

Master – Computer Science
University Paris-Sud

Open GL & GLSL Course

GLSL Tutorial
& Mapping for Relief and Reflection

Christian Jacquemin

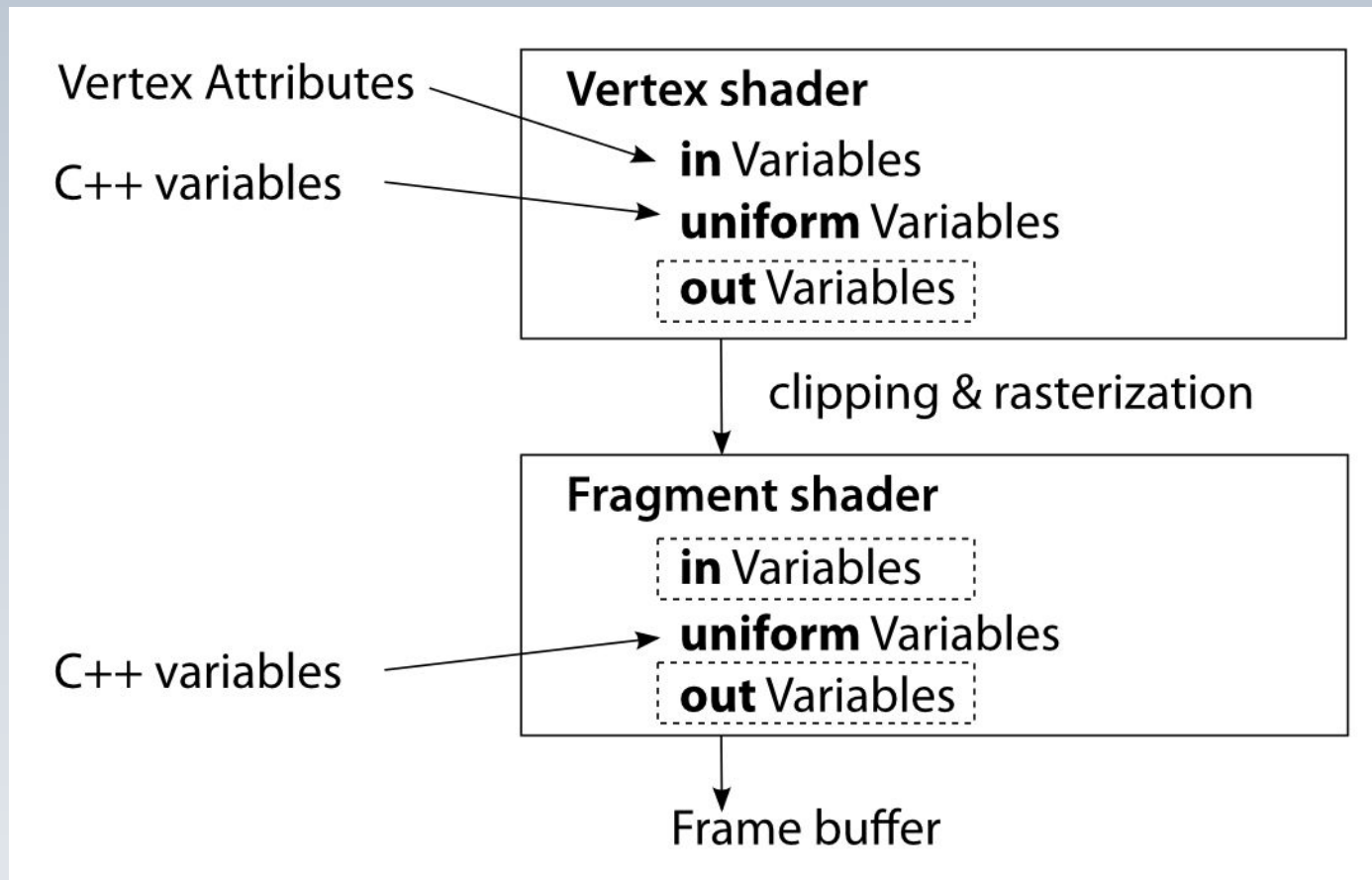
GLSL Tutorial & Relief Techniques

(I)

GLSL Tutorial

Graphic Pipe-line

vertex & fragment shader pipe-line



Data Types

- **elementary** data types
 - float, double, int, uint, bool
- **arrays**
 - dimension: 2, 3, or 4
 - vec, dvec, ivec, uvec, bvec
- **matrices** of floats or doubles
 - square matrices: size 2x2, 3x3, or 4x4: mat3, dmat4
 - non-square matrices: size {2,3,4}x{2,3,4}:
mat3x4, dmat4x2
- **texture samplers**
 - sampler1D, sampler2D, sampler3D for 1, 2, 3D power-of-two textures
 - sampler2DRect for rectangle textures
 - samplerCube for cubemap textures

Data Types

- **variable declaration and initialization** very similar to C-style
 - `float a = 1.0;`
 - `vec3 point = vec3(1.0,1.0,4.0);`
 - `mat2 mat = mat2(1.0,0.0,0.0,1.0);`
(matrices are assigned in column major order)
- **abbreviated initialization**
 - Diagonal matrix: `ident = mat4(1.0);`
 - Array with same values: `null_vec = vec3(0.0);`
- **composite initialization**
 - `vec4 point_hom = vec4(point.xy, 0.0, 1.0);`
- **constant values**
 - `#define height 1.0`

Swizzling

array components are accessed through **xyzw** or **rgba** (but xyzw and rgba have no semantics)

```
vec4 color=vec4(0.3,0.5,0.1,0.5);
```

```
color.rgb = color.rrr; // gray level from red
```

```
color = vec4(color.rgb,1.0); // opaque color
```

```
mat4 transf;
```

```
vec3 point;
```

```
// conversion into homogeneous coordinates and
```

```
// back to Cartesian coordinates
```

```
vec3 transf_point = (transf * vec4(point,1.0)).xyz;
```

Syntax – Main Control Instructions

- usual C syntax: if/else, for, while, do..while + break and continue
- **discard** instruction inside fragment shader: does not output in the frame and/or depth buffer
- main() is the main function
+ possibility of typed subroutines with parameters
- type conversion is used with functions, not with C-style cast

Variables

- **attribute** variables

```
layout(location = 0) in vec3 vp;  
// 1st param location in glVertexAttribPointer
```

- **uniform** variables

```
uniform mat4 projectionMatrix;
```

- **out** variables

```
out vec3 lightOut;
```

- **local** and **global** variables

- some **built-in** variables

- vertex shader in: `int gl_VertexID` (for indexed rendering)

vertex shader out: `vec4 gl_Position` (clip space position),
`float gl_PointSize` (pixel width/height for point rendering)

- fragment shader in: `vec4 gl_FragCoord` (location in window space)

fragment shader out: `float gl_FragDepth` (fragment depth)

GLSL Tutorial & Relief Techniques

(II)

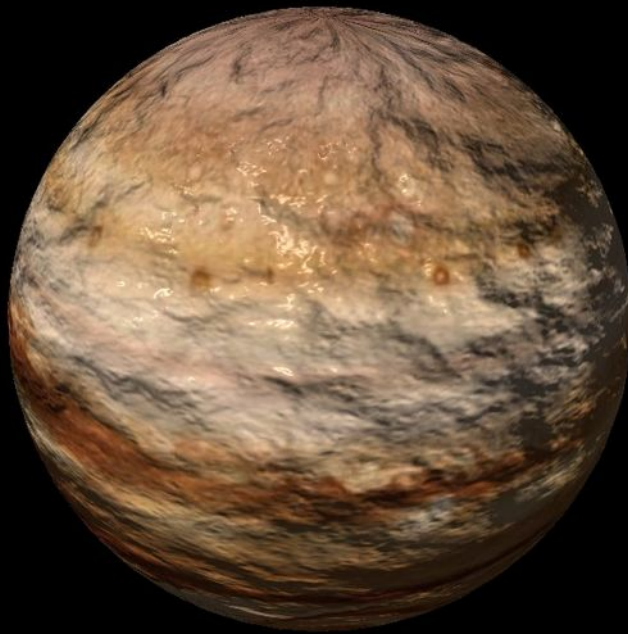
Relief Techniques

Bump- & Normal-Mapping Principles

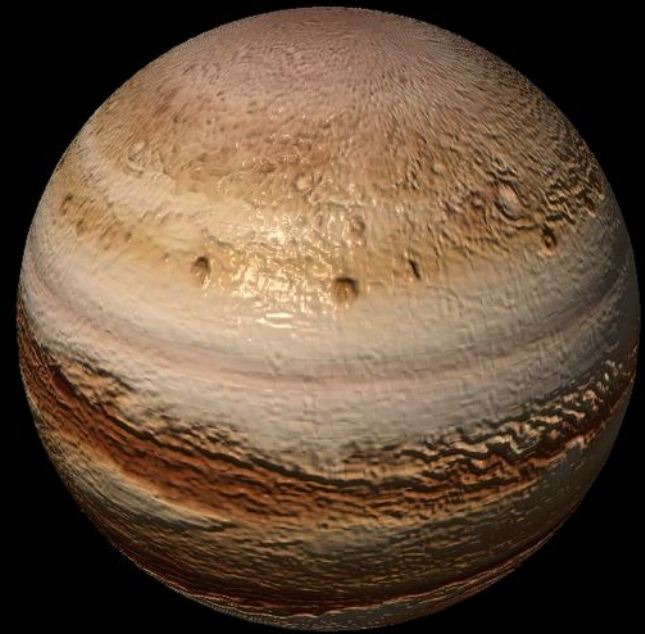
- A perceptually satisfying mesh-less rendering of bumpy surfaces through **normal displacement** (and variations of diffuse & specular light intensity).
- Basic bump-mapping involves **neither geometry, nor pixel displacement** (whether for the geometry or for the image).
- **Bump-mapping**: the normal displacements are directly computed from height field
- **Normal-mapping**: the normals are loaded from a normal map (and are precomputed)

Bump & Normal Mapping Examples

Normal Map



Bump Map



Bump- & Normal-Mapping Pros and Cons

- BENEFITS

- easy to implement
- does not require complex geometrical description
- can be detailed if texture is HD
- works with both **diffuse and specular lighting**
- the height field can be embedded in the alpha channel of the texture

Bump- & Normal-Mapping Pros and Cons

- LIMITS

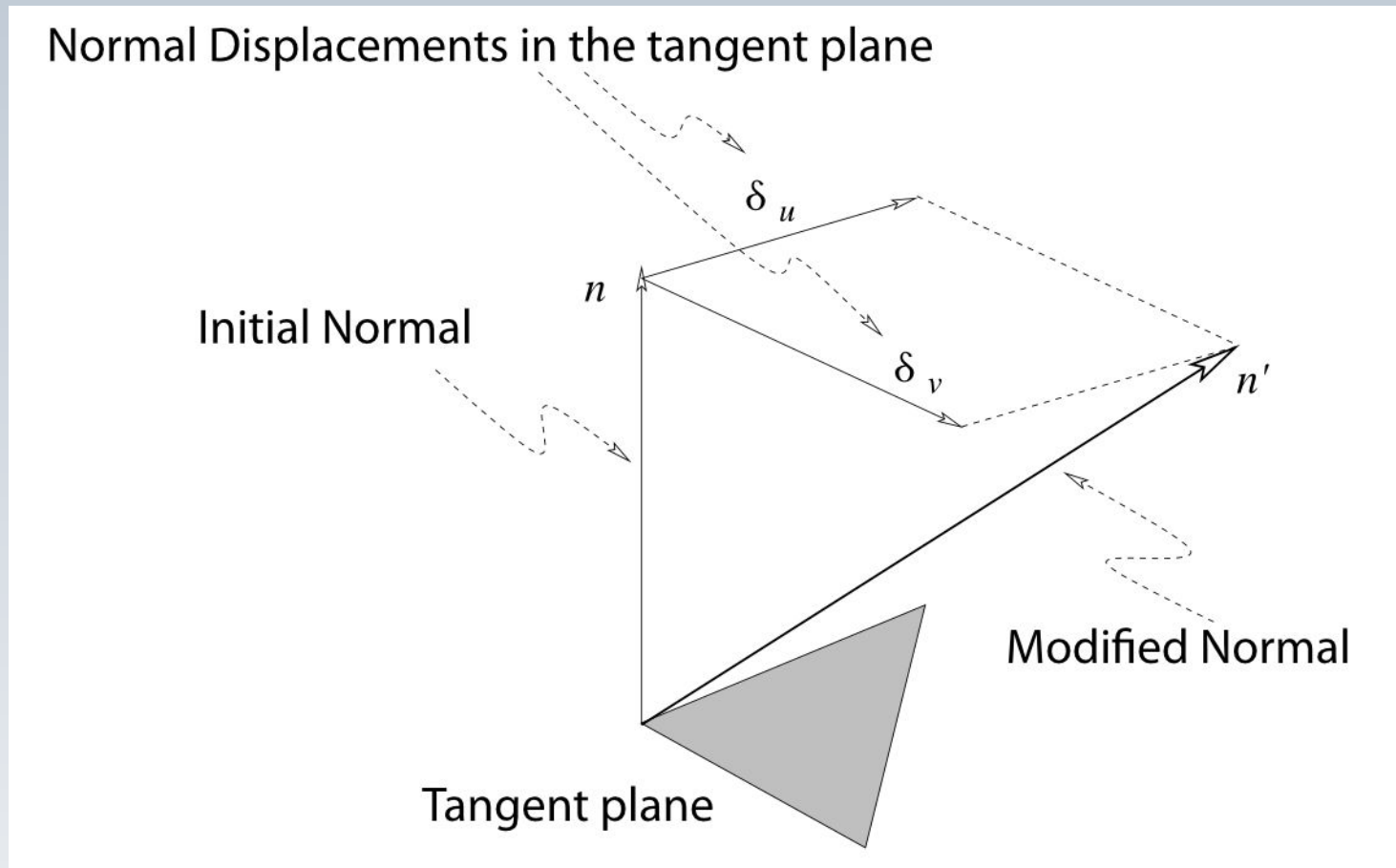
- the contours of the objects have no **relief** and the **silhouette** is not modified
- there is no **self-shadowing**
- there are no **parallax** effects
- there cannot be **holes**
- possible **aliasing** when coming close

→ Should be used for small heights, with a high definition texture

Normal Displacement Storage

Two storage techniques:

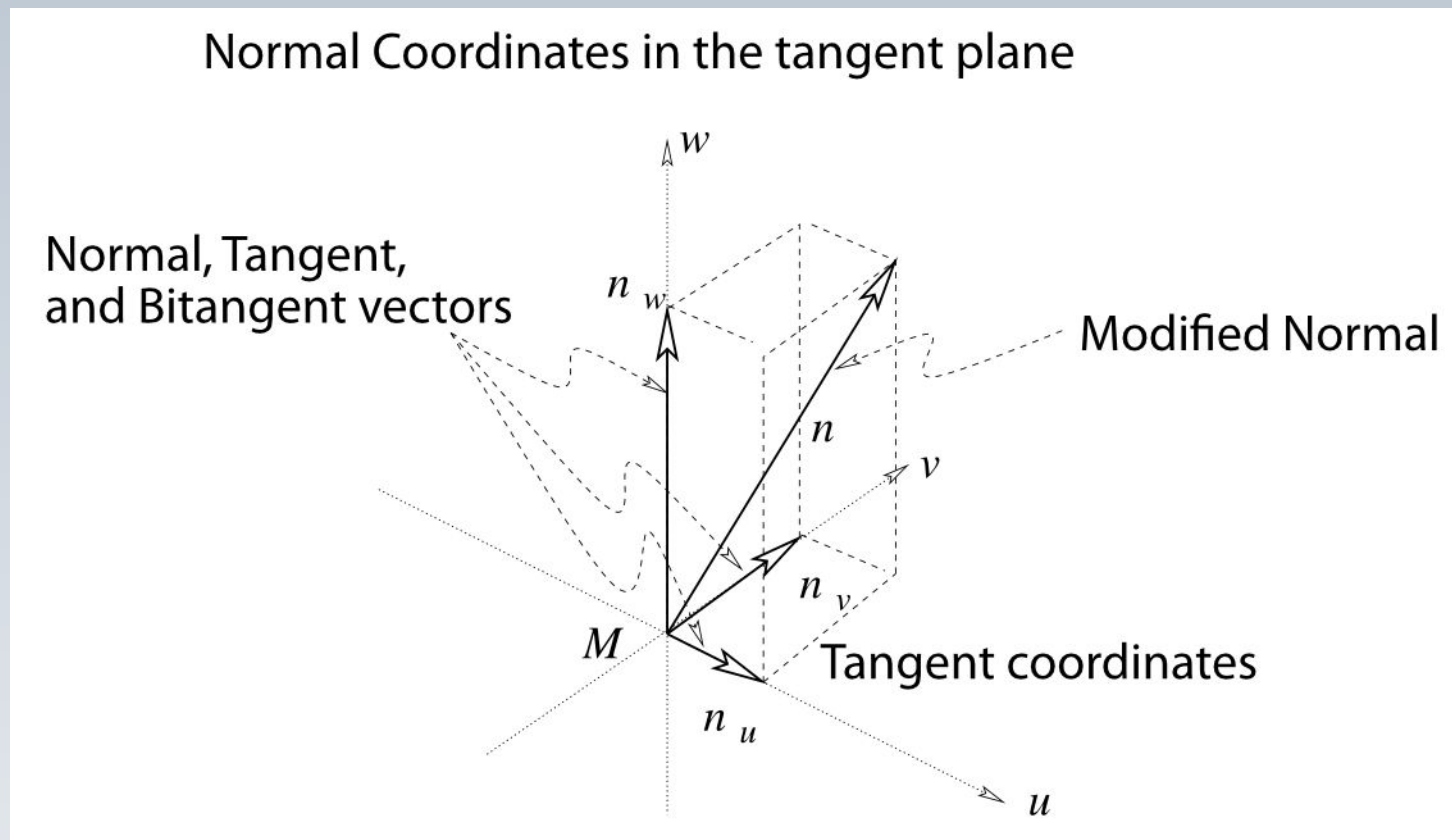
- either by storing two lateral displacements in the tangent plane (**offset map**)



Normal Displacement Storage

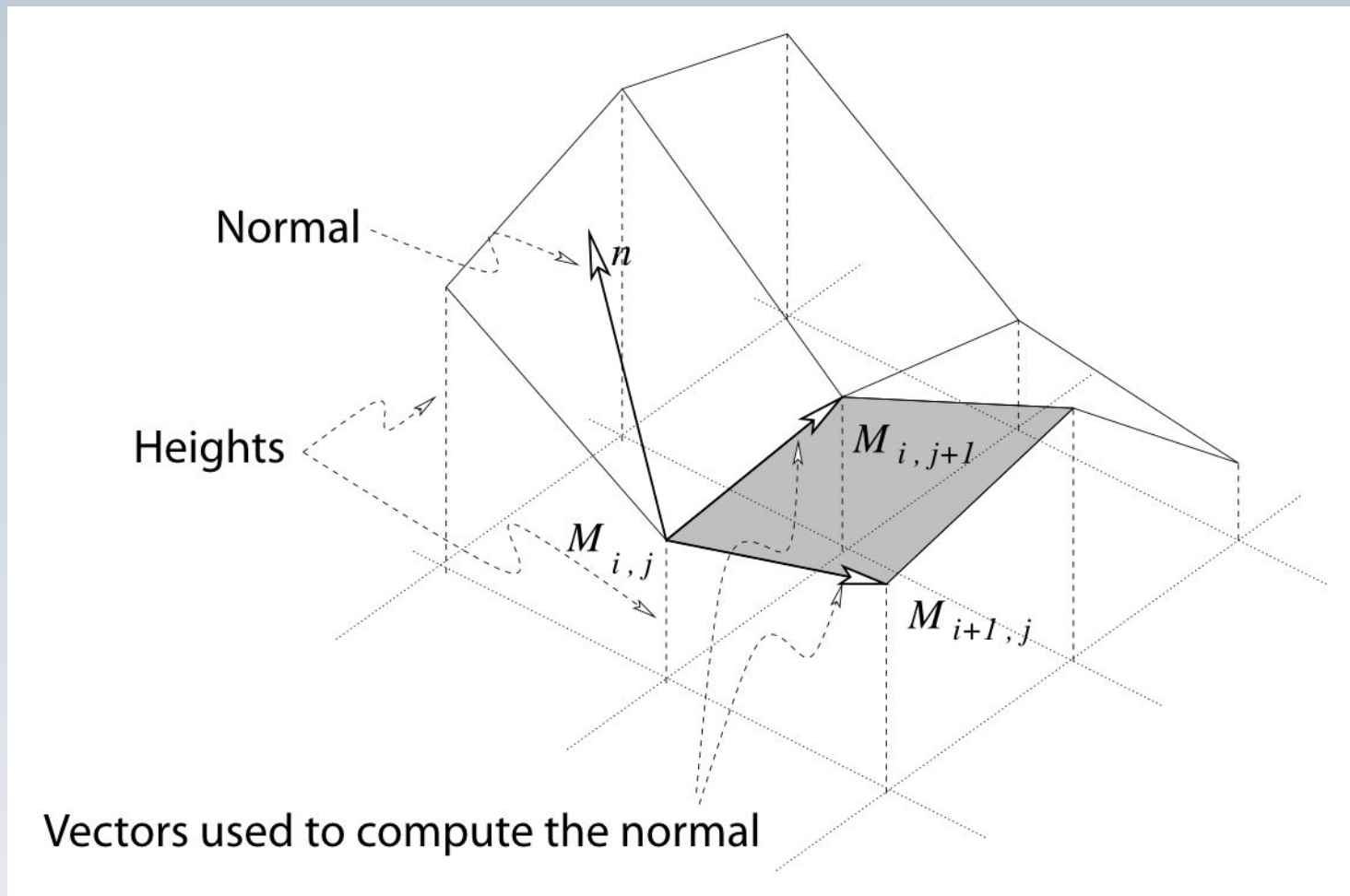
Two storage techniques:

- or by storing directly the normal coordinates



Normal Computation

Normal displacement or coordinates can be computed from a height map (a texture containing the height of each pixel in a one-channel color)



Normal Computation

- The displaced normals can be **precomputed** and stored in an **offset or a normal map**
 - for storage, the values have to be converted into positive values through linear transformation
 - the inverse computation should be made at lookup
- They can be **dynamically** computed from a **height field**
 - the computation should be made in the fragment shader for a finer resolution (the resolution of the image is generally higher than the one of the geometry)
 - a **scaling factor** should be used on the height displacements

Light Computation

- The standard formulas for diffuse and specular lighting are used with the displaced normal values
 - all the computations are to be made in a coherent system
 - the bump normals are displaced in the **tangent coordinate system**,
 - we choose to make all the computations in the **world coordinate system**:
 - light → light source given in world coordinates
 - view → origin of view coordinates transformed into world coordinates through inverse view matrix
 - bump normal is computed in **tangent coordinates** and projected on the (tangent, binormal, normal) given in **world coordinates**

Shader Implementation

- Vertex Shader
 - transformation of view origin into world coordinates
 - transformation of tangent and normal vector from model coordinate system to world coordinates
- Fragment Shader
 - texture look-up for normal displacement (in case of an offset map)
 - or normal displacement computation after 3 height values lookup (one locally and the two other in neighboring texels)
 - transformation of displaced normals into world coordinates by projecting it on the (tangent, binormal, normal) received in **world coordinates**
 - lighting computation from displaced normals

Vertex Shader Implementation

- Vertex Shader

```
// normal and tangent transformed into world
// coordinates
normalOut = (modelMatrix * vec4(norm,0.0)).xyz;
tangentOut = (modelMatrix * vec4(tangent,0.0)).xyz;

// point position transformed from model to world
// coordinates
posWorld = (modelMatrix * vec4(vp,1.0)).xyz;

// light vector in the world coordinates
lightOut = posWorld - lightPosition;

// eye is at the origin in the view coordinates
// view vector in the world space
viewOut = (inverse(viewMatrix) *
           vec4(vec3(0.0),1.0)).xyz - posWorld;
```

Fragment Shader Implementation

- Fragment Shader: displaced normals computation

```
// (1): displacement map texture lookup
normal = texture( displacementMap , texCoordOut ).rgb;
// Transforms normal coordinates from [0..1] to [-1..1]
normal.r = normal.r - 0.5;
normal.g = normal.g - 0.5;
normal = normalize( -normal );

// (2): height map lookup on two neighboring pixels
float h = texture( heightMap, texCoordOut ).r;
float h1 = texture( heightMap,
                  texCoordOut + vec2(1.0,0.0) ).r;
float h2 = texture( heightMap,
                  texCoordOut + vec2(0.0,1.0) ).r;

// normal calculation from cross product
// with alpha as height scaling factor
normal = normalize(cross(vec3(1.0,0.0,alpha*(h1-h)),
                       vec3(0.0,1.0,alpha*(h2-h))));
```

Fragment Shader Implementation

- Fragment Shader: displaced normals in world coordinates

```
// binormal is the cross product of tangent
// and normal
vec3 binormal = cross( normalOut , tangentOut );

// bump normal change of coordinate system:
// from tangent to world coordinates by
// using the tangent and normal received
// from the fragment shader in world coordinates
vec3 bumpNormal = normal.x * tangentOut
                 + normal.y * binormal
                 + normal.z * normalOut;
```

Other Relief Techniques

comparison of different displacement mapping techniques (on the GPU)

Displacement Mapping on the GPU - State of the Art.
László Szirmay-Kalos, and Tamás Umenhoffer.
Comput. Graph. Forum 27(6):1567-1592 (2008)

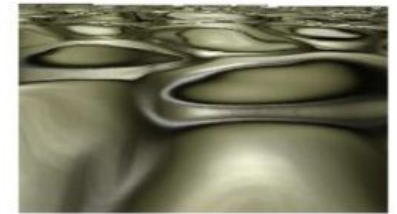
Szirmay-Kalos, Umenhoffer / Displacement Mapping on the GPU



texture mapping



bump mapping



parallax mapping



parallax mapping with offset limiting



parallax mapping with slope



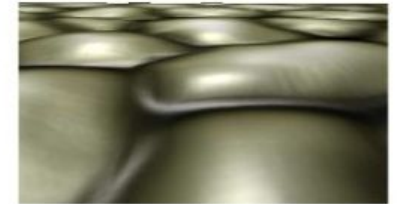
iterative parallax mapping



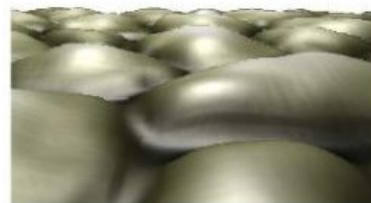
ray marching



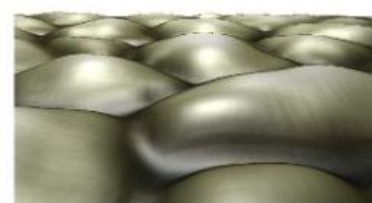
binary search



sphere tracing



relief mapping



cone stepping



per-vertex displacement mapping

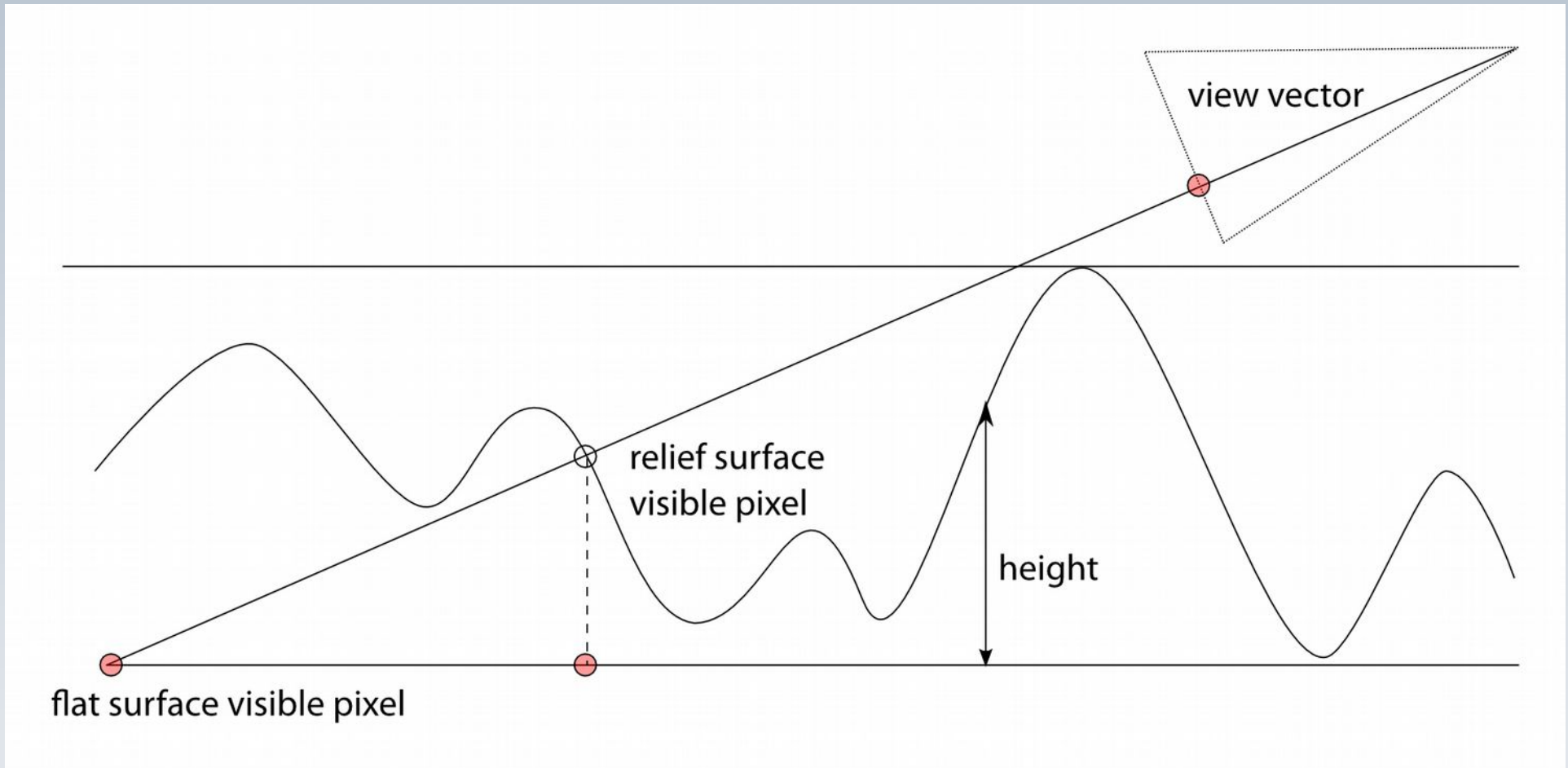
Other Relief Techniques

- same principle as Normal Mapping:
 - the micro structure is stored in a texture
 - the macro structure is stored in a mesh
- per-vertex displacement
 - the vertex shader displaces the vertices along normal
 - possibility to use geometry or tessellation shaders for finer geometrical resolution
- per-pixel displacement
 - through ray tracing, the visible pixel is accessed resulting in pixel displacement

can only work for pixels “below” the surface level

Other Relief Techniques

- ray tracing for displacement mapping



Parallax Mapping

- displacement by fetching the pixel under: parallax mapping (the preceding figure)
- iterative intersection calculation through
 - binary search (dichotomy)
 - linear search
 - sphere tracing
 - cone stepping...
- silhouette processing with local deformation of the height field to get a smooth silhouette
- self-shadowing

GLSL Tutorial & Relief Techniques

(II)

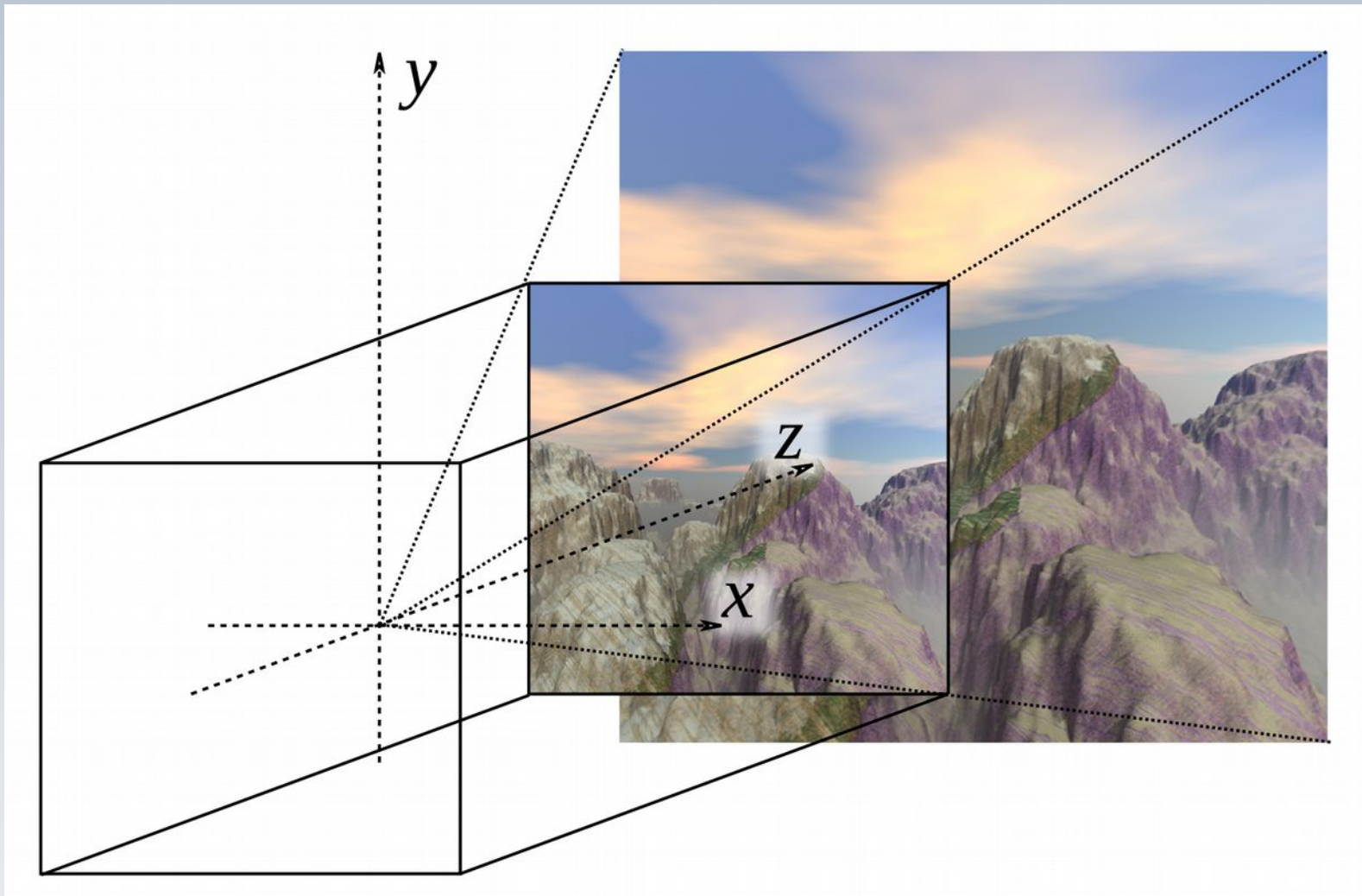
Environment Mapping

Environment Mapping

- rendering of **distant objects**
- **image-based rendering** (wo geometry)
- approximate rendering of
 - **transparency** (environment map)
 - **reflection** (environment map)
 - **lighting** (light map)
- the surfaces used to map the environment are
 - **cube**
 - **sphere**
 - **cylinder...**

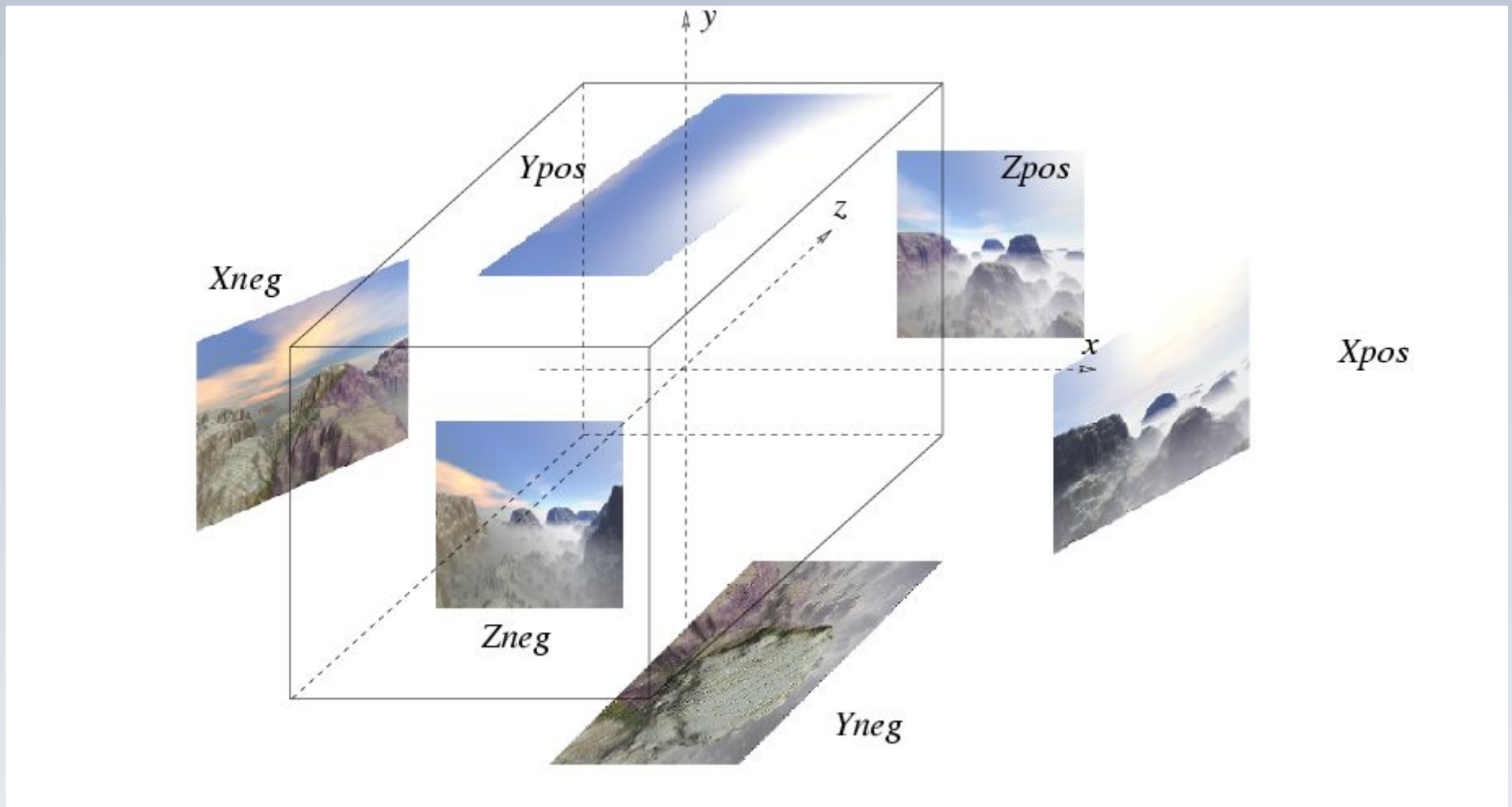
Cube Map Rendering

cube map acquisition (photos) or modeling (scene renderer)



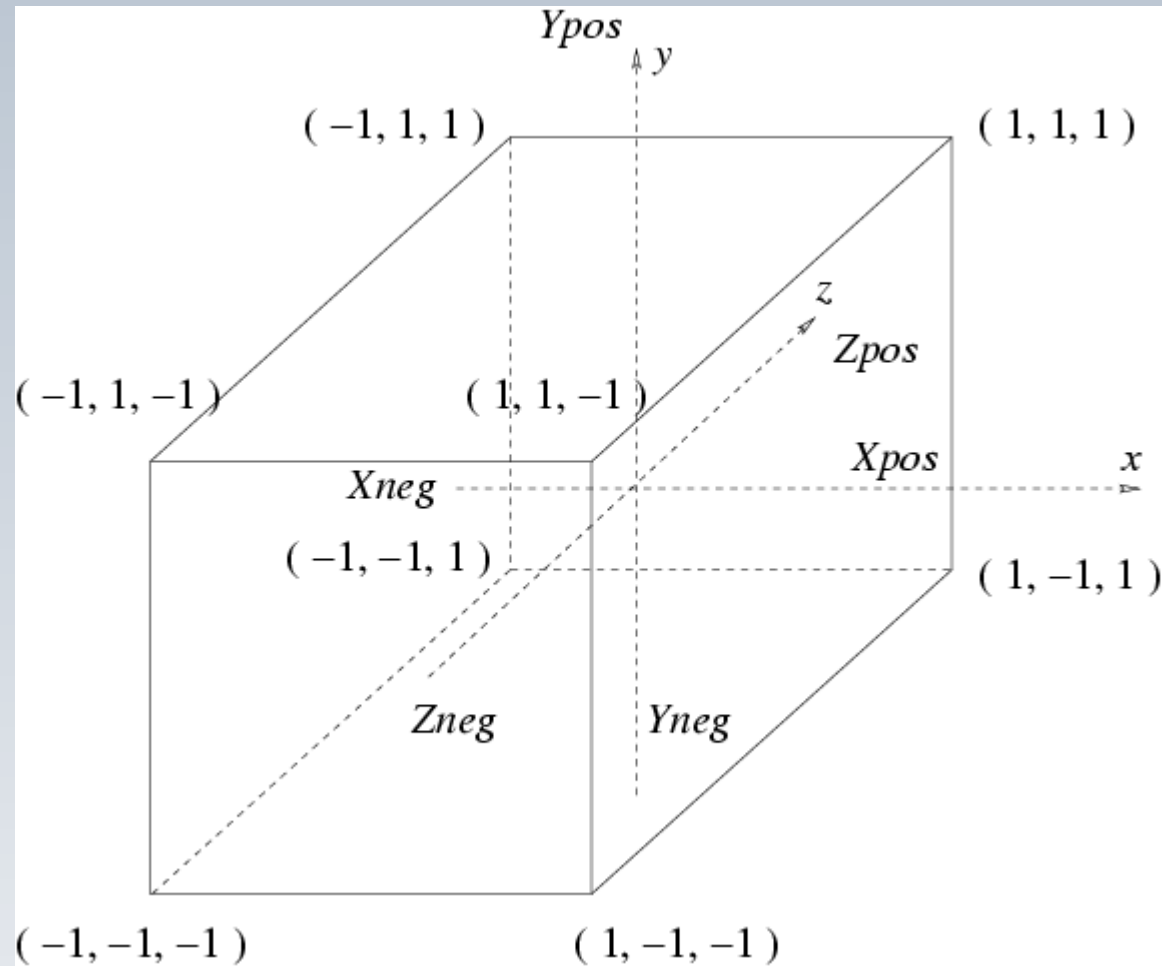
Cube Map Rendering

cube map made of 6 textures (here 3D modeling such as Bryce)



Cube Map Rendering

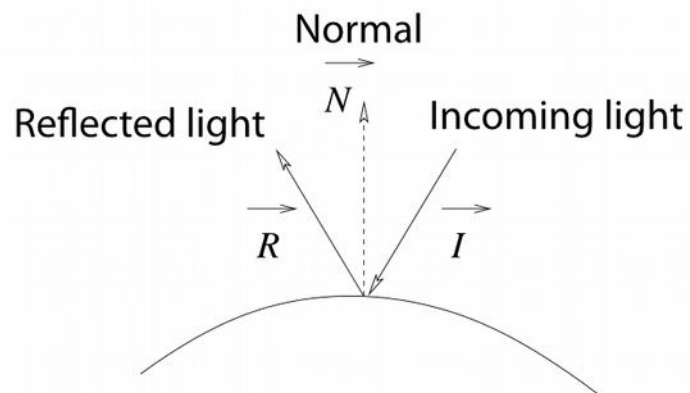
cube map normalized coordinates



Environment Map-based Reflection

instead of coming from a geometrical scene, the reflected light comes from its projection on a cube map.

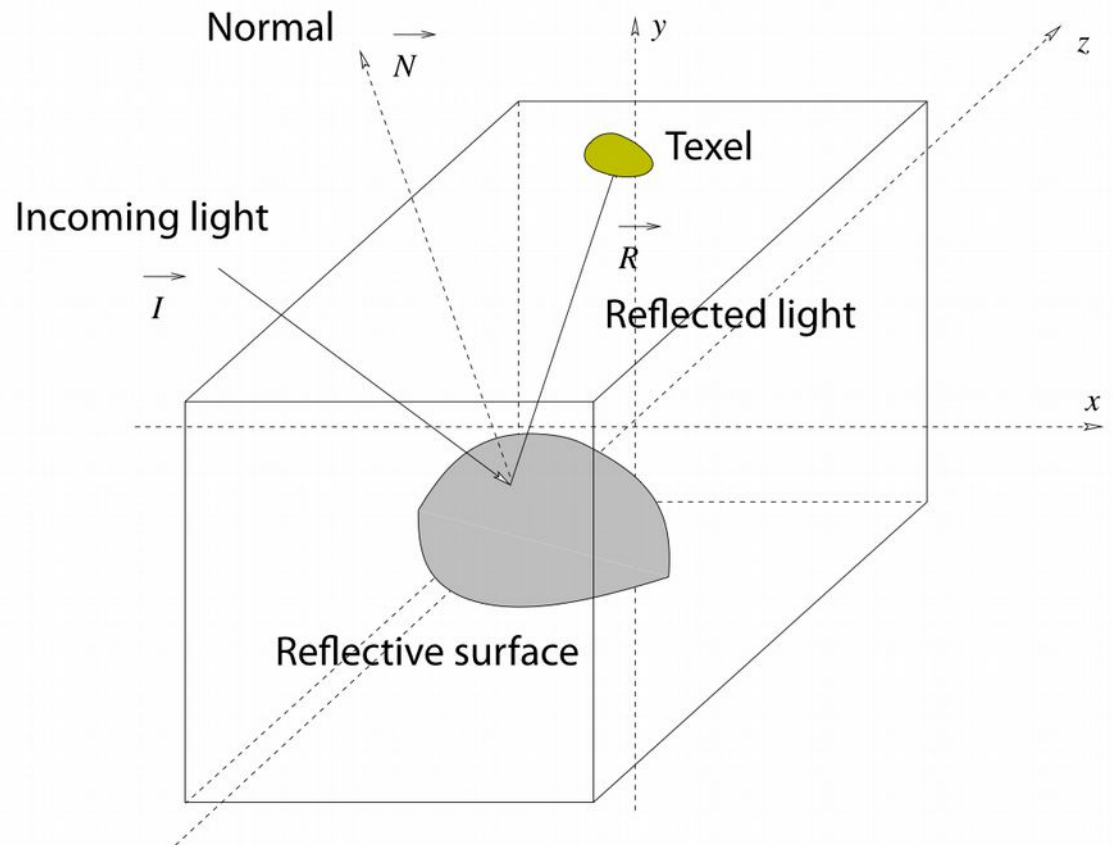
Light reflection



Reflection vector computation

$$\text{If } \|N\| = 1, \quad R - I = 2N(N \cdot I)$$

Reflection simulation through environment cube map



Pros and Cons of Environment Map-based Reflection

- easy to implement
- low computation cost
- only works well for **distant objects** (the camera should not move significantly inside the cube or the textures should be dynamically updated)
- the distant environment must be **static**
- does not model **inter-reflections and self-reflection**
- the virtual scene cannot impact the environment (such as shadowing)

Implementation of Environment Map-based Reflection

- the cube map accesses the reflected texel through a **normalized reflection vector**
 - the reflection vector is the reflection of the view vector with respect to normal on each fragment
- the reflection vector must be computed in the **cube map coordinate system** (the cube map model transformation)

Example of Environment Map-based Reflection



Implementation of Environment Map-based Reflection

- cube map texture loading

```
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X_EXT + i,  
            0, //level  
            GL_RGB, //internal format  
            imageCube[i].cols, //width  
            imageCube[i].rows, //height  
            0, //border  
            GL_BGR, //format  
            GL_UNSIGNED_BYTE, //type  
            imageCube[i].ptr()); // pixel data
```

- cube map modeling:
 - regular mesh (only vertices)

Implementation of Environment Map-based Reflection

cube map rendering: cube with coordinates large enough to contain the scene (deactivate depth test)

- vertex shader
 - texture coordinates do not have to be provided (the 3D vertex coordinates are used as texture coordinates)

```
texCoordOut = vp;
```

- fragment shader
 - specific texture type
 - texture lookup through 3D vector (the ray direction)

```
frag_colour = texture( cubeMap, texCoordOut);
```

Implementation of Environment Map-based Reflection

reflection rendering: compute reflection vector inside vertex shader in cube coordinate system

- vertex shader

```
// vertex in world coordinates
vec3 vertexWorld = (modelMatrix * vec4(vp,1.0)).xyz;
vec3 normalWorld = (modelMatrix * vec4(norm,0)).xyz;
vec3 VertexToEyeWorld = normalize(vertexWorld - eye);

// local light reflection vector in world coordinates
ViewReflectWorld =
    normalize(reflect(VertexToEyeWorld, normalWorld));
// reflection vector in cube map coordinates
ViewReflectWorld = (inverse(modelCubeMapMatrix)
    * vec4(ViewReflectWorld,0.0)).xyz;
```

Implementation of Environment Map-based Reflection

reflection rendering: fragment shader uses the reflection vector to access the texel in the cube map

- fragment shader

```
// reflection vector in cube map coordinates
in vec3 ViewReflectWorld;

// vertex in world coordinates
uniform sampler2DRect planeSurface;

//Cubemap
vec4 color
    = texture(cubemap,
              normalize(ViewReflectWorld));
```