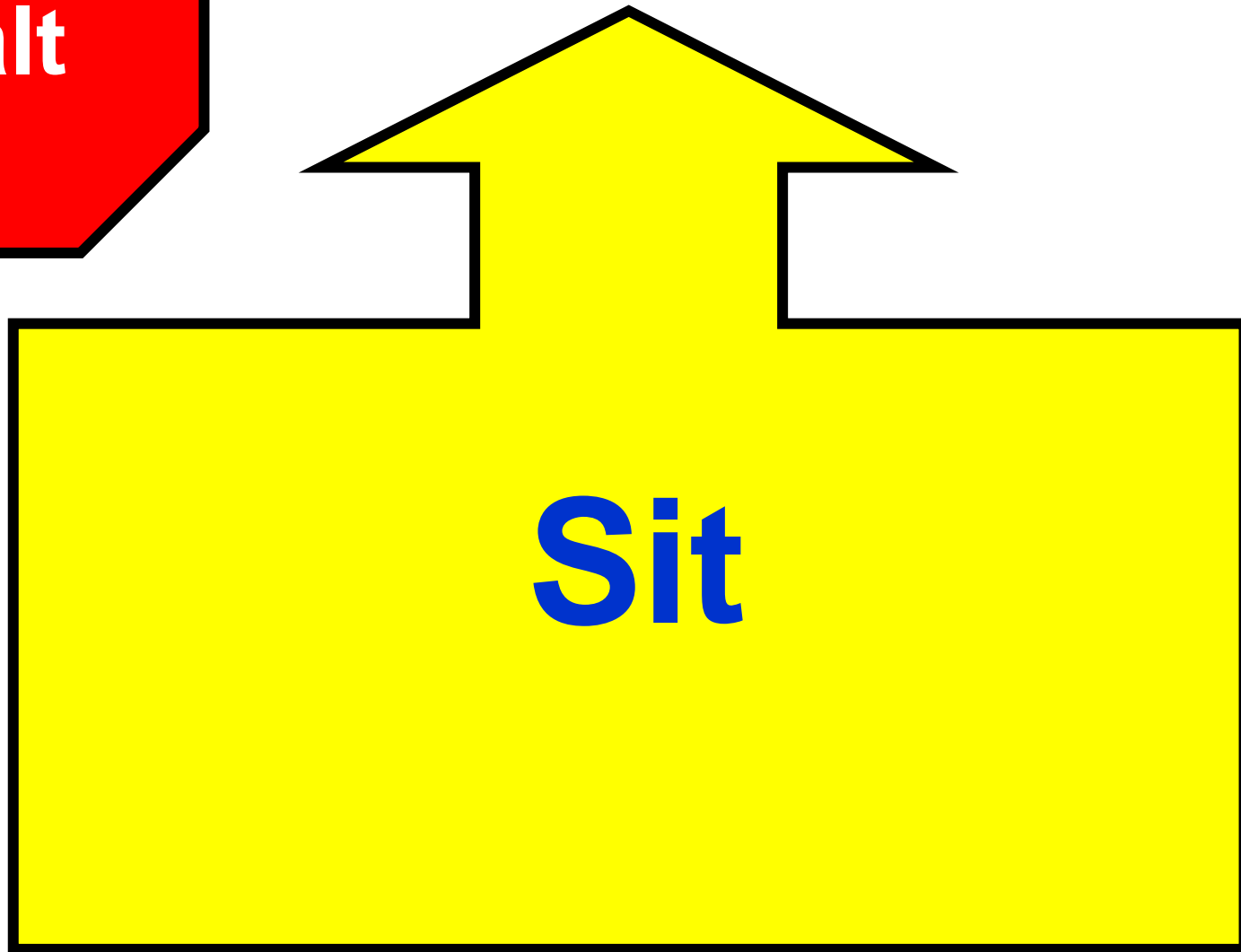


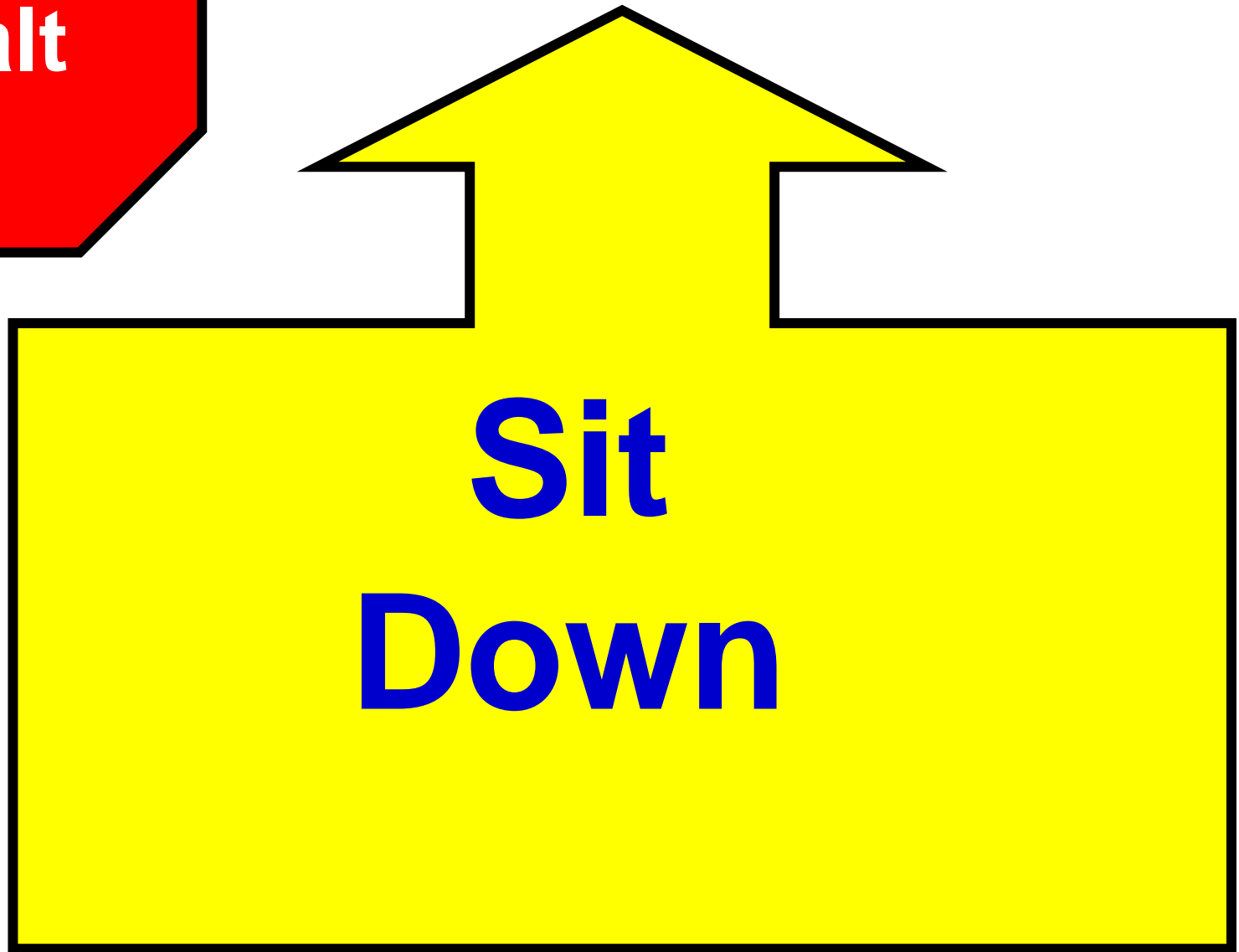


Start

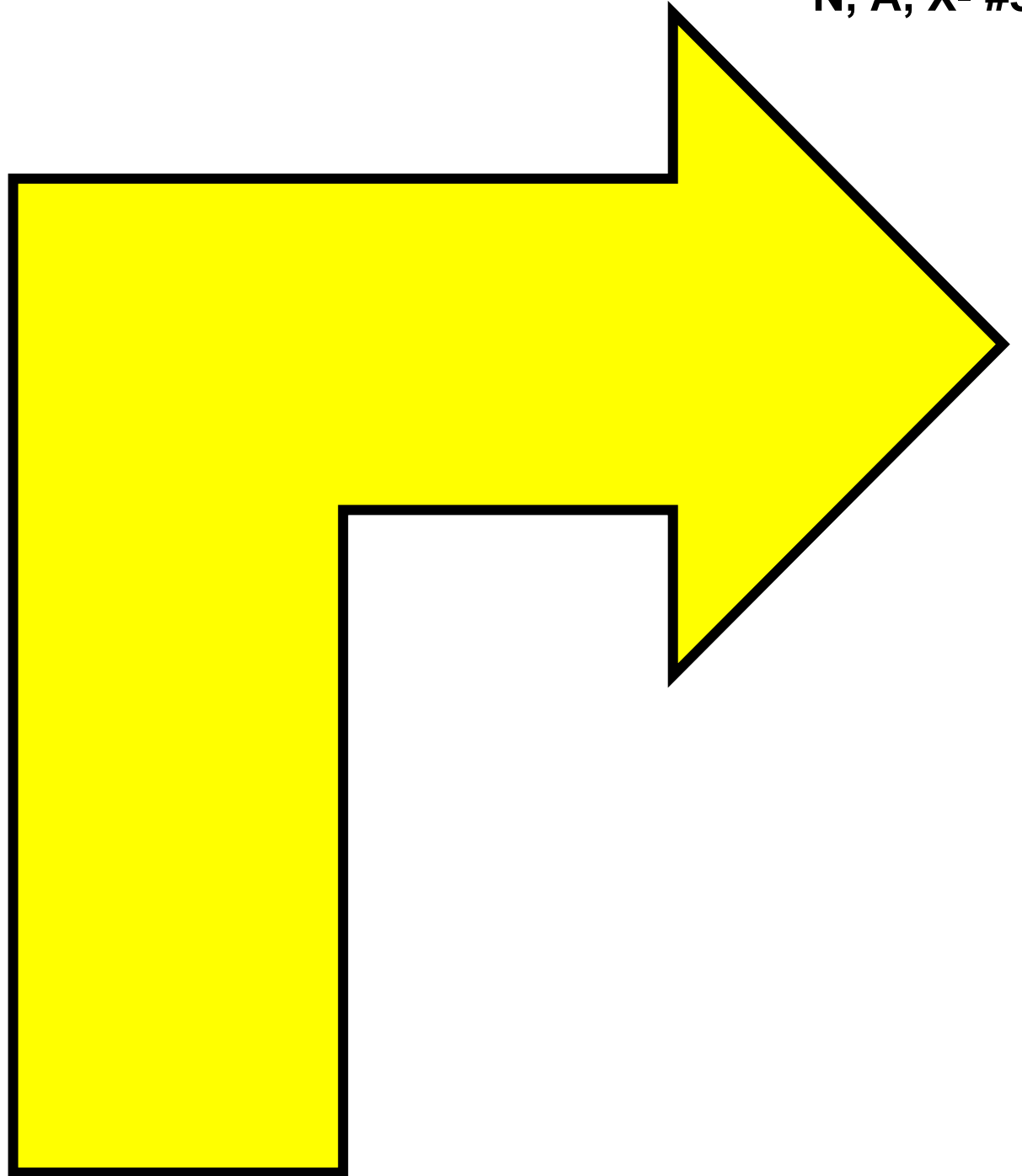


Finish

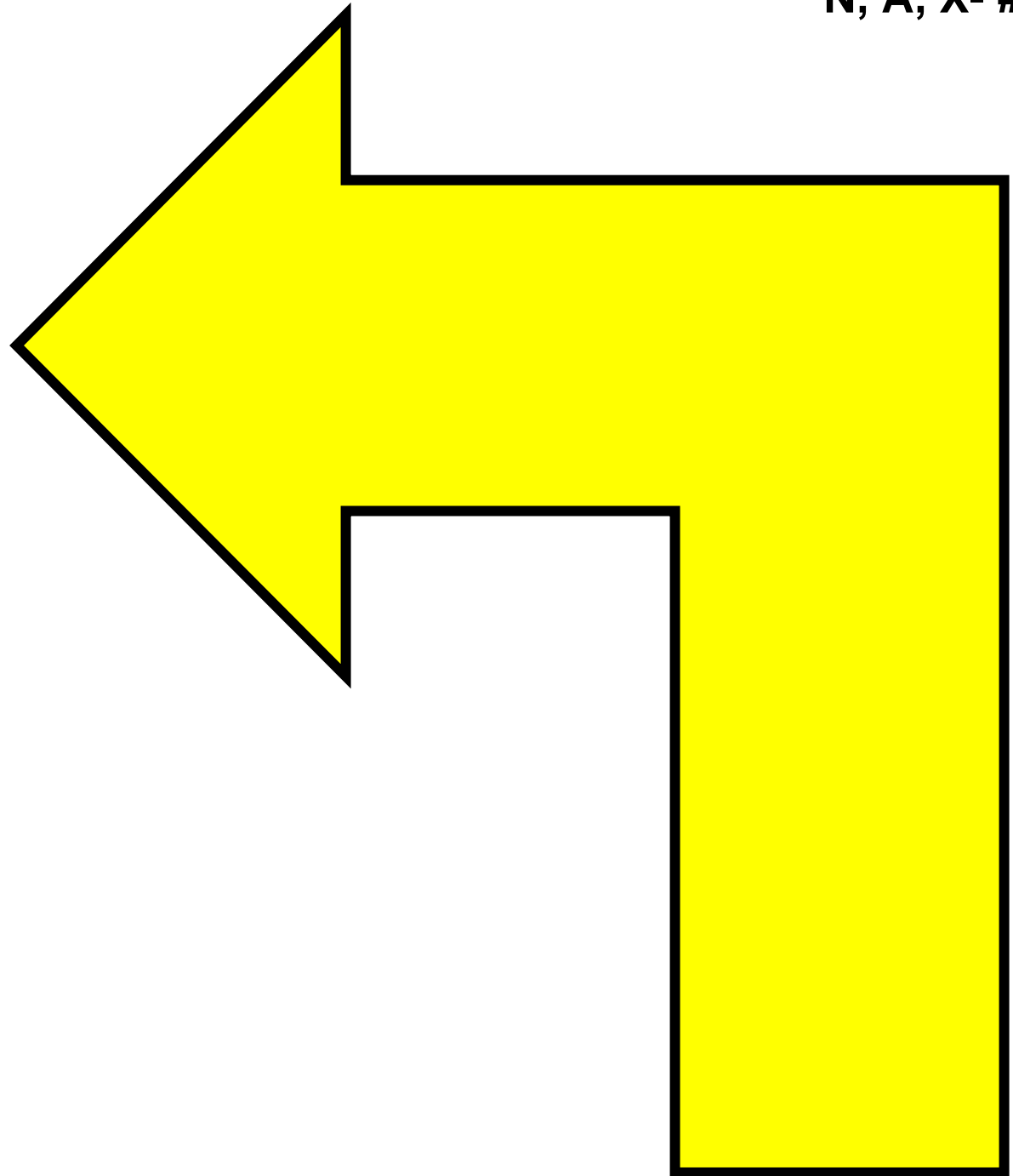




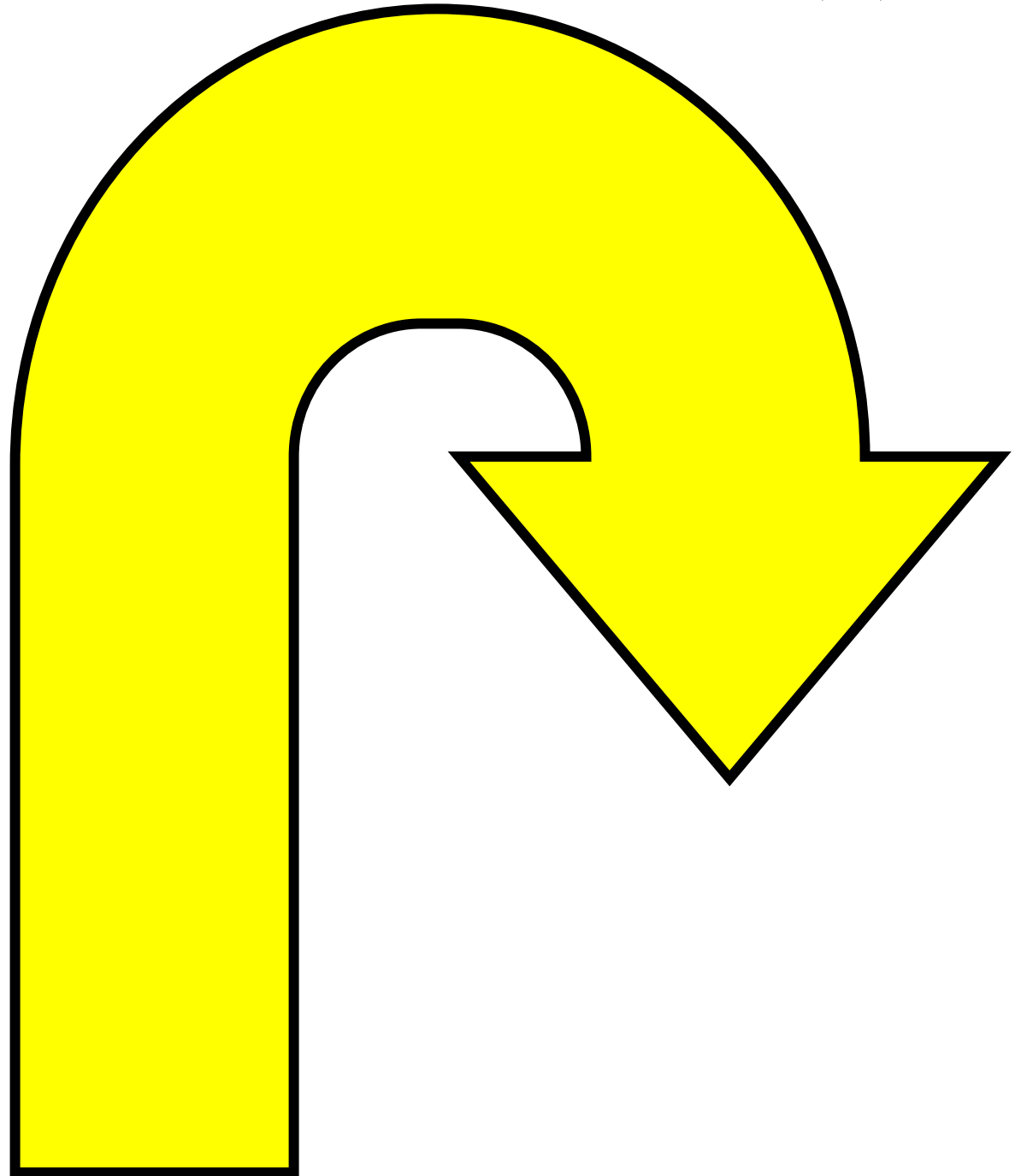
**Right
Turn**



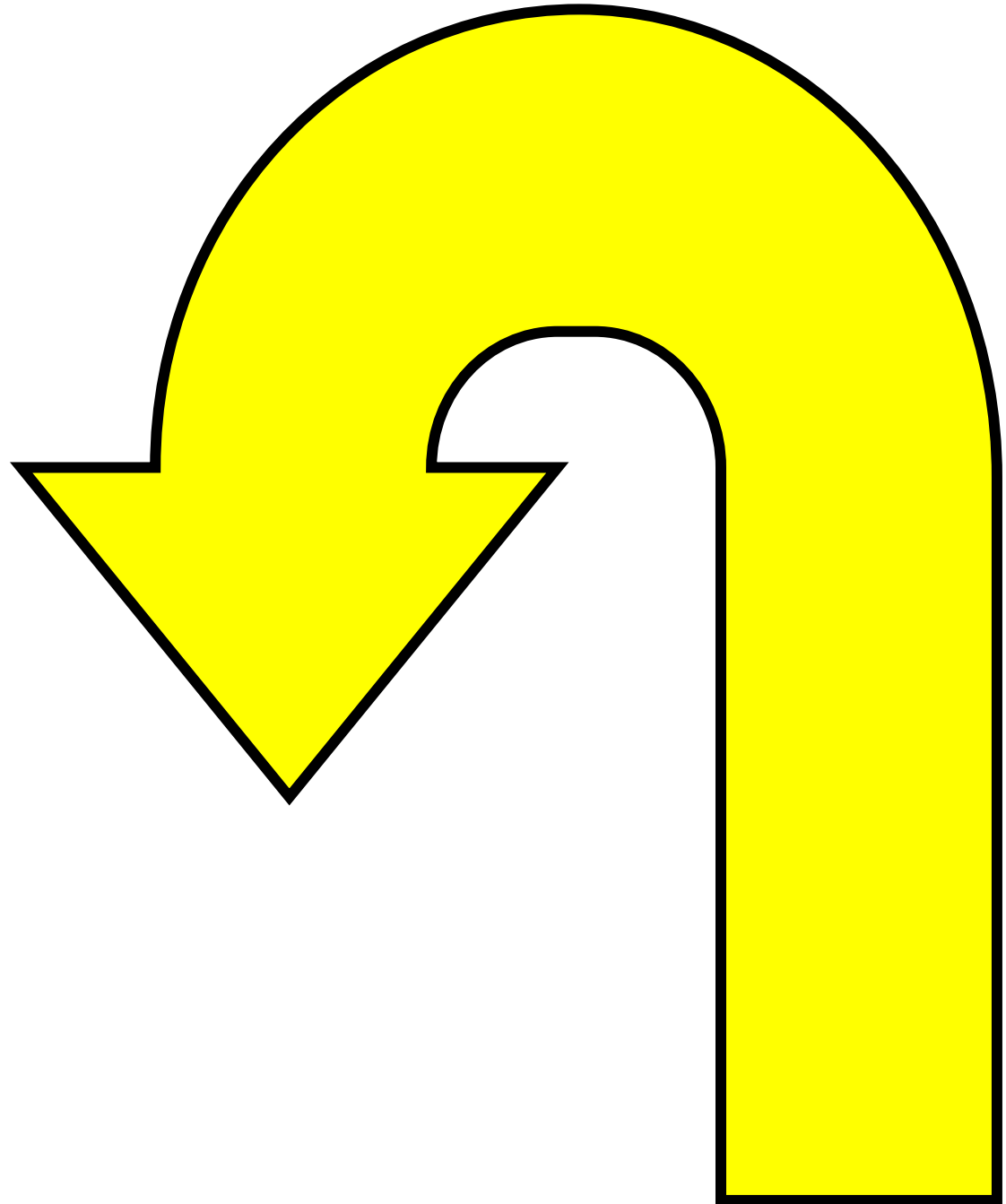
**Left
Turn**



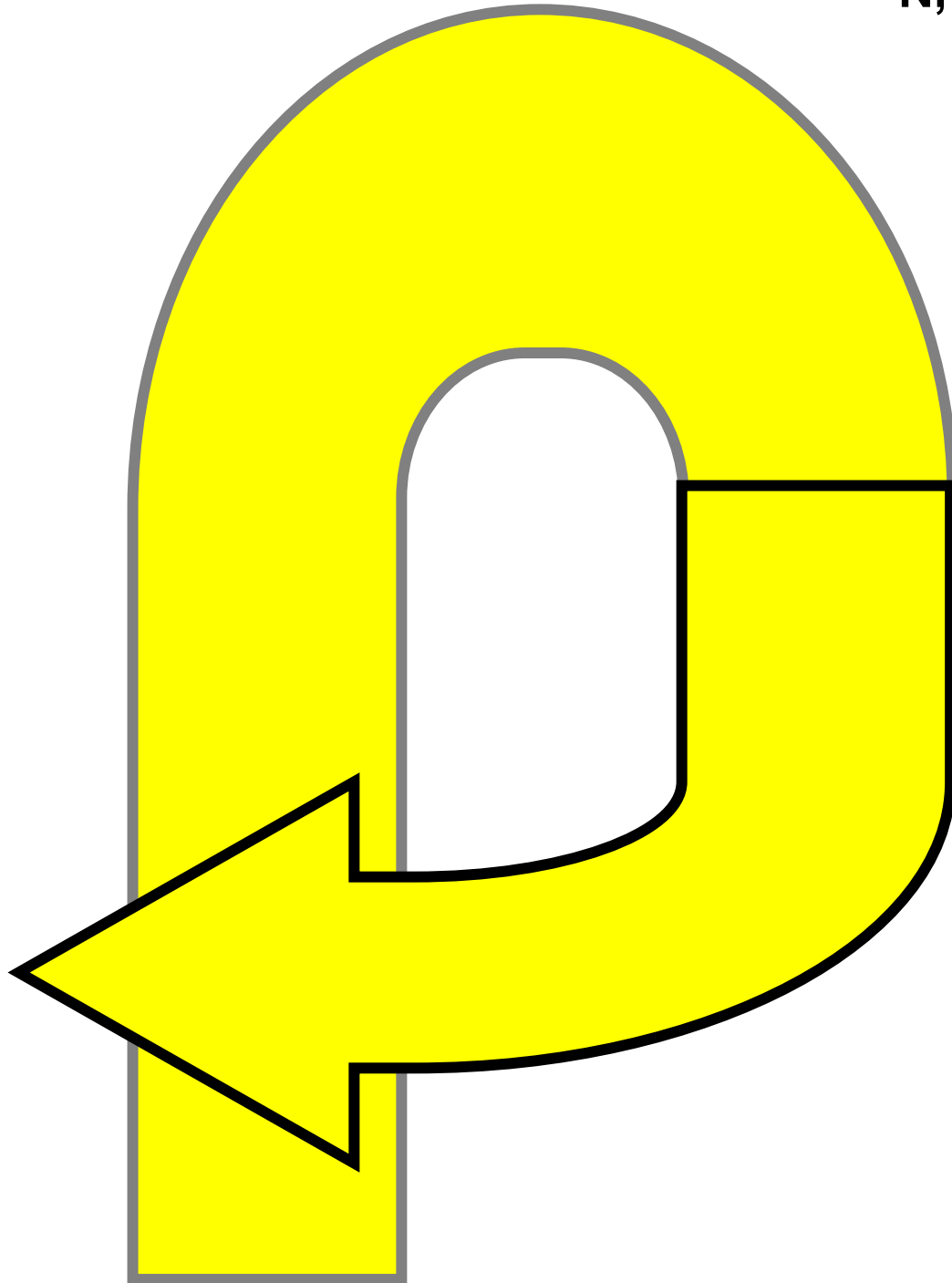
**About
Turn
Right**



**About
“U”
Turn**

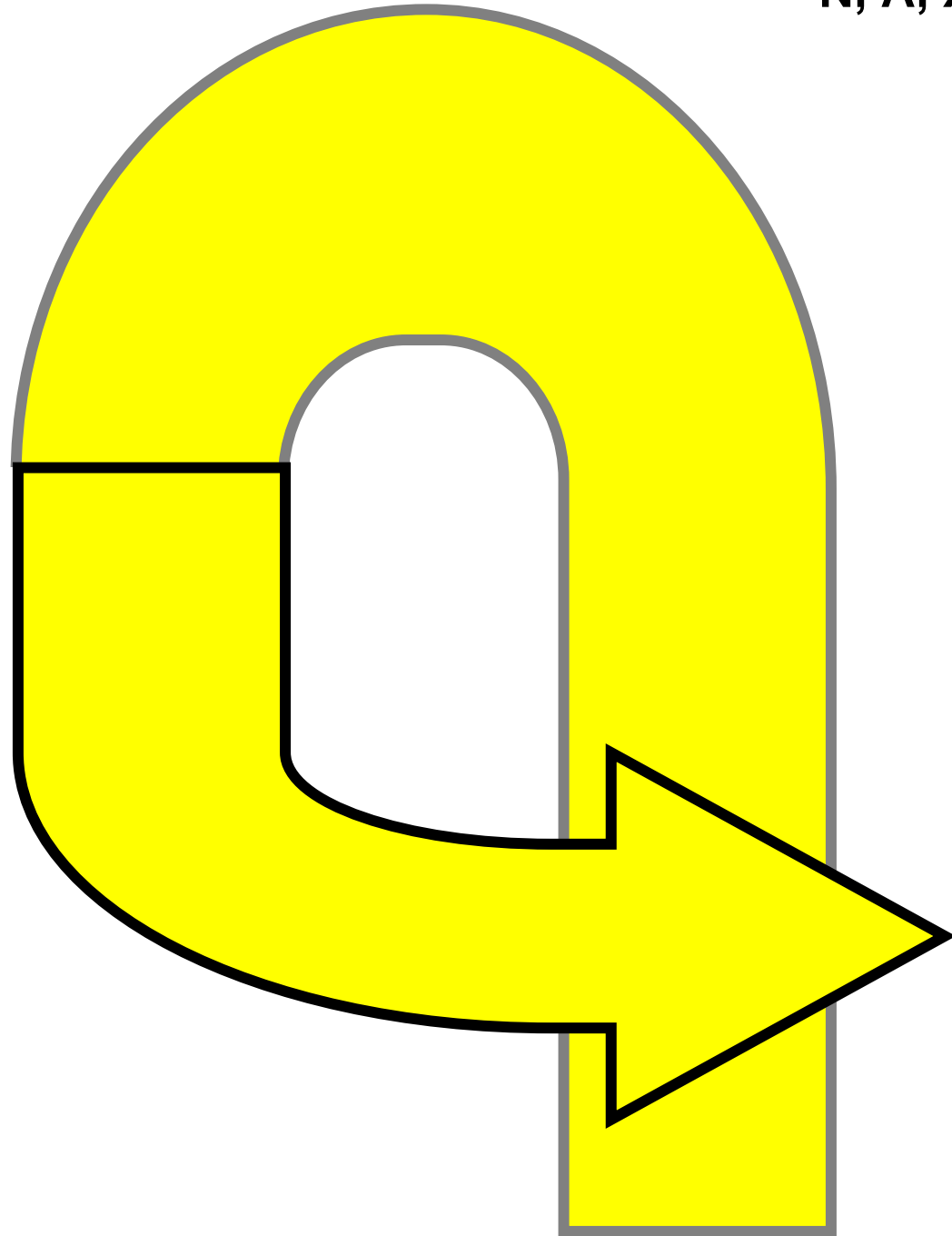


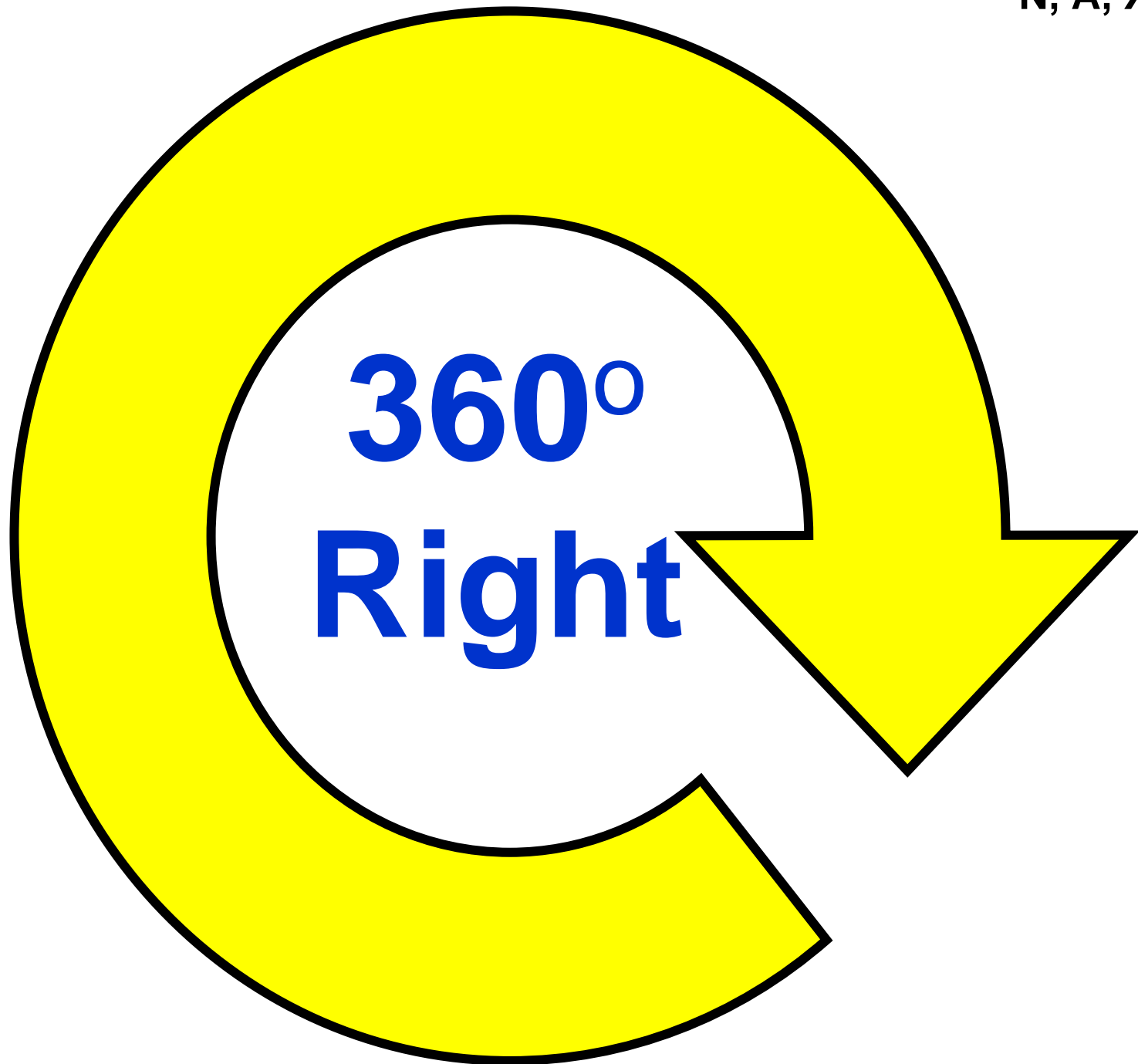
**270°
Right**

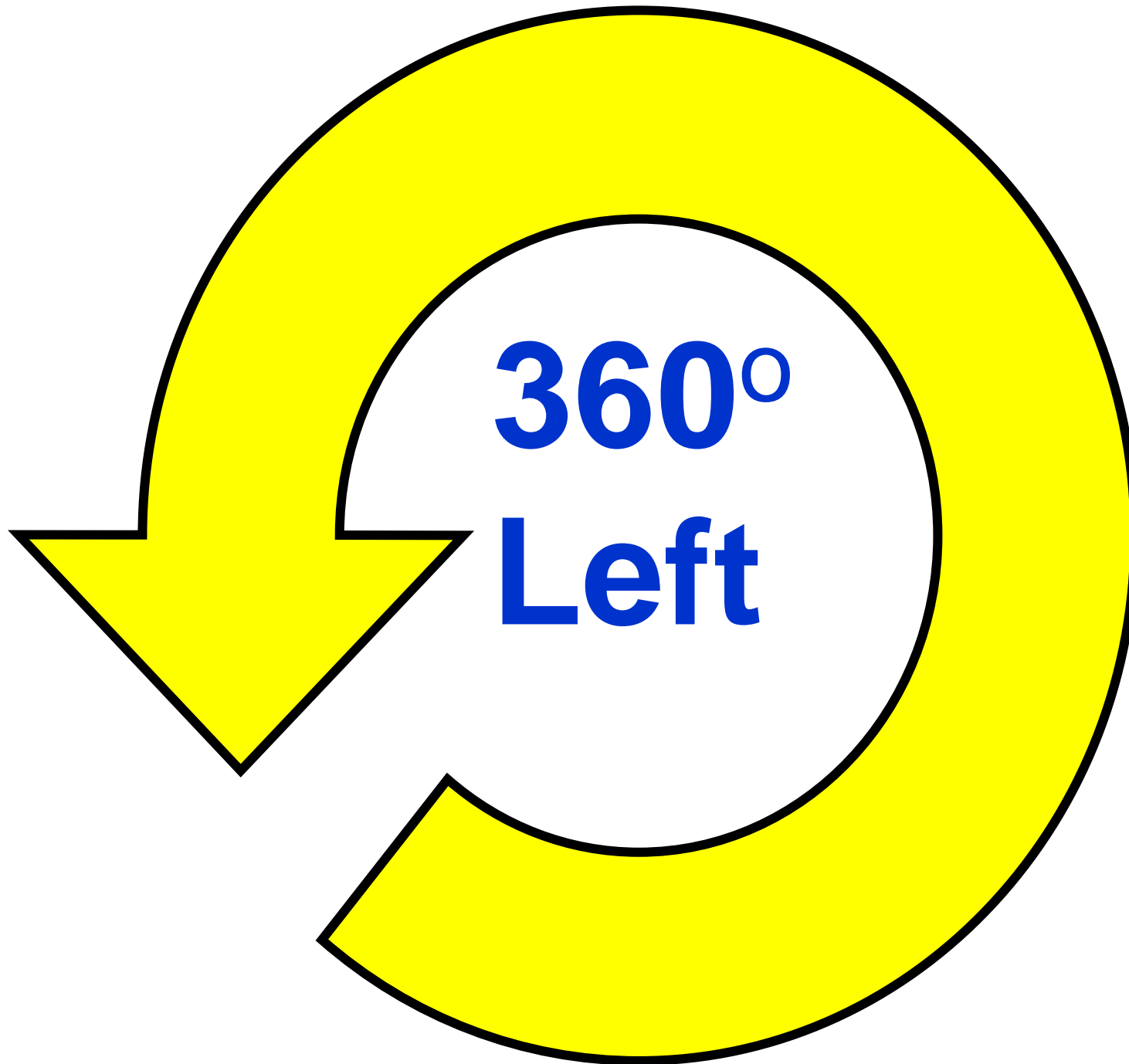


270°

Left

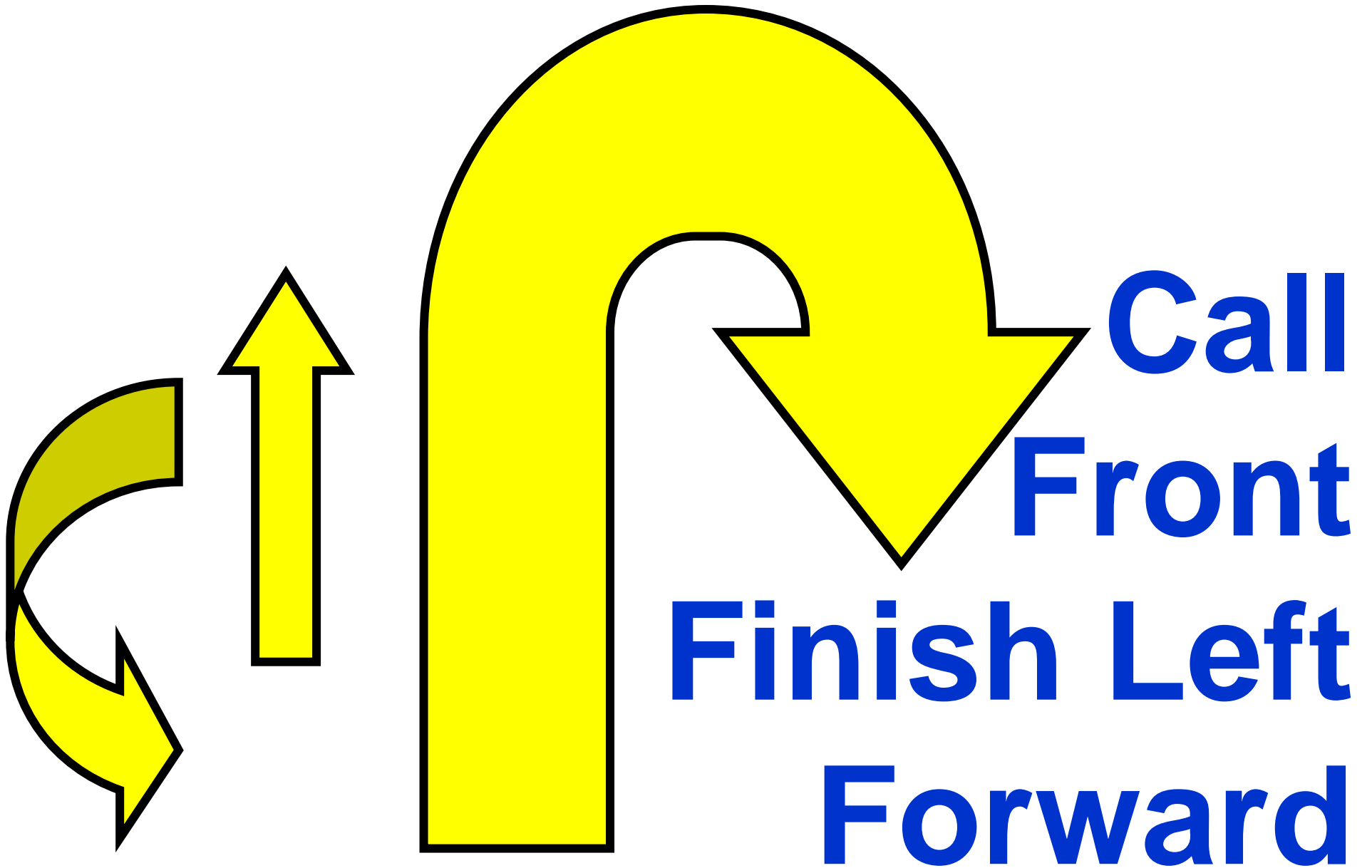








**Call
Front
Finish Right
Forward**

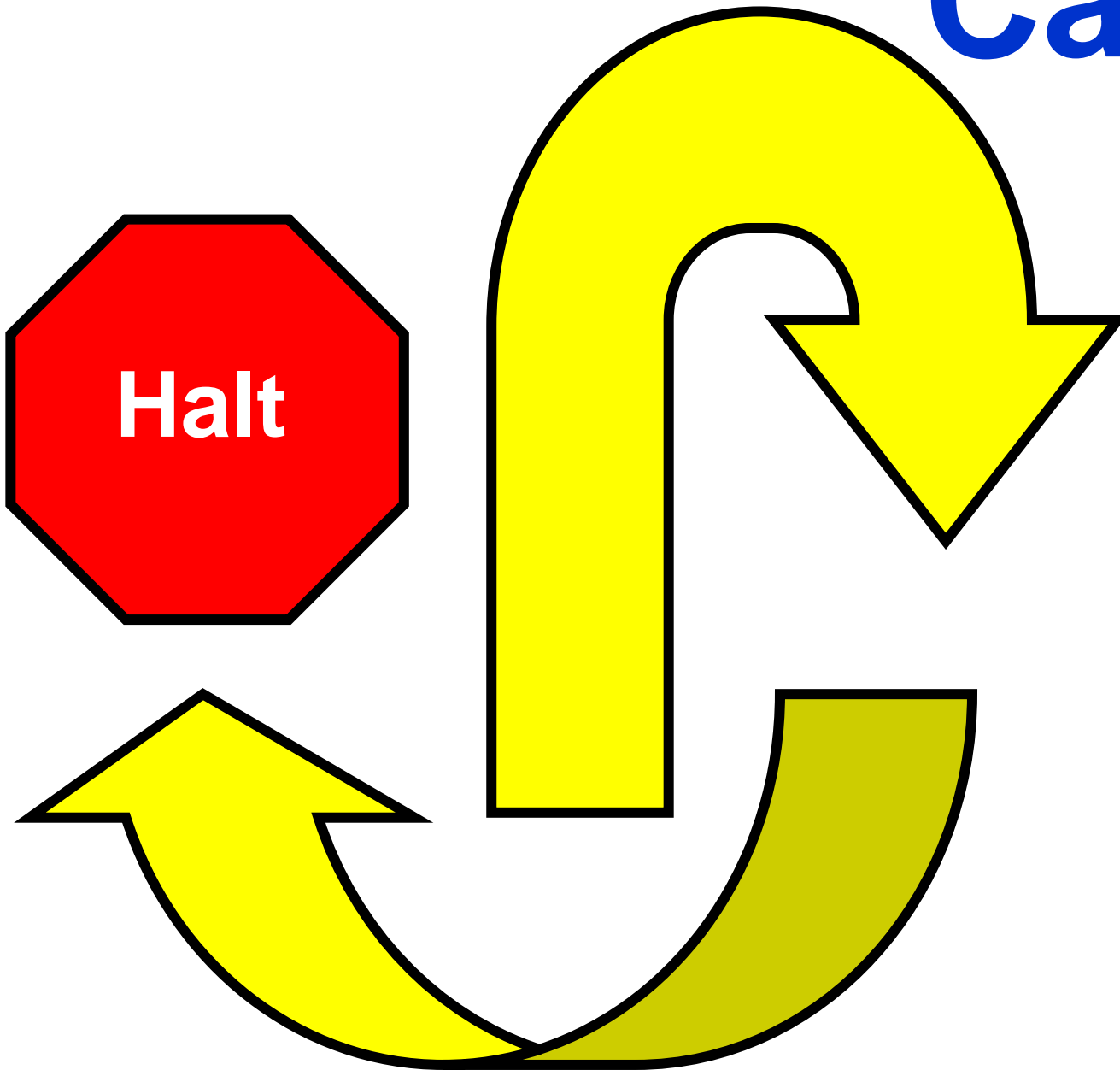


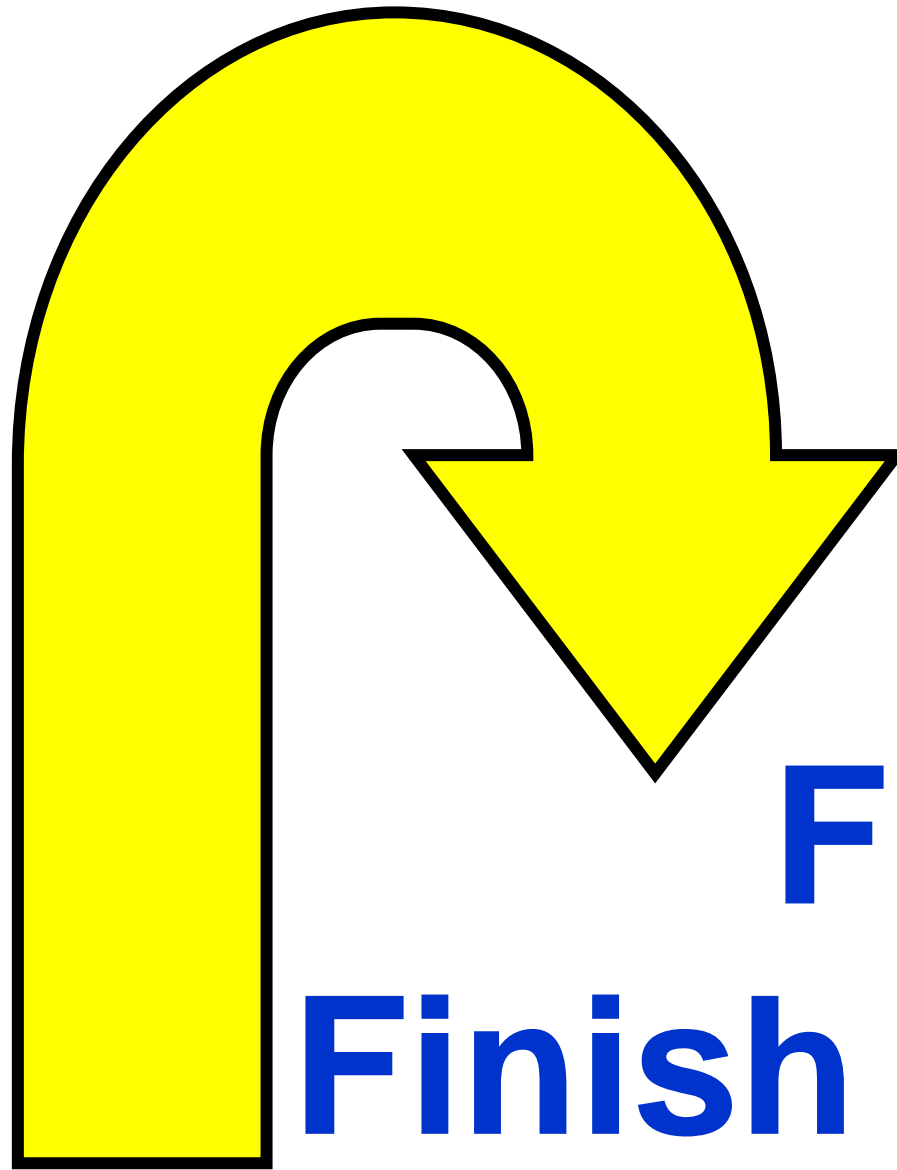
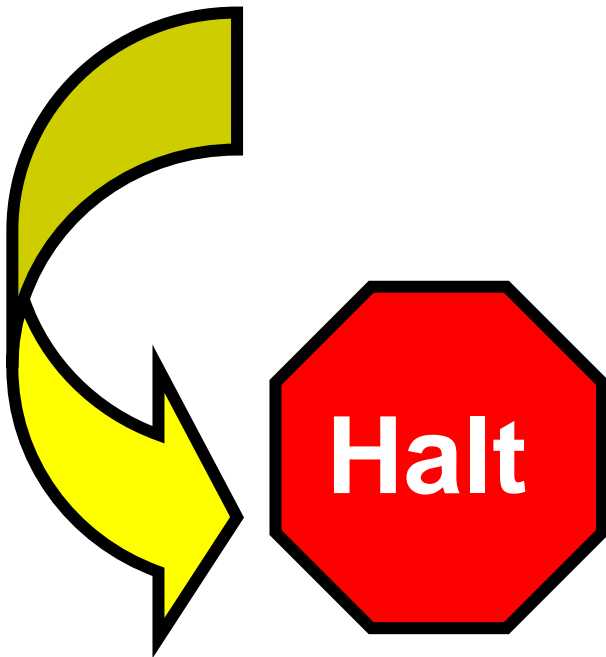
Call Front

Finish

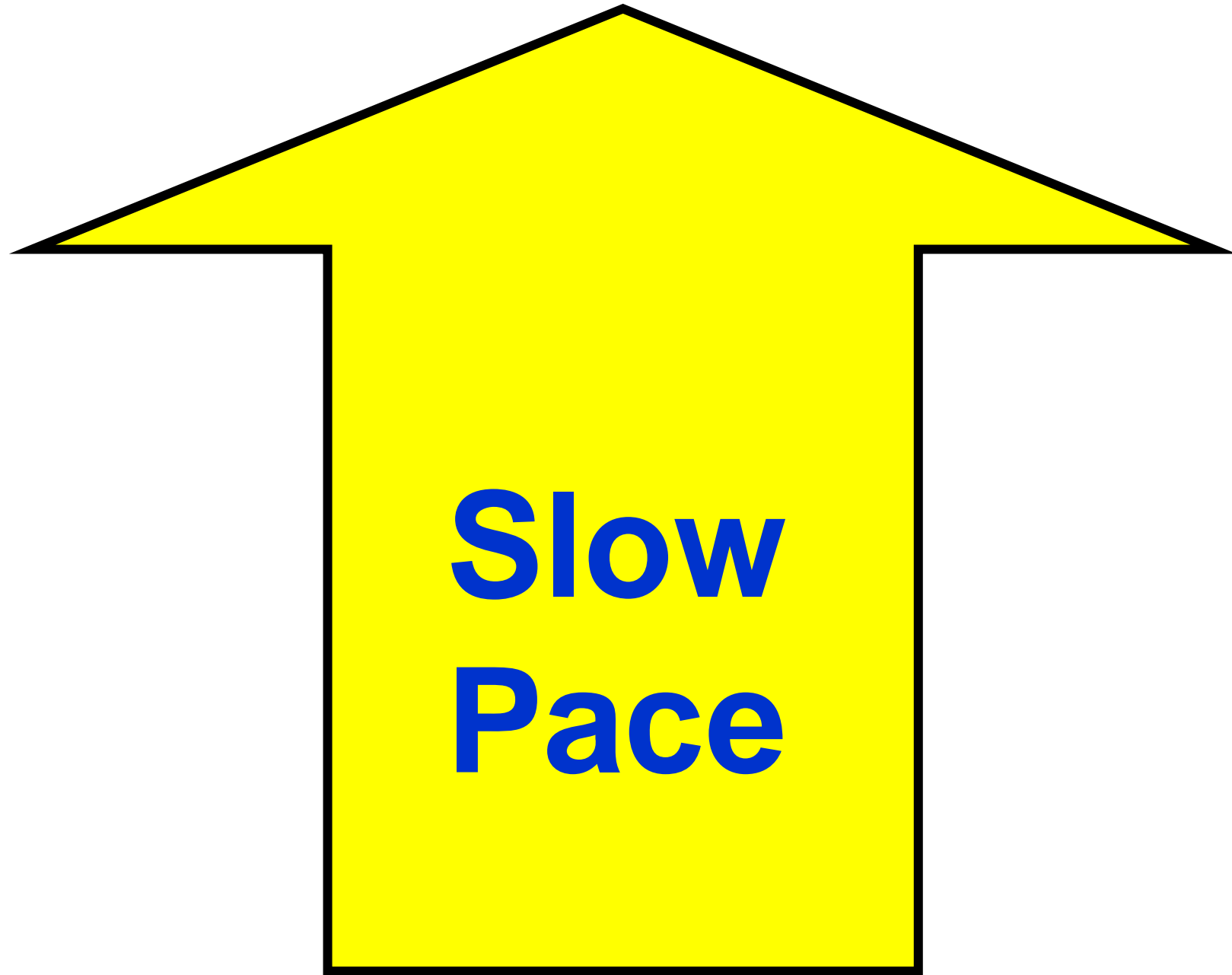
Right

Halt





**Call
Front
Finish Left
Halt**



**Slow
Pace**

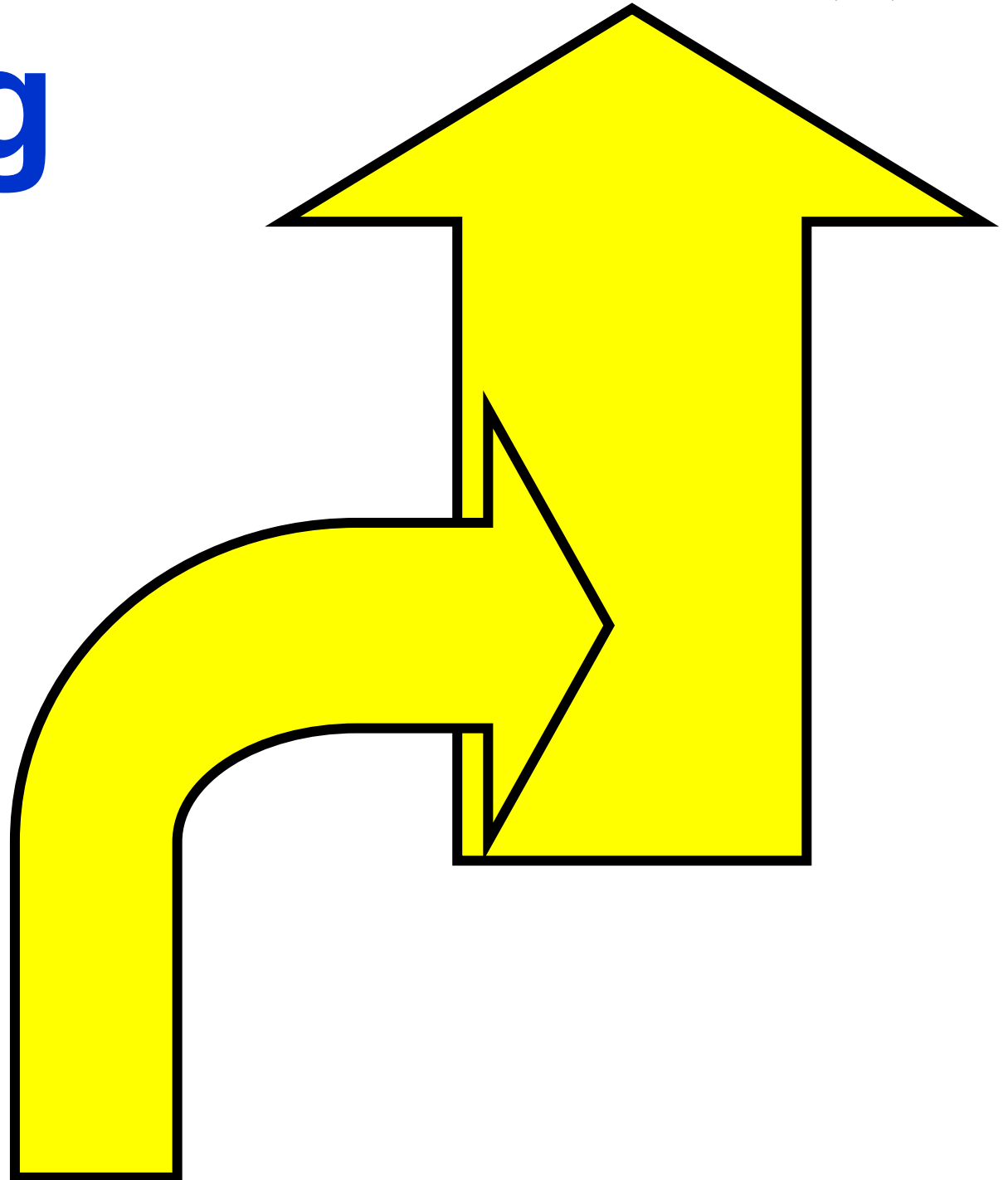


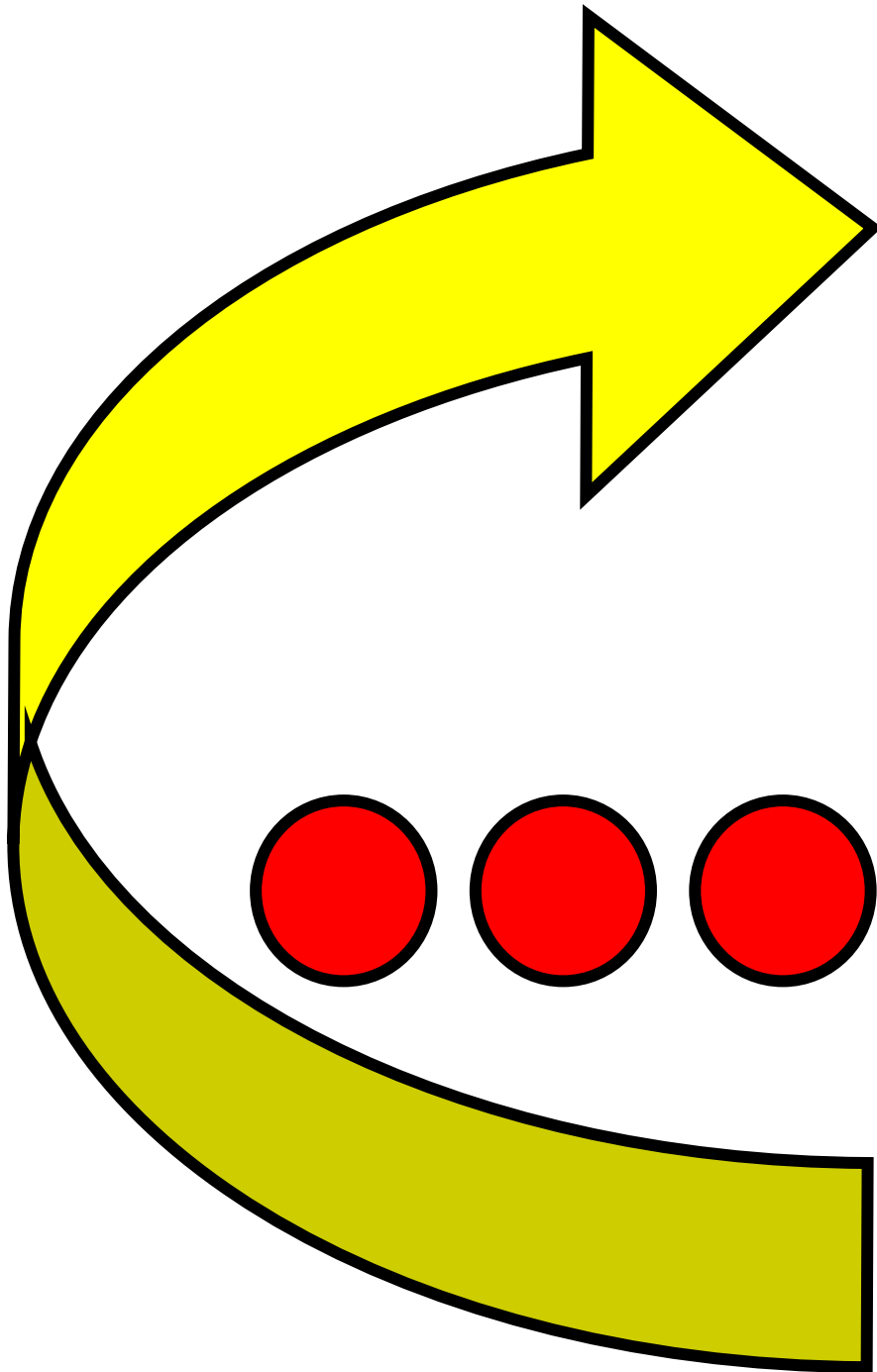
**Fast
Pace**



**Normal
Pace**

**Moving
Side
Step
Right**

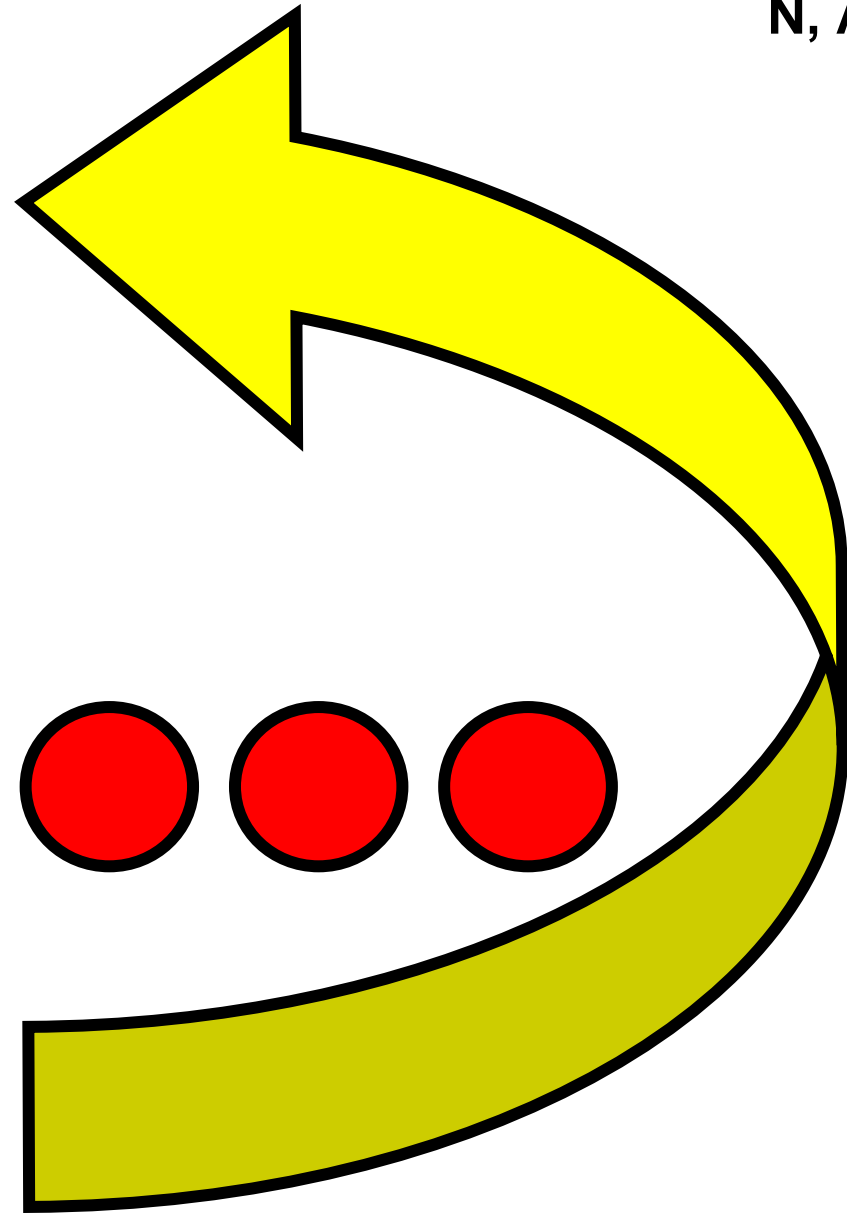




**Spiral
Right**

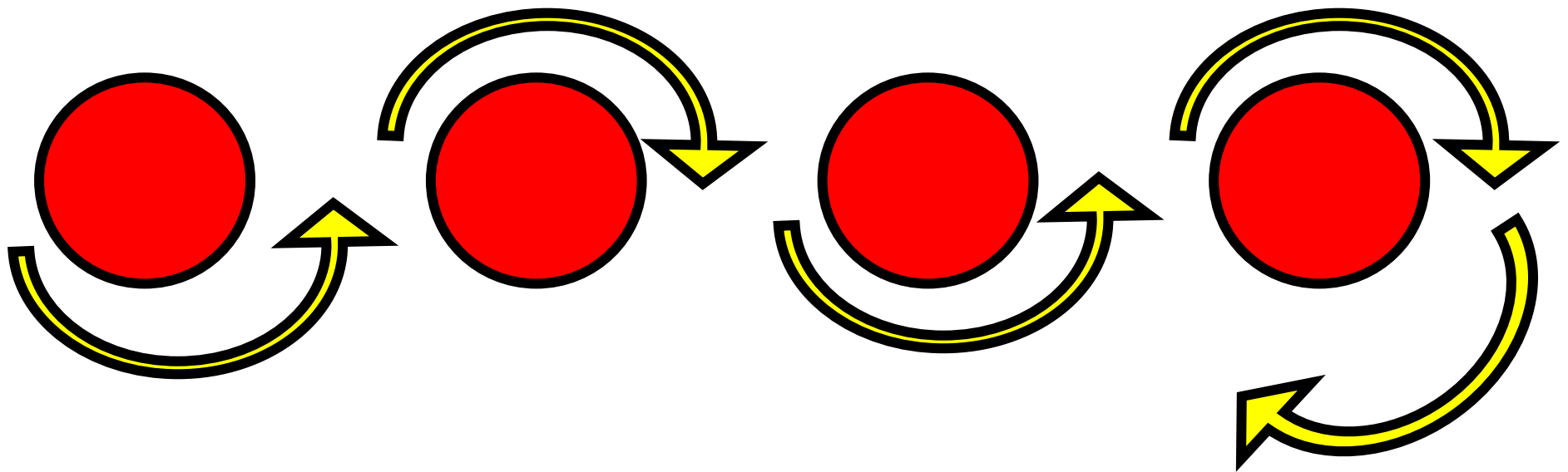
**Dog
Outside**

**Spiral
Left**

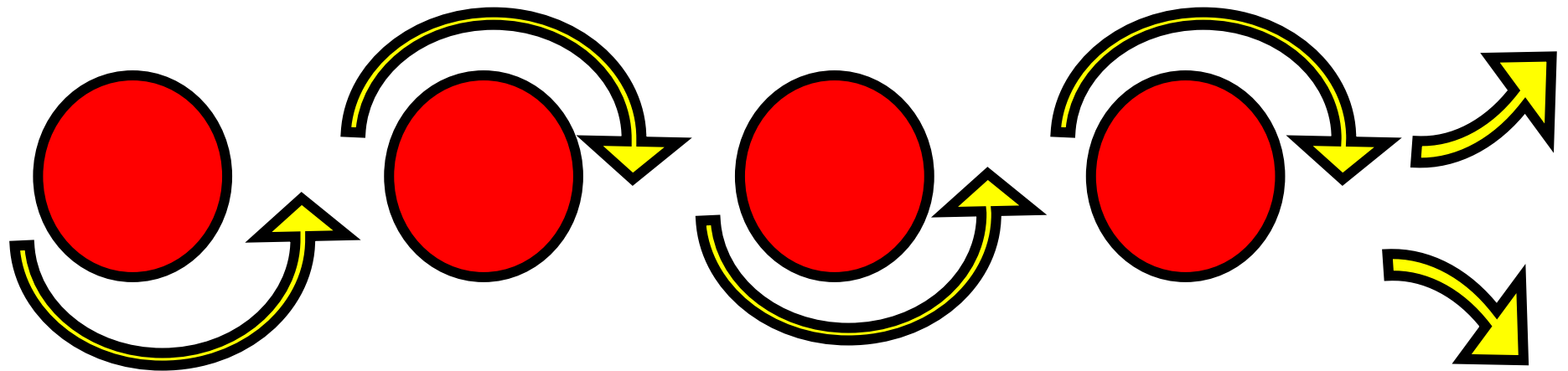


Dog Inside

Straight Figure 8 Weave Twice

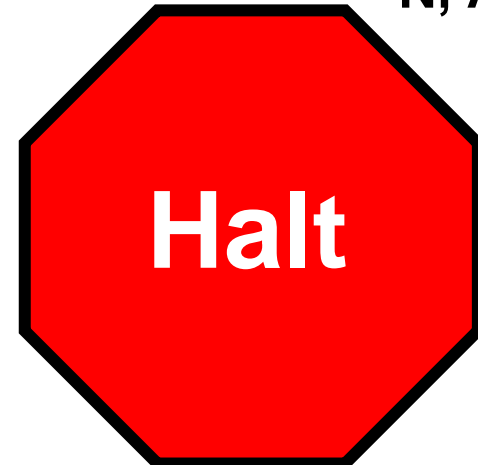


Serpentine Weave Once





1 Step



2 Steps

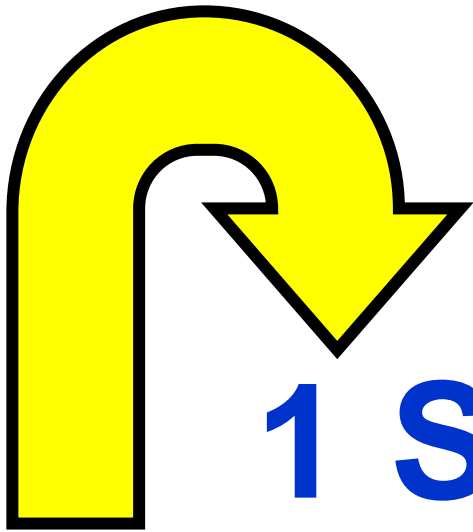


3 Steps



Call Front

N, A, X- #26



1 Step Back

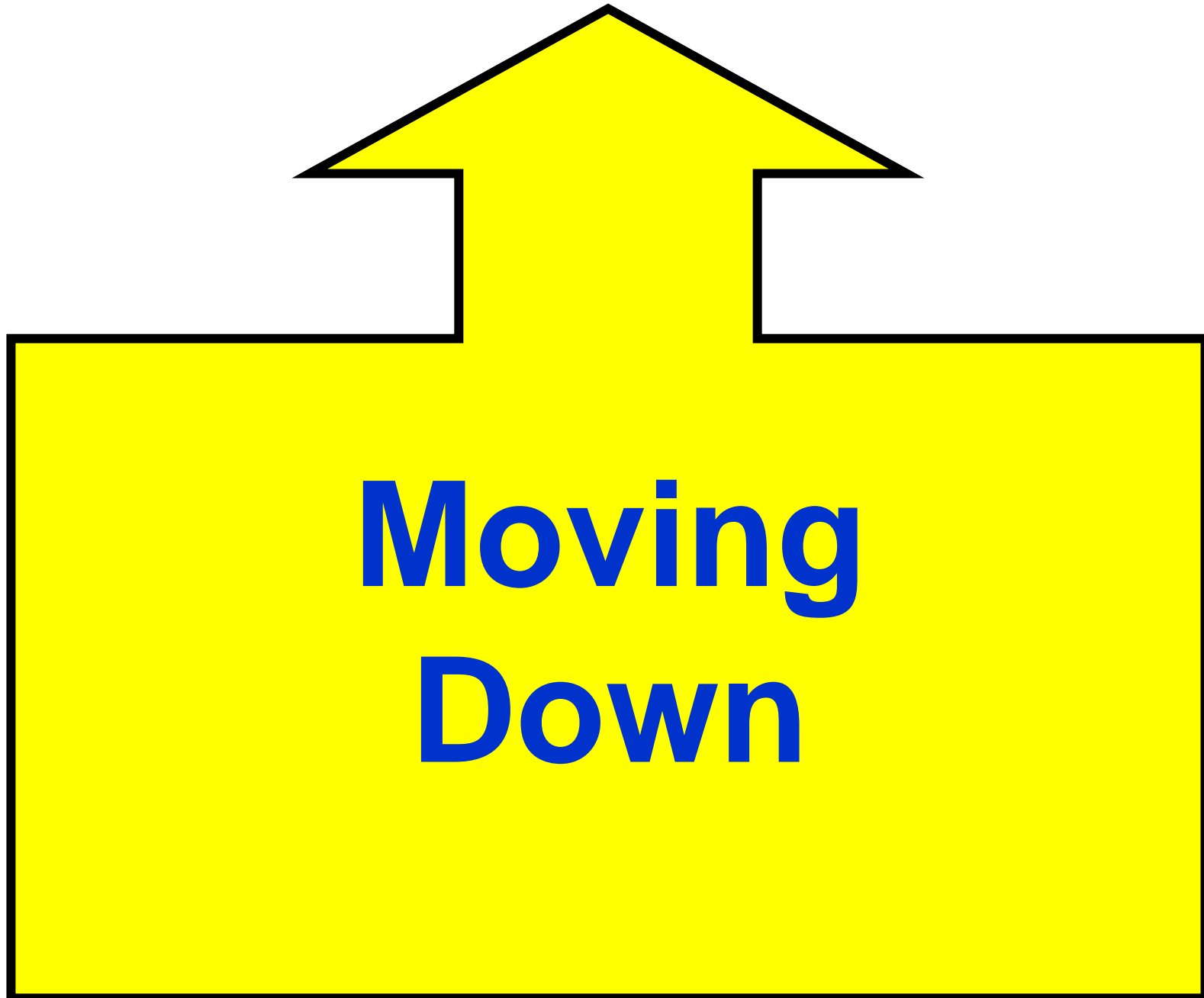


2 Steps Back



3 Steps Back

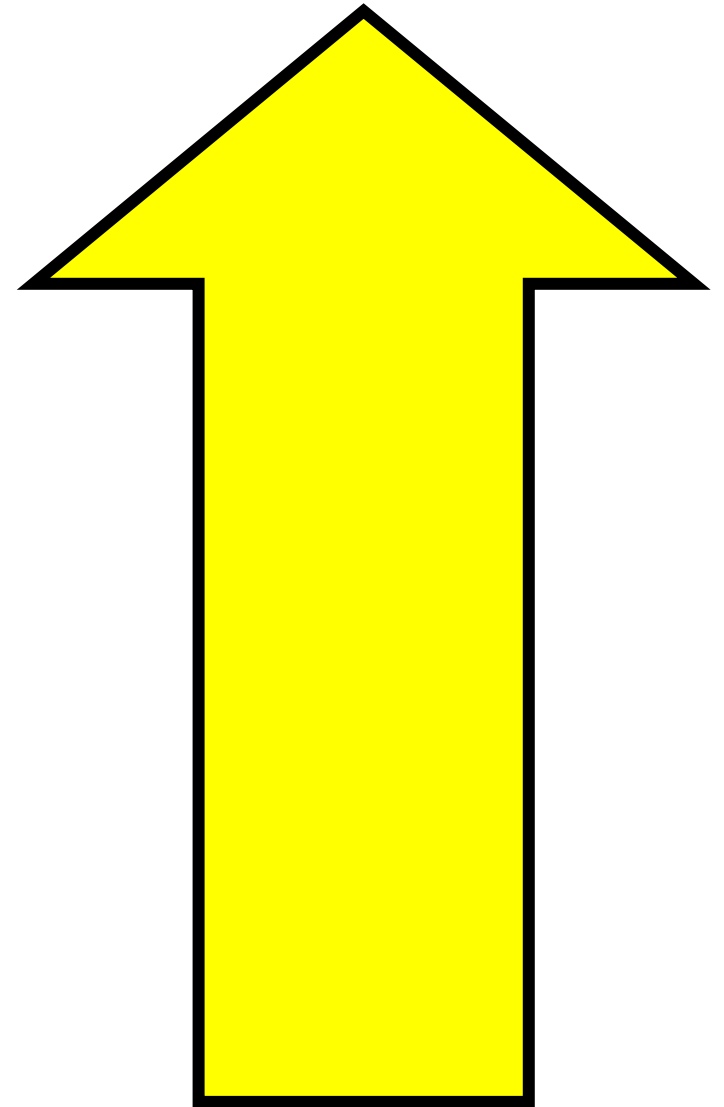




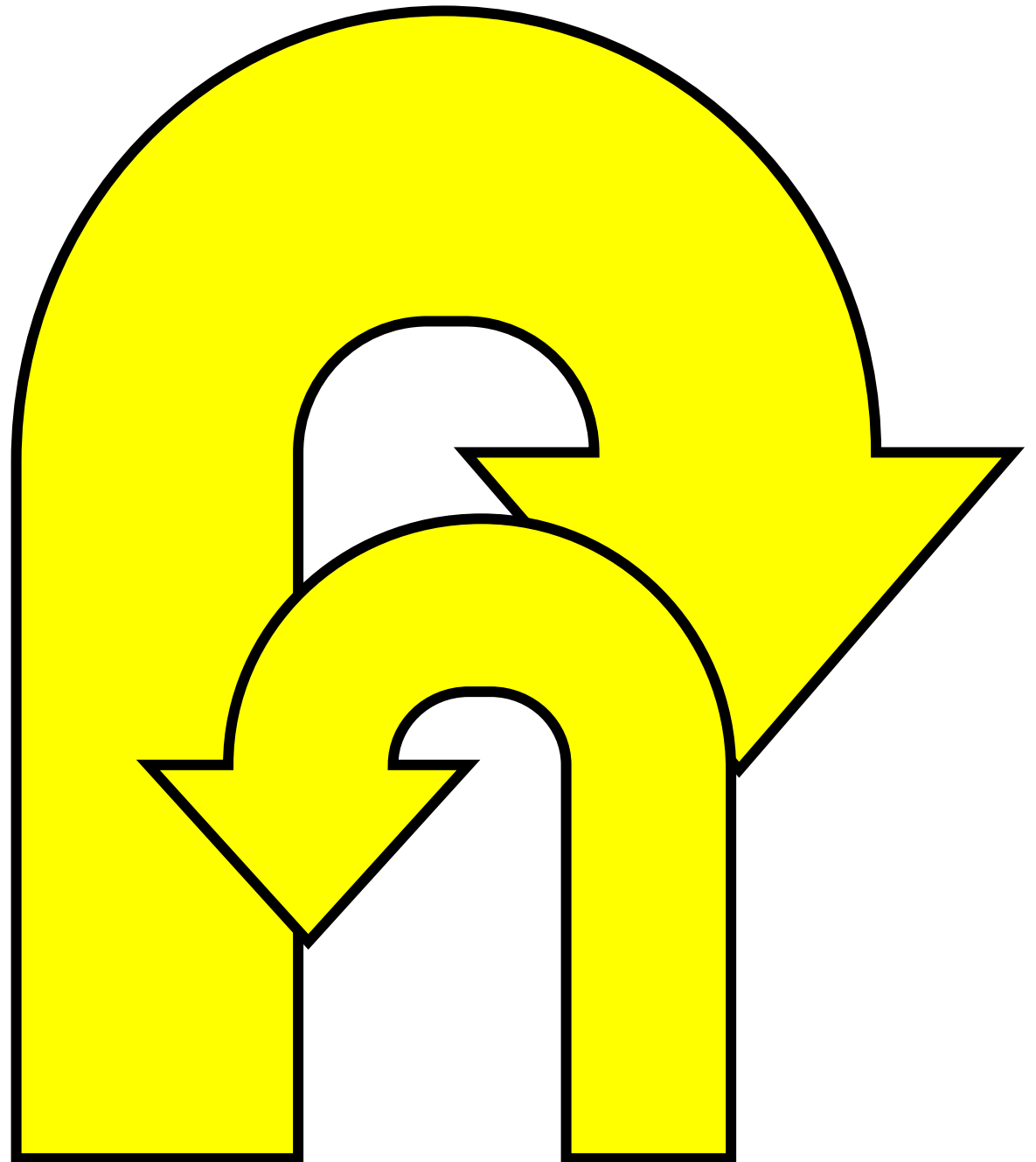
**Moving
Down**



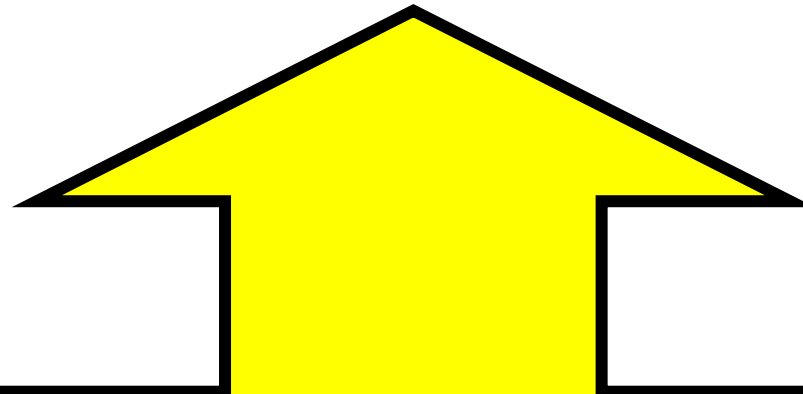
**Fast
Forward
From Sit**



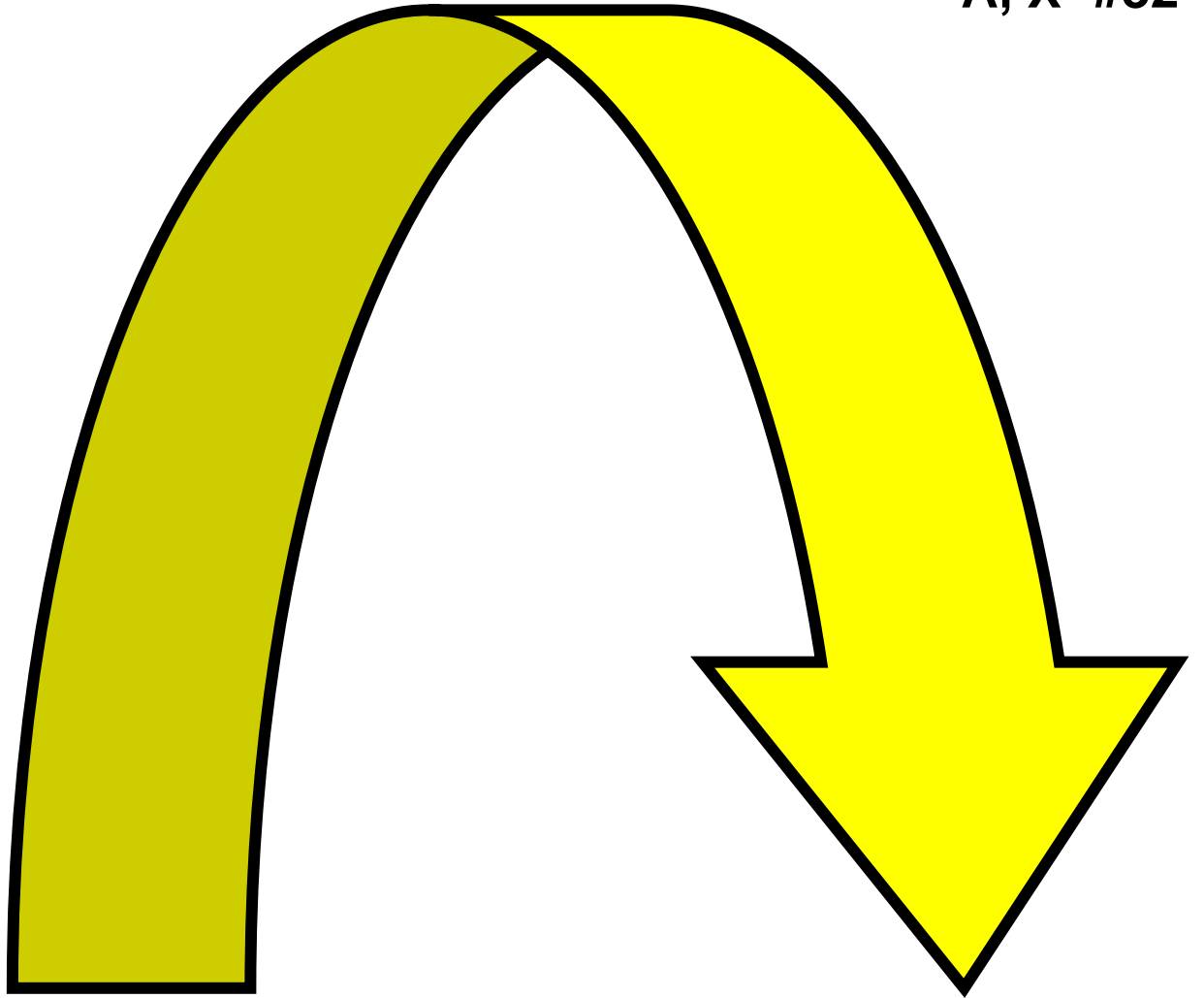
**Left
About
Turn**



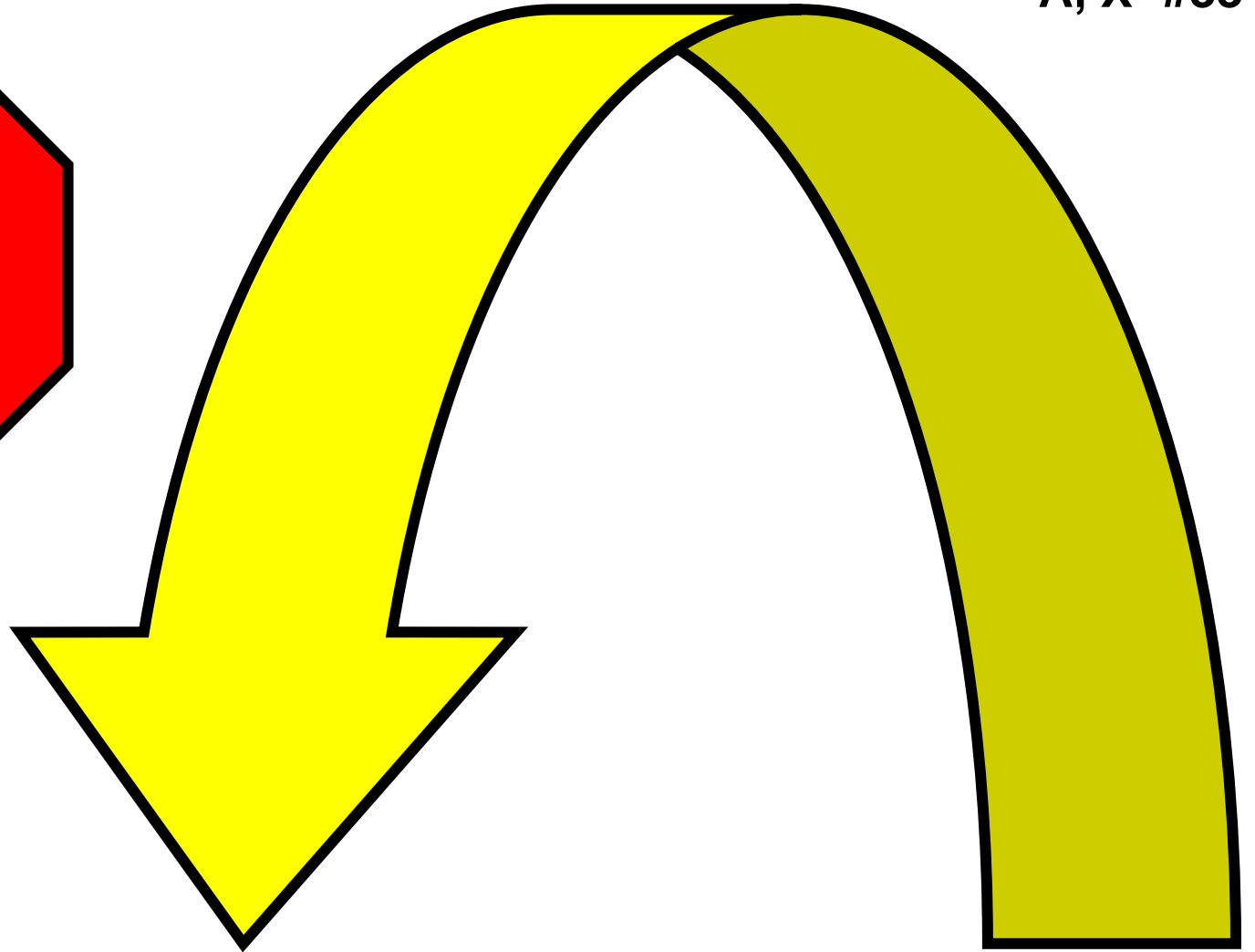




**Down
Walk Around
Dog**

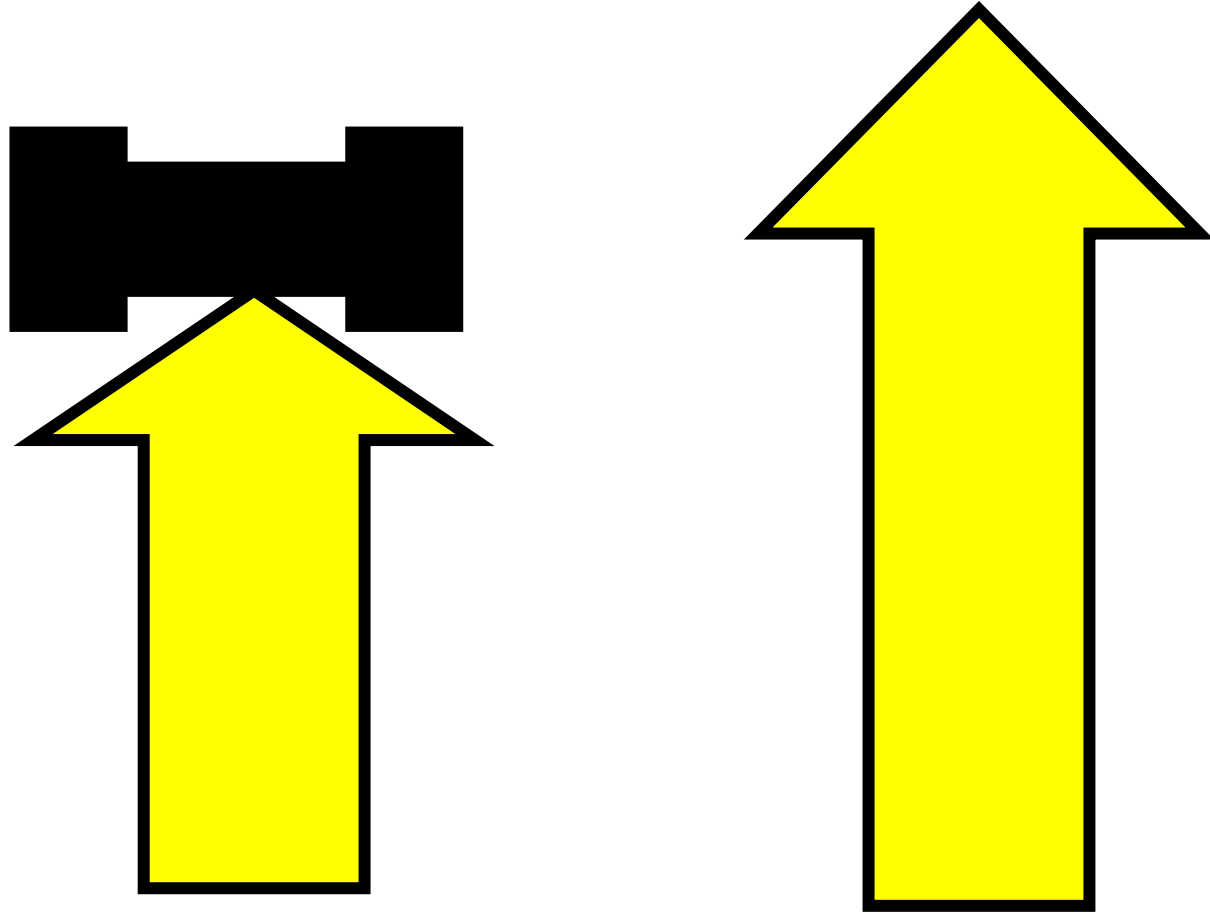


**About Turn Right
Forward**



**About “U” Turn
Forward**

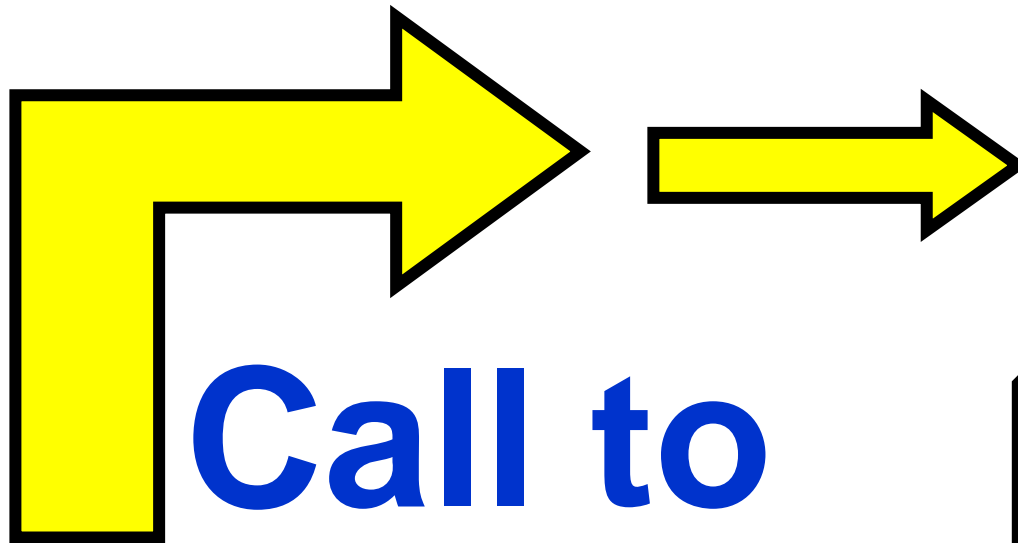
Send Over Jump



Handler Runs By



**Turn Right
1 Step**



**Call to
Heel**

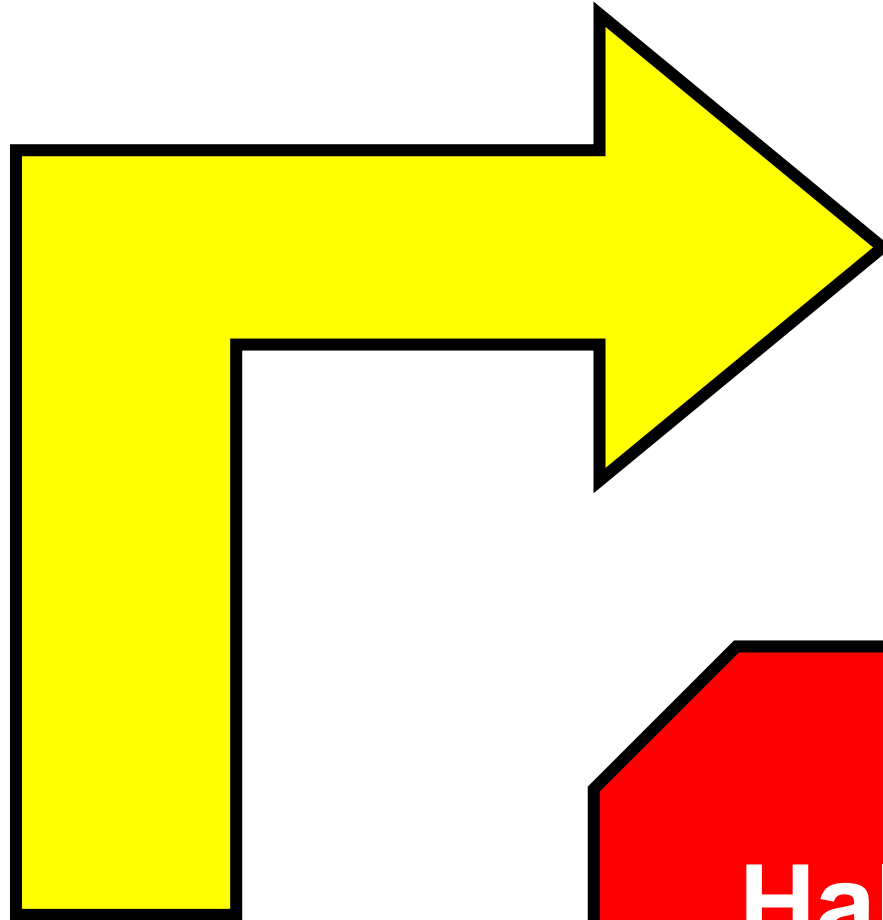


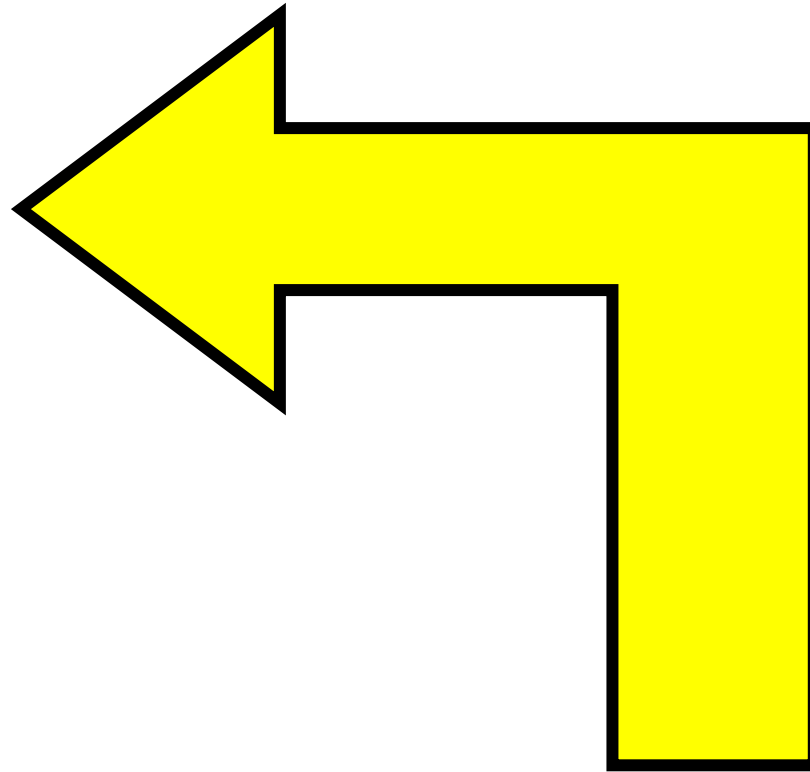


Stand
Walk
Around Dog



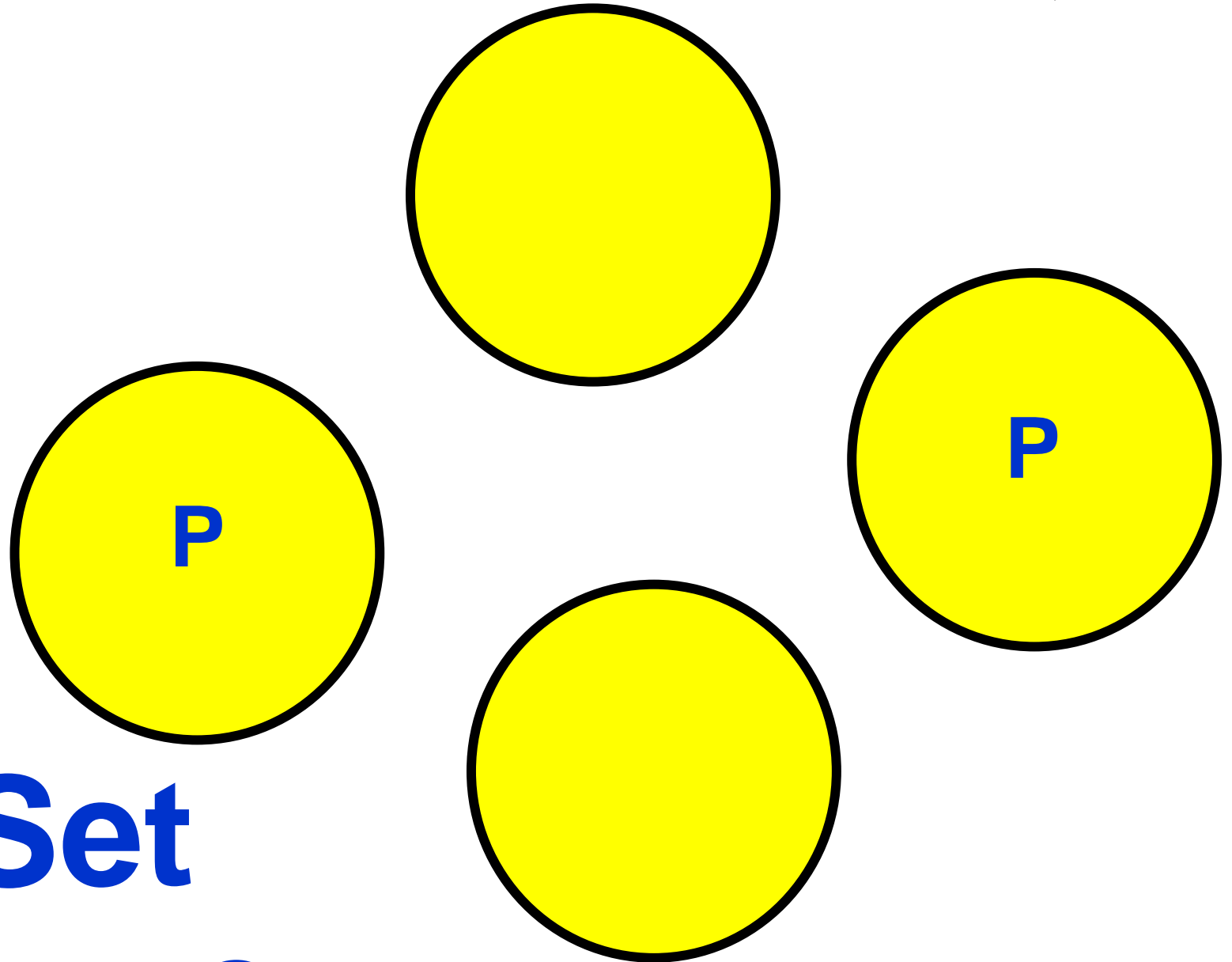
**90°
Pivot
Right**



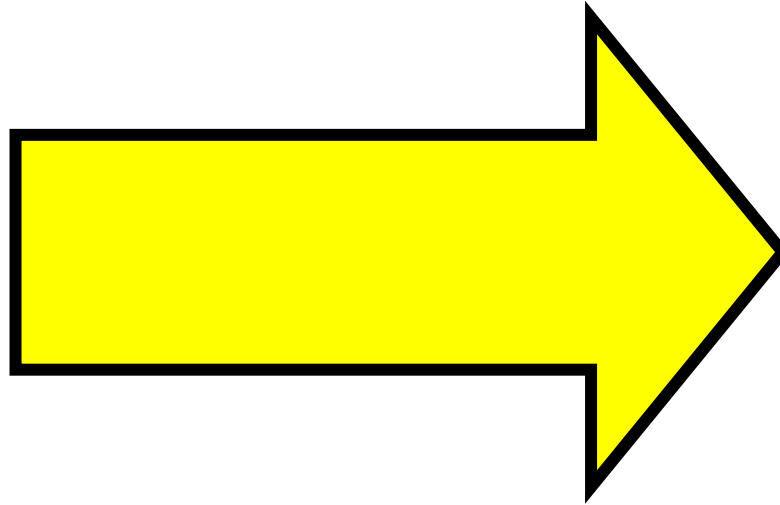


**90°
Pivot
Left**



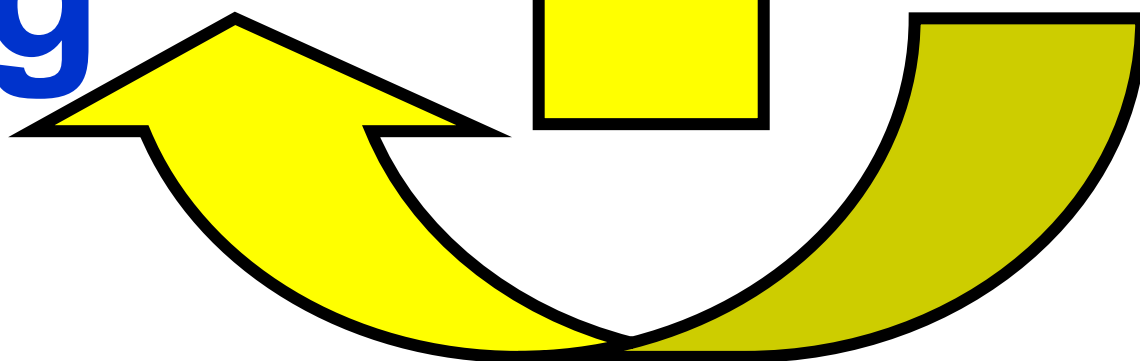
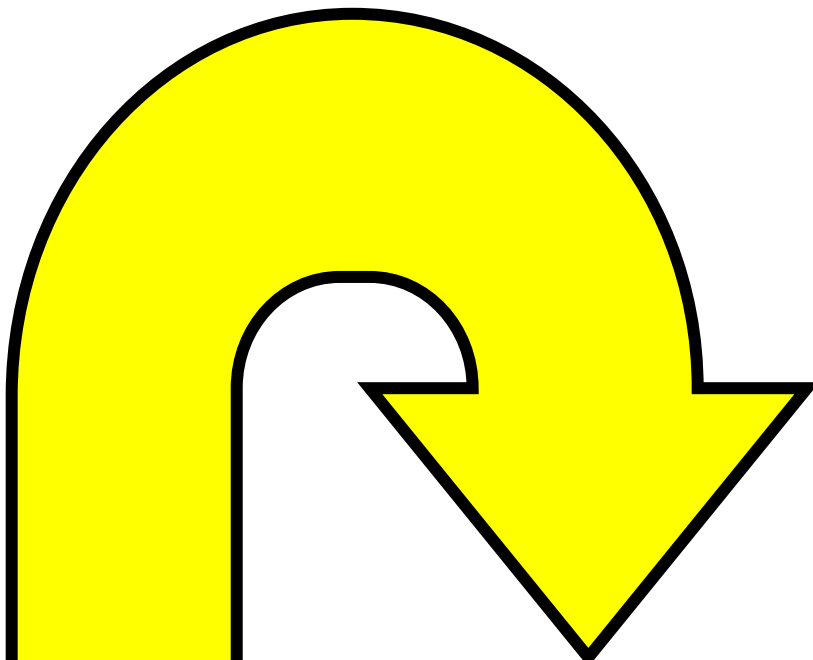
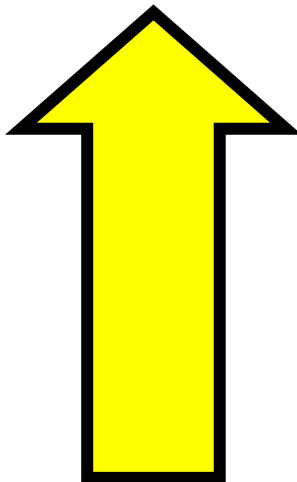


Off-Set Figure 8



**Side Step
Right**

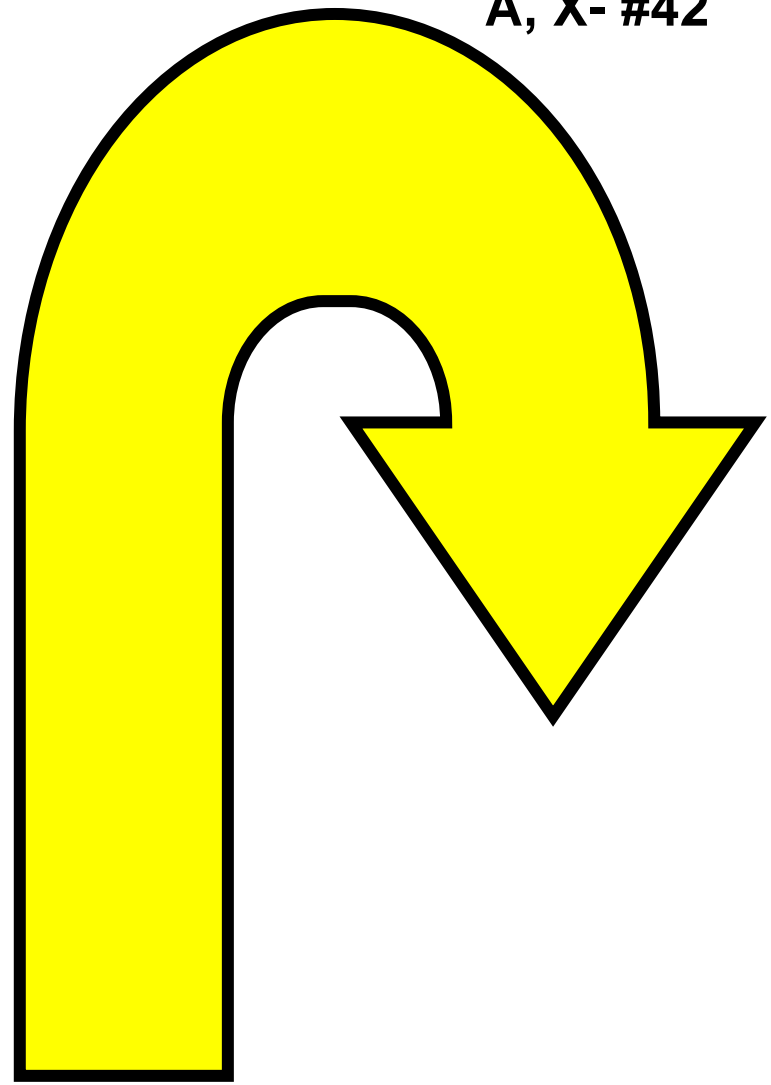
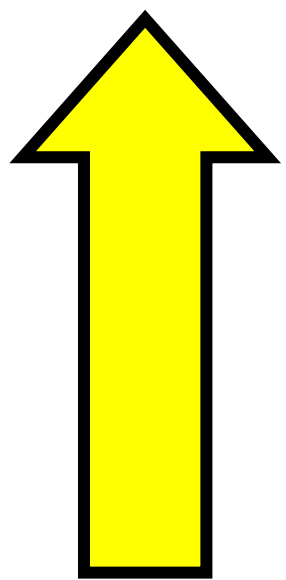
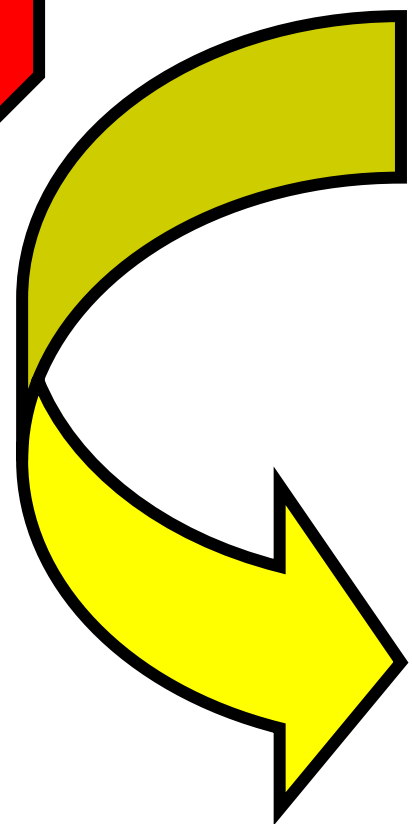




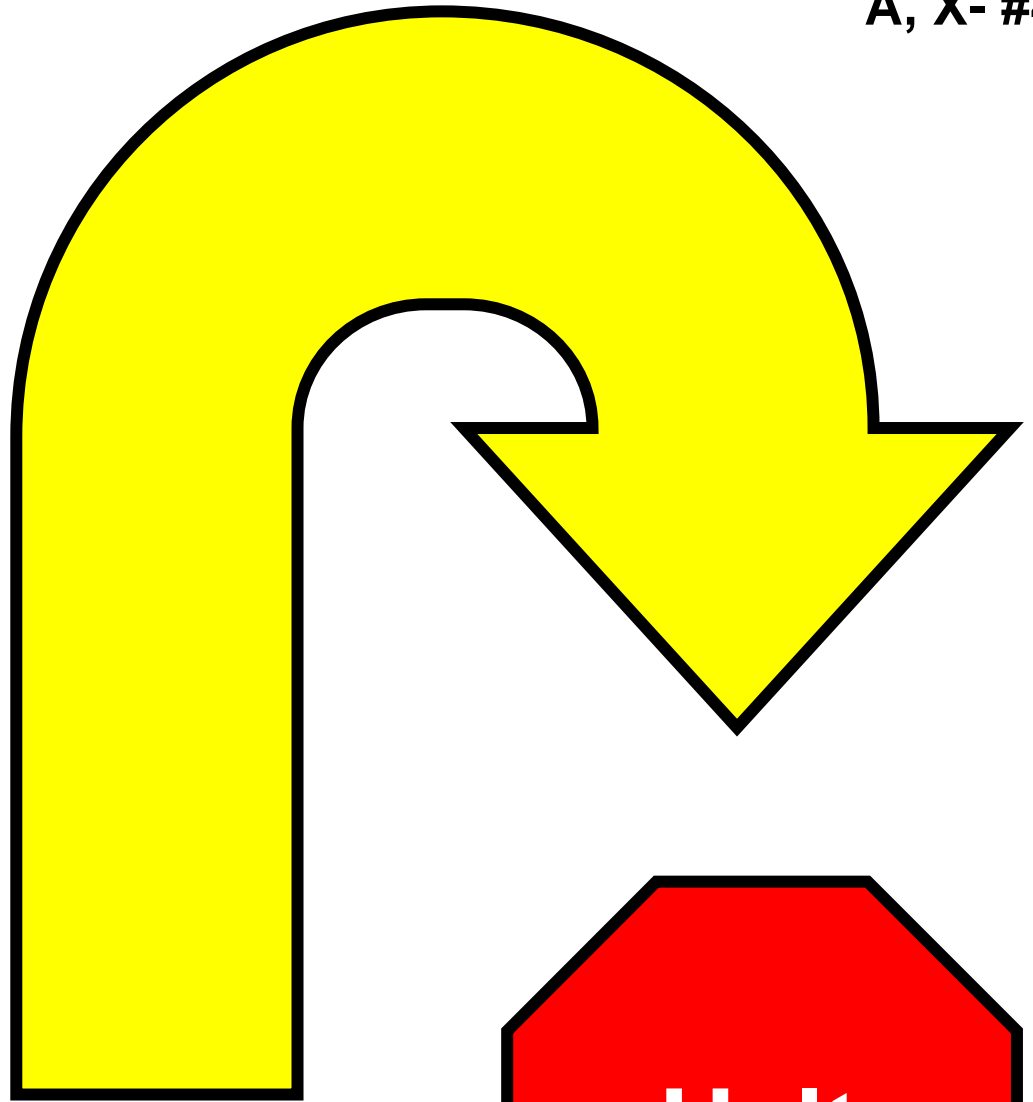
Call Dog

Front

Finish Right



**Call Dog Front
Finish Left**



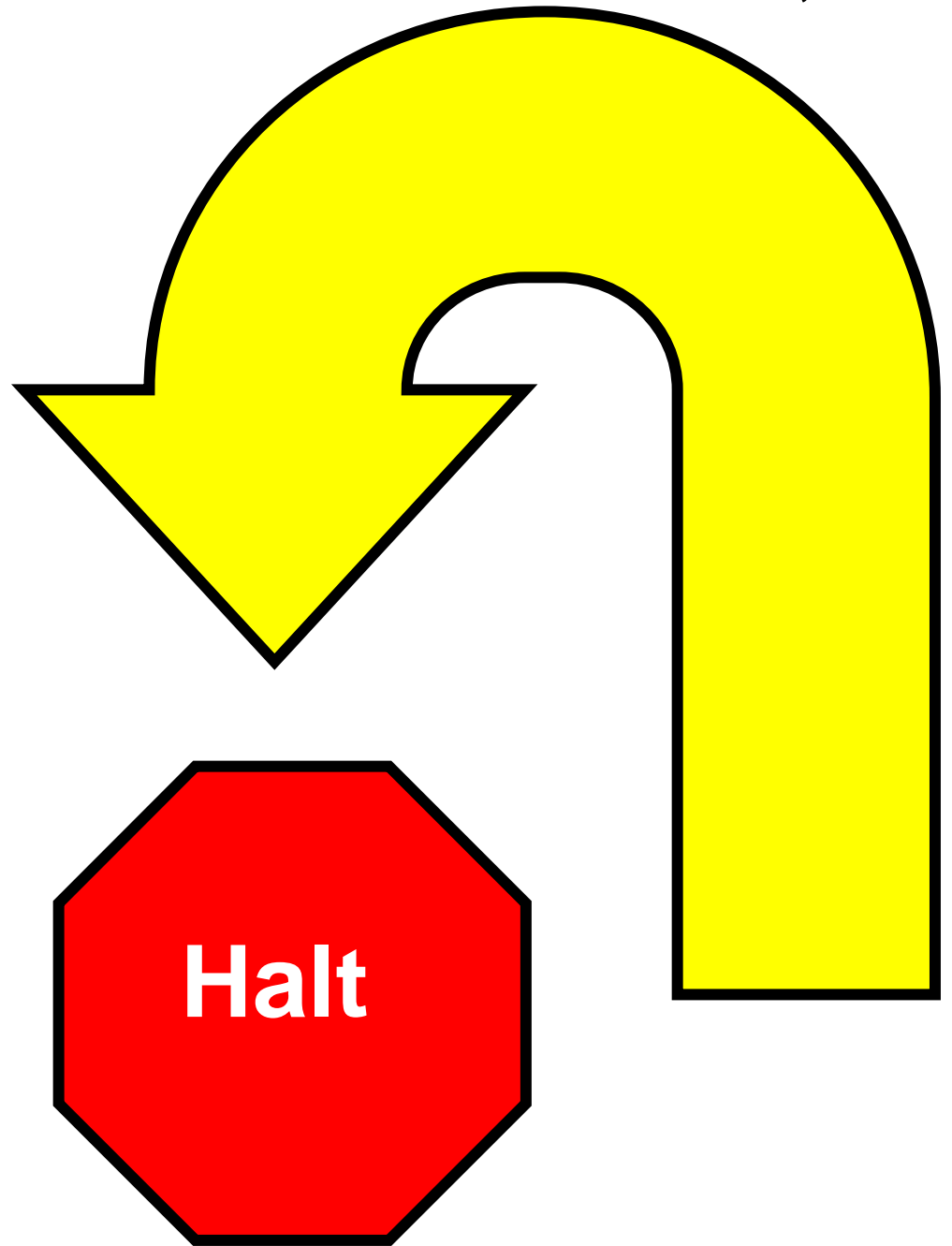
**180°
Pivot
Right**

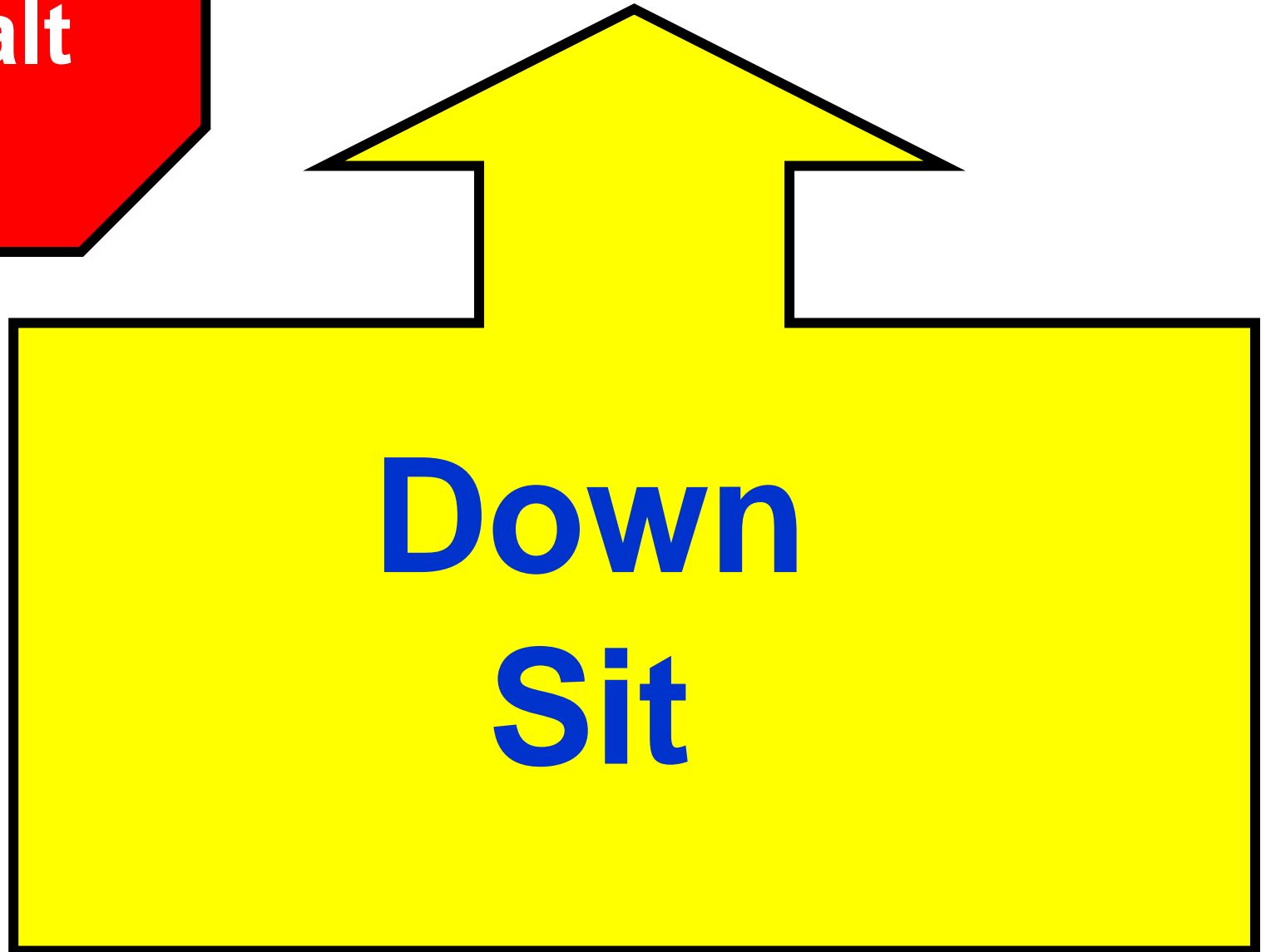


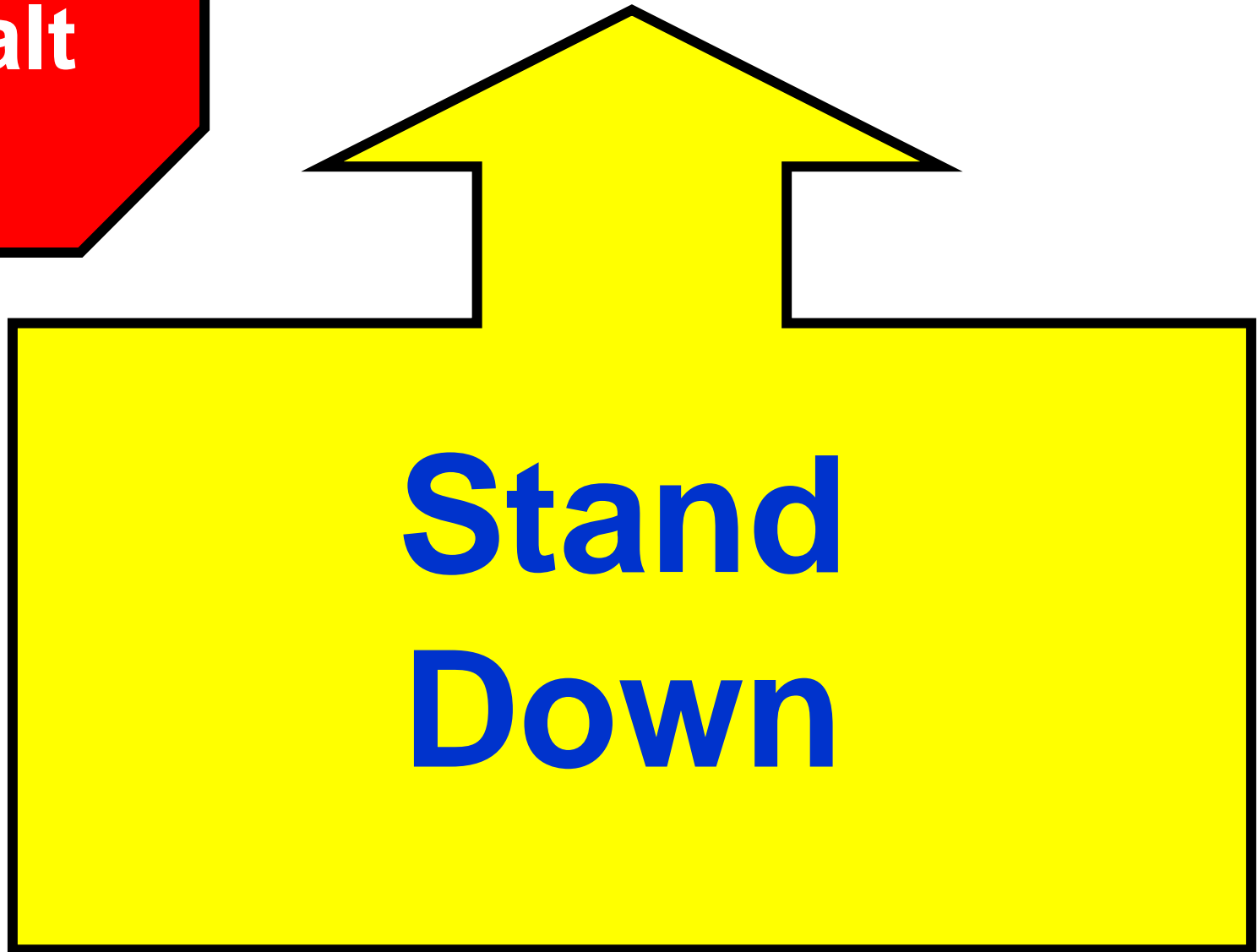
180°

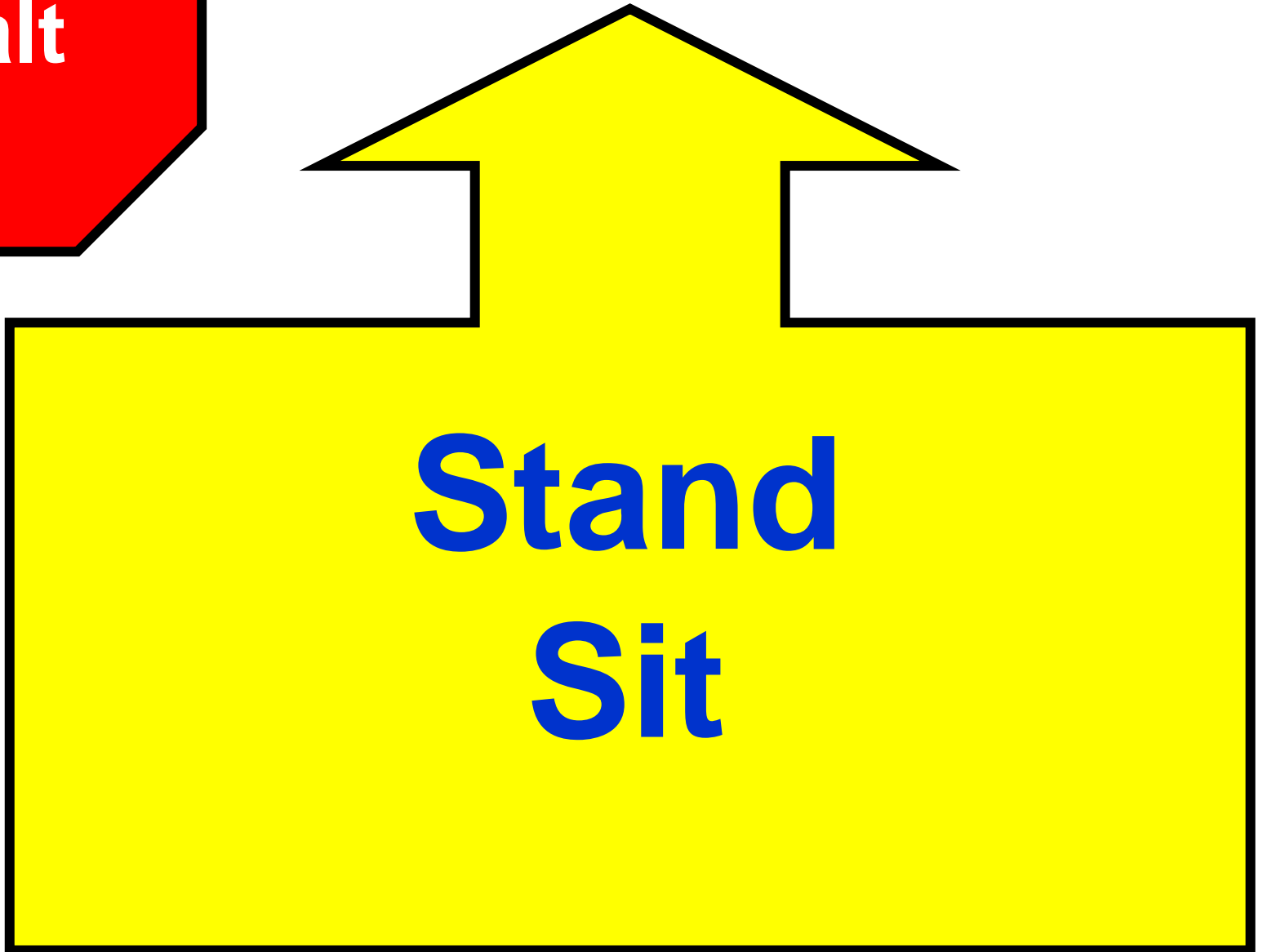
Pivot

Left



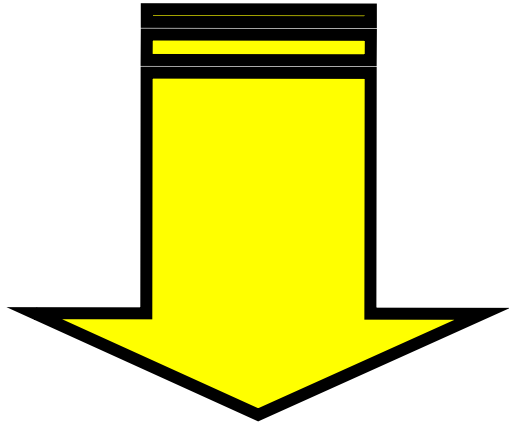




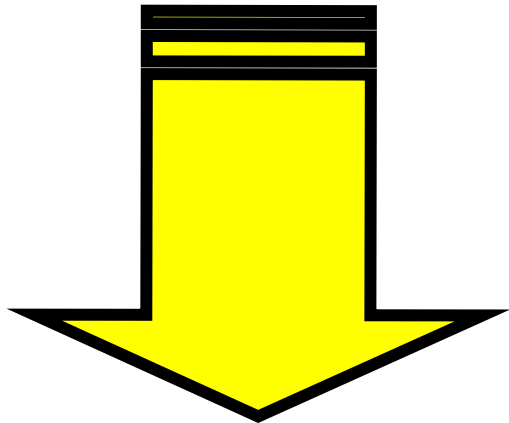




**Moving Stand
Walk Around
Dog**

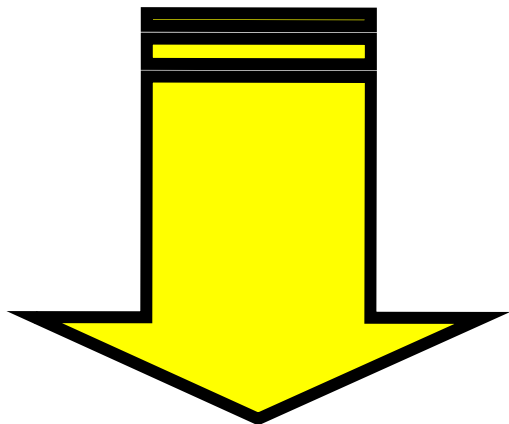


Back Up



3 Steps

Dog



Stays in

Position

Honor