# Pablo Avila

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### **EDUCATION**

## Georgia Institute of Technology

Bachelor of Science in Mechanical Engineering | May 2026 | GPA: 3.97/4.0

- Concentration in Automotive Engineering and Design.
- 2022 Gold Scholar recipient, representing the top 2% of admitted students.
- SolidWorks Certifications: CSWA, CSWP, CSWPA-DT, CSWPA-SM, CSWPA-WD.

#### PROFESSIONAL EXPERIENCE

### **Product Development Intern**

Textron GSE

June 2025 - present, Cartersville, GA

- Designed a high-load testing device for baggage tractors (50,000 lbs), performing FEA and motion analysis studies; presented in open reviews and DFM/DFA meetings to ensure manufacturability and first-pass success.
- Supported the development of a fully electric airport baggage tractor, focusing on the design of key exterior components including light guards and mounting for rear hitch mirrors, rear cameras, and work lights.
- Applied GD&T to production-ready part drawings to ensure precise manufacturing and quality control.

## **Reliability Engineer Intern**

Shaw Industries

June 2024 - August 2024, Dalton, GA

- Designed and developed lightweight, portable waste collection devices, supporting the transfer of over 15,000 lbs of resin spills, leading to improved efficiency in waste management.
- Engineered 2,000 lbs impact-resistant polycarbonate forklift roofs, enhancing associate visibility and safety.
- Automated the reorganization of the supply room by leveraging Excel functions and query viewers, identifying 4,500 outdated parts for potential use across 35 Shaw plants, optimizing inventory management.

### **Design Engineer Intern**

Shaw Industries

June 2022 - August 2022, Dalton, GA

- Designed cost-efficient, controllable camera mounts using 3D-printed filament, reducing production costs by 90%.
- Implemented rapid prototyping and programmed motors using Arduino and MQTT for automated operation.
- Practiced PCB design through schematic wiring and soldering.

#### **PROJECTS**

## **Mobility Support Device for Spinal Cord Injury Patients**

Equity in Mobility | Spring 2025 - present

- Collected feedback from 50+ individuals with spinal cord injuries via NextStep Atlanta to guide a user-centered design, focusing on documentation through Gantt Chart, HOQ, Morph Chart.
- Developed a retractable, compact, open-source lift capable of transferring a 10 kg wheelchair into a vehicle, incorporating a 1:5 mechanical advantage to accommodate limited strength and range of motion.

### **Autonomous Robotics Competition | 2nd place**

ME 2110 - Creative Decisions & Design | Fall 2023

- Led a 6-week design project for a robot under \$100 and capable of completing 5 tasks in 40 seconds.
- Applied design and management tools such as HOQ, specification sheets, function trees, Gantt charts, evaluation matrices, and FMEA to accelerate team progress by 20%.
- Documented the project's process through 3 IEEE-compliant engineering reports and formal presentations.

### **EXTRACURRICULARS**

# Lambda Theta Phi Latin Fraternity

Vice President | Spring 2025 - present

- Responsible for coordinating 2+ weekly events ranging from social gatherings to Latino cultural workshops.
- Serve as primary liaison between the executive board, 17+ members, and external connections to drive chapter recognition and engagement.

## **EcoCAR EV Challenge**

System Design & Integration Subteam | vip.gatech.edu/teams/vpu | Spring 2024 - 25

- Modeled HV box mounting, performing FEA for 20g crash scenarios to ensure structural integrity and user safety.
- Designed and assembled a test connector enclosure to contain LV and HV connections, enhancing testing safety.
- Researched stub shaft manufacturing methods and collaborated with vendors to evaluate production capabilities.
- Designed motor bushing mounts to reduce cabin vibration and prepared the front subframe for FEA validation.

## **SKILLS**

**Technical Skills:** SolidWorks, Siemens NX, Fusion 360, OnShape, MATLAB, Altair Inspire FEA, Word, Excel. **Interpersonal Skills:** Bilingual - Spanish, Leadership in Collaborative Environments, Conflict Resolution.