

## Homelynk:

Groepsadres ^	Objectnaam	Gebeurtenis s...	Gegevenstype	Actuele waarde
1/0/3	Beweging - Rolluik - Bureau		01.008 omhoog/omlaag	omhoog
1/1/3	Stap/stop - Rolluik - Bureau		01.010 start/stop	start
1/2/3	Positie - Rolluik - Bureau		05.001 schaal	0%
1/3/3	Feedback - Rolluik - Bureau		05. 1 byte unsigned integer	1

## ETS:

	24	Movement object	Channel 4	Beweging - Rolluik - Bureau	1/0/3	1 bit	C - W - -	Laag
	25	Stop object	Channel 4	Stap/stop - Rolluik - Bureau	1/1/3	1 bit	C - W - -	Laag
	26	Height	Channel 4	Positie - Rolluik - Bureau	1/2/3	1 byte	C - W - -	Laag
	28	Status feedback for height	Channel 4	Feedback - Rolluik - Bureau	1/3/0	1 byte	C R - T -	Laag

## ETS Parameters:

2: Roller shutter	Scenes	<input checked="" type="radio"/> disabled <input type="radio"/> enabled
2: Drive	Calibration	<input checked="" type="radio"/> disabled <input type="radio"/> enabled
3: Roller shutter	Weather alarm	<input checked="" type="radio"/> disabled <input type="radio"/> enabled
3: Drive	Failure mode	<input checked="" type="radio"/> disabled <input type="radio"/> enabled
<b>4: Roller shutter</b>	Status signals	<input type="radio"/> disabled <input checked="" type="radio"/> enabled
4: Drive	Manual operation when bus voltage fails (mains voltage present)	<input checked="" type="radio"/> disabled <input type="radio"/> enabled
4: Status reports		

2: Roller shutter	Extended drive parameters	<input checked="" type="radio"/> disabled <input type="radio"/> enabled
2: Drive	Time base for running time of height adjustment	<input checked="" type="radio"/> 10 ms <input type="radio"/> 100 ms
3: Roller shutter	Factor for running time for height adjustment (10-64000), 1 second=1000 ms	19000
3: Drive	Time base for additional running time in upward direction	<input checked="" type="radio"/> 10 ms <input type="radio"/> 100 ms
4: Roller shutter	Factor for additional running time in upward direction	disabled
<b>4: Drive</b>	Pause on reverse on change in direction (1-255) factor * 100 ms, manuf. data	1

2: Roller shutter	Status of height	active status response object
2: Drive		
3: Roller shutter		
3: Drive		
4: Roller shutter		
4: Drive		
<b>4: Status reports</b>		