

GMX24-MFT-X1

Proportional, Non-Spring Return, 24 V, Multi-Function Technology®



Technical Data	
Power Supply	24 VAC $\pm$ 20%, 50/60 Hz, 24 VDC $\pm$ 10%
Power Consumption Running	4.5 W
Power Consumption Holding	1.5 W
Transformer Sizing	7 VA (class 2 power source)
Shaft Diameter	Standard: 1/2" to 1.05" round, centers on 1/2" and 3/4" with insert, 1.05" without insert
Electrical Connection	3 ft., 18 GA plenum rated cable with 1/2" conduit connector (10 ft [3m] and 15 ft [5m] avail.)
Overload Protection	electronic throughout 0° to 95° rotation
Operating Range Y	2 to 10 VDC, 4 to 20 mA (default), variable (VDC, floating point, on/off)
Feedback Output U	2 to 10 VDC, 0.5 mA max, VDC variable
Angle of Rotation	max. 95°, adjustable with mechanical stop
Torque	360 in-lbs [40 Nm] minimum
Direction of Rotation (Motor)	reversible with built-in switch
Position Indication	reflective visual indicator (snap on)
Manual Override	external push button
Running Time (Motor)	150 seconds (default), variable (90 to 150 seconds)
Humidity	5 to 95% RH non-condensing
Ambient Temperature Range	-22°F to +122°F [-30°C to +50°C]
Storage Temperature Range	-40°F to +176°F [-40°C TO +80°C]
Housing	NEMA 2, IP54
Agency Listings†	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC and 2006/95/EC
Noise Level (Motor)	<45 dB (A)
Servicing	maintenance free
Quality Standard	ISO 9001
Weight	3.4 lbs [1.55 kg]

†Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.

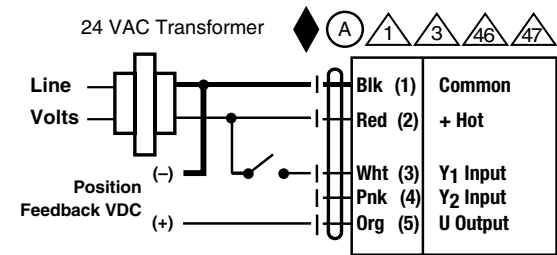
✂ INSTALLATION NOTES

- A** Actuators with appliance cables are numbered.
- 1** Provide overload protection and disconnect as required.
- 3** Actuators may also be powered by 24 VDC.
- 5** Only connect common to negative (-) leg of control circuits.
- 7** A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.
- 10** For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.
- 46** Actuators may be controlled in parallel. Current draw and input impedance must be observed.
- 47** Master-Slave wiring required for piggy-back applications. Feedback from Master to control input(s) of Slave(s).
- ◆** Meets cULus requirements without the need of an electrical ground connection.

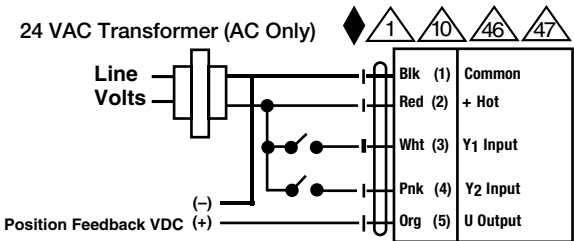
! WARNING! LIVE ELECTRICAL COMPONENTS!
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Wiring Diagrams

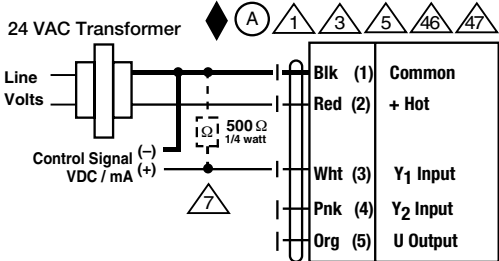
On/Off



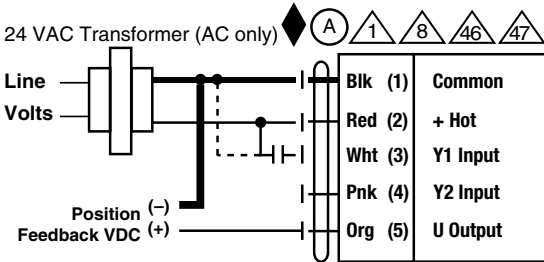
Floating Point



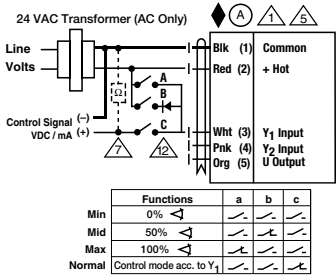
VDC/mA Control



PWM Control



Override Control



Master - Slave

