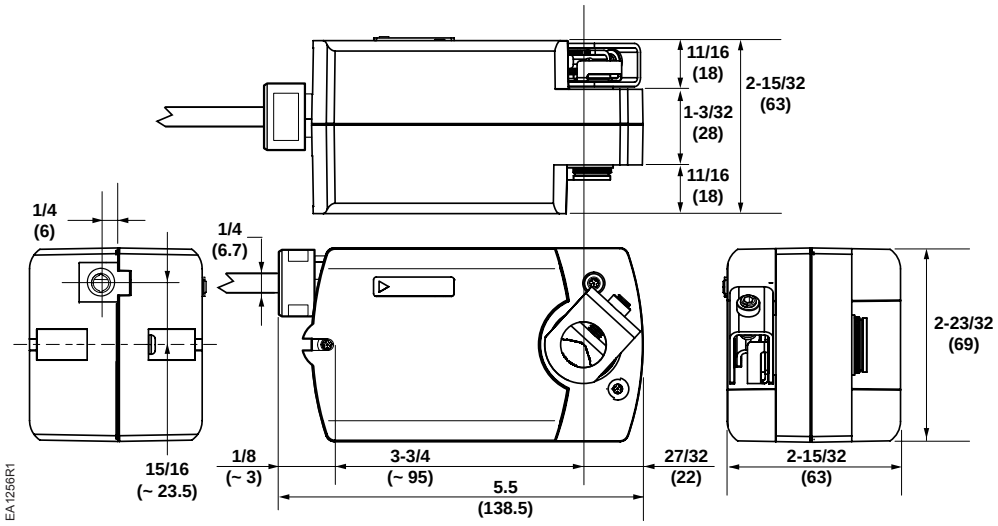


Figure 13. GQD 221.1U Actuator Only, Dimensions in Inches (Millimeters).